



Sampling based approaches to calculating marginal densities  
- Gelfand and Smith (1990)  
Journal of American Statistical Association

### Notations

$[ ]$  means density

$[X, Y]$  - Joint

$[X|Y]$  - conditional

$[X]$  - marginal

$$[X|Y] = \int \underbrace{[X|Y, Z, W] [Z|W, Y] [W|Y]}_{\substack{\text{integration with respect to } Z \text{ and } W \\ \text{(will read based on LHS)}}}$$

### Substitution or Data Augmentation Algorithm

$$[X] = \int [X|Y] * [Y] dy \quad - ①$$

$$[Y] = \int [Y|X] * [X] dx \quad - ②$$

} can be interpreted  
as expectation  
of conditional w.r.t  
marginal densities.

Substituting ② in ①

$$[X] = \int [X|Y] \underbrace{\int [Y|X'] [X']}_{\substack{\text{integration w.r.t } X \\ \text{integration w.r.t } Y}}$$

$$[X] = \iint [X|Y] [Y|X'] [X']$$

How you can go from  $x'$  to  $x$  using  $y$

$$X = \int h(X, X') [X']$$

$$\text{where } h(X, X') = \int [X|Y][Y|X']$$

integration w.r.t  $X'$   
(though no comments been made in paper)

$X \equiv X'$  which means identical which is a stronger statement than '='.

In the RMS, if we replace  $[X']$  by  $[X]_i$ , then the new fixed point equation will look like

$$[X]_{i+1} = \int h(X, X') [X]_i = \underline{I_h} [X]_i \quad (*)$$

integral operator associated with  $h$ .

Under mild conditions, the following conditions hold for iterations

- 1) Uniqueness:  $[X]$  is unique solution to  $(*)$ .
- 2) Convergence: For any starting  $[X]_0$ , the sequence  $[X]_1, [X]_2, \dots$  defined by  $[X]_{i+1} = I_h [X]_i$  converges to  $[X]$ . (We are not commenting on the distribution of  $[X_i, Y_i]$ , we are only talking about  $X_i$ 's from each iteration).
- 3) Rate:  $\int |[X]_i - [X]| \rightarrow 0$

Extending for 3 variable case

$$[X] = \int [X, Z | Y] [Y]$$

$$[Y] = \int [Y, X | Z] [Z]$$

$$[Z] = \int [Z, Y | X] [X]$$

After substitution of  $[Z]$  in  $[Y]$  and then  $[Y]$  in  $[X]$

$$\begin{aligned} [X] &= \int [X, Z | Y] \int [Y, X | Z] \int [Z, Y | X] [X] \\ &= \int [X, Z | Y] \int [Y, X' | Z] \int [Z, Y | X'] [X'] \\ &= h(X, X'', X') [X'] \end{aligned} \quad \left. \vphantom{\int [X, Z | Y] \int [Y, X' | Z] \int [Z, Y | X'] [X']} \right\} \begin{array}{l} \text{Not} \\ \text{sure} \end{array}$$

$$[X]_{i+1} = h(X, X'', X') [X]_i$$

Important condition emerge here

These conditional distributions  $[U_r, r \neq s | U_s] \forall s$ , uniquely determines the joint density. [different from convergence condition as it converges to marginal density]

## Substitution Sampling

Assumption:  $[X|Y]$  and  $[Y|X]$  are available.

Step 1: Draw  $x^{(0)}$  from  $[X]_0$  - initial distribution  
(it can be degenerate distribution as well which means for a univariate, distribution will take a single value)

Step 2: Given  $x^{(0)}$ , draw  $y^{(0)} \sim [Y|X^{(0)}]$  (given).  
 $[Y]_1 = \int [Y|X] [X]_0$

Step 3: Draw  $X^{(1)} \sim [X|Y^{(1)}]$ . Thus  $[X]_{(1)} = \int [X|Y] [Y]_1$   
 $\therefore X^{(1)} \sim [X]_1 = \int h(X, X') [X']$ . [it will converge to  $[X]$  using the conditions]

Repetition of this cycle will give  $(Y^{(2)}, X^{(2)}) \dots (Y^{(i)}, X^{(i)})$ . [thus form a procedure]

Repetition of the procedure will give  $m$  i.i.d pairs.  $(X_j^{(i)}, Y_j^{(i)})$  (we are repeating the whole procedure of let's say  $n$  iterations again as within one procedure of  $n$  iterations,  $X_i$ 's will not be independent draws)

we have independence across  $j$  but we have dependence within  $j$ .

Using convergence condition,  $X^i \xrightarrow{d} X \sim [X]$   
 $Y^i \xrightarrow{d} Y \sim [Y]$

If we use  $Y_j^{(i)}$  which is  $i^{\text{th}}$  iteration from the  $j^{\text{th}}$  procedure for  $j = 1, 2, \dots, m$ , we can estimate the marginal of  $[X]$

$$\therefore [\hat{X}]_i = \frac{1}{m} \sum_{j=1}^m [X|Y_j^{(i)}]$$

Three variable case

Assume:  $[X, Y|Z]$ ,  $[Y, X|Z]$ ,  $[Z, X|Y]$  are available

$$\begin{aligned}
 [X] &= \int [X, Y|Z][Z] = \int [X, Z|Y][Y] \\
 [Y] &= \int [Y, Z|X][X] = \int [X, Y|Z][Z] \\
 [Z] &= \int [X, Z|Y][Y] = \int [Z, Y|X][X]
 \end{aligned}
 \left. \begin{array}{l} \\ \\ \end{array} \right\} \begin{array}{l} \text{integration w.r.t} \\ \text{variables not} \\ \text{present in LHS} \end{array}$$

$\hookrightarrow$  order 1                       $\hookrightarrow$  order 2

Step 1: Draw  $X^{(0)} \sim [X]_0$ .

Step 2: Draw  $(Z^{(0)'}, Y^{(0)'}) \sim [Z, Y|X^{(0)}]$   
 $\therefore [Z, Y]_0' = \int [Z, Y|X][X]_0$ .

Step 3: Draw  $(Y^{(1)}, X^{(0)'}) \sim [Y, X|Z^{(0)'}]$

Step 4: Draw  $(X^{(1)}, Z^{(1)}) \sim [X, Z|Y^{(1)}]$

Repeat each cycle  $i$  times to produce  $(X^{(i)}, Y^{(i)}, Z^{(i)})$ .  
 $(X^{(i)} \rightarrow X \sim [X], Y^{(i)} \rightarrow Y \sim [Y] \text{ and } Z^{(i)} \rightarrow Z \sim [Z])$

Repeat the entire process  $j$  times to obtain i.i.d  
 $(X_j^{(i)}, Y_j^{(i)}, Z_j^{(i)})$

$$\begin{aligned}
 (X_j^{(i)}, Y_j^{(i)}, Z_j^{(i)}) &\rightarrow [X, Y, Z] \text{ (joint density)} \\
 &\rightarrow \underbrace{[X|Y, Z][Y|Z][Z]}
 \end{aligned}$$

Density estimator:

$$[\hat{X}]_i = \frac{1}{m} \sum_{j=1}^m [X|Y_j^{(i)}, Z_j^{(i)}]$$

where  $y_i^{(i)}$  should be drawn from  $[Y|Z]$  &  $z_i^{(i)}$  should be drawn from  $[Z]$ .

Let's say if  $[X, Z|Y]$  is not available, then it can be sampled from  $[X|Z, Y]$  and  $[Z|Y]$ .

That is, availability for full conditional and reduced conditional.

To do substitution sampling, either we need 3 joint conditional densities, i.e.  $[Y, X|Z]$ ,  $[Z, X|Y]$  and  $[Y, Z|X]$  or six full and partial conditional densities, i.e.  $[Y|X, Z]$ ,  $[X|Z]$ ,  $[Z|X, Y]$ ,  $[X|Y]$ ,  $[Y|Z, X]$  and  $[Z|X]$ . [we will explore this more in next section]

## Gibbs Sampling

$$[X] = \int [X|Y, Z] [Y|Z] [Z]$$

$$[Y] = \int [Y|X, Z] [Z|X] [X]$$

$$[Z] = \int [Z|X, Y] [X|Y] [Y]$$

6 distributions are needed for substitution sampling. (rarely we have it)

Gibbs sampler do it with only full conditionals

Given arbitrary starting set of values  $U_1^{(0)}, U_2^{(0)}, \dots$   
 $U_k^{(0)}$ , we draw

$$\begin{aligned}
 U_1^{(1)} &\sim [U_1 | U_2^{(0)} \dots U_k^{(0)}] \\
 U_2^{(1)} &\sim [U_2 | U_1^{(1)}, \dots U_k^{(0)}] \\
 &\vdots \\
 U_k^{(1)} &\sim [U_k | U_1^{(1)}, \dots U_{k-1}^{(1)}]
 \end{aligned}$$

Each variable is reached in a natural order.

after  $i$  such cycles, we arrive at  $(U_1^{(i)}, \dots, U_k^{(i)})$

Under mild conditions, the following holds

1) convergence:  $(U_1^{(i)}, \dots, U_k^{(i)}) \rightarrow [U_1, U_2 \dots U_k]$  (joint density)  
 $U_s^{(i)} \xrightarrow{d} U_s \sim [U_s]$  as  $i \rightarrow \infty \forall s$  (marginal)

2) rate

3) Ergodic Theorem:  $\lim_{i \rightarrow \infty} \frac{1}{i} \sum_{l=1}^i T(U_1^{(l)}, \dots, U_k^{(l)}) \xrightarrow{a.s.} E(T(U_1, \dots, U_k))$   
 $\forall$  measurable function  $T$ .

[Unlike substitution sampling, the procedure itself is not repeated]

If the procedure itself is repeated, then the marginal density can be estimated as in the previous section.

## Relationship between Gibbs sampling and Substitution Sampling

3 variable case



In case we only have full conditionals, how will we run substitution sampling [instead of Gibbs]

For substitution sampling, we need 6 conditionals.

$$[X] = \int [X|Y, Z] [Z|Y] [Y] \quad - a$$

$$[Y] = \int [Y|X, Z] [X|Z] [Z] \quad - b$$

$$[Z] = \int [Z|X, Y] [Y|X] [X] \quad - c$$

Let's start by estimating  $[Y|X]$

form a sub-substituting algorithm

$$\left. \begin{aligned} [Y|X] &= \int [Y|X, Z] [Z|X] \\ [Z|X] &= \int [Z|X, Y] [Y|X] \end{aligned} \right\} \begin{array}{l} \text{Similar to Data} \\ \text{augmentation} \end{array}$$

We have to draw from full conditionals only to accomodate for reduced conditional densities.

We will do same procedure for  $[Z|Y]$  and  $[X|Z]$

It will look like this

$\Rightarrow [X|Z, Y]$  will have a subloop of  $[Z|X, Y]$  and  $[X|Z, Y]$  to accomodate for  $[Z|Y]$   $[Y^{(0)} \text{ is needed}]$

$\Rightarrow [Y|X, Z]$  will have a subloop of  $[X|Z, Y]$  and  $[Y|X, Z]$  to accomodate for  $[X|Z]$   $[Z^{(0)} \text{ is needed}]$

$\Rightarrow [Z|Y, X]$  will have a subloop of  $[Y|X, Z]$  and  $[Z|Y, X]$  to accomodate for  $[Y|X]$   $[X^{(0)} \text{ is needed}]$

## Procedure

Fix  $x^{(0)}$ ,  $y^{(0)}$  and  $z^{(0)}$

Step 1: Draw  $z^{(0)'} from  $[z | y^{(0)}, x^{(0)}]$$

Step 2: Draw  $y^{(0)'} from  $[y | z^{(0)'}, x^{(0)}]$$

Step 3: Draw  $z^{(1)}$  from  $[z | x^{(0)}, y^{(0)'}]$

$y^{(0)'}$  is been drawn from loop of full conditionals with  $x^{(0)}$  fixed.  $\therefore [y]_0 \xrightarrow{d} y | x$

$y^{(0)'}$  will be used in step 1 in next cycle

Step 4: Draw  $y^{(0)''}$  from  $[y | x^{(0)}, z^{(0)}]$

Step 5: Draw  $x^{(0)'} from  $[x | y^{(0)'}, z^{(0)}]$$

Step 6: Draw  $y^{(1)}$  from  $[y | x^{(0)'}, z^{(1)}]$

$x^{(0)'}$  is been drawn from loop of full conditionals with  $z^{(0)}$  fixed.  $\therefore [x]_0 \xrightarrow{d} x | z$

$x^{(0)'}$  will be used in step 4 in next cycle

Step 7: Draw  $x^{(0)''}$  from  $[x | z^{(0)}, y^{(0)}]$

Step 8: Draw  $z^{(0)''}$  from  $[z | x^{(0)'}, y^{(0)}]$

Step 9: Draw  $x^{(1)}$  from  $[x | z^{(0)'}, y^{(1)}]$

$z^{(0)''}$  is been drawn from loop of full conditionals with  $y^{(0)}$  fixed.  $\therefore [z]_0 \xrightarrow{d} z | y$

$z^{(0)''}$  will be used in step 7 in next cycle

In the paper, a simplified version is given which is shorter and efficient.

Step 1: Draw  $y^{(0)'}$  from  $[y | x^{(0)}, z^{(0)}]$

Step 2: Draw  $z^{(0)'}$  from  $[z | y^{(0)'}, x^{(0)}]$

Step 3: Draw  $x^{(0)'}$  from  $[x | y^{(0)'}, z^{(0)'}]$

Step 4: Draw  $Y^{(1)}$  from  $[Y | X^{(0)}, Z^{(0)}]$   
Step 5: Draw  $Z^{(1)}$  from  $[Z | Y^{(1)}, X^{(0)}]$   
Step 6: Draw  $X^{(1)}$  from  $[X | Y^{(1)}, Z^{(1)}]$

It looks like 2 iterations of Gibbs sampler.