

MATH 213 - Tutorial 6: Systems solutions

- (Common midterm error) Use the definition of a linear system to formally prove that the system modelled by the the DE

$$y''(t) + 9y'(t) + 8y(t) = f(t)$$

is linear.

Solution: The response of this system to the signal $f(t)$ is

$$y(t) = \int_0^t \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 9s + 8} \right\} \Big|_{\tau} \cdot f(t - \tau) d\tau.$$

Thus if $S(f(t)) = y_f(t)$ and $S(g(t)) = y_g(t)$ then

$$\begin{aligned} S(f(t) + g(t)) &= \int_0^t \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 9s + 8} \right\} \Big|_{\tau} \cdot (f + g)(t - \tau) d\tau \\ &= \int_0^t \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 9s + 8} \right\} \Big|_{\tau} \cdot (f(t - \tau) + g(t - \tau)) d\tau \\ &= \int_0^t \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 9s + 8} \right\} \Big|_{\tau} \cdot f(t - \tau) + \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 9s + 8} \right\} \Big|_{\tau} \cdot g(t - \tau) d\tau \\ &= \int_0^t \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 9s + 8} \right\} \Big|_{\tau} \cdot f(t - \tau) d\tau + \int_0^t \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 9s + 8} \right\} \Big|_{\tau} \cdot g(t - \tau) d\tau \\ &= y_f(t) + y_g(t) \end{aligned}$$

- (Common midterm error) Use the definition of a linear system to formally show that the system modelled by the the DE

$$y''(t) + 3y'(t) + 2y(t) = f(t) + 1$$

is nonlinear.

Solution: The response of this system to the signal $f(t)$ is

$$y(t) = \int_0^t \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 3s + 2} \right\} \Big|_{\tau} \cdot (f(t - \tau) + 1) d\tau.$$

Thus if $S(f(t)) = y_f(t)$ and $S(g(t)) = y_g(t)$ then

$$\begin{aligned} S(f(t) + g(t)) &= \int_0^t \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 3s + 2} \right\} \Big|_{\tau} \cdot (f(t - \tau) + g(t - \tau) + 1) d\tau \\ &= \int_0^t \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 3s + 2} \right\} \Big|_{\tau} \cdot f(t - \tau) + \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 3s + 2} \right\} \Big|_{\tau} \cdot g(t - \tau) + \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 3s + 2} \right\} \Big|_{\tau} d\tau \\ &= \int_0^t \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 3s + 2} \right\} \Big|_{\tau} \cdot f(t - \tau) d\tau + \int_0^t \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 3s + 2} \right\} \Big|_{\tau} \cdot g(t - \tau) d\tau + \int_0^t \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 3s + 2} \right\} \Big|_{\tau} d\tau \\ &= y_f(t) + y_g(t) + \int_0^t \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 3s + 2} \right\} \Big|_{\tau} d\tau \end{aligned}$$

This system is linear if and only if the last integral is equal to 0 for all t . Since the inverse Laplace transform of this transfer is a PWC function, the integral is equal to 0 for all t exactly when the integrated is 0. Clearly the inverse Laplace transform is not uniformly 0 so this system is not linear.

3. (Common midterm error) Use the convolution theorem to compute

$$t^2 e^t * \sin(t)$$

where both functions are one sided.

Solution: The convolution theorem tells us that

$$t^2 e^t * \sin(t) = \mathcal{L}^{-1} \{ \mathcal{L} \{ t^2 e^t \} \cdot \mathcal{L} \{ \sin(t) \} \}.$$

We first compute the transforms via the Laplace table

$$\begin{aligned} \mathcal{L} \{ \sin(t) \} &= \frac{1}{s^2 + 1} \\ \mathcal{L} \{ t^2 e^t \} &= \mathcal{L} \{ t^2 \} \Big|_{s-1} \\ &= \mathcal{L} \{ t^2 \} \Big|_{s-1} \\ &= \frac{2}{(s-1)^3} \end{aligned}$$

Hence

$$t^2 e^t * \sin(t) = \mathcal{L}^{-1} \left\{ \frac{2}{(s^2 + 1)(s-1)^3} \right\}.$$

To compute the inverse transform we preform partial fractions

$$\frac{2}{(s^2 + 1)(s-1)^3} = \frac{As + B}{s^2 + 1} + \frac{C}{(s-1)^3} + \frac{D}{(s-1)^2} + \frac{E}{s-1}$$

Using the Heaviside coverup method to find A , B , and C and then solving a 2x2 system to find D and E gives us

$$\frac{2}{(s^2 + 1)(s-1)^3} = \frac{-1/2s + 1/2}{s^2 + 1} + \frac{1}{(s-1)^3} - \frac{1}{(s-1)^2} + \frac{1/2}{s-1}$$

Computing the inverse Laplace transforms of each term gives

$$\begin{aligned} \frac{-1/2s + 1/2}{s^2 + 1} &= \frac{1}{2}(\sin(t) - \cos(t)) \\ \frac{1/2}{s-1} &= \frac{1}{2}e^t \\ -\frac{1}{(s-1)^2} &= \frac{d}{ds} \left(\frac{1}{s-1} \right) && \text{calculus} \\ &= -t \mathcal{L}^{-1} \left\{ \frac{1}{s-1} \right\} && \text{mult by } t \\ &= -te^t \\ \frac{1}{(s-1)^3} &= \frac{1}{2} \frac{d}{ds} \left(\frac{1}{(s-1)^2} \right) && \text{calculus} \\ &= (-1)^2 t^2 \frac{1}{2} \mathcal{L}^{-1} \left\{ \frac{1}{s-1} \right\} && \text{mult by } t \\ &= \frac{1}{2} t^2 e^t \end{aligned}$$

Using these gives us

$$t^2 e^t * \sin(t) = \frac{1}{2}(\sin(t) - \cos(t)) + \frac{1}{2}e^t - te^t + \frac{1}{2}t^2 e^t$$

-
4. Find the system impulse response of the system modelled by the DE

$$y'''(t) + 3y''(t) + 2y'(t) = f(t)$$

Solution: The system impulse response is simply the inverse Laplace transform of the transfer function. Hence we need to compute

$$\mathcal{L}^{-1} \left\{ \frac{1}{s^3 + 3s^2 + 2s} \right\}$$

Factoring gives $s^3 + 3s^2 + 2s = s(s^2 + 3s + 2) = s(s+2)(s+1)$ and hence we make the PF ansatz

$$\frac{1}{s^3 + 3s^2 + 2s} = \frac{A}{s} + \frac{B}{s+2} + \frac{C}{s+1}.$$

The coverup method gives

$$\frac{1}{s^3 + 3s^2 + 2s} = \frac{1/2}{s} + \frac{1/2}{s+2} - \frac{1}{s+1}.$$

Hence the system's impulse response is

$$h(t) = \frac{1}{2} + \frac{1}{2}e^{-2t} - e^{-t}$$