

**EE2100: Matrix Analysis**  
**Review Notes - 32**

**Topics covered :**

1. QR Decomposition

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1. Consider a matrix  $\mathbf{A} \in \mathcal{R}^{m \times n}$ . The column vectors of  $\mathbf{A}$  are denoted by  $\mathbf{a}_i \in \mathcal{R}^m$  where  $i \in (1, \dots, n)$ . Using the Gram-Schmidt Algorithm, it is possible to generate orthogonal vectors from  $[\mathbf{a}_1, \dots, \mathbf{a}_n]$ . If  $\mathbf{u}_1, \dots, \mathbf{u}_n$  and  $\mathbf{q}_1, \dots, \mathbf{q}_n$  denote the orthogonal vectors and orthonormal vectors generated by Gram-Schmidt respectively, then

$$\begin{aligned} \mathbf{u}_1 &= \mathbf{a}_1 \text{ and } \mathbf{q}_1 = \frac{\mathbf{u}_1}{\|\mathbf{u}_1\|} \\ \mathbf{u}_2 &= \mathbf{a}_2 - \text{Proj}_{\mathbf{q}_1} \mathbf{a}_2 \text{ i.e., } \mathbf{u}_2 = \mathbf{a}_2 - (\mathbf{a}_2 \cdot \mathbf{q}_1) \mathbf{q}_1 \text{ and } \mathbf{q}_2 = \frac{\mathbf{u}_2}{\|\mathbf{u}_2\|} \\ &\vdots \quad \vdots \\ \mathbf{u}_k &= \mathbf{a}_k - \sum_{i=1}^{k-1} \text{Proj}_{\mathbf{q}_i} \mathbf{a}_k \text{ i.e., } \mathbf{u}_k = \mathbf{a}_k - \sum_{i=1}^{k-1} (\mathbf{a}_k \cdot \mathbf{q}_i) \mathbf{q}_i \text{ and } \mathbf{q}_k = \frac{\mathbf{u}_k}{\|\mathbf{u}_k\|} \end{aligned} \tag{1}$$

It is interesting to note that the column vectors  $\mathbf{a}_1, \dots, \mathbf{a}_n$  can be represented in terms of the orthonormal vectors  $\mathbf{q}_1, \dots, \mathbf{q}_n$  as

$$\begin{aligned} \mathbf{a}_1 &= \|\mathbf{u}_1\| \mathbf{q}_1 \\ \mathbf{a}_2 &= (\mathbf{a}_2 \cdot \mathbf{q}_1) \mathbf{q}_1 + \|\mathbf{u}_2\| \mathbf{q}_2 \\ &\vdots = \vdots \\ \mathbf{a}_k &= \sum_{i=1}^{k-1} (\mathbf{a}_k \cdot \mathbf{q}_i) \mathbf{q}_i + \|\mathbf{u}_k\| \mathbf{q}_k \end{aligned} \tag{2}$$

Equation (2) indicates that  $\mathbf{A}$  (which is a collection of column vectors  $[\mathbf{a}_1 \dots \mathbf{a}_n]$ ) can be represented as

$$\mathbf{A} = \mathbf{Q}\mathbf{R} \tag{3}$$

where  $\mathbf{Q} = [\mathbf{q}_1 \dots \mathbf{q}_n]$  is an orthonormal matrix and the matrix  $\mathbf{R}$  is an upper triangular matrix given by

$$\mathbf{R} = \begin{bmatrix} \|\mathbf{u}_1\| & \mathbf{a}_2 \cdot \mathbf{q}_1 & \mathbf{a}_3 \cdot \mathbf{q}_1 & \cdots & \mathbf{a}_k \cdot \mathbf{q}_1 & \cdots & \mathbf{a}_n \cdot \mathbf{q}_1 \\ 0 & \|\mathbf{u}_2\| & \mathbf{a}_2 \cdot \mathbf{q}_2 & \cdots & \mathbf{a}_k \cdot \mathbf{q}_2 & \cdots & \mathbf{a}_n \cdot \mathbf{q}_2 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & \|\mathbf{u}_k\| & \cdots & \mathbf{a}_n \cdot \mathbf{q}_k \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & \cdots & 0 & \|\mathbf{u}_n\| \end{bmatrix} \tag{4}$$

The entries of  $\mathbf{R}$  are given by

$$R_{ij} = \begin{cases} \|\mathbf{u}_i\| & \text{when } i = j \\ \mathbf{a}_j \cdot \mathbf{q}_i & \text{when } j > i \\ 0 & \text{otherwise} \end{cases} \quad (5)$$

Thus, a rectangular matrix can be represented as  $\mathbf{A} = \mathbf{QR}$ , where  $\mathbf{Q}$  is an orthonormal matrix (and hence  $\mathbf{Q}^{-1} = \mathbf{Q}^T$ ) and  $\mathbf{R}$  is an upper triangular matrix. This is often referred to as [QR Decomposition](#) of a matrix ([Note](#): There are other numerically stable algorithms for QR factorization. In this course, the idea of QR factorization is introduced through the Gram-Schmidt approach).

2. Consider the scenario of solving  $\mathbf{Ax} = \mathbf{b}$  where  $\mathbf{A} \in \mathbb{R}^{m \times n}$ ,  $\mathbf{x} \in \mathbb{R}^n$  and  $\mathbf{b} \in \mathbb{R}^m$ . The least-squares solution to such a system of linear equations is obtained by solving

$$\mathbf{A}^T \mathbf{Ax} = \mathbf{A}^T \mathbf{b} \quad (6)$$

If  $\mathbf{A}$  is represented as  $\mathbf{QR}$ , the solution can be obtained by solving

$$\mathbf{R}^T \underbrace{\mathbf{Q}^T \mathbf{Q}}_{\mathbf{I}} \mathbf{Rx} = \mathbf{R}^T \mathbf{Q}^T \mathbf{b} \implies \mathbf{R}^T \mathbf{Rx} = \mathbf{R}^T \mathbf{Q}^T \mathbf{b} \quad (7)$$

Computing  $\mathbf{x}$  using (7) is a preferred approach from the point of view of numerical stability (an aspect covered at a later point in the course).