# Computational MR imaging Laboratory 4: Reconstruction of non-Cartesian k-space data

Code submission is due by 12:00 before the next Thursday lab section. Please upload your code to StudOn in a described format. Late submissions will not be accepted.

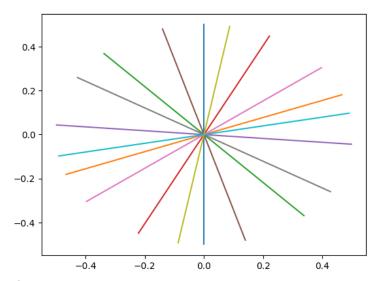
## Learning objectives

- Reconstruct non-Cartesian MRI data using gridding and NUFFT toolbox
- Apply gridding operations: density compensation, oversampling and deapodization
- Learn to use the NUFFT toolbox

## 1. Radial sampling pattern:

- a. Data load
  - i. Radial kdata is loaded on *k radial*.
    - 1. Column: the readout dimension for each radial line.
    - 2. Radial acquisition angle: 111.246117975° (golden angle)
  - ii. Plot the acquired k-space.
- b. Generate a sampling trajectory that corresponds to this data for the reconstruction. Figure 1 shows a plot of the first 10 spokes of such a trajectory for reference.
  - i. Implement a method, *get\_traj*.
    - 1. The spoke length should be 1 from -0.5 to 0.5.
    - 2. The first spoke should start at the angle of 90°.
    - 3. Use self.Pl and self.GA for  $\pi$  and golden angle, respectively. They are in *radian* unit.
    - 4. Think about a complex number in polar form.
- c. Implement a method, *calc\_nyquist*, to calculate the nyquist rate.
  - i. Consider what does each axis of *k* radial mean.

k-space trajectory: 10 spokes



**Figure 1:** Radial trajectory with golden angle increment. Note that the first angle is at pi/2.

## 2. Basic gridding reconstruction:

- Reconstruct this dataset using the provided grid function that grids 2D non-Cartesian k-space data to Cartesian k-space data using triangular gridding kernel of width 2
  - i. Implement a method, *grid\_radial*.
  - ii. Map the radial kdata to the Cartesian space using the *grid\_radial* method.
  - iii. Reconstruct the Cartesian kdata
- b. Plot the gridded k-space data and the reconstructed image.
- c. Comment on the artifacts. Can you guess what organ was imaged?

## 3. Density compensation:

- a. Implement a method, get\_ramp.
  - i. Consider the minimum and maximum value of each spoke.
- b. Implement a method, *grid\_radial\_ds*.
  - i. Apply the ramp filter from *get\_ramp* to the *k\_radial* data.
  - ii. Apply gridding function to the density compensated kdata.
- c. Reconstruct density compensated Cartesian kdata.
- d. Plot gridded kspace and the reconstructed image.
- e. Do you need to employ oversampling and de-apodization on this dataset? Explain your answer.

## 4. Oversampling

- a. Implement a method, grid\_radial\_ds\_os
  - i. Apply the ramp filter from *get\_ramp* to the *k\_radial* data.
  - ii. Apply gridding function to the density compensated kdata.
    - 1. Think about the matrix size to oversample the kdata for the gridding function.
- b. Implement a method, center\_crop\_2d.
- c. Reconstruct an oversampled data and crop it by following steps below.
  - i. Oversample the density compensated kdata.
  - ii. Apply inverse FFT.
  - iii. Crop the reconstructed image.
- d. Plot the gridded kspace data and both reconstructed images, oversampled and cropped.

#### 5. De-apodization

- a. Compute the de-apodization function in the image domain and apply to the gridded image with oversampling of 2.
  - i. Implement a method, *get\_c*, to get a gridding kernel in the image domain.
    - 1. think of the convolution of the delta function.
    - 2. The gridding kernel should be in the image domain.
  - ii. Implement a method, deapodization.
    - 1. Get the gridding kernel using *get\_c*.
    - 2. Reconstuct the density compensated oversampled kdata

a. Apple deapodization to the reconstructed image.

3. Crop the oversampled image to its original shape.

$$\widehat{m}(x,y) = \frac{1}{c(x,y) + a} \left\{ \left[ \left( m(x,y) * s(x,y) \right) c(x,y) \right] * \operatorname{III} \left( \frac{x}{FOV_x}, \frac{y}{FOV_y} \right) \right\}$$

#### 6. NUFFT toolbox

See these links for NUFFT toolbox: Source, Tutorial

- a. Reconstruct the radial dataset using a widely used NUFFT toolbox from the research community.
  - i. Implement a method, *nufft\_traj* 
    - 1. Keep in mind that the length of the trajectory spoke is  $2\pi$  ( $-\pi \sim \pi$ ) and the first spoke starts at the angle of 90°.
    - 2. Trajectory for the NUFFT operator needs to be in shape of (2, x) where 2 is the separate channels of real and imaginary part of the trajectory.
  - ii. Implement a method, nufft\_kdata
    - 1. Use density compensated kdata
  - iii. Implement a method, *nufft\_recon* 
    - Call nufft\_traj and nufft\_kdata to define trajectory and kdata for NUFFT.
    - 2. Define a NUFFT adjoint operator to reconstruct the kdata.
    - 3. Reconstruct the kdata with the NUFFT adjoint operator.
- b. Compare NUFFT reconstructions with gridding reconstruction using the triangular kernel and discuss results.