
EE1101: Circuits and Network Analysis

Lecture 24: First-Order Circuits

September 22, 2025

Topics :

1. Quantifying Transient Response
 2. Examples of First-order Circuits
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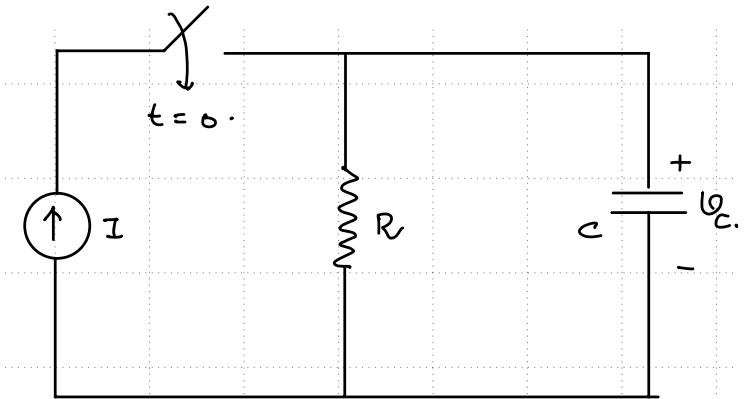
Examples of First-order Circuits

by KCL, $\dot{I}_S = \dot{I}_R + \dot{I}_C$

$$\dot{I}_S = \frac{\dot{V}_C}{R} + C \frac{d\dot{V}_C}{dt}$$

$$\frac{d\dot{V}_C}{dt} + \frac{1}{RC} V_C = \frac{\dot{I}_S}{C} \rightarrow ①$$

Integrating factor = $e^{\int \frac{1}{RC} dt} = e^{t/RC}$



Transient Response:

mul ① on both sides with IF \Rightarrow

$$\frac{d}{dt} (e^{t/RC} V_C(t)) = \frac{\dot{I}_S}{C} e^{t/RC}$$

Integrate on both sides.

$$e^{t/RC} V_C = \frac{\dot{I}_S}{C} \times RC e^{t/RC} + C$$

$$V_C = R \dot{I}_S + C e^{-t/RC}$$

$$C: V_C(0) = 0 \Rightarrow C = -R \dot{I}_S \quad \& \quad V_C(t) = R \dot{I}_S (1 - e^{-t/RC})$$

as $t \rightarrow \infty$, $V_C = R \dot{I}_S$ (Steady state response) ←

$$\underbrace{V_C(t)}_{\text{Steady state value}} - \underbrace{V_C(0)}_{\text{Initial value}} = -R \dot{I}_S e^{-t/RC}$$

Steady state value determines the variation of transient response

Quantifying Transient Response

for first order circuits: Nature of transient response is exponentially decaying

for Series RL circ

$$\tau = L/R$$

for parallel RC circ

$$\tau = R/C$$

{ one way to quantify the transient response is to indicate the rate of decay.

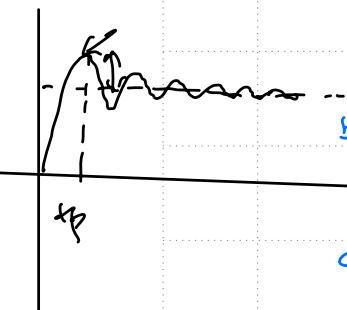
time constant : (τ)

$$-t/\tau$$

for higher order circs (circs having $L, C \&$ multiple energy storage elem)

a) rise time (t_r) : time taken from 2%, of the final value to 98% of final value

$$(5\% - 95\%) (t_r) (f_0 - f_{0.2})$$



steady state

b) settling time (t_s) : time to reach 98% (or) 95% of the final value. ($\pm 2\%$ of final value)

c) Peak overshoot (M_p) : Peak value as a fraction of final value (%)

d) time to peak (t_p) : time to reach Peak value

Examples of First-order Circuits

for $0 < t < t_0$: RL Ckt driven by $V_s u(t)$

$$i(t) = \frac{V_s}{R_1} (1 - e^{-t/\tau})$$

$$\text{where } \tau = \frac{L}{R_1}$$

at t_0 when switch transition happens

$$i_L(t_0^-) = i_L(t_0^+)$$

t_0 : large enough for the Ckt to operate in

steady-state

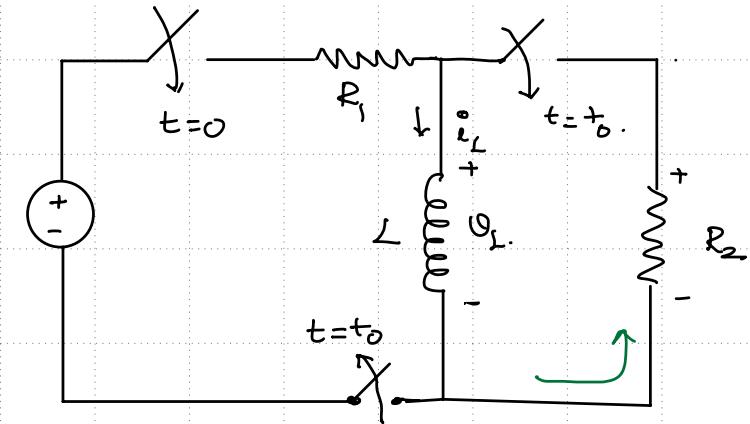
$\Rightarrow t_0$ is large enough for $i_L(t_0) = \text{Steady}$

State

Current

$v_L(t_0) = \text{Steady}$

Steady State Voltage



for $t > t_0$:

$$v_{R_2} = v_L.$$

$$L \frac{di_L}{dt} = v_{R_2} = -i_L R_2.$$

$$\frac{di_L}{dt} + \frac{R_2}{L} i_L = 0. \rightarrow (3)$$

$$\text{IF} = e^{t/\tau_2} \quad \text{when } \tau_2 = L/R_2$$

mul (3) by IF on both sides

$$\frac{d}{dt} (e^{t/\tau_2} i_L) = 0$$

$$i_L = C e^{-t/\tau_2}.$$

$$\text{at } t_0: i_L(t_0) = C e^{-t_0/\tau_2}$$

$$C = i_L(t_0) e^{t_0/\tau_2}$$

$$\Rightarrow i_L(t) = i_L(t_0) e^{-\frac{(t-t_0)}{\tau_2}}$$

Examples of First-order Circuits (Response to $e^{-\alpha t}$)

by KVL (for $t > 0$):

$$\frac{di}{dt} + \frac{R}{L} i = \frac{1}{L} e^{-2t} \quad \text{--- (1)}$$

Integrating factor = $e^{\frac{R}{L}t}$

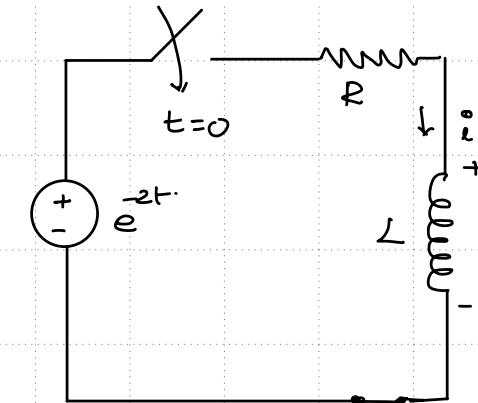
upon mul ① by IF & rearranging

$$\frac{d}{dt} (e^{\frac{R}{L}t} i(t)) = \frac{1}{L} e^{(\frac{R}{L}-2)t}$$

$$i(t) = \frac{e^{-\frac{R}{L}t}}{L} \cdot \frac{1}{(R/L - 2)} e^{\frac{R}{L}t - 2t} + C e^{-\frac{R}{L}t}$$

$$i(t) = \frac{1}{(R-2L)} e^{-2t} + C e^{-\frac{R}{L}t}$$

C : based on Init Cond.



Zero-input and Zero-state Response

