

# Computational methods for imprecise continuous-time birth-death processes: a preliminary study of flipping times

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## The Precise Case

Consider a continuous time and finite-state Markov process with state space  $\mathcal{X}$ . At any time  $t \in [0, +\infty)$ , the stochastic matrix of the process  $P_t$  is derived from a transition rate matrix  $Q$ . For  $i, j \in \mathcal{X}$ , the element at the  $i$  row and  $j$  column of  $Q$  is denoted by  $Q(i, j)$ . For the matrix  $Q$ , the following properties hold

- (P1)  $Q(i, j) \geq 0$  for all  $i, j \in \mathcal{X}$  such that  $i \neq j$
- (P2)  $\sum_{j \in \mathcal{X}} Q(i, j) = 0, \forall i \in \mathcal{X}$

A matrix  $Q$  is said to be bounded if  $Q(i, i) > -\infty$  for all  $i \in \mathcal{X}$  or, equivalently, if  $\|Q\| < \infty$ . Our results hold for various types of norm, but the one we consider is the infinite norm defined by  $\|Q\| := \|Q\|_\infty = \max\{\sum_{j \in \mathcal{X}} |Q(i, j)| : i \in \mathcal{X}\}$ .

When  $Q$  is bounded, then  $P_t$  satisfies the Kolmogorov backward equation

$$\frac{d}{dt}P_t = QP_t. \quad (1)$$

If we let  $f_t(i) := E_t(f|X_0 = i)$ , with  $f$  a real-valued function on the finite state space  $\mathcal{X}$  and  $i \in \mathcal{X}$  an initial state, then we can rewrite Equation (1) as follows

$$\frac{d}{dt}f_t = Qf_t. \quad (2)$$

Combined with the boundary condition  $f_0 = f$ , the unique solution of Equation (2) is  $f_t = e^{tQ}f$ . Instead of considering a time-invariant  $Q$ , we can also let  $Q_t$  be a function of the time  $t$ . In that case, Equation (2) can be rewritten as

$$\frac{d}{dt}f_t = Q_t f_t. \quad (3)$$

which, in general, has no analytical solution.

## A "messy" case

Consider the state space  $\mathcal{X} := \{0, 1, 2, 3\}$ , the following set  $\mathcal{Q}$  of bounded matrices

$$\left\{ \begin{pmatrix} -p_i & p_i & 0 & 0 \\ q_j & -q_j & 0 & 0 \\ 0 & 0 & -r & r \\ 0 & 0 & s & -s \end{pmatrix} : a_i \in [\underline{a}, \bar{a}] \text{ and } b_j \in [\underline{b}, \bar{b}] \right\}$$

and a function  $f$  of the form  $[c, c, f_2, f_3]^T$ . In this case, we cannot efficiently identify  $Q_{\tau_0}$ , because for any  $Q, Q' \in \mathcal{Q}$ , we have that  $Q^k f = Q'^k f$ , for all  $k \in \mathbb{N}$ .

Is there a simple way to check when two different matrices  $Q, Q'$  yield the same expected value, without calculating  $Q^k$  and  $Q'^k$  for all  $k$ ?

## Imprecise Birth-Death Process

We focus on the case where every state has an interval-valued birth and/or death rate. The transition rate matrices have the following form

$$\begin{pmatrix} -\lambda_0 & \lambda_0 & 0 & \cdots & \cdots & \cdots & 0 \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots & \vdots \\ 0 & \cdots & \mu_i & -(\mu_i + \lambda_i) & \lambda_i & \cdots & 0 \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots & \vdots \\ 0 & \cdots & \cdots & \cdots & 0 & \mu_L & -\mu_L \end{pmatrix}$$

where, for all  $i \in \{0, \dots, L-1\}$  and  $j \in \{1, \dots, L\}$ ,  $\lambda_i \in [\underline{\lambda}, \bar{\lambda}]$  and  $\mu_j \in [\underline{\mu}, \bar{\mu}]$  and  $L \in \mathbb{N}$ . In this way, we have a set of matrices  $\mathcal{Q}$  with finite numbers of extreme points, separately specified rows and which avoids the special case above.

## The Imprecise Case

**Set of matrices** Instead of a single transition matrix  $Q$ , we consider a set of such matrices, denoted by  $\mathcal{Q}$ . We assume that each matrix in  $\mathcal{Q}$  is bounded and satisfies (P1) and (P2). Let  $\mathcal{R}$  be the set of all rate matrices, then for any set  $\mathcal{Q} \subseteq \mathcal{R}$  of rate matrices, we let

$$\mathcal{Q}_i := \{Q(i, \cdot) : Q \in \mathcal{Q}\} \text{ for all } i \in \mathcal{X},$$

and we say that  $\mathcal{Q}$  has *separately specified rows* if

$$Q \in \mathcal{Q} (\forall i \in \mathcal{X}) Q(i, \cdot) \in \mathcal{Q}_i.$$

We further assume that  $\mathcal{Q}$  is the convex hull of a *finite* number of extreme transition rate matrices.

**Our Approach** At any time  $t \in [0, +\infty)$ , the only assumption we make about  $Q_t$  is that it is an element of  $\mathcal{Q}$ . Every such possible choice of non-stationary transition rate matrices will, by (3), result in a—possibly different—solution  $f_t$ . Our goal is to calculate exact lower and upper bounds for the set of all these solutions  $f_t$ , as denoted by  $\underline{f}_t$  and  $\bar{f}_t$ . In the recent work of Škulj and with respect to the lower bound,  $\underline{f}_t$  is the solution to

$$\frac{d}{dt}\underline{f}_t = \min_{Q \in \mathcal{Q}} Q\underline{f}_t, \text{ with boundary condition } \underline{f}_0 = f. \quad (4)$$

Since  $\mathcal{Q}$  is the convex hull of a finite number of extreme transition rate matrices and that the solution to (4) is continuous, there must be time points  $0 = t_0 < t_1 < \dots < t_n < t_{n+1} < \dots$  such that, for all  $t \in \tau_n := [t_n, t_{n+1}]$ , the minimum in (4) is obtained by the same extreme transition rate matrix  $Q_{\tau_n} \in \mathcal{Q}$ . We call these time points  $t_n$  *flipping times*. Equation (4) is then piecewise linear and has the following solution

$$\underline{f}_t = e^{(t-t_n)Q_{\tau_n}} e^{(t_n-t_{n-1})Q_{\tau_{n-1}}} \dots e^{(t_2-t_1)Q_{\tau_1}} e^{t_1 Q_{\tau_0}} f, \text{ for } t \in [t_n, t_{n+1}]. \quad (5)$$

**Calculating Lower Expectations** We need to find the flipping times  $t_n$  and the corresponding extreme transition rate matrices  $Q_{\tau_n}$  when calculating the lower expectation of a given  $f$  on  $\mathcal{X}$ . It is known that

$$\frac{\partial}{\partial t}[e^{tQ}f] \Big|_{t=0} = Qf \Rightarrow (\forall \varepsilon > 0)(\exists \delta > 0)(\forall t \in (0, \delta)) \|e^{tQ}f - f - tQf\|_\infty < t\varepsilon \quad (6)$$

and it can be further proved that for any pair of matrices  $Q, Q'$  in  $\mathcal{Q}$

$$\text{if } Qf < Q'f, \text{ then } (\exists \delta > 0)(\forall t \in (0, \delta)) e^{tQ}f < e^{tQ'}f,$$

where  $Qf < Q'f$  if  $Qf(i) \leq Q'f(i)$  for all  $i \in \mathcal{X}$  and  $Qf \neq Q'f$ . In order to find  $Q_{\tau_0}$  in (5), we need to find a  $Q$  such that  $Qf < Q'f$ , for all  $Q' \in \mathcal{Q} \setminus \{Q\}$ . Since  $\mathcal{Q}$  has separately specified rows, we can identify  $Q_{\tau_0}$  by minimising  $Qf$  at each row separately. Hence,  $Q_{\tau_0}$  belongs to the set

$$\mathcal{Q}_{\tau_0} := \{Q \in \mathcal{Q} : Qf(i) \leq Q'f(i), \forall i \in \mathcal{X} \text{ and } \forall Q' \in \mathcal{Q} \setminus \{Q\}\}.$$

In practice,  $\mathcal{Q}_{\tau_0}$  might not be a singleton and in this case, for any two matrices  $Q, Q'$  in  $\mathcal{Q}_{\tau_0}$ , we have that  $Qf = Q'f$ . Since we know that  $\frac{\partial^k}{\partial t^k}[e^{tQ}f] \Big|_{t=0} = Q^k f$ , it can be proved that

$$\text{if } Q^k f < Q'^k f \text{ and } Q^{k'} f = Q'^{k'} f \text{ for all } k' \in \{1, \dots, k-1\}, \text{ then } (\exists \delta > 0)(\forall t \in (0, \delta)) e^{tQ}f < e^{tQ'}f \quad (7)$$

Therefore, if  $\mathcal{Q}_{\tau_0}$  is not a singleton, then  $Q_{\tau_0}$  is a single matrix  $Q$  of  $\mathcal{Q}_{\tau_0}$ , for which (7) holds.

Having found  $Q_{\tau_0}$ , then  $\underline{f}_{t_1} = e^{t_1 Q_{\tau_0}} f$  and  $\tau_0 := [t_1, 0]$  due to (5). In order to find the corresponding, if any, flipping time  $t_1$ , we take the derivative of  $e^{tQ}\underline{f}_{t_1}$  evaluated at  $t = 0$ .

$$\frac{\partial}{\partial t}[e^{tQ}\underline{f}_{t_1}] \Big|_{t=0} = Q\underline{f}_{t_1} = Qe^{t_1 Q_{\tau_0}} f$$

and due to continuity, it holds that

$$Q_{\tau_0} e^{t_1 Q_{\tau_0}} f = Qe^{t_1 Q_{\tau_0}} f. \quad (8)$$

We solve (8) for each  $i \in \mathcal{X}$  separately, since  $\mathcal{Q}$  has separately specified rows and the smallest positive real solution of  $t_1$  is the first flipping time and the corresponding matrix  $Q$  is the matrix  $Q_{\tau_1}$ . We continue the same procedure till we find no more flipping times.

## Numerical Results

We calculate the lower expected probability of state 1,  $\underline{E}(X_t = 1)$ , of an imprecise birth-death chain with state space  $\mathcal{X} := \{0, 1, 2, 3\}$  for  $t$  approaching infinity. The set of transition rate matrices  $\mathcal{Q}$  is derived from the intervals  $\lambda_i \in [1, 3]$  and  $\mu_j \in [2, 5]$ , for all  $i \in \{0, \dots, L-1\}$  and  $j \in \{1, \dots, L\}$  and the input function is  $f = [0, 1, 0, 0]^T$ .

Following the procedure described before, we start by finding a matrix  $Q$ , such that  $Qf < Q'f$  for all  $Q' \in \mathcal{X} \setminus \mathcal{Q}$ . Due to the values of  $f$ , there are multiple  $Q$ , such that  $Qf$  is pointwise minimum. These matrices have the following form

$$Q^* = \begin{pmatrix} -1 & 1 & 0 & 0 \\ 5 & -8 & 3 & 0 \\ 0 & 2 & -(2 + \lambda_2) & \lambda_2 \\ 0 & 0 & \mu_3 & -\mu_3 \end{pmatrix}$$

where,  $\lambda_2 \in \{1, 3\}$  and  $\mu_3 \in \{2, 5\}$ .

Continuing with the procedure, we check whether there is a matrix  $Q$ , such that  $Q^2 f < Q'^2 f$  for all  $Q' \in \mathcal{X} \setminus \mathcal{Q}$ . Indeed, there is such a matrix and therefore we have that

$$Q_{\tau_0} = \begin{pmatrix} -1 & 1 & 0 & 0 \\ 5 & -8 & 3 & 0 \\ 0 & 2 & -5 & 3 \\ 0 & 0 & 2 & -2 \end{pmatrix}$$

for which the flipping time is  $t_1 = 0.6403991$  and  $Q_{\tau_1}$  is

$$Q_{\tau_1} = \begin{pmatrix} -3 & 3 & 0 & 0 \\ 2 & -5 & 3 & 0 \\ 0 & 2 & -5 & 3 \\ 0 & 0 & 2 & -2 \end{pmatrix}$$

For the matrix  $Q_{\tau_1}$  there is no flipping time and by taking  $t \rightarrow \infty$ , we have that  $\underline{E}(X = 1) = 0.0937540788$ .