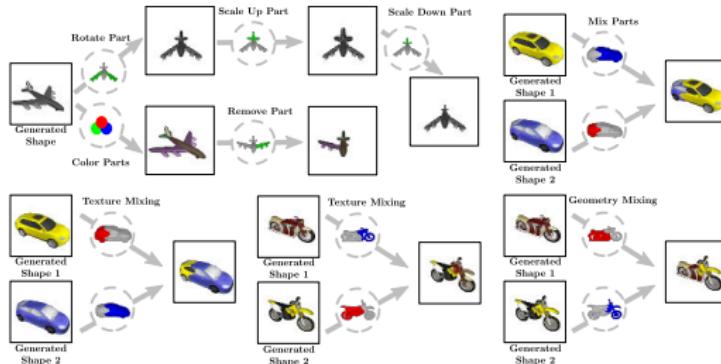


# PartNeRF: Generating Part-Aware Editable 3D Shapes without 3D Supervision

Konstantinos Tertikas<sup>1,3</sup> Despoina Paschalidou<sup>2</sup> Boxiao Pan<sup>2</sup>  
Jeong Joon Park<sup>2</sup> Mikaela Angelina Uy<sup>2</sup> Ioannis Emiris<sup>3,1</sup> Yannis Avrithis<sup>4</sup>  
Leonidas Guibas<sup>2</sup>

<sup>1</sup>National and Kapodistrian University of Athens <sup>2</sup>Stanford University  
<sup>3</sup>Athena RC, Greece <sup>4</sup>Institute of Advanced Research in Artificial Intelligence (IARAI)

[https://ktertikas.github.io/part\\_nerf](https://ktertikas.github.io/part_nerf)



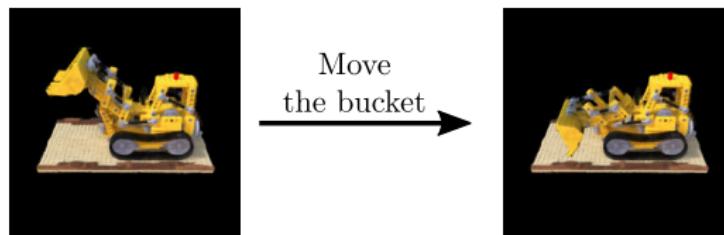
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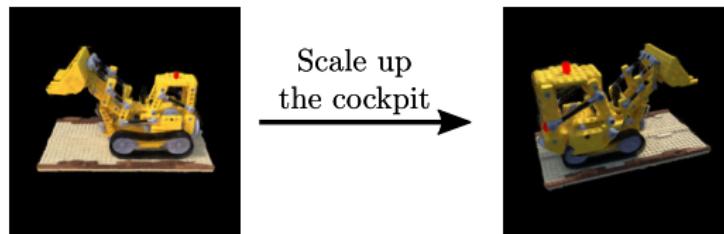
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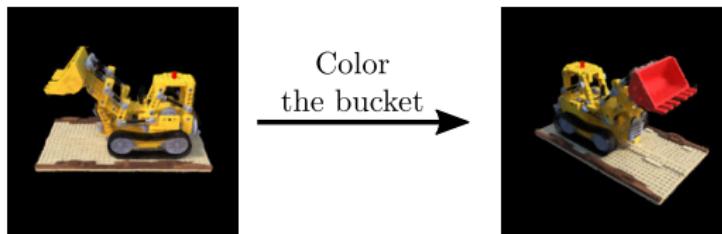
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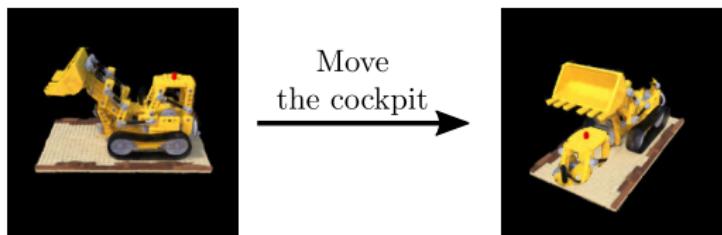
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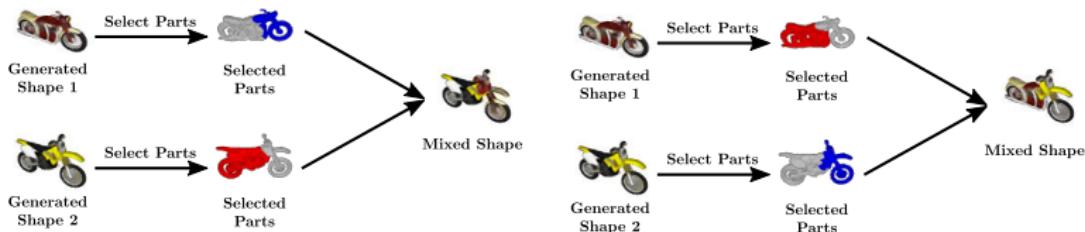
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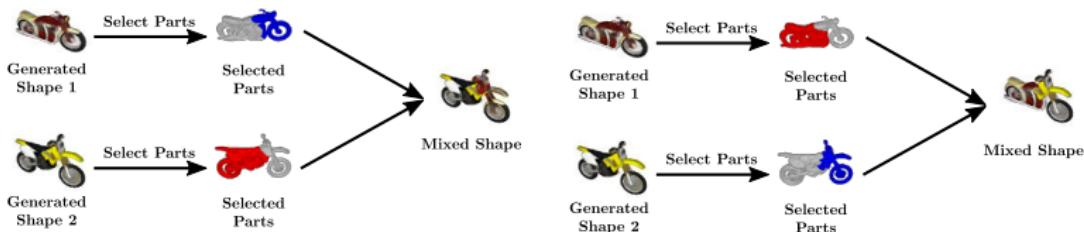
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We can specify **what object regions to edit** through parts.

# Generative Models for 3D Object Synthesis

## Part-based Generative Models



Hao et al. 2020



Hertz et al. 2022

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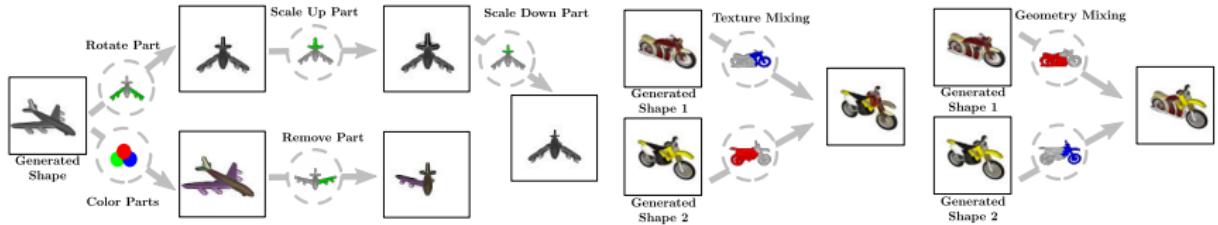
✗ Cannot change the appearance of an object

✓ Can generate high quality 3D meshes

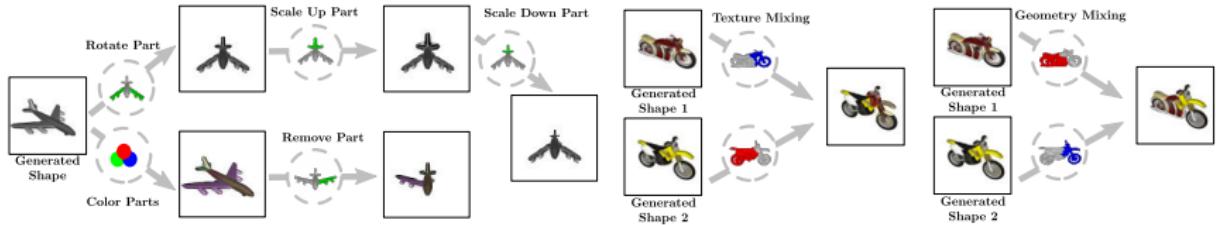
✓ Require 2D supervision during training

✗ No explicit part-level control

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**Bonus:** We want our model to be **trained only from posed images!!!**

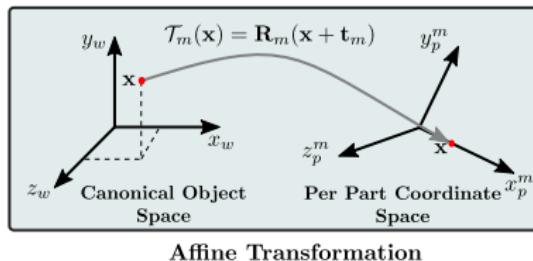
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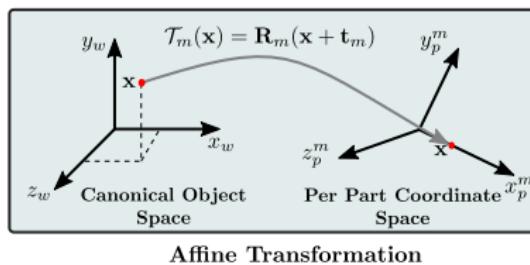
1. an *affine transformation*  $T_m(x) = R_m(x + t_m)$  that maps a 3D point  $x$  to the **local coordinate system of the part**, where  $t_m \in \mathbb{R}^3$  is the translation vector and  $R_m \in SO(3)$  is the rotation matrix



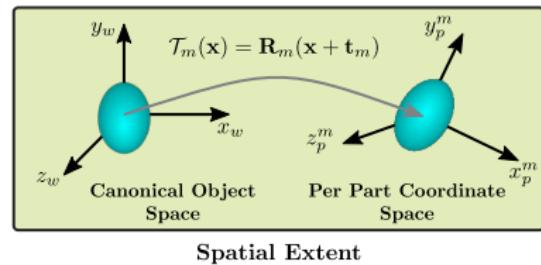
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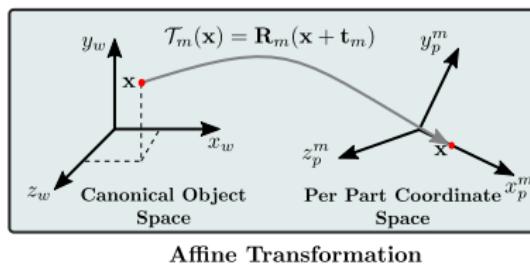


Spatial Extent

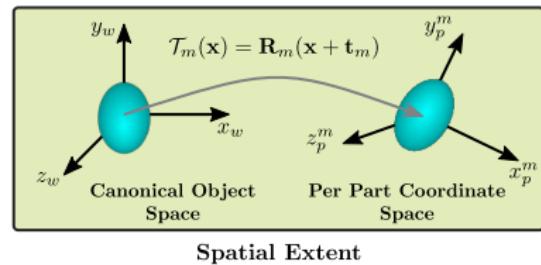
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3. two latent codes: **shape**  $z_m^s \in \mathbb{R}^{L_s}$  and **texture**  $z_m^t \in \mathbb{R}^{L_t}$  that control and shape and the appearance of each part.



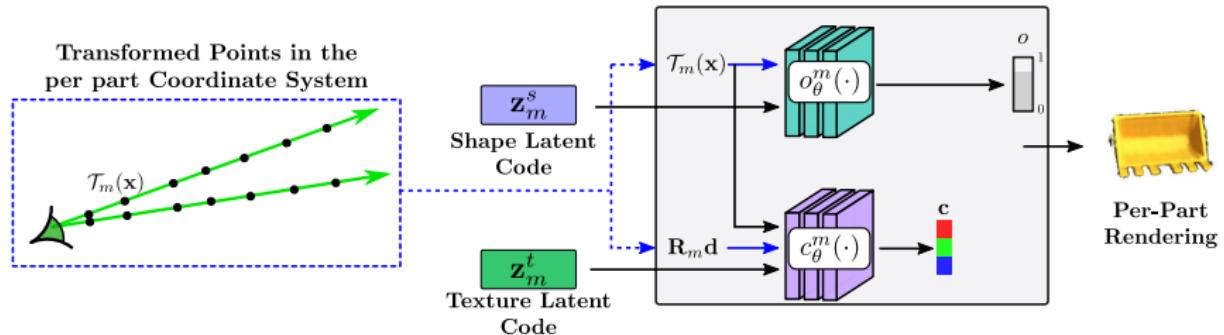
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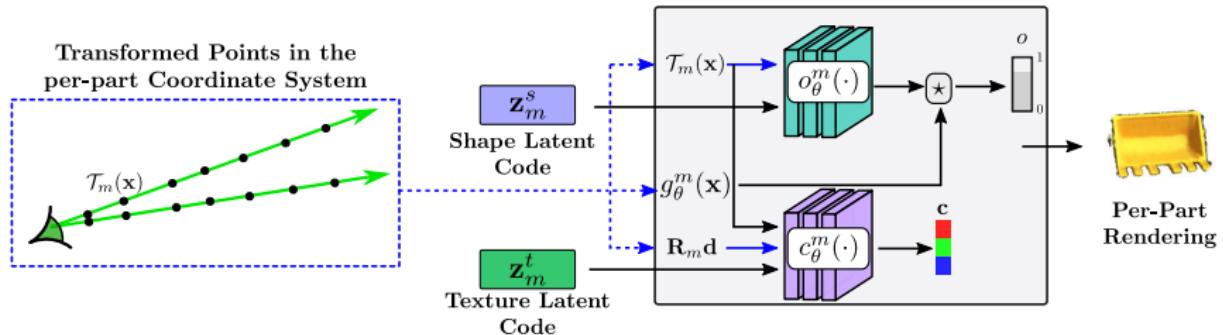
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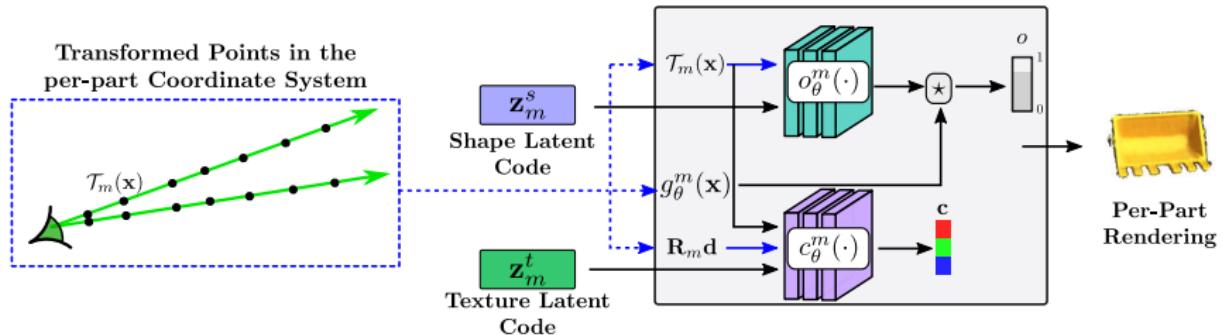
To enforce that **each part only captures continuous regions of the object**, we multiply its occupancy function with the **occupancy function of an axis-aligned 3D ellipsoid**

$$h_\theta^m(\mathbf{x}) = o_\theta^m(\mathbf{x})g_\theta^m(\mathbf{x}),$$

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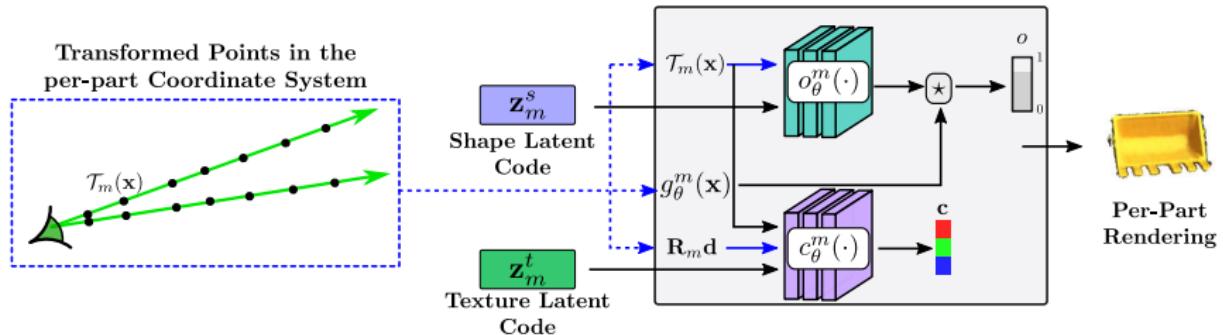
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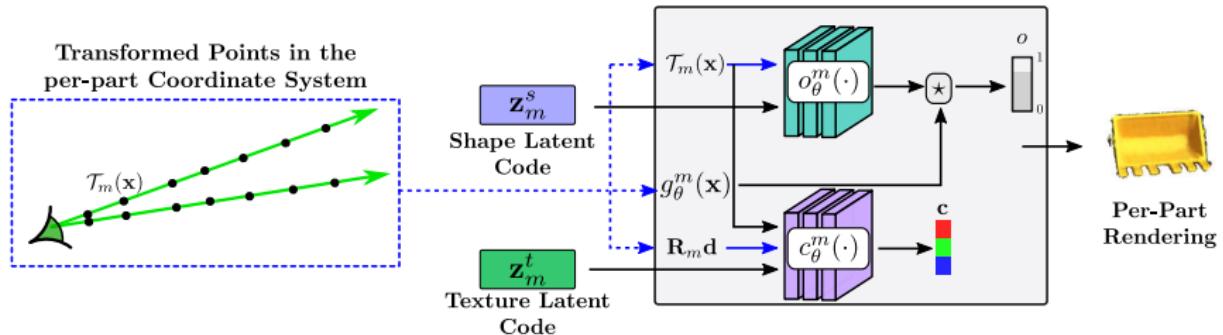


Instead of predicting volume densities, we predict occupancy values and the rendering equation of the  $m$ -th part becomes:

$$\hat{C}_m(r) = \sum_{i=1}^N h_\theta^m(\mathbf{x}_i^r) \prod_{j < i} (1 - h_\theta^m(\mathbf{x}_j^r)) c_\theta^m(\mathbf{x}_i^r, \mathbf{d}^r)$$

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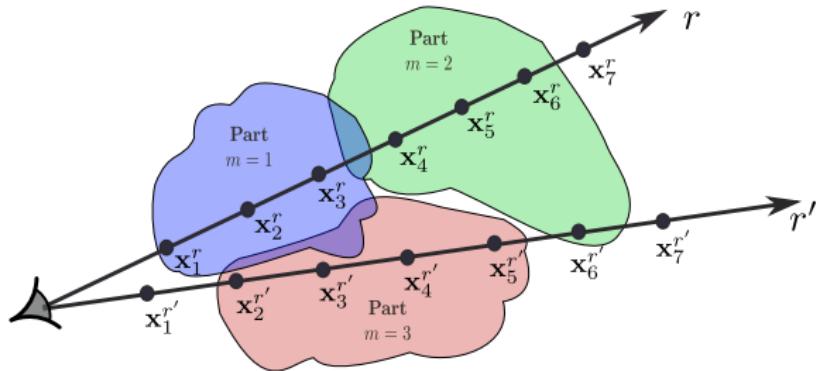
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where  $h_\theta^m(\mathbf{x}_i^r)$  is the **occupancy value** at point  $\mathbf{x}_i^r$  and  $c_\theta^m(\mathbf{x}_i^r, \mathbf{d}^r)$  its color.

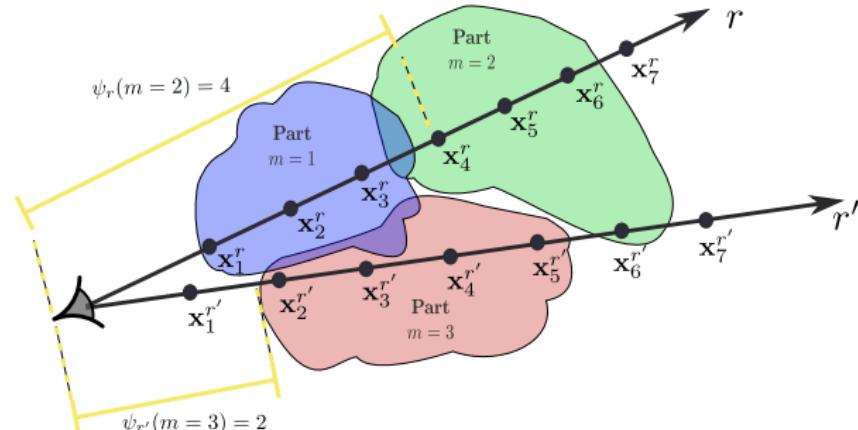
## Hard Assignment between Rays and Parts

Given the ordered set of points  $\mathcal{X}_r$  sampled along ray  $r$ , we define a hard assignment between rays and parts, by **associating a ray with the first part it intersects**.



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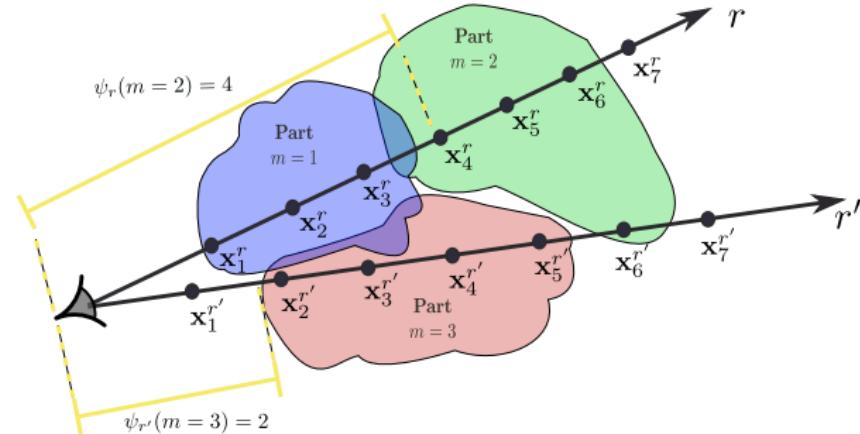
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$$\underbrace{\psi_r(m)}_{\begin{array}{l} \text{Index of the first point} \\ \text{inside each part} \\ \text{intersecting with each ray} \end{array}} = \min \{i \in \{1, \dots, N\} : h_\theta^m(\mathbf{x}_i^r) \geq \tau\}$$

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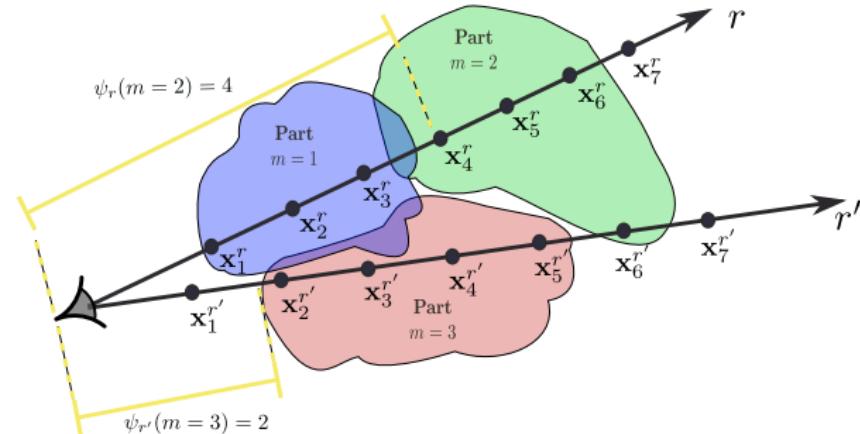


We define the set of rays  $\mathcal{R}_m$  associated with the  $m$ -th part, as **the set of rays that first intersect with it**, namely:

$$\underbrace{\mathcal{R}_m}_{\substack{\text{Set of rays} \\ \text{assigned to part } m}} = \left\{ r \in \mathcal{R} : m = \operatorname{argmin}_{k \in \{0 \dots M\}} \psi_r(k) \right\}.$$

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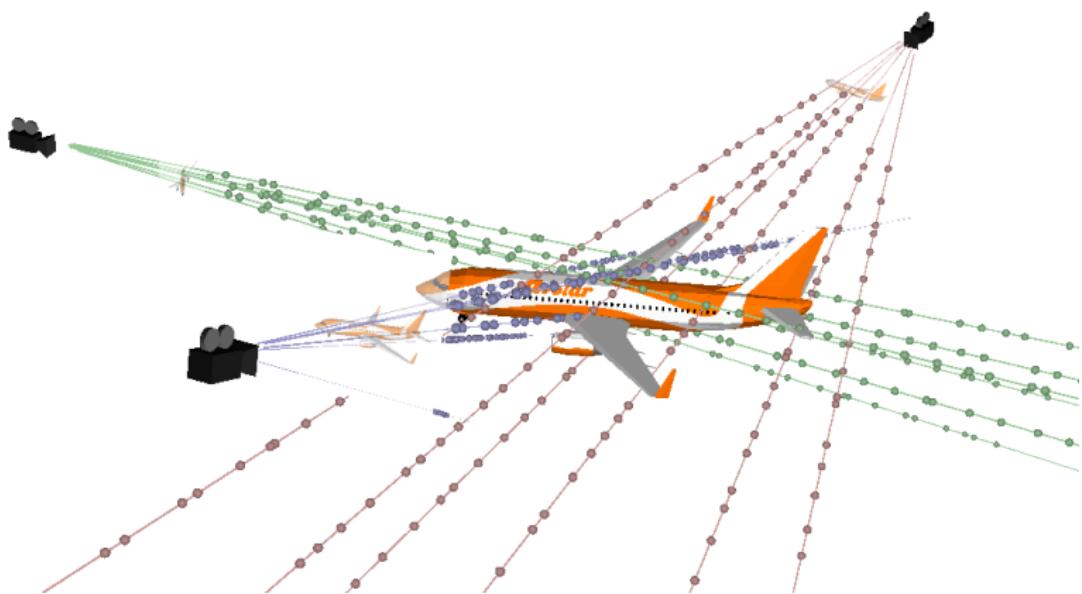


The rendering equation for the entire object using  $M$  NeRFs becomes

$$\hat{C}(r) = \sum_{m=1}^M \mathbb{1}_{r \in \mathcal{R}_m} \hat{C}_m(r).$$

# Object Generation

We are given a **collection of posed 2D images of objects** in a semantic class, each accompanied by an **object mask**. The latter is a binary image indicating whether each pixel is inside the object or not.



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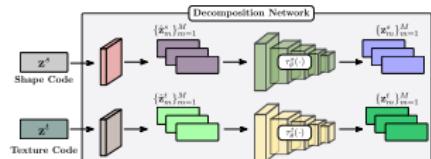
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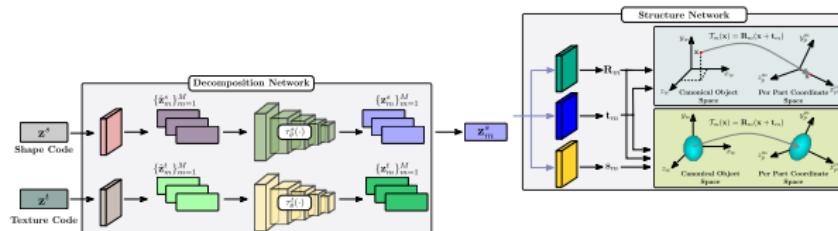


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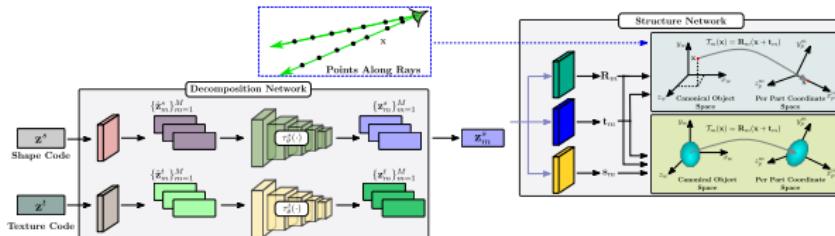


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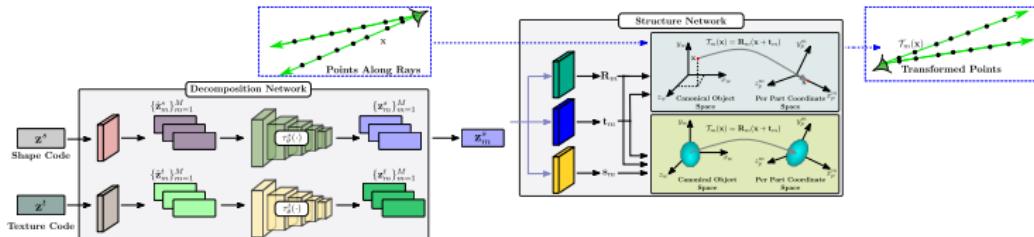


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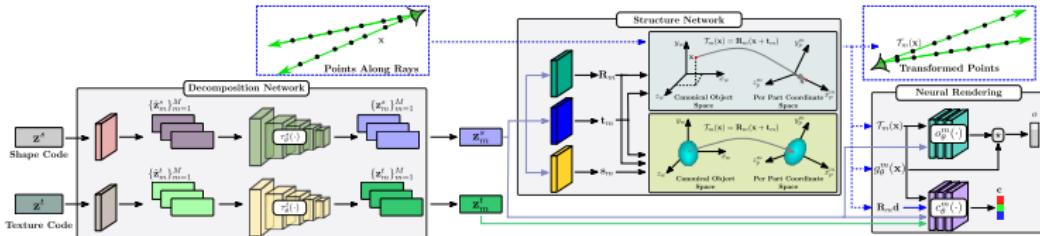


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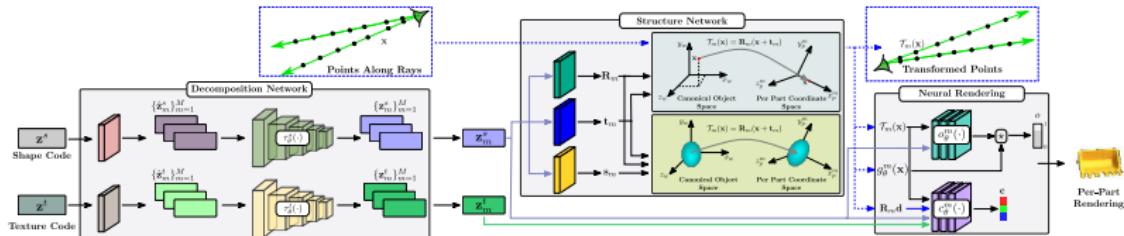


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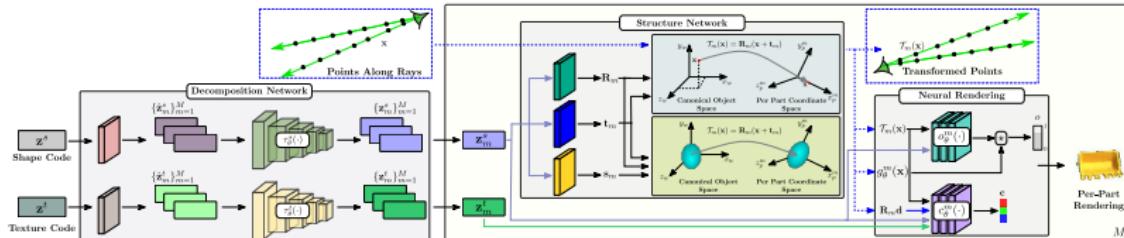


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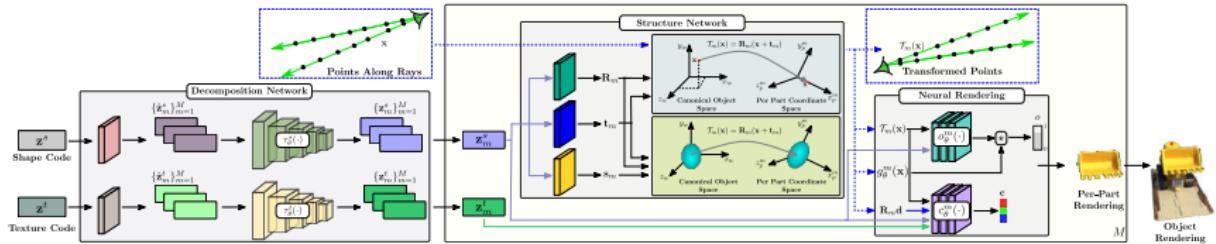


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## Optimization Objective

Our optimization objective  $\mathcal{L}$  is the sum over six terms combined with two regularizers on the shape and texture embeddings  $\mathbf{z}^s, \mathbf{z}^t$ , namely

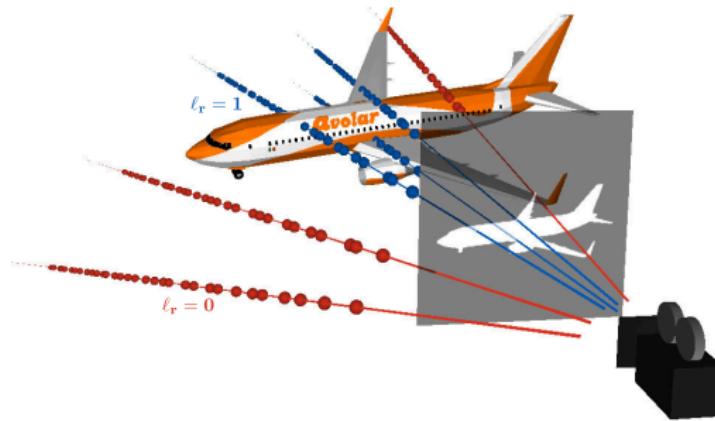
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As supervision, we use the **observed RGB color**  $C(r) \in \mathbb{R}^3$  and the **object mask**  $I(r) \in \{0, 1\}$  for each ray  $r \in \mathcal{R}$ . We also associate  $r$  with a binary label  $\ell_r = I(r)$ , indicating whether a ray  $r$  is *inside*, ( $\ell_r = 1$ ) or *outside* ( $\ell_r = 0$ ).



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- **Reconstruction Loss:** The **rendered** and the **observed** images should match.

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As supervision, we use the **observed RGB color**  $C(r) \in \mathbb{R}^3$  and the **object mask**  $I(r) \in \{0, 1\}$  for each ray  $r \in \mathcal{R}$ . We also associate  $r$  with a binary label  $\ell_r = I(r)$ , indicating whether a ray  $r$  is *inside*, ( $\ell_r = 1$ ) or *outside* ( $\ell_r = 0$ ).

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- **Coverage Loss:** **Prevent** degenerate part arrangements.
- **Overlapping Loss:** **Prevent** overlapping parts.
- **Control Loss:** **Ensure** uniform control across the shape.

How well does it work?

# Scene-Specific Editing

No Editing

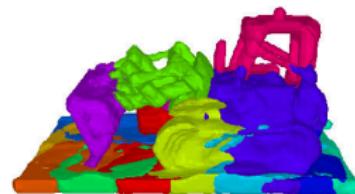


# Scene-Specific Editing

No Editing



Rotation



# Scene-Specific Editing

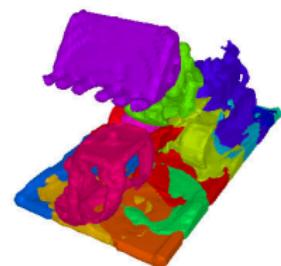
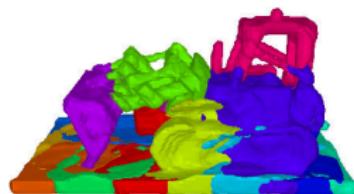
No Editing



Rotation



Translation



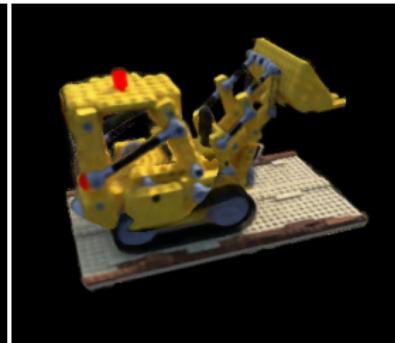
During all editing operations, **only a specific parts of the object changes**, while the rest do not change.

# Scene-Specific Editing

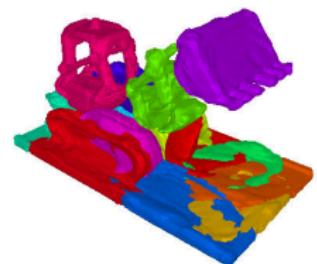
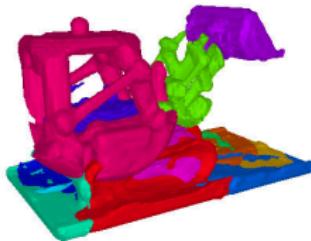
No Editing



Scaling

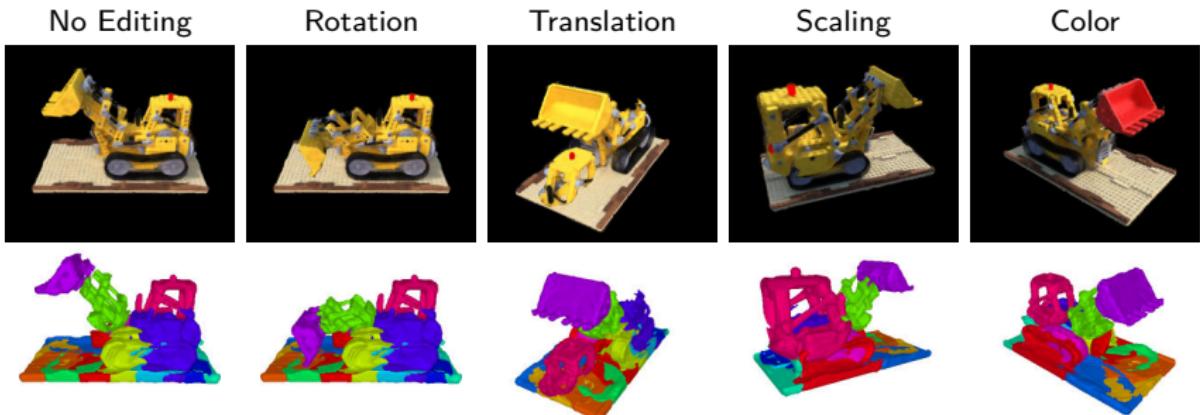


Color

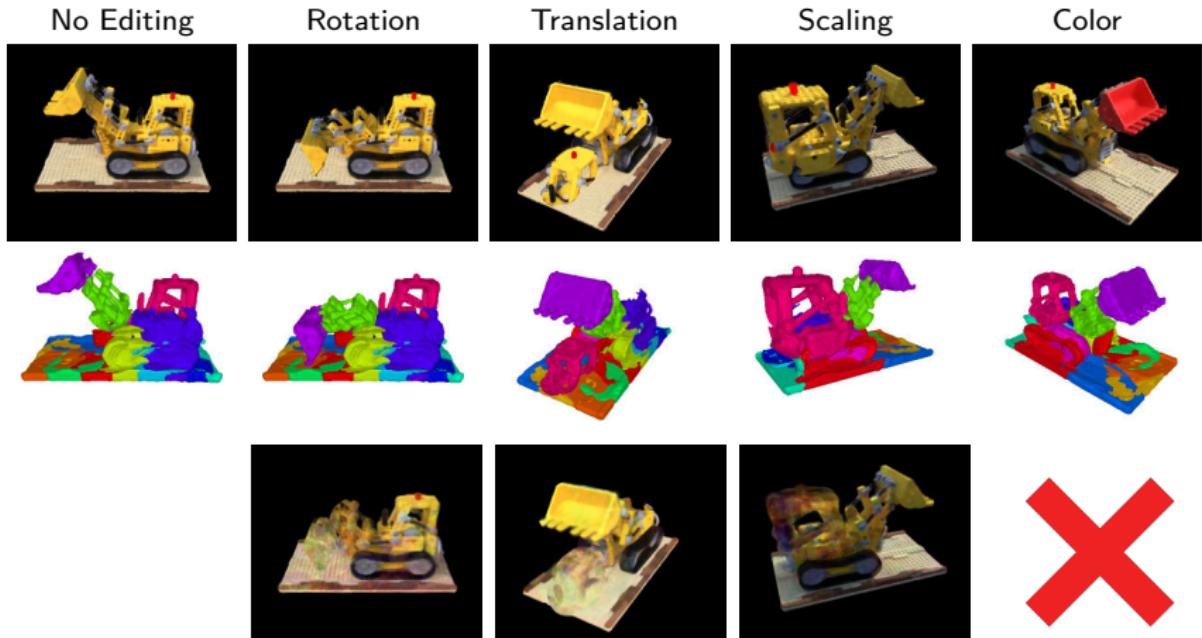


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# Impact of Hard Ray-Part Assignment



# Impact of Hard Ray-Part Assignment

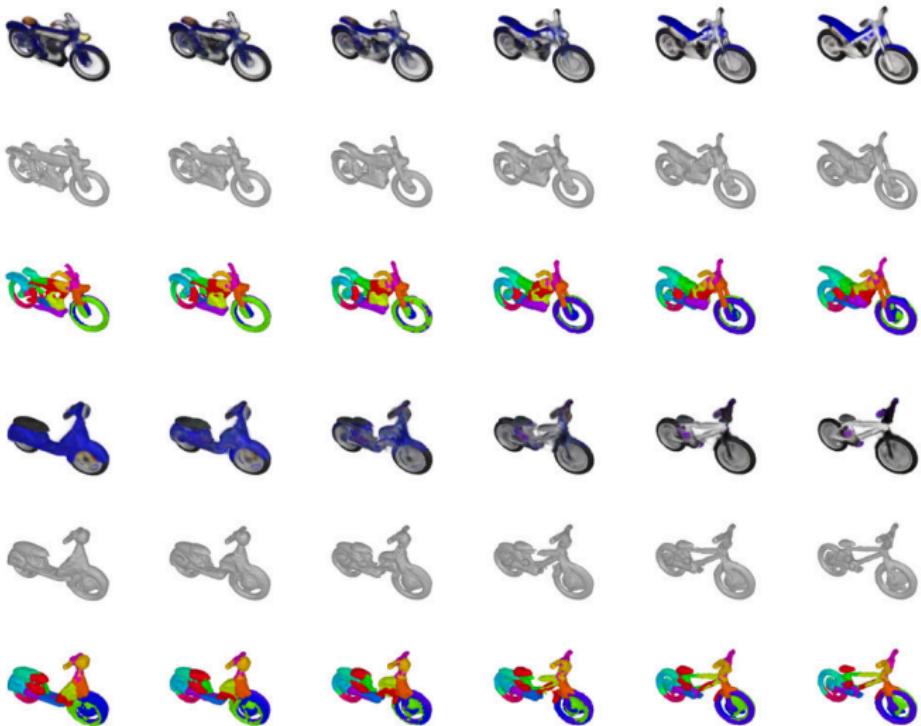


The **hard ray-part assignment** enforces that the color of a ray is determined by a **single NeRF/part**, hence transforming one part **does not alter the other parts**.

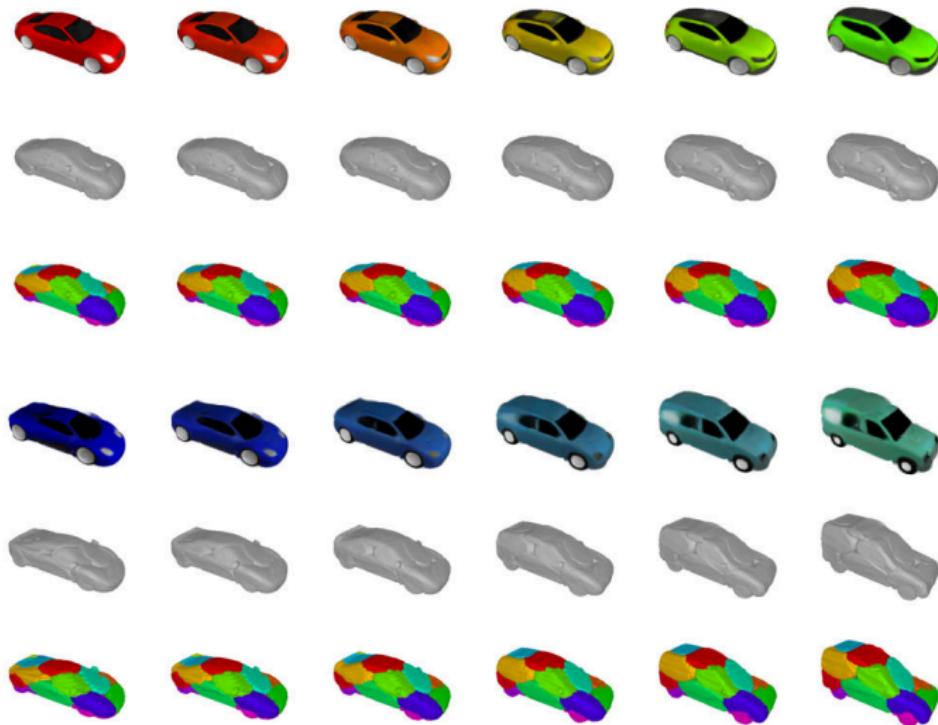
# Shape Synthesis



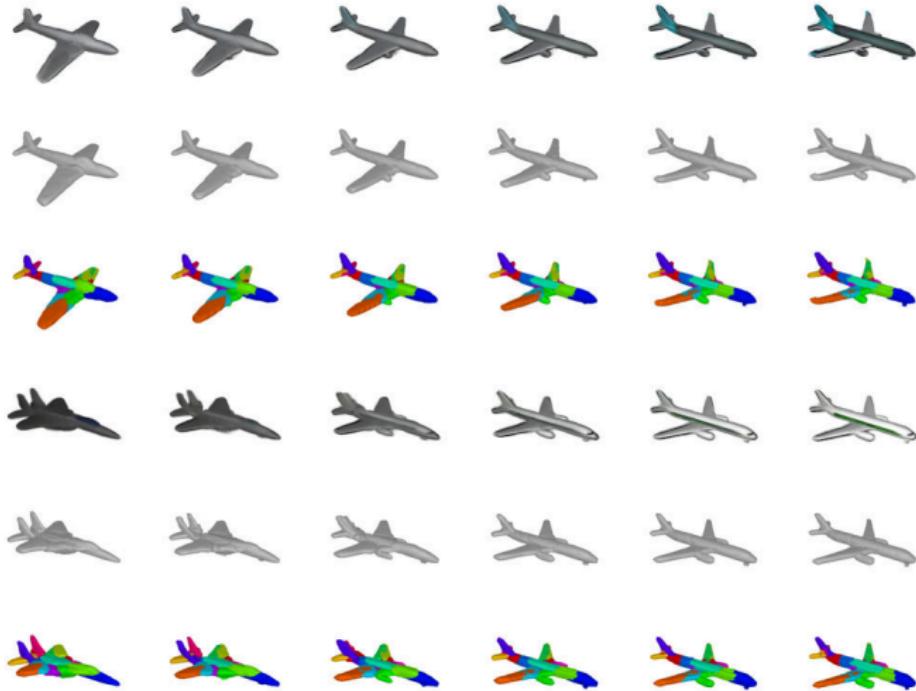
## Shape Interpolations



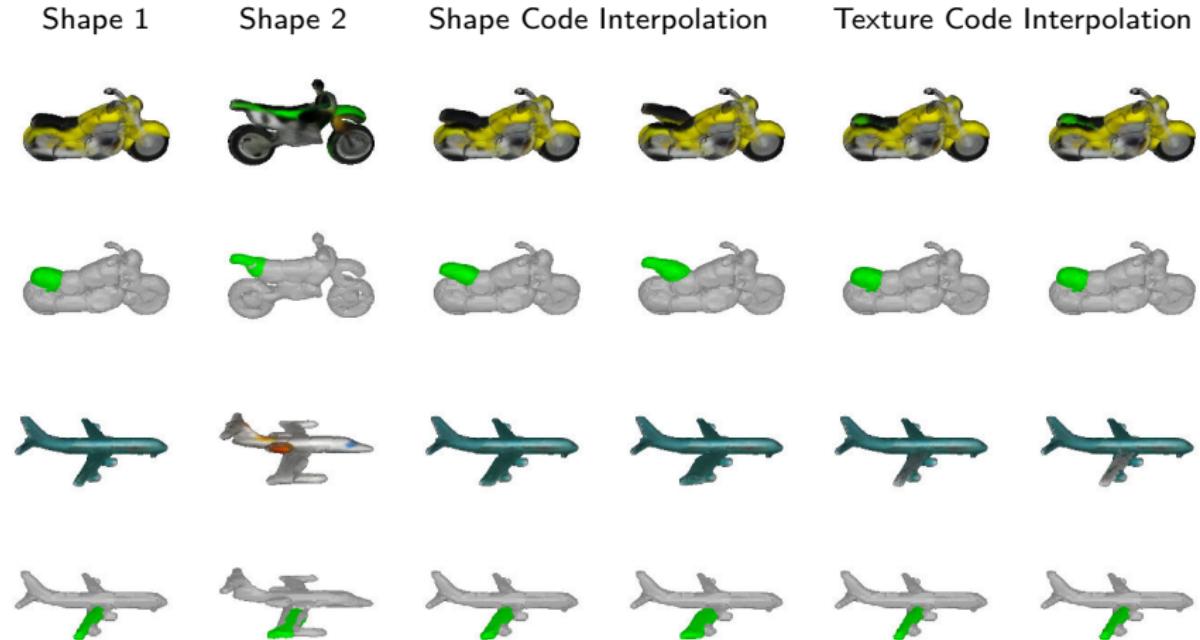
# Shape Interpolations



## Shape Interpolations



# Part Interpolation



# Shape Mixing

Shape 1



Shape 2



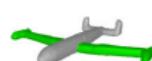
Geometry Mixing



Texture Mixing



Combined



# Shape Mixing

Shape 1   Shape 2   Shape 3



Geometry Mixing

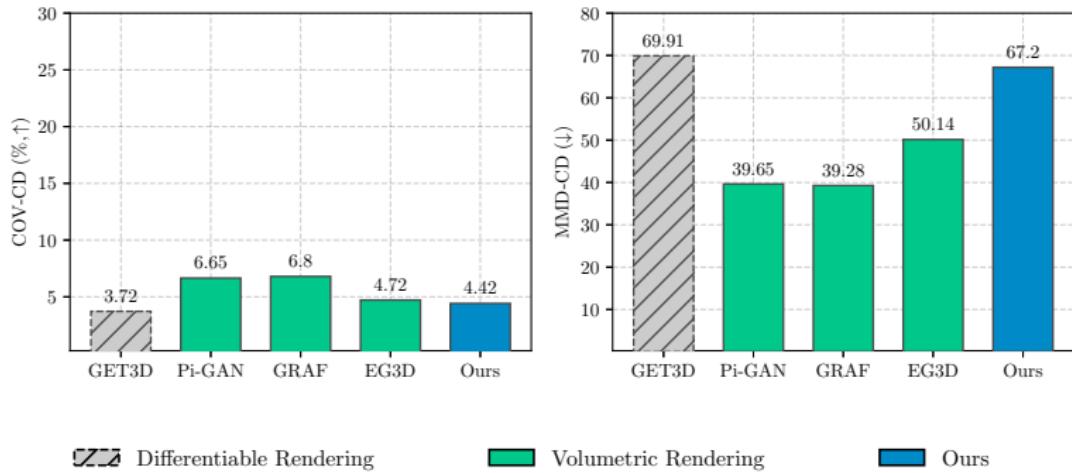


Texture 1   Texture 2   Texture 3

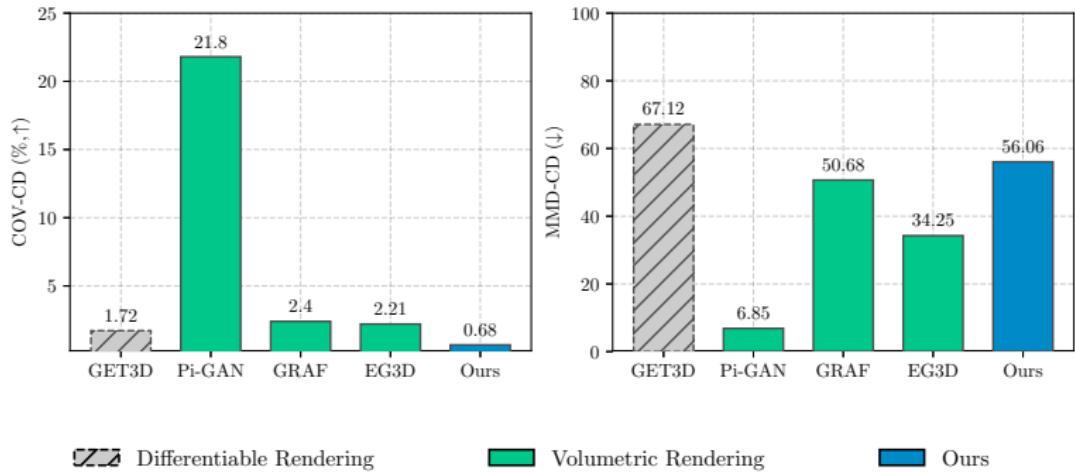


Texture Mixing

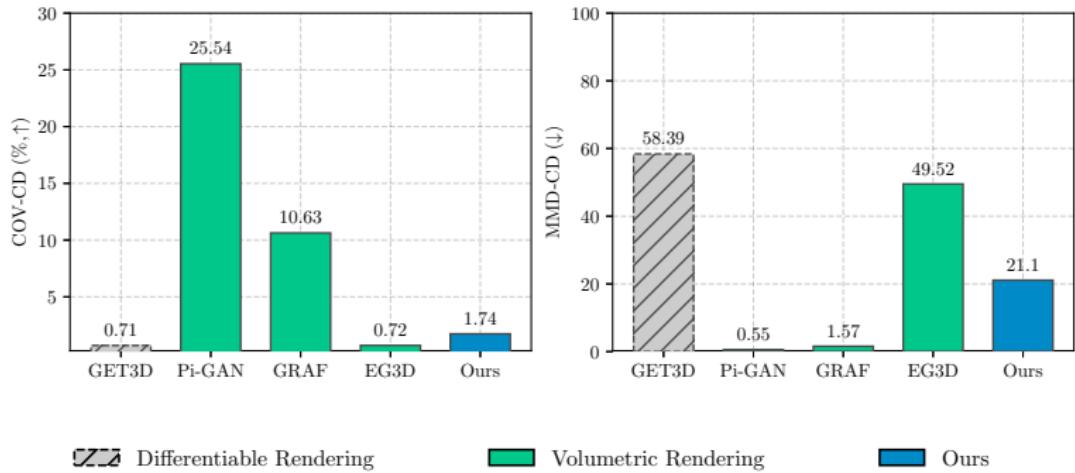
# ShapeNet Comparison - Chairs



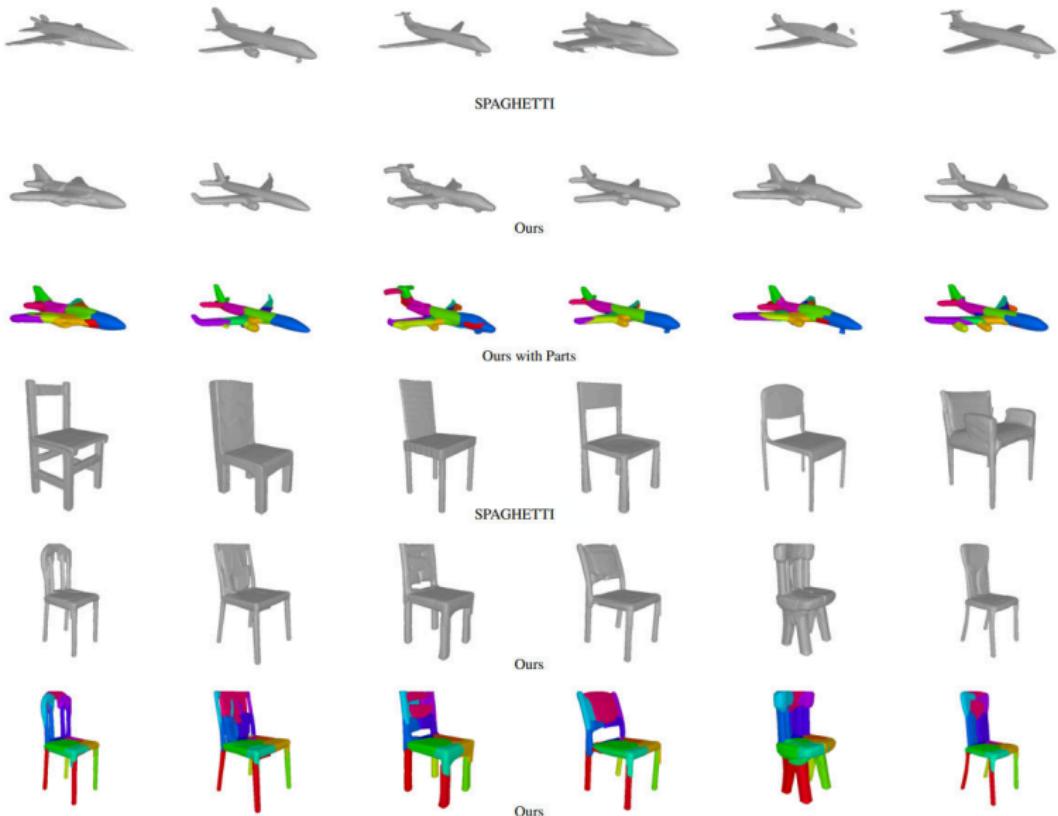
# ShapeNet Comparison - Motorbikes



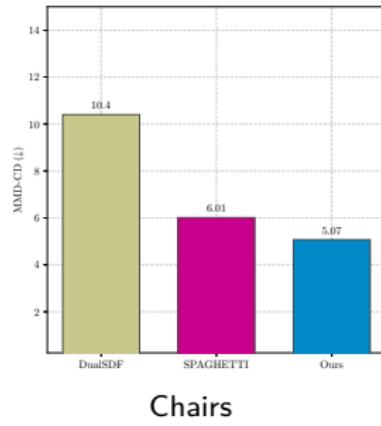
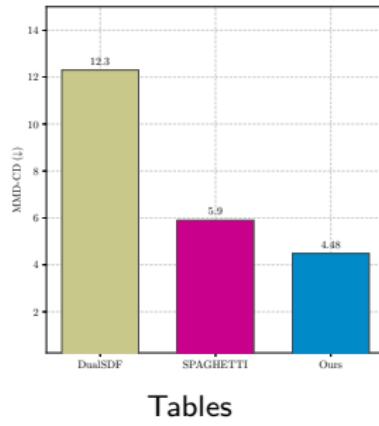
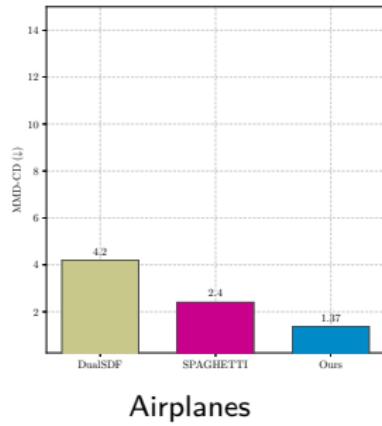
# ShapeNet Comparison - Cars



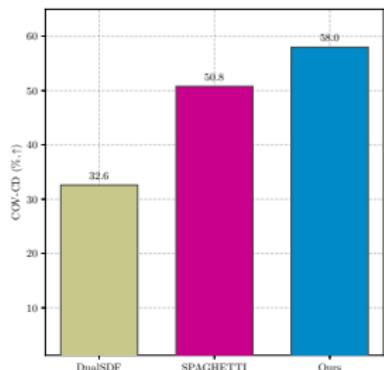
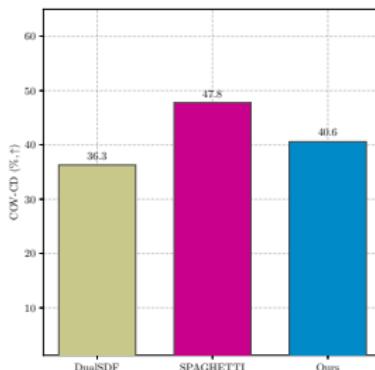
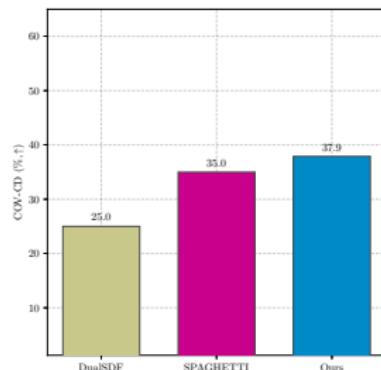
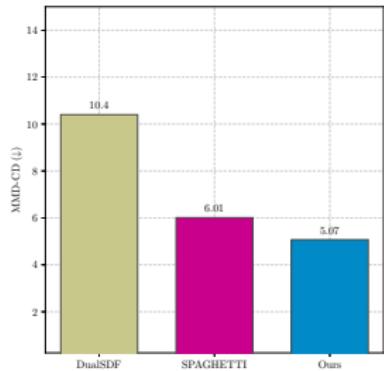
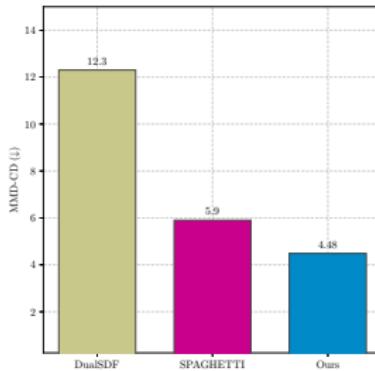
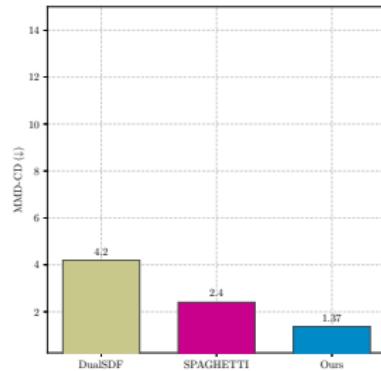
# ShapeNet Comparison to Part-based Methods



# ShapeNet Comparison - Part-based Methods



# ShapeNet Comparison - Part-based Methods

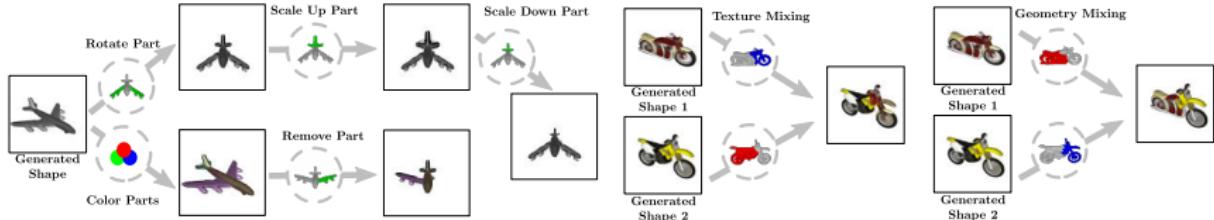


Airplanes

Tables

Chairs

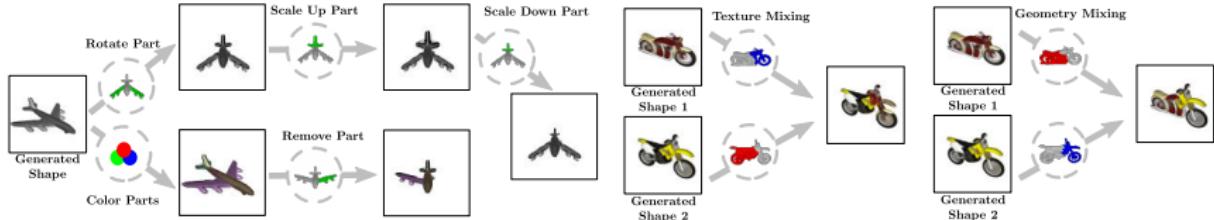
# Summary and Limitations



- We introduced the **first part-aware generative model that parametrizes parts as NeRFs**.

	Representation	Supervision	Parts	Shape Editing	Texture Editing	Mixing
GET3D	Mesh	2D	✗	✗	✗	✗
GRAF			✗	✗	✗	✗
Pi-GAN	Neural Field	2D	✗	✗	✗	✗
EG3D			✗	✗	✗	✗
DualSDF			✓	✓	✗	✗
SPAGHETTI	Implicit	3D	✓	✓	✗	✓
PartNeRF	Neural Field	2D	✓	✓	✓	✓

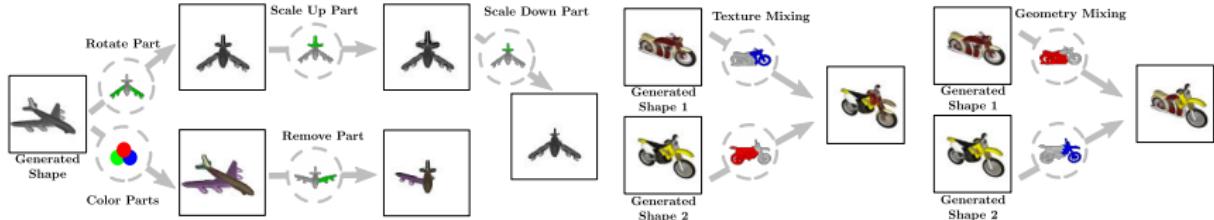
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GRAF			✗	✗	✗	✗
Pi-GAN	Neural Field	2D	✗	✗	✗	✗
EG3D			✗	✗	✗	✗
DualSDF			✓	✓	✗	✗
SPAGHETTI	Implicit	3D	✓	✓	✗	✓
PartNeRF	Neural Field	2D	✓	✓	✓	✓

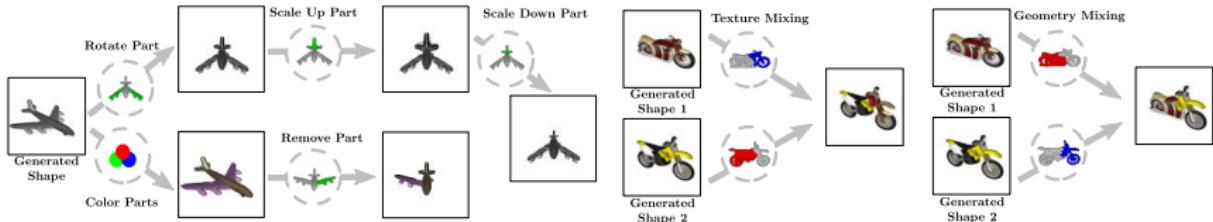
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EG3D			✗	✗	✗	✗
DualSDF			✓	✓	✗	✗
SPAGHETTI	Implicit	3D	✓	✓	✗	✓
PartNeRF	Neural Field	2D	✓	✓	✓	✓

# Summary and Limitations

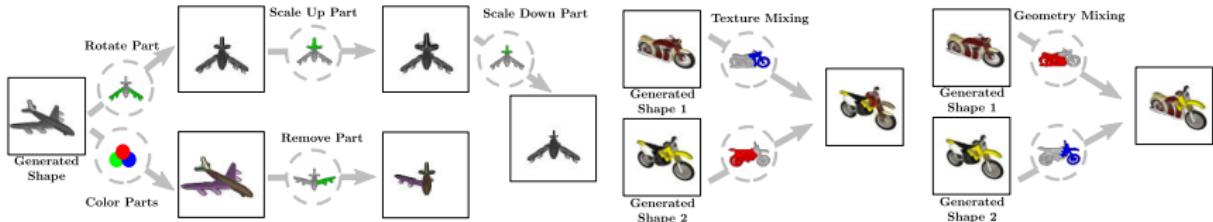


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- The generated parts are not necessarily interpretable.

Thank you for your attention!