

Package ‘alphashape’

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Type Package

Title Create Delaunay triangulations, Voronoi vertices and alpha shape for n number of dimension using the QHULL library

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Description Makes an Alpha shape for any number of N dimension using the Delaunay triangulations generated using via the Qhull library (www.qhull.org)
This package has been tested to work up to 5 number of dimension.

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Depends R (>= 3.5.1)

Imports devtools

Encoding UTF-8

LazyData true

RoxygenNote 7.0.2

Suggests testthat

NeedsCompilation no

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alphashape

Computation of n dimension α -shape

Description

Implementation in n dimension of the alpha shape using the Q-hull library

Package: alphashape
 Date: 2019-03-14
 License: GPL-2
 LazyLoad: yes

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References

<http://www.qhull.org/html/qh-code.htm>

alpha_shape	<i>alpha_shape</i>
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Description

Compute an alpha Shape Grid using the Q-hull library.

Usage

```
alpha_shape(point, alphaRange, maxs, mins, n)
```

Arguments

point	observation as dataframe or matrix
alphaRange,	range of alpha value
mins	Vector of length n listing the point space minimum for each dimension. @param
	maxs Vector of length n listing the point space maximum for each dimension.
n	n dimension point co-ordinate

Details

The calculation is done by assigning the trigulation index when the grid cell center lies within the trigulation or -1 if it lies outside

Value

grid stack as vector, gridSimplex, and the inputted grid point.

Examples

```
x = c(30,70,20,50,40,70,20)
y = c(35,80,70,50,60,20,30)
p = data.frame(x,y)
alpha_shape(point = p,maxs = c(70,80),mins = c(20,20),n = 5,alphaRange = c(1:20))
```

convex_hull	<i>Convex hull in d-dimensions.</i>
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Description

This function calculates the **convex hull** around a set of n points in d -dimensional space using the **Qhull** library.

Usage

```
convex_hull(points = NULL)
```

Arguments

points	points is an n -by- d of dataframe or matrix. The rows of points represent n points in d -dimensional space.
options	String containing extra options for the underlying Qhull command.(See the Qhull documentation (../doc/html/qdelaun.html) for the available options.) The Qbb option is always passed to Qhull. The default options are Qt. The degenerate (zero area) regions are returned. For silent operation, specify the option Pp.

Value

Returns a list consisting of...

References

Barber CB, Dobkin DP, Huhdanpaa H (1996) The Quickhull algorithm for convex hulls. ACM Transactions on Mathematical Software, 22(4):469-83 <https://doi.org/10.1145/235815.235821>.

See Also

Used internally by [convex_layer](#)

Examples

```
# Define points
x <- c(30, 70, 20, 50, 40, 70)
y <- c(35, 80, 70, 50, 60, 20)
p <- data.frame(x, y)
# Create convex hull and plot
ch <- convex_hull(points = p)
plot(p, pch = as.character(seq(nrow(p))))
polygon(ch$hull_points, border = "red")
```

delaunay	<i>Delaunay triangulation in N-dimensions.</i>
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Description

The Delaunay triangulation is a tessellation of the convex hull of the points such that no N-sphere defined by the N-triangles contains any other points from the set. This function calculates the Delaunay triangulation in N-dimensions using the qhull library

Usage

```
delaunay(points = NULL)
```

Arguments

point	point is an n-by-dim dataframe or matrix. The rows of point represent n points in dim-dimensional space.
options	String containing extra options for the underlying Qhull command. (See the Qhull documentation (../doc/html/qdelaun.html) for the available options.) The Qbb option is always passed to Qhull. The default options are Qcc Qc Qt Qz for dim < 4 and Qcc Qc Qt Qx for dim ≥ 4. If neither of the QJ or Qt options are supplied, the Qt option is passed to Qhull. The Qt option ensures all Delaunay regions are simplicial (e.g., triangles in 2-d). See ../doc/html/qdelaun.html for more details. The degenerate (zero area) regions are returned. For silent operation, specify the option Pp.
full	Return all information associated with the triangulation as a list and these are triangulation (tri), a vector of facet areas (areas) and a list of neighbours of each facet (neighbours) OR return the convexhull and the input point

Examples

```
# Define points
x <- c(30, 70, 20, 50, 40, 70)
y <- c(35, 80, 70, 50, 60, 20)
p <- data.frame(x, y)
# Create Delaunay triangulation and plot
dt <- delaunay(points = p)
plot(p, pch = as.character(seq(nrow(p))))
```

find_simplex	<i>Find Simplex</i>
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Description

Returns the simplices of the delaunay triangulation which contains a given point.

Usage

```
find_simplex(tri, inputPoint, testPoint)
```

Arguments

tri	delaunay trigulation simplex using delaunay
inputPoint	n-by-dim dataframe or matrix of original inputPoint.
testPoint	n-by-dim dataframe of points or matrix to check.

Details

Given a grid point and a test point point, the find Simplex will identify the simplicies containing the test point. It works by first checking for all point inside a convex hull, and then check if the center of the grid cell is inside the trigulation

Value

A n*m vector containing the result. -1 if a given point is outside the trigulation, or the trigulation index if the center of the cell is inside the alpha shape

Examples

```
x = c(30,70,20,50,40,70)
y = c(35,80,70,50,60,20)
p = data.frame(x,y)
v=voronoi(point =p)
meshGrdSpace = grid_coordinates(mins=c(15,0), maxs=c(35,200), nCoords=5)
simplex <- find_simplex(v$tri, v$inputPoints,meshGrdSpace)
```

grid_coordinates	<i>Grid Coordinates</i>
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Description

Create an n-dimensional grid of coordinates across space.

Usage

```
grid_coordinates(mins, maxs, nCoords)
```

Arguments

mins	Vector of length n listing the point space minimum for each dimension.
maxs	Vector of length n listing the pointspace maximum for each dimension.
nCoords	Number of coordinates across the point space in all dimensions.

Details

This function creates a grid of coordinates systematically located throughout the specified point space to enable visualisation of alpha shape . The extent of the grid is given by the mins and maxs, and the number of coordinates for each dimension is given by nCoords.

Value

A matrix with n columns.

Examples

```
# Point space grid coordinates usage
xy = grid_coordinates(mins=c(15,0), maxs=c(35,200), nCoords=5)
```

in_convex_hull	<i>in convex hull</i>
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Description

To test if a given point is inside the convex hull. TRUE if the point lies within the hull and FALSE if it lies outwith the hull

Usage

```
in_convex_hull(hull = NULL, test_points = NULL)
```

Arguments

points points to make convex hull
test_points: dataframe or matrix n-by-dim of points to check.

Value

A $n \times m$ vector containing the result. True if a given point was inside the convexhull , otherwise false

Examples

```
# Define points to create the convex hull
x <- c(30, 70, 20, 50, 40, 70)
y <- c(35, 80, 70, 50, 60, 20)
p <- data.frame(x, y)
ch <- convex_hull(points = p)
# Check if some new points are in the convex hull
new = data.frame(c(20, 50), c(20, 50))
checks <- in_convex_hull(hull=ch, test_points = new)
```

voronoi	<i>Get Voronoi triangle and Delaunay triangulation</i>
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Description

Get Voronoi vertices(circumcenters of Delaunay triangle) and Delaunay triangulation in N-dimensions using the qhull library. The Voronoi diagram is the nearest-neighbor map for a set of points. Each region contains those points that are nearer one input site than any other input site. They can also be describe as the circumcenters of Delaunay triangle. The Delaunay triangulation is a tessellation of the convex hull ofthe points such that no N-sphere defined by the N-triangles contains any other points from the set.

Usage

```
voronoi(points = NULL)
```

Arguments

point	point is an n-by-dim dataframe or matrix. The rows of point represent n points in dim-dimensional space.
options	String containing extra options for the underlying Qhull command.(See the Qhull documentation (../doc/html/qvoronoi.html) for the available options.) The Qbb option is always passed to Qhull. The default options are Qcc Qc Qt Qz for dim < 4 and Qcc Qc Qt Qx for dim ≥ 4. If neither of the QJ or Qt options are supplied, the Qt option is passed to Qhull. The Qt option ensures all Delaunay regions are simplicial (e.g., triangles in 2-d). See ../doc/html/qdelaun.html for more details.
full	Return all information associated with triangulation as a list. This will return the triangulation (tri), list of voronoi Vertices (voronoiVertices) , vpoints (points) ,matrix list of the circum radii (circumRadii), matrix list of (SimplicesPoints) and a list of neighbours of each facet (neighbours).

Value

The voronoi vertices, circumRadii, triangulation Points and Delaunay triangulation

Examples

```
# Define points
x <- c(30, 70, 20, 50, 40, 70)
y <- c(35, 80, 70, 50, 60, 20)
p <- data.frame(x, y)
# Create Voronoi diagram and plot
vd <- voronoi(points = p)
plot(p, pch = as.character(seq(nrow(p))))
```


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