Implementation

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def householder reflection(a):
    Create a Householder reflection matrix for a vector a.
    Parameters:
    a (numpy.ndarray): Input vector.
    Returns:
    v (numpy.ndarray): Householder reflection vector.
    v = a.copy()
    v[0] += np.sign(a[0]) * np.linalg.norm(a)
    v = v / np.linalg.norm(v)
    return v
def golub kahan bidiagonalization(A):
    Perform Golub-Kahan bidiagonalization on matrix A.
    Parameters:
    A (numpy.ndarray): Input matrix with shape (m, n).
    Returns:
    B (numpy.ndarray): Bidiagonal matrix.
    U (numpy.ndarray): Orthogonal matrix U.
    V (numpy.ndarray): Orthogonal matrix V.
    m, n = A.shape
    U = np.eye(m)
    V = np.eye(n)
    B = A.copy()
    for i in range(min(m, n)):
        # Hosholder's reflection from the left
        x = B[i:, i]
        v = householder_reflection(x)
        H = np.eye(m - \overline{i}) - 2 * np.outer(v, v)
        B[i:, :] = np.dot(H, B[i:, :])
        U[:, i:] = np.dot(U[:, i:], H)
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if i < n - 1:
            # Hosholder's reflection from the right
            x = B[i, i+1:]
            v = householder reflection(x)
            H = np.eye(n - (i+1)) - 2 * np.outer(v, v)
            B[:, i+1:] = np.dot(B[:, i+1:], H)
            V[:, i+1:] = np.dot(V[:, i+1:], H)
    return B, U, V
def compute svd from bidiagonal(B, U, V):
    m, n = B.shape
    U b, Sigma, Vt b = np.linalg.svd(B)
    U = np.dot(U, U b)
    V = np.dot(V, Vt b.T)
    return U, Sigma, V.T
def reconstruct matrix(U, Sigma, Vt):
    Sigma mat = np.zeros((U.shape[0], Vt.shape[1]))
    np.fill_diagonal(Sigma_mat, Sigma)
    A reconstructed = np.dot(U, np.dot(Sigma mat, Vt))
    return A reconstructed
```

Example