

q -deformation of Poincaré algebra

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Standard (Drinfeld–Jimbo) q -deformation of the Cartan–Weyl basis for $\mathfrak{o}(3, 2)$ (real form of B_2) $\simeq \mathfrak{sp}(4|\mathbb{R})$ (real form of C_2) is calculated. The limit $R \rightarrow \infty$ (R is the anti-de Sitter radius) accompanied by a particular limit of the deformation parameter $q(iR \ln q \rightarrow \text{const.})$ is performed. We obtain a modified Minkowski geometry with abelian translations but the four-momentum-dependent modification of the Lorentz boost algebra. The q -covariant generalization of the Klein–Gordon equation is given.

1. Introduction

As a possible application of the notion of quantum group and quantum algebra (see e.g. refs. [1–6]) it is interesting to study the deformations of space–time symmetries and their supersymmetric extensions. At present, quantum groups appear mostly as the deformation of the internal symmetry sector (e.g. in $D=2$ conformal field theory [7], with the Virasoro algebra remaining not modified); however, it is quite plausible that the description of space–time at very short distances requires modifications which are interesting to explore. The formalism of so-called q -deformations in the framework of quasi-triangular Hopf algebras being available [3,4] it is important to derive the corresponding deformation of the Poincaré group or Poincaré algebra.

In this paper we shall discuss the quantum-algebraic aspect of the problem, however, the results could be as well obtained in the dual framework of the quantum groups^{#1}. Because the Poincaré algebra is a semidirect sum of Lorentz- and translation subalgebras ($\mathcal{P} = \mathfrak{O}(3, 1) \rtimes T_4$), the q -deformation of the Poincaré algebra is not described by the Drinfeld–Jimbo scheme [3,4] valid for the q -deformation of simple Cartan–Lie algebras. In order to obtain the q -deformation of Poincaré algebra we shall perform firstly the q -deformation of the anti-de Sitter algebra $\mathfrak{o}(3, 2) [\mathfrak{o}(3, 2) \rightarrow \mathcal{U}_q(\mathfrak{o}(3, 2))]$ and after introducing the de Sitter radius R we shall consider the contraction, introduced first by the Firenze group [8],

$$R \rightarrow \infty, \quad iR \log q \rightarrow \kappa^{-1} \quad (0 < \kappa < \infty). \quad (1.1)$$

We see from (1, 1) that such a prescription pro-

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^{#1} Following ref. [1] we distinguish here the quantum group G_q as the q -deformation of the (algebra of functions on the) Lie group G , and the quantum algebra $\mathcal{U}_q(\hat{\mathfrak{g}})$, described by the q -deformation of the universal enveloping algebra $\mathcal{U}(\hat{\mathfrak{g}})$ of the Lie algebra $\hat{\mathfrak{g}}$.

vides a particular way of approaching $q \rightarrow 1$, however, in such a way that a new mass-like parameter κ appears. It is the aim of this paper to show how the finite values of κ modify the Poincaré algebra.

Firstly, in section 2, we shall discuss the undeformed case ($q=1$); in particular the Cartan–Weyl basis for B_2 and C_2 , the assignments of $\mathfrak{o}(5; \mathbb{C})$ generators, the real form $[\mathfrak{o}(5; \mathbb{R})$ and $\mathfrak{o}(3, 2; \mathbb{R})]$ as well as the contraction $R \rightarrow \infty$. In particular, we shall consider the mapping between simple and positive roots of B_2 and C_2 , described by the same two-dimensional root diagram (see e.g. ref. [9]). It should be recalled that the Drinfeld–Jimbo q -deformation distinguishes simple roots as well as the normal order in the positive root system. In section 3, we shall describe the q -deformation of the C_2 Lie algebra with suitable assignment of q -deformed $\mathfrak{sp}(4) \simeq \mathfrak{o}(5)$ generators $M_{AB} = -M_{BA}$ ($A, B=0, 1, 2, 3, 4$) to the Cartan–Weyl basis, and its relations with the q -deformation of B_2 . Extending the involutions introducing real forms to $q \neq 1$ we shall see that the real forms $\mathcal{U}_q(\mathfrak{o}(3, 2; \mathbb{R}))$ and $\mathcal{U}_q(\mathfrak{sp}(4; \mathbb{R}))$ require $|q|=1$. In section 4, we shall consider the contraction $(1, 1)$. It appears that:

(1) $O(3)$ space rotations are not modified.

(2) The algebra of Lorentz boosts is modified by the appearance of the rotated generators L_i by the angle $\alpha = P_0/\kappa$ [see (4.12)] and additional quadratic deformation terms in boosts and three-momentum variables.

(3) The translations commute.

(4) A second deformation (by a factor $(1/\kappa) \times \sin(P_0/\kappa)$ and the terms quadratic in three-momentum components) is obtained in the transformation law of the translations under the Lorentz boosts.

We see, therefore, that our deformation introduces a mass scale into the theory which modifies the isotropy properties of the Minkowski geometry in the cost \mathcal{P}/E_3 , where $E_3 = O(3) \oplus T_3$ denotes the euclidean group of motion.

In section 5, we introduce the q -deformed relativistic mass square operator, defined as the Casimir of the q -deformed Poincaré algebra, and the corresponding modified Klein–Gordon equation. The first correction to the Klein–Gordon equation, of order $1/\kappa^2$, contains a fourth time derivative.

It should be mentioned that the technique of contractions was recently applied to the quantum alge-

bras describing the deformation of Lie algebras of rank one [8,10,11]. Because $D=4$ anti-de Sitter algebras are of rank two, in order to obtain the deformation of all ten generators one has to extend the Cartan–Chevalley basis of the quantized algebra to the q -deformed Cartan–Weyl basis [12–14], in consistency with the q -deformed Serre relations.

2. Anti-de Sitter algebras $\mathfrak{o}(3, 2) \simeq \mathfrak{sp}(4)$ and its contraction to the Poincaré limit

We would like to recall that the anti-de Sitter algebra can be obtained as a real form of the complex Lie algebras $B_2 \simeq \mathfrak{o}(5)$ and $C_2 \simeq \mathfrak{sp}(4)$. The Cartan–Chevalley basis of these two algebras is described by the set of relations

$$\begin{aligned} [h_i, h_j] &= 0, \quad [e_i, e_{-j}] = \delta_{ij} h_j, \\ [h_i, e_{\pm j}] &= \pm \alpha_{ij} e_{\pm j}, \end{aligned} \quad (2.1)$$

where the symmetrized Cartan matrices $\alpha_{ij} = \langle \alpha_i, \alpha_j \rangle$ ($i, j=1, 2$) are

$$B_2: \tilde{\alpha} = \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix}, \quad C_2: \alpha = \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix} \quad (2.2)$$

and the standard choice of simple roots in the following (see e.g. ref. [9]):

$$B_2: \tilde{\alpha}_1 = (1, -1), \quad \tilde{\alpha}_2 = (0, 1), \quad (2.3a)$$

$$C_2: \alpha_1 = (1/\sqrt{2}, -1/\sqrt{2}), \quad \alpha_2 = (0, \sqrt{2}). \quad (2.3b)$$

We choose normal orders $(\tilde{\alpha}_1, \tilde{\alpha}_3, \tilde{\alpha}_4, \tilde{\alpha}_2)$, $(-\tilde{\alpha}_2, -\tilde{\alpha}_4, -\tilde{\alpha}_3, -\tilde{\alpha}_1)$ for B_2 , and $(\alpha_1, \alpha_4, \alpha_3, \alpha_2)$, $(-\alpha_2, -\alpha_3, -\alpha_4, -\alpha_1)$ for C_2 , implying the following defining relations $[\alpha_3 = \alpha_1 + \alpha_2, \tilde{\alpha}_3 = \tilde{\alpha}_1 + \tilde{\alpha}_2, \alpha_4 = 2\alpha_1 + \alpha_2, \tilde{\alpha}_4 = \tilde{\alpha}_1 + 2\tilde{\alpha}_2; \tilde{e}_\rho \equiv e_{\tilde{\alpha}_\rho}, e_\rho \equiv e_{\alpha_\rho} (\rho=1, 2, 3, 4)]$:

$$\begin{aligned} B_2: \tilde{e}_3 &= [\tilde{e}_1, \tilde{e}_2], \quad \tilde{e}_{-3} = [\tilde{e}_{-2}, \tilde{e}_{-1}], \\ \tilde{e}_4 &= [\tilde{e}_3, \tilde{e}_2], \quad \tilde{e}_{-4} = [\tilde{e}_{-2}, \tilde{e}_{-3}], \end{aligned} \quad (2.4a)$$

$$\begin{aligned} C_2: e_3 &= [e_1, e_2], \quad e_{-3} = [e_{-2}, e_{-1}], \\ e_4 &= [e_1, e_3], \quad e_{-4} = [e_{-3}, e_{-1}]. \end{aligned} \quad (2.4b)$$

In order to relate the Cartan–Lie algebras for B_2 and C_2 we observe that the identification $\tilde{\alpha}_1 = -\alpha_2$, $\tilde{\alpha}_2 = -\alpha_1$ leads to the following:

(1) Identification of the Cartan matrices for B_2 and C_2 .

(2) Identification of the first (second) normal order for B_2 with the second (first) normal order of C_2 .

Indeed, introducing $\tilde{h}_1 = -h_2$ and

$$\tilde{e}_1 = e_{-2}, \quad \tilde{e}_2 = e_{-1}, \quad \tilde{e}_3 = e_{-3}, \quad \tilde{e}_4 = e_{-4}, \quad (2.5)$$

we see easily that the relations (2.1) and (2.4) for B_2 and C_2 are identical^{#2}.

The complete set of the commutation relations for the $B_2 \simeq C_2$ algebra in the Cartan–Weyl basis will be given with $q \neq 1$ in the next section. Here, we would like to write the relations expressing “physical” $O(3, 2)$ rotation generators M_{AB} ($M_{AB} = -M_{BA}$; $A, B = 0, 1, 2, 3, 4$)

$$[M_{AB}, M_{CD}] = i(\eta_{BC}M_{AD} - \eta_{AC}M_{BD} + \eta_{AD}M_{BC} - \eta_{BD}M_{AC}), \quad (2.6)$$

where $\eta_{AB} = (+ - - - +)$, in terms of the Cartan–Weyl generators for C_2 . We obtain

$$\begin{aligned} M_{12} &= h_1, & M_{23} &= (1/\sqrt{2})(e_1 + e_{-1}), \\ M_{31} &= (1/i\sqrt{2})(e_1 - e_{-1}), & M_{04} &= h_3 = h_1 + h_2, \\ M_{34} &= (-1/\sqrt{2})(e_3 - e_{-3}), \\ M_{03} &= (1/i\sqrt{2})(e_3 + e_{-3}), \\ M_{02} &= \frac{1}{2}(e_4 - e_{-4} + e_2 - e_{-2}), \\ M_{01} &= (-1/2i)(e_4 + e_{-4} - e_2 - e_{-2}), \\ M_{24} &= (1/2i)(e_4 + e_{-4} + e_2 + e_{-2}), \\ M_{14} &= \frac{1}{2}(e_4 - e_{-4} - e_2 + e_{-2}). \end{aligned} \quad (2.7)$$

In the algebra $B_2 \simeq C_2$ one can introduce two reality conditions as follows:

(1) $\mathfrak{o}(3, 2; \mathbb{R}) \simeq \mathfrak{sp}(4; \mathbb{R})$,

$$e_1 = e_{-1}^*, \quad e_2 = -e_{-2}^*, \quad (2.8a)$$

$$e_3 = -e_{-3}^*, \quad e_4 = -e_{-4}^*,$$

$$h_1 = h_1^*, \quad h_2 = h_2^*. \quad (2.8b)$$

In such a case we obtain the algebra (2.6) with *real* generators.

^{#2} The change from clockwise to anti-clockwise normal order follows from the fact that two root diagrams for C_2 , one given by (2.3b) and the second given by the transformation $\tilde{\alpha}_1 \rightarrow -\alpha_2$, $\tilde{\alpha}_2 \rightarrow -\alpha_1$, are not identical, but are related by a Weyl reflection.

(ii) $\mathfrak{o}(5; \mathbb{R}) \simeq \mathfrak{sp}(2, \mathbb{H}) \equiv \mathfrak{sp}(4; \mathbb{C}) \cap \mathfrak{u}(4)$,

$$e_1 = e_{-1}^*, \quad e_2 = e_{-2}^*, \quad (2.9a)$$

implying

$$\begin{aligned} e_3 &= e_{-3}^*, \quad e_4 = e_{-4}^*, \\ h_1 &= h_1^*, \quad h_2 = h_2^*. \end{aligned} \quad (2.9b)$$

In such a case one obtains after the replacement in (2.7) ($r, s = 1, 2, 3$)

$$\begin{aligned} M_{rs} &\rightarrow M_{rs}, \quad M_{0r} \rightarrow iM_{0r}, \\ M_{04} &\rightarrow M_{04}, \quad M_{4r} \rightarrow iM_{4r} \end{aligned} \quad (2.10)$$

the $\mathfrak{o}(5)$ algebra with real generators.

In order to obtain from (2.6) the Poincaré algebra, we introduce the rescaling ($\mu, \nu = 1, 2, 3, 4$) by introducing the anti-de Sitter radius R :

$$P_\mu = \frac{1}{R} M_{0\mu} \quad (2.11)$$

and the remaining generators $M_{\mu\nu}$ describing the Lorentz group algebra are left unchanged. We obtain from (2.6) and (2.11) that

$$[M_{\mu\nu}, P_\rho] = -i(\eta_{\mu\rho}P_\nu - \eta_{\nu\rho}P_\mu), \quad (2.12a)$$

$$[P_\mu, P_\nu] = -i \frac{M_{\mu\nu}}{R^2}. \quad (2.12b)$$

We see easily that in the limit $R \rightarrow \infty$ we obtain the Poincaré algebra.

3. Quantum algebra $U_q(\mathfrak{sp}(4; \mathbb{R})) \approx U_q(\mathfrak{o}(3, 2))$

In order to describe the q -deformation of $C_2 \simeq B_2$ we shall use the normal order ($\alpha_1, \alpha_4, \alpha_3, \alpha_2$) of C_2 roots in the Drinfeld–Jimbo prescription for the deformation of the Cartan–Chevalley basis (e_i, e_{-i}, h_i) and the following q -deformation of the defining relations (2.4)^{#3} [12–14]:

$$\begin{aligned} e_3 &\equiv e_1 e_2 - q^{-\alpha_{12}} e_2 e_1 = [e_1, e_2]_q, \\ e_{-3} &\equiv e_{-2} e_{-1} - q^{\alpha_{12}} e_{-1} e_{-2} = [e_{-2}, e_{-1}]_{q^{-1}}, \end{aligned} \quad (3.1)$$

^{#3} For simplicity we shall denote the q -deformed basis in section 3 by the same letters. We recall that in general $[e_\gamma, e_\delta]_{q^{\pm 1}} = e_\gamma e_\delta - q^{\pm \gamma \delta} e_\delta e_\gamma$, the sign $+$ ($-$) depending on the clockwise (anti-clockwise) order on the root diagram. Of course $[A, B]_q \equiv AB - qBA$.

$$\begin{aligned}
e_4 &\equiv e_1 e_3 - q^{-\alpha_{13}} e_3 e_1 = [e_1, e_3], \\
e_{-4} &\equiv e_{-3} e_{-1} - q^{\alpha_{13}} e_{-1} e_{-3} = [e_{-3}, e_{-1}], \\
\end{aligned}
\quad (3.1 \text{ cont'd})$$

where we extended the scalar product defined for simple roots by the Cartan matrix to all roots ($\alpha_{\rho\tau} \equiv \langle \alpha_\rho, \alpha_\tau \rangle$; $\rho, \tau = 1, 2, 3, 4$).

The complete set of commutation relations for $U_q(C_2)$ in the q -deformed Cartan–Weyl basis looks as follows ($i, j = 1, 2$):

$$\begin{aligned}
[e_i, e_{-j}] &= \delta_{ij} [h_i]_q, \quad [h_i, h_j] = 0, \\
[h_i, e_{\pm j}] &= \pm \alpha_{ij} e_{\pm j}, \\
[e_3, e_{-3}] &= [h_3]_q, \quad h_3 = h_1 + h_2, \\
[e_4, e_{-4}] &= [h_4]_q, \quad h_4 = h_1 + h_3, \\
\end{aligned}
\quad (3.2a)$$

$$\begin{aligned}
[e_1, e_4]_{q^{-1}} &= 0, \quad [e_{-2}, e_{-3}]_q = 0, \\
[e_4, e_3]_{q^{-1}} &= 0, \quad [e_{-3}, e_{-4}]_q = 0, \\
[e_3, e_2]_{q^{-1}} &= 0, \quad [e_{-4}, e_{-1}]_q = 0. \\
\end{aligned}
\quad (3.2b)$$

(3.2b) is equivalent to the q -Serre relations

$$\begin{aligned}
[e_2, e_4] &= (1 - q^{-1}) e_3^2, \quad [e_{-2}, e_{-4}] = (q - 1) e_{-3}^2, \\
[e_1, e_{-3}] &= -q^{-h_1} e_{-2}, \quad [e_3, e_{-1}] = -e_2 q^{h_1}, \\
[e_3, e_{-2}] &= q^{-h_2} e_1, \quad [e_2, e_{-3}] = e_{-1} q^{h_2}, \\
[e_4, e_{-3}] &= q^{-h_3} e_1, \quad [e_3, e_{-4}] = e_{-1} q^{h_3}, \\
[e_1, e_4] &= -q^{h_1} e_{-3}, \quad [e_{-1}, e_4] = q^{h_1} e_3, \\
[e_4, e_{-2}] &= -(1 - q^{-1}) q^{-h_2} e_1^2, \\
[e_2, e_{-4}] &= -(1 - q) e_{-1}^2 q^{h_2}, \\
\end{aligned}
\quad (3.2c)$$

where $[x]_q \equiv (q^x - q^{-x}) / (q - q^{-1})$ and the relation $[\alpha_{12}]_q = -1$ has been extensively used.

The Drinfeld–Jimbo q -deformation $U_q(B_2)$ is obtained if we supplement the relations (2.5) also by the identification $\tilde{q} = q^{-1}$, i.e.,

$$U_{q^{-1}}(B_2) \simeq U_q(C_2). \quad (3.3)$$

In order to obtain the real forms of (3.3), we should supplement the relations (2.8) and (2.9) by the conditions on q . One should assume [see (2.8) and (2.9)]

$$U_{q^*}(\mathfrak{o}(5)) \simeq U_q(\mathfrak{sp}(2|\mathbb{H})), \quad (3.4a)$$

$$U_{q^*}(\mathfrak{o}(3, 2)) \simeq U_q(\mathfrak{sp}(4|\mathbb{R})). \quad (3.4b)$$

Further, we describe the relations (3.2) in the $O(3, 2)$ basis (2.7) with the physical assignment of the generators. We introduce:

(i) Three dimensional rotations (M_{\pm}, M_3),

$$M_3 = M_{12}, \quad M_{\pm} = M_{23} \pm iM_{31}. \quad (3.5a)$$

We obtain

$$[M_+, M_-] = 2[M_3]_q, \quad [M_3, M_{\pm}] = \pm M_{\pm}. \quad (3.5b)$$

(ii) Lorentz boosts (L_{\pm}, L_3),

$$L_3 = M_{34}, \quad L_{\pm} = M_{14} \pm iM_{24}. \quad (3.6)$$

One gets

$$\begin{aligned}
[L_-, L_+] &= [M_{04} + M_3]_q + [M_3 - M_{04}]_q \\
&\quad + \frac{1}{2}(q - 1)[(K^-)^2 - q^{-1}(K^+)^2], \\
[L_3, L_+] &= -\frac{1}{2}q^{-M_{04}}(1 + q^{M_3})M_+ \\
&\quad - \frac{1}{4}(1 - q)[K_-(N_- - L_+) - (N_- + L_+)K_+], \\
[L_3, L_-] &= \frac{1}{2}M_- q^{M_{04}}(1 + q^{-M_3}) \\
&\quad + \frac{1}{4}(1 - q)[K_+(N_+ - L_-) - (N_+ + L_-)K_-], \\
\end{aligned}
\quad (3.7)$$

where

$$K_{\pm} = iM_{03} \mp M_{34}, \quad N_{\pm} = M_{02} \pm iM_{01}. \quad (3.8)$$

(iii) $[M, L]$ sector,

$$\begin{aligned}
[M_3, L_3] &= 0, \\
[M_3, L_{\pm}] &= \pm L_{\pm}, \\
[M_-, L_3] &= \frac{1}{2}(N_+ + L_-) - \frac{1}{2}(N_+ - L_-)q^{M_3}, \\
[M_-, L_+] &= q^{M_3}K_+ - K_- \\
&\quad + \frac{1}{2}(1 - q^{-1})M_-(L_+ - N_-), \\
[M_-, L_-] &= \frac{1}{2}(1 - q)M_-(N_+ + L_-), \\
[M_+, L_3] &= -\frac{1}{2}(N_- + L_+) + \frac{1}{2}q^{-M_3}(N_- - L_+), \\
[M_+, L_+] &= \frac{1}{2}(1 - q)M_+(N_- + L_+), \\
[M_+, L_-] &= q^{-M_3}K_- - K_+ \\
&\quad + \frac{1}{2}(1 - q)(N_+ - L_-)M_+. \\
\end{aligned}
\quad (3.9)$$

The relations (3.5), (3.7) and (3.9) describe the q -deformation of the Lorentz generators $\mathfrak{sl}(2; \mathbb{C}) \simeq \mathfrak{o}(3, 1)$ which belong to the quantum algebra $U_q(\mathfrak{o}(3, 2))$.

One can also write the q -deformation of the remaining commutators of the $o(3, 2)$ algebra. Here we shall only write the commutators, describing the q -deformation of relation (2.12b) which provides after contraction the commutators of the translation generators P_μ .

(iv) Curved translations sector ($M_{0\mu}$),

$$\begin{aligned} [M_{04}, M_{03}] &= iM_{34}, \\ [M_{04}, M_{02}] &= iM_{24}, \\ [M_{04}, M_{01}] &= iM_{14} \\ [M_{03}, M_{02}] &= -\frac{1}{4}i[M_- q^{M_{04}}(1+q^{-M_3}) + q^{-M_{04}}(1+q^{M_3})M_+] \\ &\quad + \frac{1}{8}i(q-1)[K_+(L_- - N_+) + (N_- + L_+)K_+ \\ &\quad + (N_+ + L_-)K_- + K_-(L_+ - N_-)], \\ [M_{03}, M_{01}] &= \frac{1}{4}[M_- q^{M_{04}}(1+q^{-M_3}) + q^{-M_{04}}(1+q^{M_3})M_+] \\ &\quad + \frac{1}{8}i(q-1)[K_-(L_+ - N_-) + (N_- + L_+)K_+ \\ &\quad - (N_+ + L_-)K_- + K_+(N_+ - L_-)], \\ [M_{02}, M_{01}] &= \frac{1}{2}i\{[M_{04} + M_3]_q - [M_{04} - M_3]_q\} \\ &\quad + \frac{1}{4}i(1-q)\{(K_-)^2 - q^{-1}(K_+)^2\}. \end{aligned} \quad (3.10)$$

It should be stressed that the q -deformed Lorentz sector (M_\pm, M_3, L_\pm, L_3) does not form a quantum group, because it is also deformed by generators belonging before deformation to the coset $O(3, 2)/O(3, 1)$.

4. Contraction and q -deformed Poincaré

Let us recall that $|q|=1$, i.e., $g=e^{iw}$. We introduce the following rescaling ($0 < \kappa < \infty$) (see also ref. [8]):

$$M_{\mu\nu} = M_{\mu\nu}, \quad M_{0\mu} = R \cdot P_\mu, \quad w = \frac{1}{\kappa} \cdot \frac{1}{R}, \quad (4.1)$$

where κ is a geometric mass parameter.

Using (4.1) for example we obtain

$$\begin{aligned} [M_3 + M_{04}]_q + [M_3 - M_{04}]_q \\ = 2 \frac{\sin(M_3/\kappa R)}{\sin(1/\kappa R)} \cos \frac{P_0}{\kappa}. \end{aligned} \quad (4.2)$$

Performing the limit $R \rightarrow \infty$ in (4.2) we get

$$\begin{aligned} \lim_{R \rightarrow \infty} [M_3 + M_{04}]_q + [M_3 - M_{04}]_q \\ = 2M_3 \cos(P_0/\kappa). \end{aligned} \quad (4.3)$$

Using the formulae (4.1) and performing the limit $R \rightarrow \infty$ we obtain the following set of relations:

(a) Lorentz sector ($M_\pm = M_1 \pm iM_2$),

$$[M_+, M_-] = 2M_3, \quad [M_3, M_\pm] = \pm M_\pm, \quad (4.4)$$

$$\begin{aligned} [L_-, L_+] &= 2M_3 \cos \frac{P_0}{\kappa} - \frac{1}{\kappa} (P_3 L_3 + L_3 P_3) \\ &\quad + \frac{1}{2\kappa^2} P_3^2, \\ [L_3, L_\pm] &= \mp \exp\left(\mp i \frac{P_0}{\kappa}\right) M_\pm \pm \frac{1}{2\kappa} L_\pm P_3 \\ &\quad + \frac{i}{2\kappa} L_3 P_\mp, \end{aligned} \quad (4.5)$$

$$[M_3, L_3] = 0,$$

$$[M_3, L_\pm] = \pm L_\pm,$$

$$[M_+, L_3] = -L_+ - \frac{i}{2\kappa} M_3 P_-,$$

$$[M_-, L_3] = +L_- - P_+ \frac{i}{2\kappa} M_3,$$

$$[M_+, L_-] = +2L_3 + \frac{1}{2i\kappa} P_+ M_+ + \frac{1}{\kappa} P_3 M_3,$$

$$[M_-, L_+] = -2L_3 + \frac{1}{2i\kappa} M_- P_- - \frac{1}{\kappa} P_3 M_3,$$

$$[M_\pm, L_\pm] = \frac{1}{2i\kappa} M_\pm P_\mp. \quad (4.6)$$

(b) Translation sector ($P_\pm = P_2 \pm iP_1$),

$$[P_\mu, P_\nu] = 0, \quad (4.7)$$

$$[M_i, P_0] = 0, \quad [M_i, P_k] = i\epsilon_{ikl} P_l, \quad (4.8)$$

$$[L_3, P_0] = iP_3,$$

$$[L_3, P_3] = i\kappa \sin(P_0/\kappa),$$

$$[L_3, P_2] = \frac{1}{2i\kappa} P_1 P_3, \quad (4.9)$$

$$\begin{aligned}
[L_3, P_1] &= -\frac{1}{2i\kappa} P_2 P_3, \\
[L_\pm, P_0] &= i P_\mp P_2, \\
[L_\pm, P_3] &= \frac{1}{2i\kappa} P_\mp P_3, \\
[L_\pm, P_2] &= \mp \kappa \sin \frac{P_0}{\kappa} - \frac{1}{2i\kappa} P_3^2, \\
[L_\pm, P_1] &= i\kappa \sin \frac{P_0}{\kappa} \pm \frac{1}{2\kappa} P_3^2. \quad (4.9 \text{ cont'd})
\end{aligned}$$

We see from the formulae (4.4)–(4.9) that:

(i) The three-dimensional rotations [eq. (4.4)] and the translation subgroup [eq. (4.7)] are not deformed.

(ii) The modification is obtained in the closure of the boost sector and in the transformation of four-momenta under the boost transformations.

It is easy to see that if $\kappa \rightarrow \infty$ we recover the conventional Poincaré algebra.

Let us perform the time reversal transformation T , which is an antiinvolution, changing the sign of the imaginary unit i . It is easy to check that the invariance of the relations (4.4)–(4.9) under the discrete transformation

$$\begin{aligned}
T: M_i &\rightarrow -M_i, \quad L_i \rightarrow L_i, \\
P_i &\rightarrow -P_i, \quad P_0 \rightarrow P_0
\end{aligned} \quad (4.10)$$

implies that

$$q \rightarrow q^* \quad (4.11)$$

and because $|q|=1$ the parameter κ is T -invariant. Indeed, the relations (4.5b) can be written as

$$\begin{aligned}
[L_3, L_1] &= i(-\cos \alpha M_2 + \sin \alpha M_1) \\
&\quad + \frac{i}{2\kappa} (L_2 P_3 + L_3 P_2), \\
[L_3, L_2] &= i(\sin \alpha M_2 + \cos \alpha M_1) \\
&\quad - \frac{i}{2\kappa} (L_1 P_3 - L_3 P_1), \\
\alpha &= (P_0/\kappa). \quad (4.12)
\end{aligned}$$

From the antiunitarity of T follows that the iM_i are T -invariant, and the deformation (4.5) of the boost algebra is not changed under time reversal.

In order to show that the deformed Poincaré algebra is a quantum group, one needs to define the co-product. The following expressions were obtained as the contraction of the coproduct for $\mathcal{U}_q(\mathfrak{o}(3,2))$ and can be shown to be a homomorphism of the algebra (4.4) to (4.9):

$$\begin{aligned}
\Delta M_i &= M_i \otimes I + I \otimes M_i, \quad i=1, 2, 3, \\
\Delta P_0 &= P_0 \otimes I + I \otimes P_0, \\
\Delta P_i &= P_i \otimes \exp\left(\frac{iP_0}{2\kappa}\right) + \exp\left(\frac{-iP_0}{2\kappa}\right) \otimes P_i, \\
i &= 1, 2, 3, \\
\Delta L_3 &= L_3 \otimes \exp\left(\frac{iP_0}{2\kappa}\right) + \exp\left(\frac{-iP_0}{2\kappa}\right) \otimes L_3 \\
&\quad + \frac{i}{2\kappa} \exp\left(\frac{-iP_0}{2\kappa}\right) M_+ \otimes P_+ \\
&\quad - \frac{i}{2\kappa} P_- \otimes M_- \exp\left(\frac{iP_0}{2\kappa}\right), \\
\Delta L_+ &= L_+ \otimes \exp\left(\frac{iP_0}{2\kappa}\right) + \exp\left(\frac{-iP_0}{2\kappa}\right) \otimes L_+ \\
&\quad + \frac{i}{2\kappa} P_- \otimes M_3 \exp\left(\frac{iP_0}{\kappa}\right) \\
&\quad - \frac{i}{2\kappa} \exp\left(\frac{-iP_0}{2\kappa}\right) M_3 \otimes P_- \\
&\quad + \frac{1}{\kappa} \exp\left(\frac{-iP_0}{2\kappa}\right) M_+ \otimes P_3, \\
\Delta L_- &= L_- \otimes \exp\left(\frac{iP_0}{2\kappa}\right) + \exp\left(\frac{-iP_0}{2\kappa}\right) \otimes L_- \\
&\quad + \frac{i}{2\kappa} P_+ \otimes M_3 \exp\left(\frac{iP_0}{2\kappa}\right) \\
&\quad - \frac{i}{2\kappa} \exp\left(\frac{-iP_0}{2\kappa}\right) M_3 \otimes P_+ \\
&\quad + \frac{1}{\kappa} P_3 \otimes M_- \exp\left(\frac{iP_0}{2\kappa}\right).
\end{aligned}$$

The counit is defined in the usual way. The antipode S compatible with the coproduct is given by

$$S(P_\mu) = -P_\mu,$$

$$S(M_i) = -M_i,$$

$$S(L_3) = -L_3 - \frac{1}{2\kappa} P_3 + \frac{i}{2\kappa} (M_+ P_+ - P_- M_-),$$

$$S(L_+) = -L_+ - \frac{i}{\kappa} P_- + \frac{1}{\kappa} M_+ P_3,$$

$$S(L_-) = -L_- + \frac{i}{\kappa} P_+ + \frac{1}{\kappa} P_3 M_-.$$

This shows that the q -deformed Poincaré algebra is a quantum group.

5. First Casimir of q -deformed Poincaré and modified Klein–Gordon equation

Let us observe that all ten generators of the q -deformed Poincaré algebra commute with the following operator:

$$I_2 = P_1^2 + P_2^2 + P_3^2 + 2\kappa^2 \left(\cos \frac{P_0}{\kappa} - 1 \right) \\ = P_1^2 + P_2^2 + P_3^2 - P_0^2 + \frac{1}{12\kappa^2} P_0^4 + O(\kappa^{-4}), \quad (5.1)$$

which is the q -deformation of the first Casimir describing the relativistic mass squared operator. It is interesting to note that an analogous formula, obtained by putting $P_3=0$, is valid for the algebraically much simpler three-dimensional q -deformed Poincaré algebra [8]. Introducing $P_\mu = (1/i)(\partial/\partial x^\mu)$ one obtains the following q -generalization of the Klein–Gordon equation ($x_0 \equiv t$) as the scalar realization of q -deformed Poincaré algebra:

$$\Delta\phi(\mathbf{x}, t) + 2\kappa^2 [\cosh(\partial_t/\kappa) - 1] \phi(\mathbf{x}, t) \\ = m^2 \phi(\mathbf{x}, t), \quad (5.2)$$

or in $O(1/\kappa^4)$ approximation

$$(\partial_\mu \partial^\mu - m^2) \phi(\mathbf{x}, t) \\ = \frac{-1}{12\kappa^2} \partial_t^4 \phi(\mathbf{x}, t) + O(\kappa^{-4}). \quad (5.3)$$

Eq. (5.2) can be obtained from the following lagrangian density:

$$\mathcal{L} = -\frac{1}{2} (\nabla\phi)^2 - \frac{1}{2} m^2 \phi^2 + \frac{1}{2} \sum_{n=1}^{\infty} \frac{\kappa^{2-2n}}{(2n)!!} (\partial_t^n \phi)^2. \quad (5.4)$$

The energy spectrum of the quanta described by eq. (5.2) (or the position of the poles of the free q -deformed propagator) is given by the formula

$$p^0 = \kappa \arccos \left(1 - \frac{\mathbf{p}^2 + m^2}{2\kappa^2} \right). \quad (5.5)$$

The q -deformed mass-shell condition is invariant under the change $p_0 \rightarrow p_0 + 2\pi n\kappa$, i.e., the energy dependence on the three-momentum \mathbf{p}^2 is a periodic function.

6. Outlook

The aim of this paper is to study the deformation of the Poincaré algebra which originates in the q -deformation of $\mathfrak{sp}(4)$. It is not clear to us if there exists another reasonable contraction of $U_q(\mathfrak{sp}(4))$, in particular providing commuting translation generators.

The formulae (4.4)–(4.6) describe our proposal for the q -deformation of a Lorentz algebra, which is embedded in the q -deformation of the universal enveloping algebra of a whole Poincaré algebra (quantum Poincaré algebra). In this respect our q -deformation is different from other proposals for q -deformations of $SL(2, \mathbb{C})$ leading to the appearance of a quantum Lorentz algebra (or quantum Lorentz group as a dual object) [15–17]. It follows from our calculations that the semidirect product structure (even taking into consideration the q -deformation of commutators between Lorentz and translation generators) of the Poincaré algebra is not preserved for $q \neq 1$.

This paper contains only partial results. For completeness one should consider also the deformation of the second Casimir operator (squared of the Pauli–Lubanski four-vector), and calculate the contraction limit for the universal R -matrix. The complete description of the quantum Poincaré algebra as a quasi-triangular Hopf algebra [3] will be given elsewhere.

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