

EE2100: Matrix Analysis**Review Notes - 35**

Topics covered :

1. Singular Value Decomposition
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1. **Singular Value Decomposition:** A rectangular matrix (say $\mathbf{A} \in \mathcal{R}^{m \times n}$) can be decomposed as

$$\mathbf{A} = \mathbf{U}\Sigma\mathbf{V}^T \quad (1)$$

where $\mathbf{U} \in \mathcal{R}^{m \times m}$ and $\mathbf{V} \in \mathcal{R}^{n \times n}$ are orthonormal matrices whose column vectors are referred to as left singular vectors and right singular vectors respectively. The matrix $\Sigma \in \mathcal{R}^{m \times n}$ is a matrix that has only diagonal entries (a few of which can be zero). The diagonal entries of Σ are referred to as the singular values.

Proof: For any $\mathbf{A} \in \mathcal{R}^{m \times n}$, the Gram matrix $\mathbf{A}^T\mathbf{A}$ (say $\mathbf{G} \in \mathcal{R}^{n \times n}$) is always real and Symmetric. Accordingly, by Spectral Theorem, the Gram matrix can be expressed as

$$\mathbf{G} = \mathbf{V}\mathbf{D}\mathbf{V}^T \quad (2)$$

where $\mathbf{D} \in \mathcal{R}^{n \times n}$ is a diagonal matrix whose entries are Eigen values of \mathbf{G} (some of which can be zero, if \mathbf{G} is singular). The matrix $\mathbf{V} \in \mathcal{R}^{n \times n}$ is an orthonormal matrix whose column vectors are Eigen vectors of \mathbf{G} . Let $\mathbf{v}_i \in \mathcal{R}^n$ denote the i^{th} column vector (or Eigen vector associated with Eigen value λ_i) of \mathbf{V} .

Similarly, for any $\mathbf{A} \in \mathcal{R}^{m \times n}$, the matrix $\mathbf{A}\mathbf{A}^T$ (say $\mathbf{H} \in \mathcal{R}^{m \times m}$) is always real and Symmetric. Accordingly, by Spectral Theorem, \mathbf{H} can be expressed as

$$\mathbf{H} = \mathbf{U}\mathbf{D}_1\mathbf{U}^T \quad (3)$$

where $\mathbf{D}_1 \in \mathcal{R}^{m \times m}$ is a diagonal matrix whose entries are Eigen values of \mathbf{H} (some of which can be zero, if \mathbf{H} is singular). The matrix $\mathbf{U} \in \mathcal{R}^{m \times m}$ is an orthonormal matrix whose column vectors are Eigen vectors of \mathbf{H} . Let $\mathbf{u}_i \in \mathcal{R}^m$ denote the i^{th} column vector (or Eigen vector associated with Eigen value λ_i) of \mathbf{U} .

Further, it is also known that, the rank and nullity of the Gram matrix is the same as the rank and nullity of \mathbf{A} respectively (i.e., **rank**(\mathbf{G})=**rank**(\mathbf{A}) and **nullity**(\mathbf{G})=**nullity**(\mathbf{A})). Stated alternately, any vector in the null space of \mathbf{A} is also in the null space of \mathbf{G} .

Let $r(\leq n)$ denote the rank of \mathbf{A} (i.e., **rank**(\mathbf{A}) = r). Accordingly, the matrix \mathbf{G} has r non-zero and positive Eigen values (some of which can be repeated).

Let $\sigma_1^2, \sigma_2^2, \dots, \sigma_r^2, \underbrace{0, 0, \dots, 0}_{n-r}$ denote the Eigen values of \mathbf{G} (note that we are using a slightly different notation for Eigen values). Let the corresponding Eigen Vectors of \mathbf{G} be denoted by $\mathbf{v}_1, \dots, \mathbf{v}_r, \mathbf{v}_{r+1}, \dots, \mathbf{v}_n$ (where \mathbf{v}_i). Further, **assume that the Eigen values and Eigen vectors of \mathbf{G} are indexed such that $\sigma_1^2 \geq \sigma_2^2 \geq \dots \geq \sigma_r^2, 0 \dots, 0$** (this is a commonly adopted indexing which we will follow in this course). Under this indexing scheme, the vectors

$\mathbf{v}_i \forall i > r$ are in the null space of \mathbf{A} and \mathbf{G} and the vectors $\mathbf{v}_i \forall i \leq r$ satisfy the equation

$$\mathbf{G}\mathbf{v}_i = \sigma_i^2 \mathbf{v}_i \quad (4)$$

Pre-multiplying on the either sides of (4) by \mathbf{A} results in

$$\mathbf{A}\mathbf{A}^T \mathbf{A}\mathbf{v}_i = \sigma_i^2 \mathbf{A}\mathbf{v}_i \implies \mathbf{H}(\mathbf{A}\mathbf{v}_i) = \sigma_i^2 (\mathbf{A}\mathbf{v}_i) \quad (5)$$

Equation (5) indicates that $\mathbf{A}\mathbf{v}_i$ (for $i \leq r$) is an Eigen Vector of \mathbf{H} with the associated Eigen value of σ_i^2 . Thus \mathbf{G} and \mathbf{H} have the same non-zero Eigen values. The norm of the computed Eigen vectors of \mathbf{H} is

$$\|\mathbf{A}\mathbf{v}_i\|_2 = \sqrt{\mathbf{v}_i^T \mathbf{A}^T \mathbf{A} \mathbf{v}_i} = \sqrt{\sigma_i^2 \mathbf{v}_i^T \mathbf{v}_i} = \sigma_i \quad (6)$$

In order to choose the Eigen vectors of unit norm for \mathbf{H} , the Eigen vectors are scaled by σ_i . Accordingly, \mathbf{u}_i as defined in (??) are the Eigen vectors i.e.,

$$\mathbf{u}_i = \frac{\mathbf{A}\mathbf{v}_i}{\sigma_i} \quad (7)$$

The r Eigen vectors of \mathbf{G} and the r Eigen vectors of \mathbf{H} satisfy the set of equations (??).

$$\left. \begin{array}{l} \sigma_1 \mathbf{u}_1 = \mathbf{A}\mathbf{v}_1 \\ \sigma_2 \mathbf{u}_2 = \mathbf{A}\mathbf{v}_2 \\ \vdots = \vdots \\ \sigma_r \mathbf{u}_r = \mathbf{A}\mathbf{v}_r \end{array} \right\} r \text{ equations} \quad (8)$$

Equation ?? can be alternately represented as

$$[\mathbf{u}_1 \ \mathbf{u}_2 \ \dots \ \mathbf{u}_r] \begin{bmatrix} \sigma_1 & 0 & \dots & 0 \\ 0 & \sigma_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_r \end{bmatrix} = \mathbf{A} [\mathbf{v}_1 \ \mathbf{v}_2 \ \dots \ \mathbf{v}_r] \quad (9)$$

Noting that $\mathbf{A}\mathbf{v}_i = \mathbf{0} \ \forall i > r$, (9) can be modified as

$$[\mathbf{u}_1 \ \mathbf{u}_2 \ \dots \ \mathbf{u}_r] \begin{bmatrix} \sigma_1 & 0 & \dots & 0 & \color{red}{0} & \dots & 0 \\ 0 & \sigma_2 & \dots & 0 & \color{red}{0} & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \dots & \sigma_r & \color{red}{0} & \dots & 0 \end{bmatrix} = \mathbf{A} [\mathbf{v}_1 \ \mathbf{v}_2 \ \dots \ \mathbf{v}_r \ \mathbf{v}_{r+1} \ \dots \ \mathbf{v}_n] \quad (10)$$

In order to account for the other possible Eigen vectors of \mathbf{H} , (10) can be further modified as

$$[\mathbf{u}_1 \ \mathbf{u}_2 \ \cdots \ \mathbf{u}_r \ \mathbf{u}_{r+1} \cdots \ \mathbf{u}_m] \begin{bmatrix} \sigma_1 & 0 & \cdots & 0 & 0 & \cdots & 0 \\ 0 & \sigma_2 & \cdots & 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & \sigma_r & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & 0 & 0 & \cdots & 0 \end{bmatrix} = \mathbf{A} [\mathbf{v}_1 \ \mathbf{v}_2 \ \cdots \ \mathbf{v}_r \ \mathbf{v}_{r+1} \cdots \ \mathbf{v}_n] \quad (11)$$

Equation (11) can be written as

$$\mathbf{U}\Sigma = \mathbf{AV} \quad (12)$$

where $\mathbf{U} \in \mathcal{R}^{m \times m}$ is an orthonormal matrix that contains the Eigen Vectors of \mathbf{AA}^T , $\mathbf{V} \in \mathcal{R}^{n \times n}$ is an orthonormal matrix that contains the Eigen Vectors of $\mathbf{A}^T\mathbf{A}$ and $\Sigma \in \mathcal{R}^{m \times n}$ is a matrix whose diagonal entries are σ_i . Since \mathbf{U} and \mathbf{V} are orthonormal matrices, the matrix \mathbf{A} can be written as

$$\mathbf{A} = \mathbf{U}\Sigma\mathbf{V}^T \quad (13)$$