CS3712 - Image Processing

Noise filter implementation results

Index No: 190290U

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1. Mean filter

Function: applyMeanFiltering(image, kernelSize)

Parameters:

- image: The matrix representation of the input image
- kernelSize: The number of rows or columns of the kernel (preferably an odd number)

returns: The matrix representation of the output image

Original image:



Result when kernelSize = 3



Result when kernelSize = 5



Result when kernelSize = 7



2. Median filter

Function: applyMedianFiltering(image, kernelSize):

Parameters:

- image: The matrix representation of the input image
- kernelSize: The number of rows or columns of the kernel (preferably an odd number)

returns: The matrix representation of the output image

Original image:



Result when kernelSize = 3



Result when kernelSize = 5



Result when kernelSize = 7



3. K-closest averaging filter

Function: applyKClosetAveraging(image, kernelSize, K)

Parameters:

- image: The matrix representation of the input image
- kernelSize: The number of rows or columns of the kernel (preferably an odd number)
- K: The K value which determines the effective number of elements in the kernel that is considered (Should be less than or equal to square of kernelSize)

returns: The matrix representation of the output image

Original image:



Result when kernelSize=5 and K=23



Result when kernelSize=5 and K=8



4. Threshold averaging filter

Function: applyThresholdAveraging(image, kernelSize, T)

Parameters:

- image: The matrix representation of the input image
- kernelSize: The number of rows or columns of the kernel (preferably an odd number)
- T: The threshold value (0 < T < 255)

returns: The matrix representation of the output image

Original image:

noisy image: gaussian noise with mea= 0.005 & vari= 0.005

Result when kernelSize=5 and T=25 $\,$



Result when kernelSize=5 and T=210

