

$$\textcircled{1} \quad Y \sim N(0, 1)$$

$$X|Y=y \sim N(y, 1).$$

$$f_{X,Y}(x, y) = f_Y(y) f_{X|Y}(x|y).$$

$$= \frac{e^{-y^2/2}}{\sqrt{2\pi}} \frac{e^{-(x-y)^2/2}}{\sqrt{2\pi}}$$

$$f_{Y,Z}(y, z) = \frac{e^{-y^2/2}}{\sqrt{2\pi}} \frac{e^{-z^2/2}}{\sqrt{2\pi}}$$

z, y independent

$$(W \stackrel{?}{=} Y+Z, Z) \iff (Y, Z)$$

$$W = g_1(Y, Z) = Y + Z$$

$$g_2(Z) = Z.$$

$$f_{W,Z}(w, z) = \underbrace{f_{Y,Z}(y, z)}_{\text{st } w = y+z} \frac{J(y, z)}{J(y, z)}.$$

$$J(y, z) = \begin{vmatrix} \frac{\partial g_1(y, z)}{\partial y} & \frac{\partial g_1(y, z)}{\partial z} \\ \frac{\partial g_2(y, z)}{\partial y} & \frac{\partial g_2(y, z)}{\partial z} \end{vmatrix} = \begin{vmatrix} 1 & 1 \\ 0 & 1 \end{vmatrix}$$

$$\Rightarrow f_{W,Z}(w, z) = f_{Y,Z}(w-z, z).$$

$$= \frac{e^{-z^2/2}}{\sqrt{2\pi}} \frac{e^{-(w-z)^2/2}}{\sqrt{2\pi}}$$

$$= f_{X,Y}(w, z).$$

$$\textcircled{b} \quad \begin{pmatrix} X \\ Y \end{pmatrix} = \underbrace{\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}}_A \begin{bmatrix} Z \\ T \end{bmatrix}.$$

as the joint distribution of X, Y
is same as $T+Z, T$

$\Rightarrow \begin{pmatrix} X \\ Y \end{pmatrix}$ is Gaussian random vector |
 X, Y are jointly Gaussian

as we can write it as a matrix A multiplying
standard normal iid Gaussian vector.

$$\textcircled{c} \quad E[X] = E[E[X|T]].$$

$$E[X|T=y] = y \text{ by defn. as } X|T=y \sim N(y, 1)$$

$$\Rightarrow E[X] = E[E[X|T]] = E[T] = 0.$$

$$\text{Var}(X) = E[\text{Var}(X|T)] + \text{Var}(E[X|T])$$

$$= E[1] + \text{Var}(T).$$

$$\text{as } \text{Var}(X|T=y) = 1 \text{ by defn as } X|T=y \sim N(y)$$

$$E[X|T=y] = y \quad " "$$

$$\Rightarrow \text{Var}(X) = 2.$$

$$\text{Cov}(X, T) = E[X T] - \underbrace{E[X] E[T]}_0$$

$$= E[E[X T|T]].$$

$$= E[T E[X|T]].$$

$$= E[T^2] = \text{Var}(T) + (E[T])^2 = 1.$$

$$\textcircled{e} \quad f_{Y|X}(y|x) = \frac{f_{X|Y}(x|y) f_Y(y)}{f_X(x)}$$

$$X \sim N(0, 2).$$

① Since we have shown (\bar{X}, Y) is jointly Gaussian we know X should be Gaussian too.

$$\text{as } X = \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} \bar{X} \\ Y \end{pmatrix}.$$

② The parameters of distribution are $E[X]$, $\text{Var}(X)$ determined earlier.

$$= \frac{1}{\sqrt{2\pi}} e^{-\frac{(x-y)^2}{2}} \cdot \frac{1}{\sqrt{2\pi}} e^{-\frac{y^2}{2}}$$

$$\frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}}$$

$$\textcircled{f} \quad E[Y|X=x] = x/2. \text{ from } f_{Y|X}(y|x) \text{ above.}$$

Could've used the linear MMSE expression to compute this directly.

$$\begin{aligned} \text{note that this notation is slightly different from notes as usually we find } E[X|Y=y] \text{ to estimate } x. \\ E[Y|X=x] &= \frac{\text{Cov}(X, Y)}{\text{Var}(X)} (x - E[X]) + E[Y]. \\ &= \frac{\text{Cov}(X, Y)}{\text{Var}(X)} x = \frac{x}{2}. \end{aligned}$$

② Will change notation of q_n for ease to match with class notes.
Rephrased

Qn:

$$\text{let } Y_1 = X + N_1 + \alpha N_2$$

$$Y_2 = X + 3N_1 + \alpha N_2.$$

③ Find estimate for X from Y_1, Y_2 .

Two ways: ① Using the formula we derived.

$$\hat{\mathbf{y}}_{\text{LMMSE}} = R_{XX}^{-1} K_Y^{-1} \mathbf{y}.$$

$$K_Y = \begin{bmatrix} \text{Var}(Y_1) & \text{Cov}(Y_1, Y_2) \\ \text{Cov}(Y_1, Y_2) & \text{Var}(Y_2) \end{bmatrix}.$$

$$R_{XX} = \begin{bmatrix} \text{Cov}(x, Y_1) & \text{Cov}(x, Y_2) \end{bmatrix}$$

$$\text{Cov}(x, Y_1) = E[x Y_1] = E[x(x + N_1 + \alpha N_2)]$$

$$\downarrow \text{both have mean 0} \\ = E[x^2 + N_1 x + \alpha N_2 x]$$

$$= E[x^2] + E[N_1] E[x] + \alpha E[N_2] E[x].$$

$$\begin{array}{c} X, N_1, N_2 \\ \text{and} \\ \text{independent} \end{array} \quad = E[x^2] = 1.$$

Similarly

$$\text{Cov}(x, Y_2) = E[x Y_2] = 1.$$

$$\text{Var}(Y_1) = E[Y_1^2] = E[(x + N_1 + \alpha N_2)^2]$$

$$\begin{array}{c} \text{rest of} \\ \text{the terms} \\ \text{vanish} \end{array} \quad = E[x^2] + E[N_1^2] + \alpha^2 E[N_2^2] \\ = 2 + \alpha^2.$$

$$\text{Var}(Y_2) = E[(x + 3N_1 + \alpha N_2)^2].$$

$$= E[x^2] + 9 E[N_1^2] + \alpha^2 E[N_2^2]$$

$$= 10 + \alpha^2.$$

$$\hat{x}_{\text{LMMSE}}(y_1, y_2) = R_{X,Y} K_Y^{-1} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}.$$

$$= [1 \quad 1] \begin{bmatrix} 2+\alpha^2 & 4+\alpha^2 \\ 4+\alpha^2 & 10+\alpha^2 \end{bmatrix}^{-1} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

$$\text{Cov}(Y_1, Y_2) = E[(x+3N_1 + \alpha N_2)(x+N_1 + \alpha N_2)]$$

all the other terms are 0

$$= E[x^2] + 3E[N_1^2] + \alpha^2 E[N_2^2].$$

$$= 4 + \alpha^2.$$

$$\Rightarrow \hat{x}_{\text{LMMSE}}(y_1, y_2) = \frac{1}{4+4\alpha^2} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 10+\alpha^2 & -(4+\alpha^2) \\ -(4+\alpha^2) & (2+\alpha^2) \end{bmatrix}^{-1} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

$$\det(K_Y) = (2+\alpha^2)(10+\alpha^2) - (4+\alpha^2)^2.$$

$$= \frac{20+\alpha^4+12\alpha^2 - 16-\alpha^4-8\alpha^2}{4+4\alpha^2}.$$

$$= \frac{1}{4(1+\alpha^2)} \begin{bmatrix} 6 & -2 \end{bmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

$$= \frac{(6y_1 - 2y_2)}{4(1+\alpha^2)}.$$

MSE for LMMSE estimator

$$E \left[X - \left(\frac{6Y_1 - 2Y_2}{4(1+\alpha^2)} \right) \right]^2.$$

$$6Y_1 - 2Y_2 = 6(x+N_1 + \alpha N_2) - 2(x+3N_1 + \alpha N_2)$$

$$= 4(x + \alpha N_2)$$

$$= E \left[\left(x - \frac{(x + \alpha N_2)}{(1+\alpha^2)} \right)^2 \right].$$

$$= E \left[(x(1+\alpha^2) - x - \alpha N_2)^2 \right] \frac{1}{(1+\alpha^2)^2}$$

$$= E \left[(2x - \alpha N_2)^2 \right] \frac{1}{(1+\alpha^2)^2}.$$

$$= \frac{\alpha^2}{(1+\alpha^2)^2} E \left[(\alpha x - N_2)^2 \right].$$

$$= \frac{\alpha^2}{(1+\alpha^2)^2} \cancel{(\alpha^2 + 1)} = \frac{\alpha^2}{1+\alpha^2}.$$

(c) At $\alpha = 0$.

③ a) $x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$

$$x_1 = \underbrace{(1 \ 0 \ 0)}_{M_1} x$$

$E[x_1] = M_1 \mu = 1$ or The first element of M_1 .

$$\text{Var}(x_1) = M_1 K_x M_1^T$$

first element of K_x .

$$f_{x_1}(x_1) = \frac{e^{-\frac{(x_1-1)^2}{2}}}{\sqrt{2\pi}}$$

b)

Made with Goodnotes

$$f_{x_2, x_3 | x_1}(x_2, x_3 | x_1) = \frac{f_{x_1, x_2, x_3}(x_1, x_2, x_3)}{f_{x_1}(x_1)}$$

$$K_{\bar{x}} = \begin{pmatrix} 1 & 0 \\ 1 & 0 \\ 0 & 9 \end{pmatrix} = \frac{-e^{-\frac{(x_1 - \bar{x}_1)^2}{2}}}{(2\pi)^{3/2} (\det(K))^{1/2}} \cdot \frac{\sqrt{2\pi}}{e^{-\frac{x_1^2}{2}}}$$

$$\bar{x} = \begin{pmatrix} x_2 \\ x_3 \end{pmatrix}$$

$$R_{\bar{x}, x_1} = \begin{pmatrix} \text{Cov}(x_2, x_1) \\ \text{Cov}(x_3, x_1) \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$K_x = 1$$

Can show

$$x_2 | x = x_1$$

$$\sim N(\hat{\mu}, R_{x_2, x_2})$$

$$\hat{\mu} = R_{\bar{x}, x_1} K_{x_1}^{-1} x_1$$

$$\bar{x} = \begin{pmatrix} x_2 \\ x_3 \end{pmatrix}$$

$$\Rightarrow \hat{\mu} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} x_1 = \begin{pmatrix} x_1 \\ 0 \end{pmatrix}$$

$$R_{x_2, x_3} = \begin{pmatrix} 4 & 0 \\ 0 & 9 \end{pmatrix}$$

$$\Rightarrow f_{x_2, x_3 | x_1}(x_2, x_3 | x_1) = \frac{e^{-\frac{1}{2} \left[\frac{(x_2 - \bar{x}_2)^2}{4} + \frac{x_3^2}{9} \right]}}{(2\pi)^{1.5}}$$

$$\textcircled{a} \quad Y = 2x_1 + x_2 + x_3$$

$$= (2 \ 1 \ 1) \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$$\Rightarrow E[Y] = (2 \ 1 \ 1) E[x] = (2 \ 1 \ 1) \begin{pmatrix} 1 \\ 5 \\ 2 \end{pmatrix} = 2 + 5 + 2 = 9$$

$$\text{Made with } \text{Geogebra} \quad E[YY^T] = E[(2 \ 1 \ 1)x x^T \begin{pmatrix} 2 \\ 1 \end{pmatrix}]$$

$$= [z \ 1] K \times \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$= [z \ 1] \begin{bmatrix} 1 & 1 & 0 \\ 1 & 4 & 0 \\ 0 & 0 & 9 \end{bmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$= [3 \ 6 \ 9] \cdot \begin{pmatrix} 2 \\ 1 \end{pmatrix} = 6 + 6 + 9$$

$$= 21 \cdot$$

$$f_Y(y) = \frac{e^{-\frac{(y-9)^2}{2 \times 21}}}{\sqrt{2\pi \times 21}}$$

④

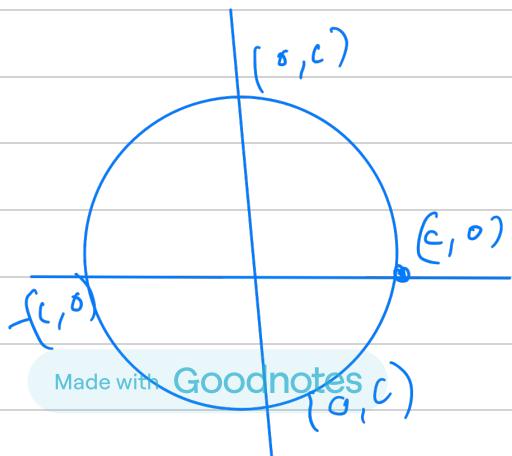
$$\text{Let } x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\frac{e^{-\frac{x^T K^{-1} x}{2}}}{2\pi (\det(K))^{1/2}} = \frac{0.8}{2\pi (\det(K))^{1/2}}$$

$$\Rightarrow \frac{x^T K^{-1} x}{2} = \log\left(\frac{1}{0.8}\right)$$

$$\textcircled{a} \quad K = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \Rightarrow K^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\Rightarrow x_1^2 + x_2^2 = 2 \log\left(\frac{1}{0.8}\right)$$

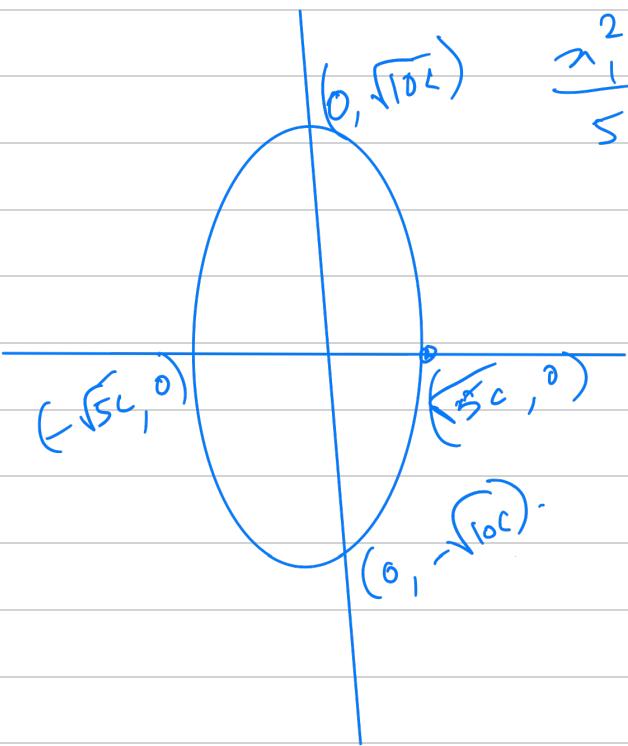


$$\textcircled{b} \quad K = \begin{bmatrix} 5 & 0 \\ 0 & 10 \end{bmatrix}.$$

$$x^T K^{-1} x = c \cdot = 2 \log\left(\frac{1}{0.8}\right).$$

$$(x_1, x_2) \begin{bmatrix} x_1 \\ \frac{x_2}{10} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = c$$

$$(0, \sqrt{10}c) \quad \frac{x_1^2}{5} + \frac{x_2^2}{10} = c.$$



$$\textcircled{c} \quad K = \begin{bmatrix} 4 & 2 \\ 2 & 4 \end{bmatrix},$$

$$D = \begin{bmatrix} 6 & 0 \\ 0 & 2 \end{bmatrix}.$$

$$\begin{bmatrix} 4 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 6 \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}.$$

$$4x_1 + 2x_2 = 6x_1.$$

$$\underline{x_2 = x_1}$$

$$x_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

To find eigen values

$$\begin{vmatrix} 4-\lambda & 2 \\ 2 & 4-\lambda \end{vmatrix} = 0$$

$$(4-\lambda)^2 - 4 = 0$$

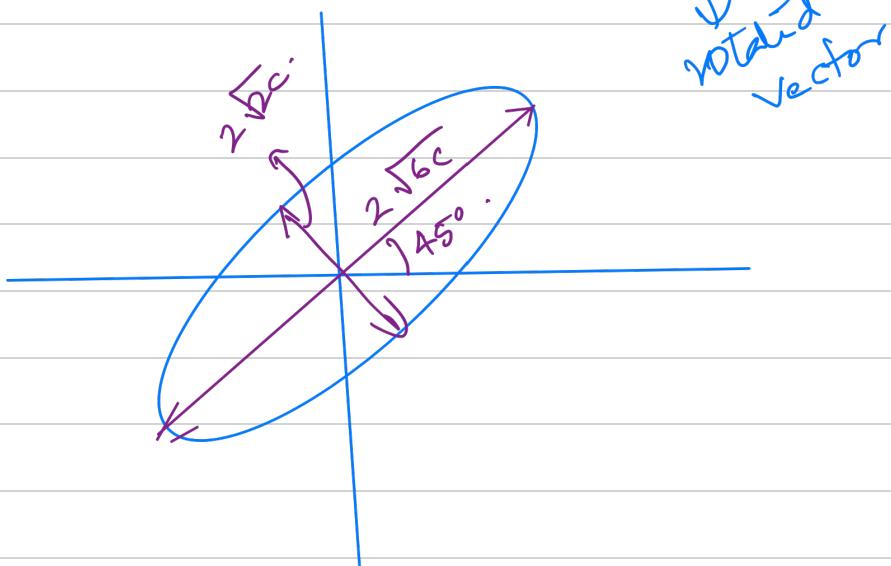
$$(16 - 8\lambda + \lambda^2 - 4) = 0$$

$$\lambda^2 - 8\lambda + 12 = 0$$

$$\Rightarrow \underline{q}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix} \quad \text{since it is orthogonal to } \underline{q}_1$$

$$K = \underbrace{\begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}}_Q \underbrace{\begin{bmatrix} 6 & 0 \\ 0 & 2 \end{bmatrix}}_D \underbrace{\begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}}_{Q^T}$$

$$\underline{x}^T Q D^{-1} Q^T \underline{x} = c.$$



(5) $K = \begin{bmatrix} 4 & 3 \\ 3 & 2 \end{bmatrix}$ Nope. $\det(K) < 0$.
can't be since
 K is p.s.d.
its $\det(K) \geq 0$

(6) $\|z - y\|_2^2 = (z - y)^T (z - y)$.

$$\begin{aligned} \|Qz - Qy\|_2^2 &= [Q(z - y)]^T Q(z - y) \\ &= (z - y)^T \underbrace{Q^T Q}_{I} (z - y) \\ &= (z - y)^T I (z - y) \\ &= \|z - y\|_2^2 \end{aligned}$$

$$\textcircled{1} \quad K = \begin{bmatrix} 3/4 & 1/4 \\ 1/4 & 3/4 \end{bmatrix}.$$

\textcircled{b} Eigen vectors of
 $K' = \alpha K$ and K will be same

Say $Kx = \lambda x$.

$$\alpha Kx = \alpha \lambda x.$$

$$\Rightarrow K'x = (\alpha \lambda) x.$$

Eigen values get scaled by α .

\textcircled{a} Can find eigen values of $K' = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}$
 and scale them by $\frac{1}{\alpha}$

$$(3 - \lambda)^2 - 1 = 0.$$

$$8 - 6\lambda + \lambda^2 = 0.$$

$$\lambda = 4, 2.$$

\Rightarrow eigen values of K are
 $\pm 1/4, \pm 2/4 = 1/2$

\textcircled{c} K^m since K is p.s.d $\exists Q, D \triangleright$ diag
 orthonormal st

$$K = Q D Q^T$$

$$K^2 = (Q D Q^T)(Q D Q^T)$$

$$= Q D^2 Q^T.$$

$$\text{Similarly } K^m = Q D^m Q^T$$

\Rightarrow Eigen vectors of K^m are same
as that of K

Eigen values of K^m are m -th
power of eigen values of K .

$$K = \begin{pmatrix} 1 & p & p^2 \\ p & 1 & p \\ p^2 & p & 1 \end{pmatrix}$$

We can pick a vector to have 0's at 3rd position

$$(a_1, a_2, 0) K \begin{pmatrix} a_1 \\ a_2 \\ 0 \end{pmatrix} \geq 0.$$

$$(a_1, a_2) \begin{bmatrix} 1 & p \\ p & 1 \end{bmatrix} \begin{pmatrix} a_1 \\ a_2 \\ 0 \end{pmatrix} \geq 0.$$

$$\Rightarrow \det \begin{pmatrix} 1 & p \\ p & 1 \end{pmatrix} \geq 0$$

$$\Rightarrow 1 - p^2 \geq 0.$$

[otherwise it would imply that there is a -ve eigen vector for matrix $\begin{pmatrix} 1 & p \\ p & 1 \end{pmatrix}$]

(X, Y) are jointly Gaussian

$$K = \begin{bmatrix} \sigma_x^2 & \rho \sigma_x \sigma_y \\ \rho \sigma_x \sigma_y & \sigma_y^2 \end{bmatrix}.$$

a) Find $f_{X|V}(x|v)$ where $V = Y^3$.

b) Find $f_{X|U}(x|u)$ where $U = Y^2$.

$(X, Y) \iff (X, V) \quad V = g(Y)$

$$J(x, y) = \begin{bmatrix} 1 & 0 \\ 0 & g'(y) \end{bmatrix}$$

⁴
invertible function

$$f_{X,V}(x,v) = \frac{f_{X,Y}(x, g^{-1}(v))}{g'(g^{-1}(v))}$$

$$f_{V|U}(v) = \frac{f_Y(g'(v))}{g'(g^{-1}(v))}.$$

$$f_{X|Y}(x|v) = \frac{f_{X,Y}(x,v)}{f_V(v)}.$$

$$= \frac{f_{X,Y}(x, v^{1/3})}{f_Y(v^{1/3})} = f_{X|Y}(x|v^{1/3}).$$

$$X|Y=v \sim N\left(\rho \frac{\sigma_x}{\sigma_y} v^{1/3}, (1-\rho^2)\sigma_x^2\right)$$

$$\frac{Cov(X, Y)}{\text{Var}(Y)} v^{1/3}$$

Check HW4

sols
for detailed
proof for

$f_{X|Y}$

$$U = Y^2.$$

$$f_U(u) = \underbrace{f_Y(\sqrt{u}) + f_Y(-\sqrt{u})}_{2\sqrt{u}} \underbrace{\frac{1}{2\sqrt{u}}}_{\text{PDF}}$$

Similarly:

$$= \underbrace{f_X(\sqrt{u}) + f_X(-\sqrt{u})}_{2\sqrt{u}}$$

$$f_{X,U}(x,u) = \underbrace{f_{X,Y}(x, \sqrt{u}) + f_{X,Y}(x, -\sqrt{u})}_{2f_{X,Y}(x, \sqrt{u})}.$$

$$\Rightarrow f_{X|U}(x|u) = \underbrace{f_{X,Y}(x, \sqrt{u}) + f_{X,Y}(x, -\sqrt{u})}_{2f_{X,Y}(x, \sqrt{u})}.$$

$$f_X(\sqrt{u}) + f_X(-\sqrt{u}).$$

$$f_Y(y) = \frac{e^{-y^2/2\sigma_y^2}}{\sqrt{2\pi}}$$

$$f_Y(\sqrt{u}) = f_X(-\sqrt{u}) = \frac{e^{-u/2\sigma_y^2}}{\sqrt{2\pi}}.$$

$$f_U(u) = 2 f_Y(\sqrt{u})$$

$$f_{X|U}(x|u) = \frac{f_{X,Y}(x, \sqrt{u})}{2 f_Y(\sqrt{u})} + \frac{f_{X,Y}(x, -\sqrt{u})}{2 f_Y(\sqrt{u})}$$

$$= \frac{1}{2} f_{X|Y}(x|\sqrt{u}) + \frac{1}{2} f_{X|Y}(x|-\sqrt{u})$$

i., $X|_{U=u}$ is a mixture of two Gaussian distributions.

$$N\left(\frac{s\sigma_x}{\sigma_y}\sqrt{u}, (1-s^2)\sigma_x^2\right), N\left(-\frac{s\sigma_x}{\sigma_y}\sqrt{u}, (1-s^2)\sigma_x^2\right)$$

$X|_{U=u}$ is not Gaussian but a mixture of Gaussian distributions.