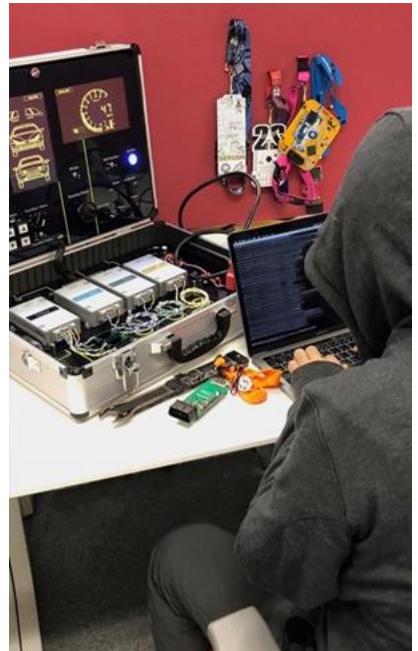




PASTA: Portable Automotive Security Testbed with Adaptability

Tsuyoshi Toyama, Takuya Yoshida, Hisashi Oguma, Tsutomu Matsumoto

Who are we?



Tsuyoshi Toyama



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Hisashi Oguma



Tsutomu Matsumoto



Yokohama National University
http://er-web.jmk.ynu.ac.jp/html/MATSUMOTO_Tsutomu/en.html

- Background of vehicular security
- What is PASTA ?
- Demo
- Use cases
- Roadmap
- Take away

Background

- Lots of ECUs are in a vehicle to realize comfortable driving.
- ECUs interact with other ECUs, sensors, and actuators using CAN protocol, etc.
- CAN Protocol was developed with no concern about cyber security attacks.

Vehicle hacking is real threat

- July 2015, two hackers presented that Jeep Chrysler can be remotely controlled.
- Controlling wipers, audio system, steering wheels, etc. of a running car.
- As a result, Chrysler recalled 1.4 million vehicles.

Remote Exploitation of an
Unaltered Passenger Vehicle

Dr. Charlie Miller (cmiller@openrce.org)
Chris Valasek (cvalasek@gmail.com)

August 10, 2015



ANDY GREENBERG SECURITY 07.24.15 12:30 PM
**AFTER JEEP HACK,
CHRYSLER RECALLS 1.4M
VEHICLES FOR BUG FIX**



CNN Money Business Markets Tech Personal Finance Small Business Luxury stock tickers

Cyber-Safe
Chryslers can be hacked over the Internet

✉️ 📱 🌐 🌐 ... Recommend 6.3k



By Jose Pagliery @Jose

Most Popular



cheaper than
bottles of water



The median
price here is
\$980,000

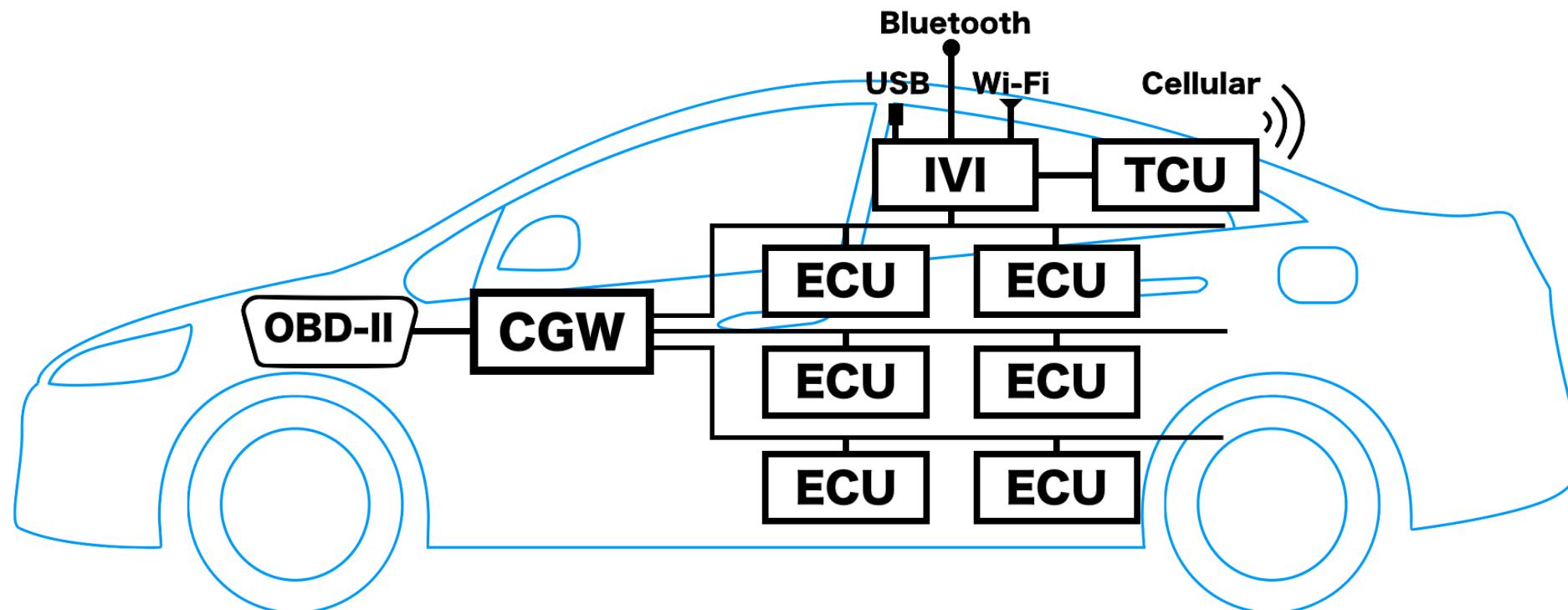


OPEC pump
oil in three y

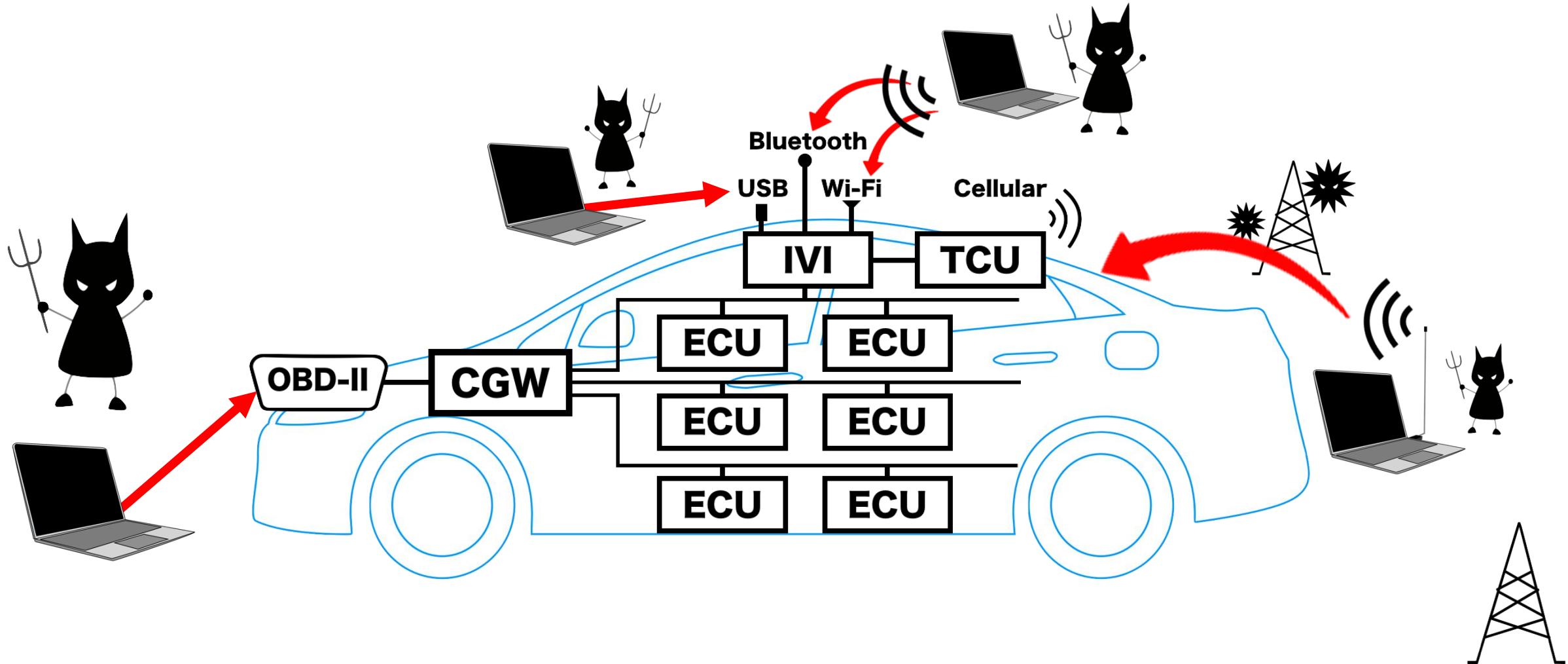
Problems in automotive industry

- Problems of cyber security technology for automobiles;
- Delay in development of cyber security technology in automotive industry.
- Lack of cyber security engineers in the automotive industry.

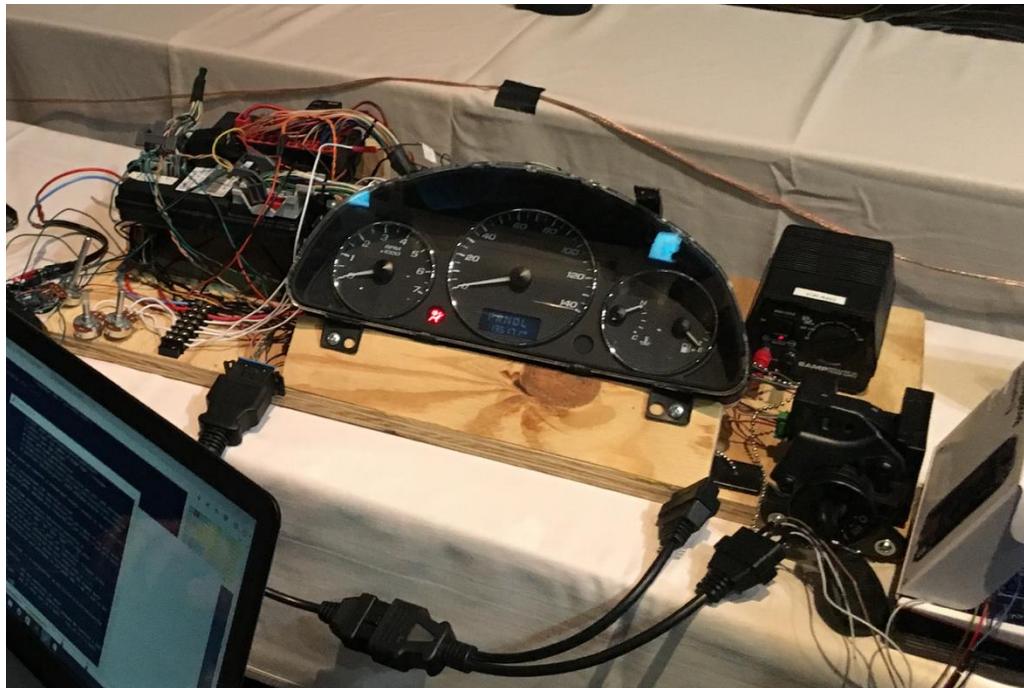
Typical architecture of a vehicle



Typical attack surfaces in recent vehicles



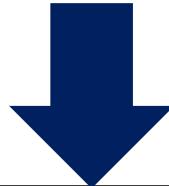
CAR HACKING VILLAGE in DefCon



Hacking event such as CTF is very fun! However, it is doubtful that it can be systematic way of learning vehicular security.

Motivation for developing platform

- There are no harmless real car for testers and no “generalized” one.
- We need to develop a platform not only for “Crack” but also “Hack”
 - Anyone can hack and study by “playground vehicle”
 - A newly proposed security technology can be evaluated its feasibility in common platform.



**Open, safe, and attractive platform for
vehicular cyber security is required**



Philosophy of PASTA



Open

Safe

Adaptable

Portable



□ **Open**

- It must be based on non-proprietary technologies.

□ **Adaptable**

- Users should be able to rewrite the firmware of ECUs, re-design the architecture and connect their own devices, for example.

□ **Safe**

- There should be no real actuators; it can avoid incidents.
- Such as wheels, brakes and window should be realized by simulator rather than the real things.

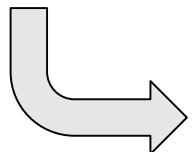
□ **Portable**

- Platform is preferred to be small and portable so that users can study, research, and hack it anywhere.

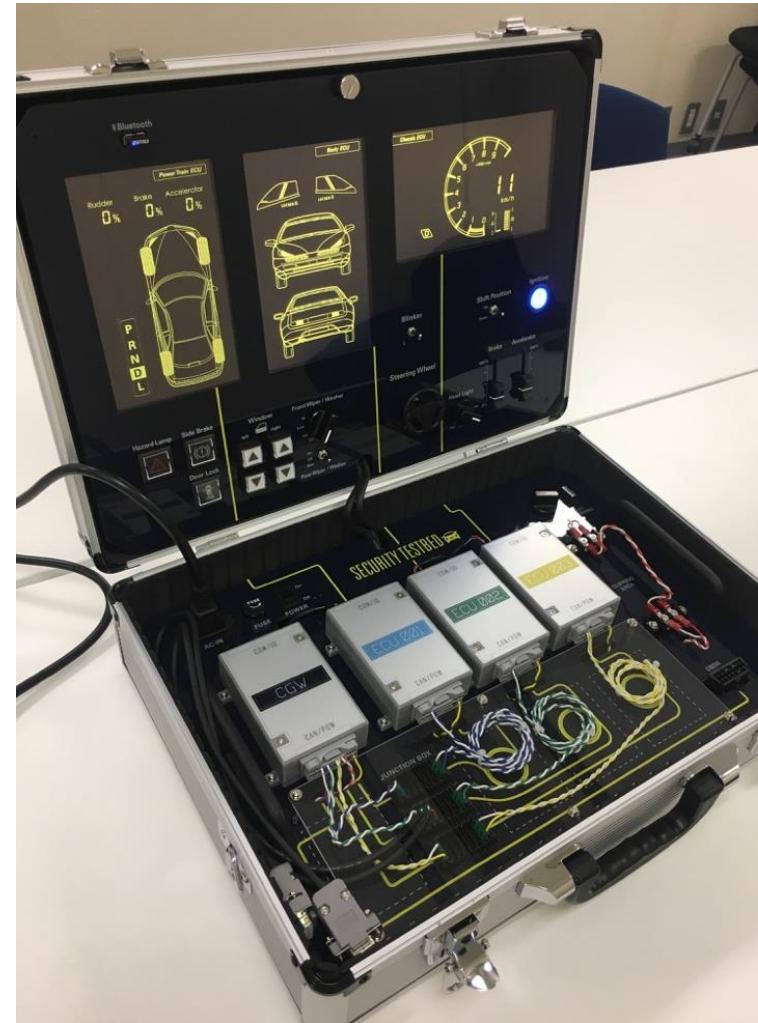
PASTA



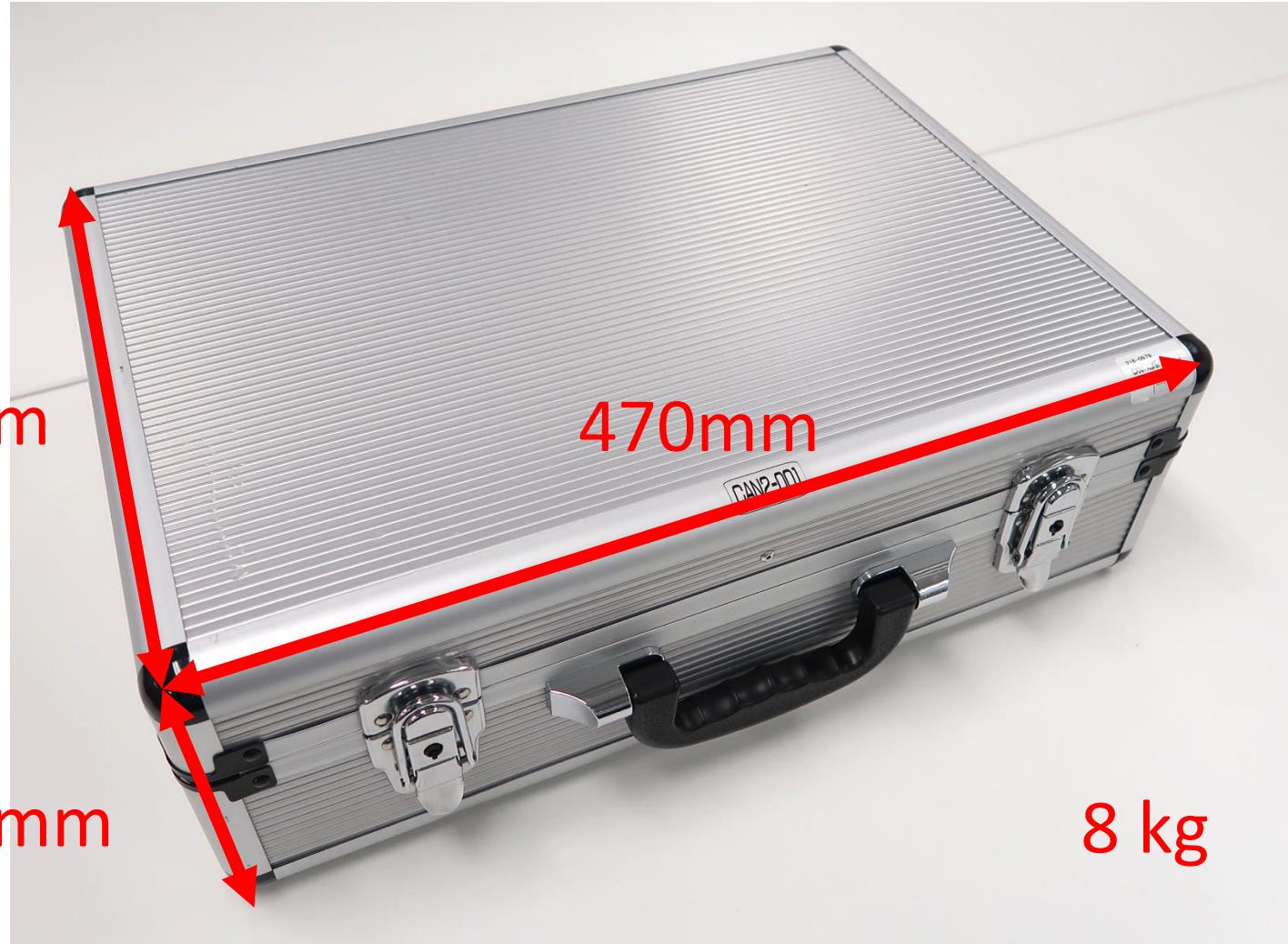
It seems an ordinary attaché case...



Once it opened,
PASTA appears.

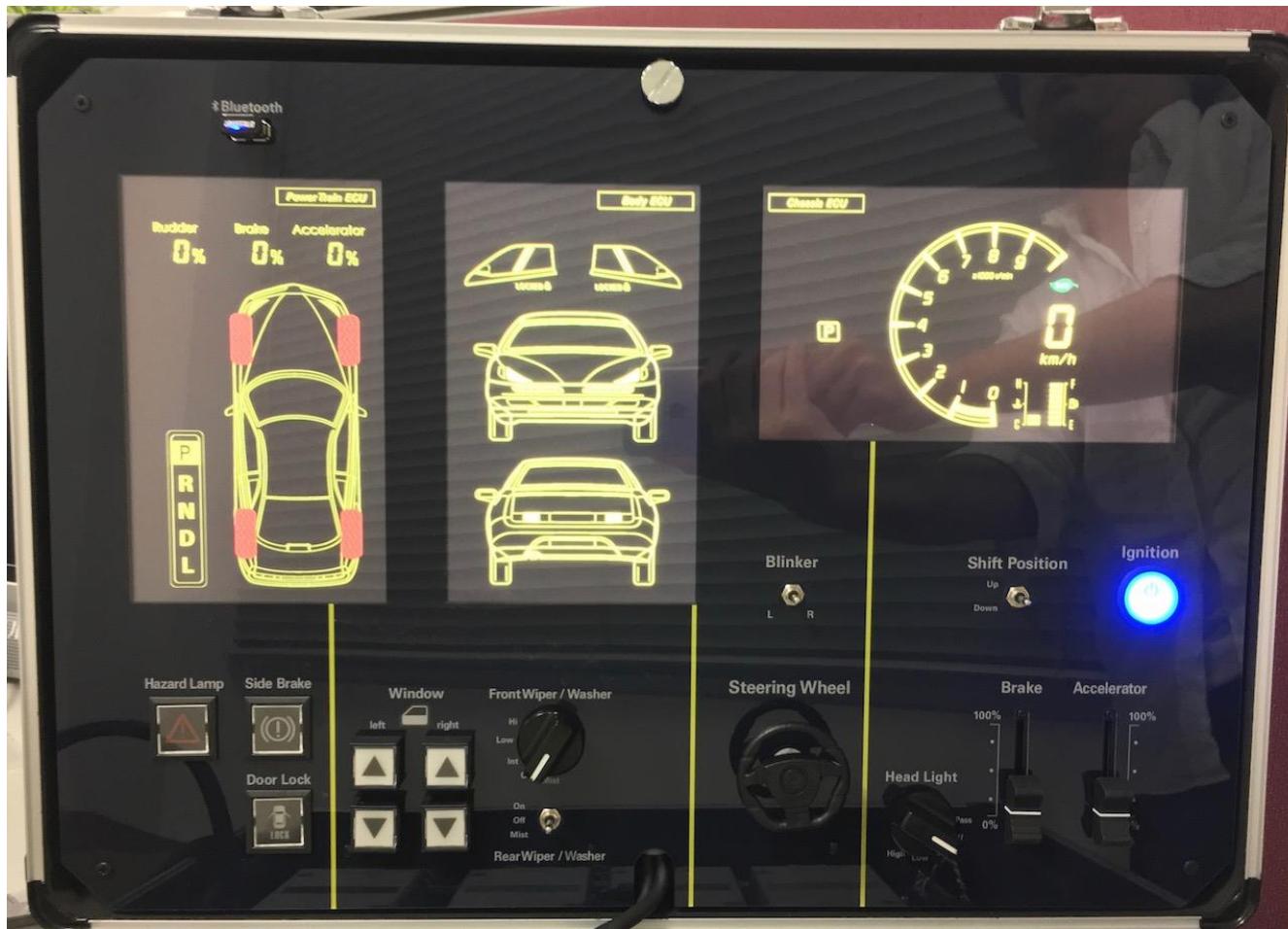


Portability of PASTA



Portable!

Upper side of PASTA



- There is a simple simulator in the attaché case, and it can be operated with the physical controller.
- The behavior by the operation can be confirmed from three LED panels.

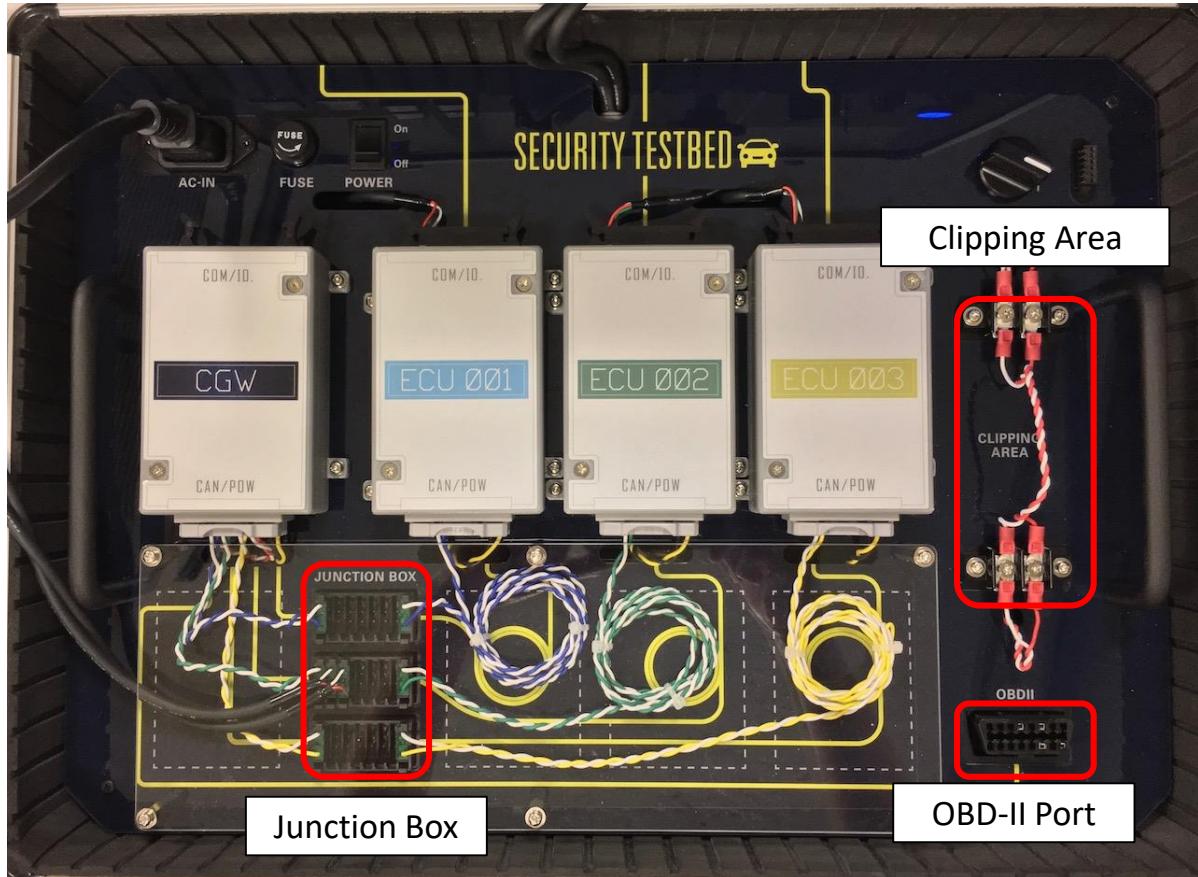
SAFE!

Bottom side of PASTA



- Frequently used attack surfaces are equipped.
 - Since if it is easy to simulate a CAN message injection, security evaluation is easy.
- You can modify the program of these ECUs in C language.

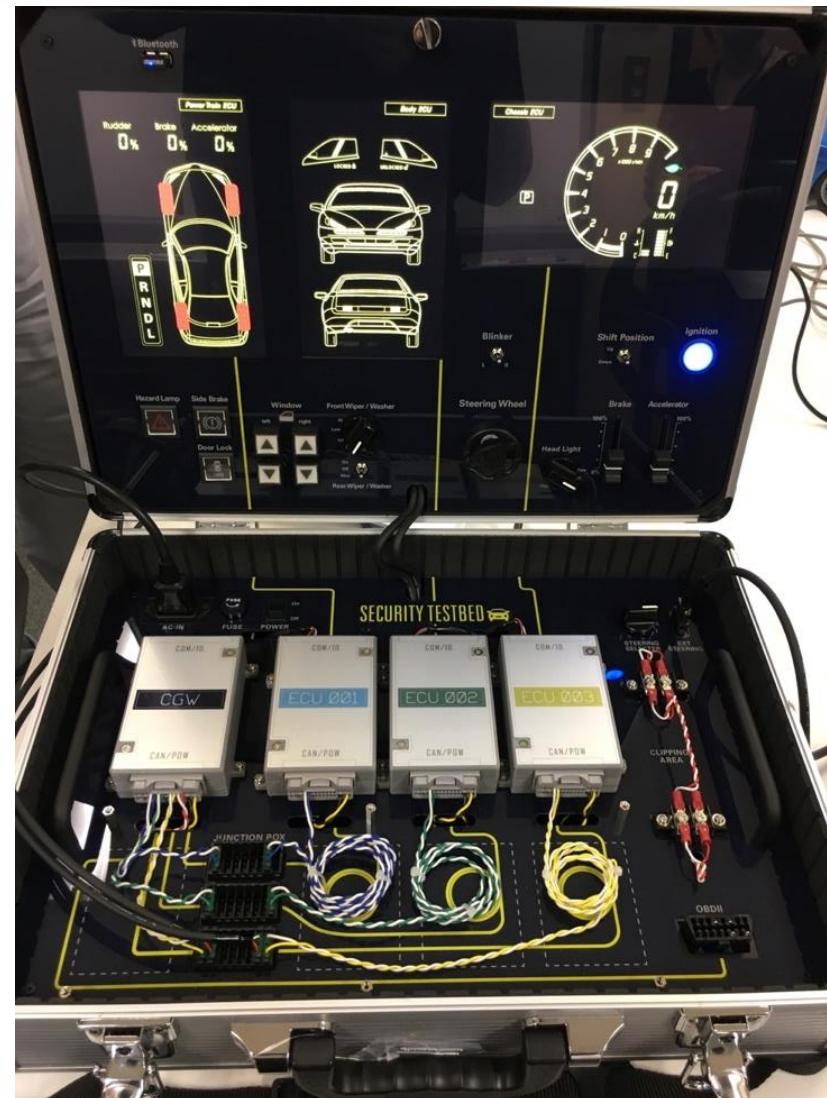
Attack surfaces in PASTA



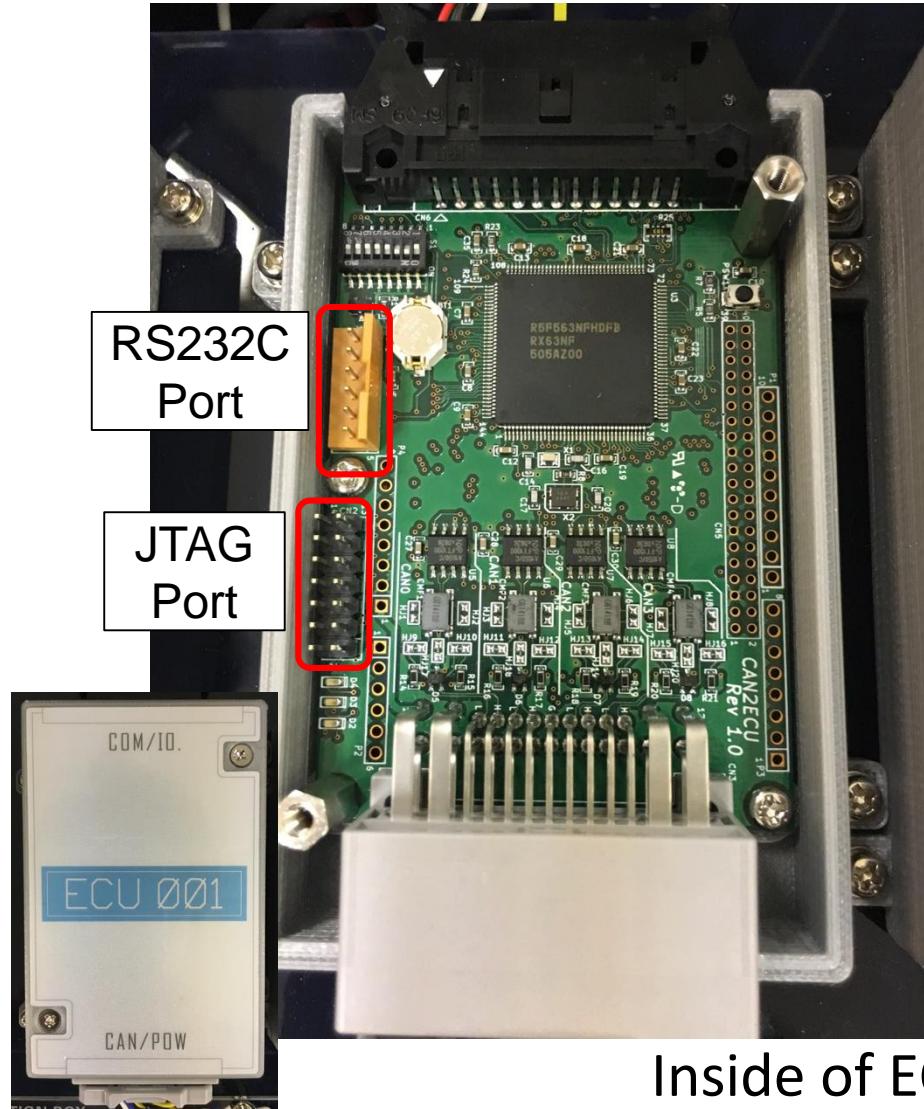
- Attack Surface are
 - OBD-II
 - Clipping Area
 - Junction Box

- Junction Box is implemented also for adaptability

Whole image of PASTA



Inside of the ECU



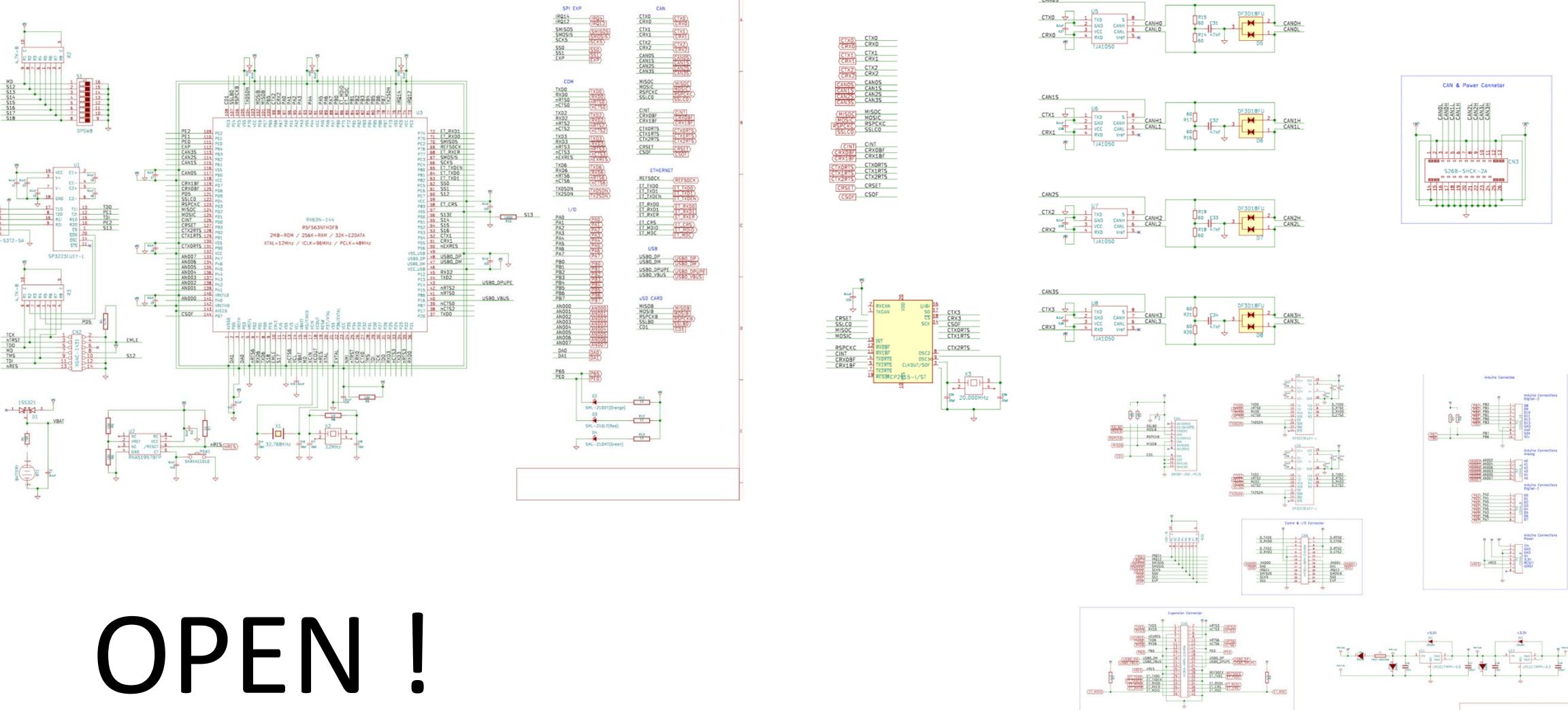
- Based on microcontroller(RX63N) by Renesas, we have designed and developed a ECU for PASTA from scratch.
- If you prepare for develop environment of Renesas microcontroller, you can apply your own program in C language.

Adaptable!



Design of the ECU

OPEN !



CAN IDs can be opened

New Spy Setup - Vehicle Spy 3 Professional												
File Setup Spy Networks Measurement Embedded Tools Scripting and Automation Run Tools Help												
Online... Platform: (None) Desktop 1												
<input type="checkbox"/> Messages Editor <input checked="" type="checkbox"/> Messages												<input type="button" value="Data"/>
Filter	Add	Details	Expand	Time Abs	Pause	Save	Erase	Find: ArbId/Header	Prev	Next	...	
Count	Time (abs/rel)	Tx	Er	Description	ArbId/Header	Len	DataBytes	Network	Node	ChangeCnt	Timestamp	M
1767	55.374 ms	HS CAN \$183		183		8	59 DA 08 C0 19 C7 12 4A	HS CAN		1766	2018/11/27 08:42:55:179330	.
1767	55.324 ms	HS CAN \$18D		18D		8	00 D9 82 F0 A3 A0 68 80	HS CAN		1766	2018/11/27 08:42:55:179758	.
1767	55.320 ms	HS CAN \$198		198		8	00 13 BA 27 65 74 00 B8	HS CAN		1766	2018/11/27 08:42:55:180176	.
1767	55.324 ms	HS CAN \$19A		19A		8	01 L6 1E BC F6 E1 4C 0C	HS CAN		1766	2018/11/27 08:42:55:180597	.
4425	20.302 ms	HS CAN \$1A		1A		8	00 00 69 40 97 D9 5F 30	HS CAN		4424	2018/11/27 08:42:55:211549	.
1766	59.810 ms	HS CAN \$1A7		1A7		8	00 DD 2A CEF8 DCC9 C1	HS CAN		1765	2018/11/27 08:42:55:181019	.
1766	59.314 ms	HS CAN \$1B1		1B1		8	00 49 2C 75 FB 3F DB 7A	HS CAN		1765	2018/11/27 08:42:55:181443	.
1766	40.256 ms	HS CAN \$1B8		1B8		8	00 B7 2C 1D EC 9E 55 FF	HS CAN		1765	2018/11/27 08:42:55:181865	.
1767	38.305 ms	HS CAN \$1B8		1B8		8	00 75 52 B3 C3 08 0D 4E	HS CAN		1766	2018/11/27 08:42:55:182281	.
1715	42.981 ms	HS CAN \$1C9		1C9		8	00 88 BD DE 67 EE 01 AD	HS CAN		1714	2018/11/27 08:42:55:182708	.
1767	42.973 ms	HS CAN \$1D3		1D3		8	00 53 F4 2A 1F AC 1C 43	HS CAN		1766	2018/11/27 08:42:55:183132	.
4425	19.824 ms	HS CAN \$24		24		8	00 00 71 AD 8F 76 38 0D	HS CAN		4424	2018/11/27 08:42:55:212930	.
883	100.028 ms	HS CAN \$25C		25C		8	00 00 FE 21 0D 3A 6E 0C	HS CAN		882	2018/11/27 08:42:55:171525	.
883	99.984 ms	HS CAN \$266		266		8	00 00 90 6D 72 FB 7E 65	HS CAN		882	2018/11/27 08:42:55:170952	.
906	99.907 ms	HS CAN \$271		271		8	00 00 CC 73 3D FF F3 DB	HS CAN		905	2018/11/27 08:42:55:176374	.
906	100.028 ms	HS CAN \$27B		27B		8	00 BE 8C 8C 7F F0 88 24	HS CAN		905	2018/11/27 08:42:55:172015	.
906	100.017 ms	HS CAN \$286		286		8	00 08 FC FC 1E 86 65 CE	HS CAN		905	2018/11/27 08:42:55:177445	.
906	100.022 ms	HS CAN \$290		290		8	03 5A 05 15 07 7D EA 84	HS CAN		905	2018/11/27 08:42:55:173492	.
906	100.065 ms	HS CAN \$29C		29C		8	00 71 D1 C1 45 DC 4C 63	HS CAN		905	2018/11/27 08:42:55:178453	.
906	100.020 ms	HS CAN \$2A6		2A6		8	00 01 B5 30 4D 75 7F 0F	HS CAN		905	2018/11/27 08:42:55:173966	.
906	99.706 ms	HS CAN \$2B1		2B1		8	00 5B E3 54 2B 5E 7D 54	HS CAN		905	2018/11/27 08:42:55:179098	.
905	100.020 ms	HS CAN \$2B8		2B8		8	00 01 05 65 FD 55 71 F9	HS CAN		904	2018/11/27 08:42:55:174477	.
4423	20.302 ms	HS CAN \$2F		2F		8	00 00 19 C8 E7 66 A1 F3	HS CAN		4422	2018/11/27 08:42:55:212011	.
4423	19.842 ms	HS CAN \$39		39		8	00 0A 41 E0 BF 58 72 5E	HS CAN		4422	2018/11/27 08:42:55:213398	.

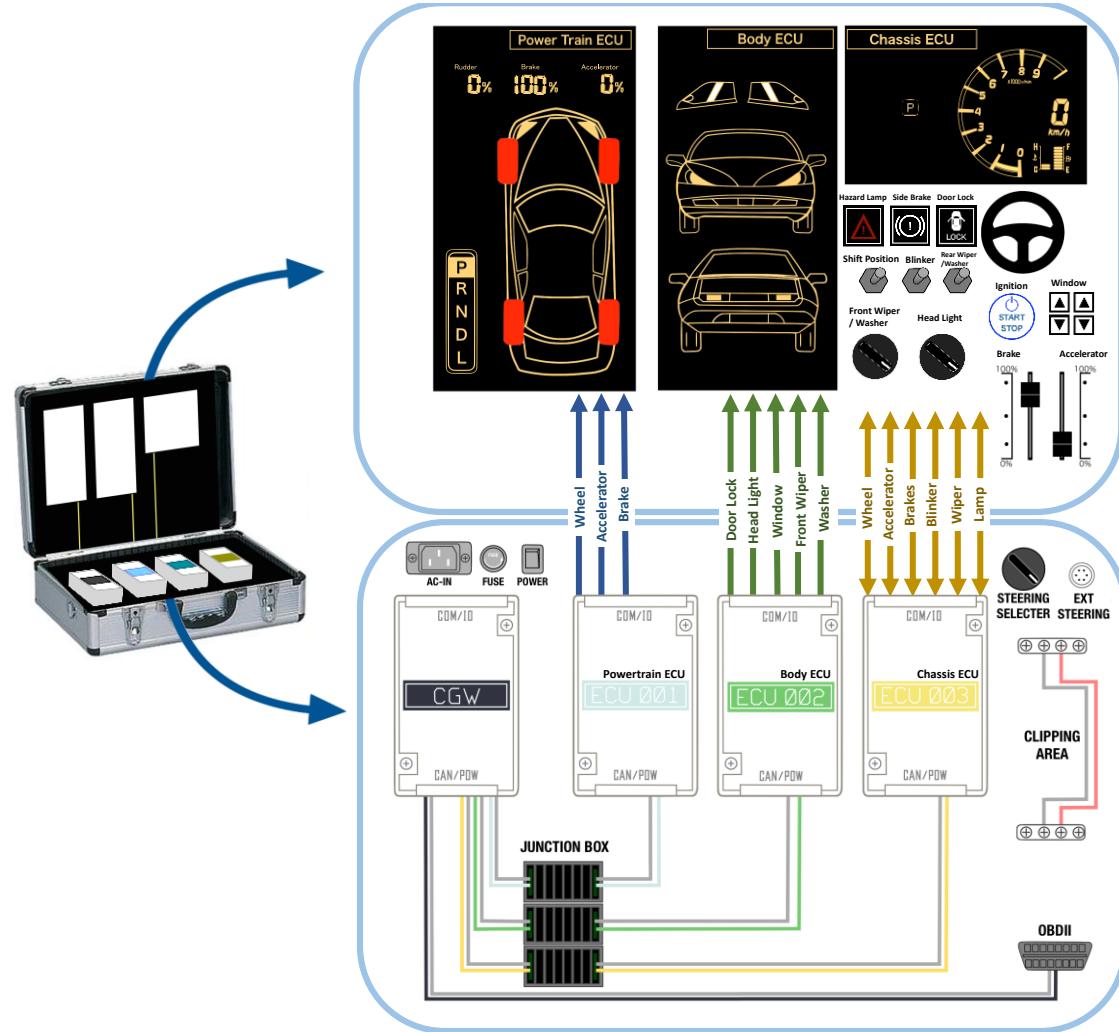
Details for "HS CAN \$183"

- 0x01A: Brake
- 0x02F: accelerator
- 0x1B1: headlight flashing
- 0x1B8: Ignition switch
- ...

OPEN !

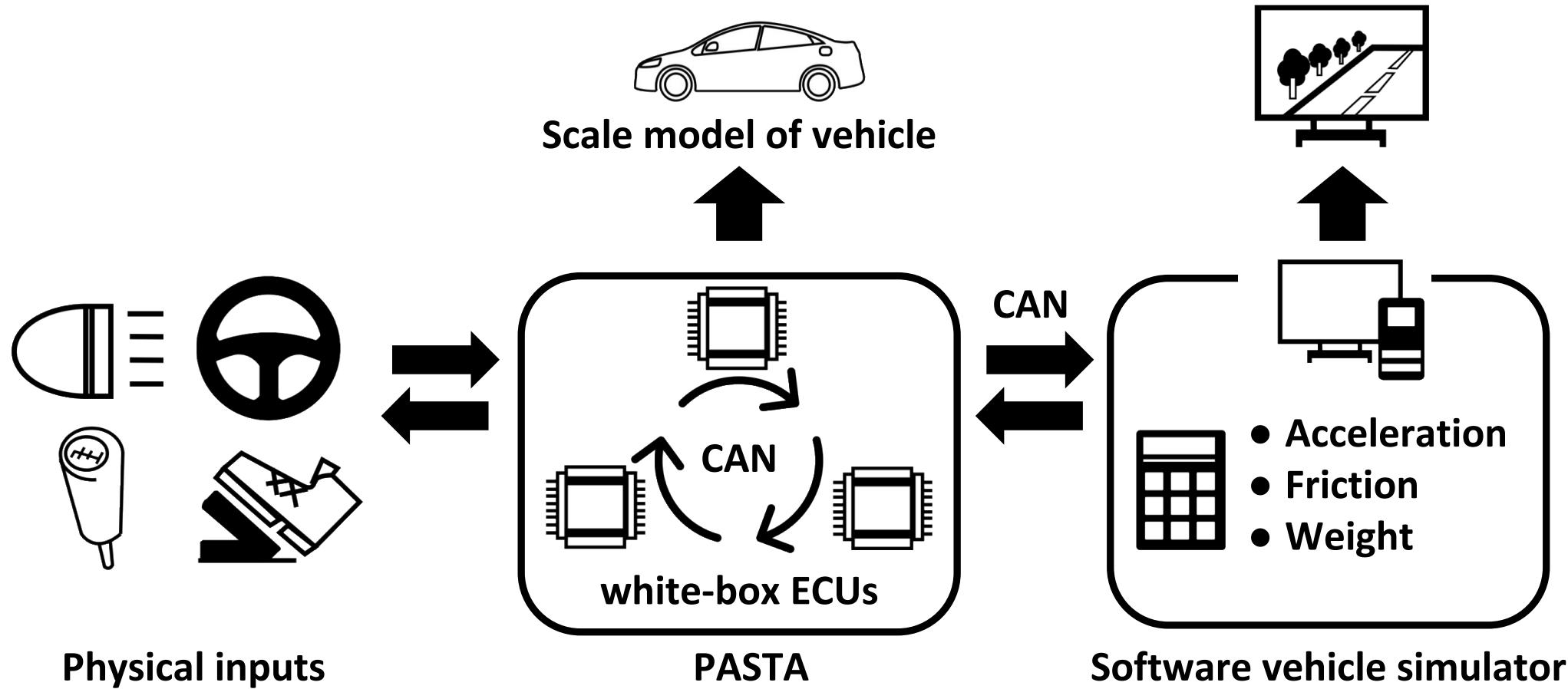
- CAN ID assignment table of PASTA is designed only for PASTA; Different from real vehicles.
- Users can create their own table and reprogram ECUs.

Information flow in PASTA



- In the attaché case, controller and vehicle simulator and ECUs are integrated.
- ECUs receive operations from controller, and ECUs send CAN messages. Thus ECUs share the information from operations and status of the vehicle.
- ECUs control actuators of simulator according to received CAN messages.

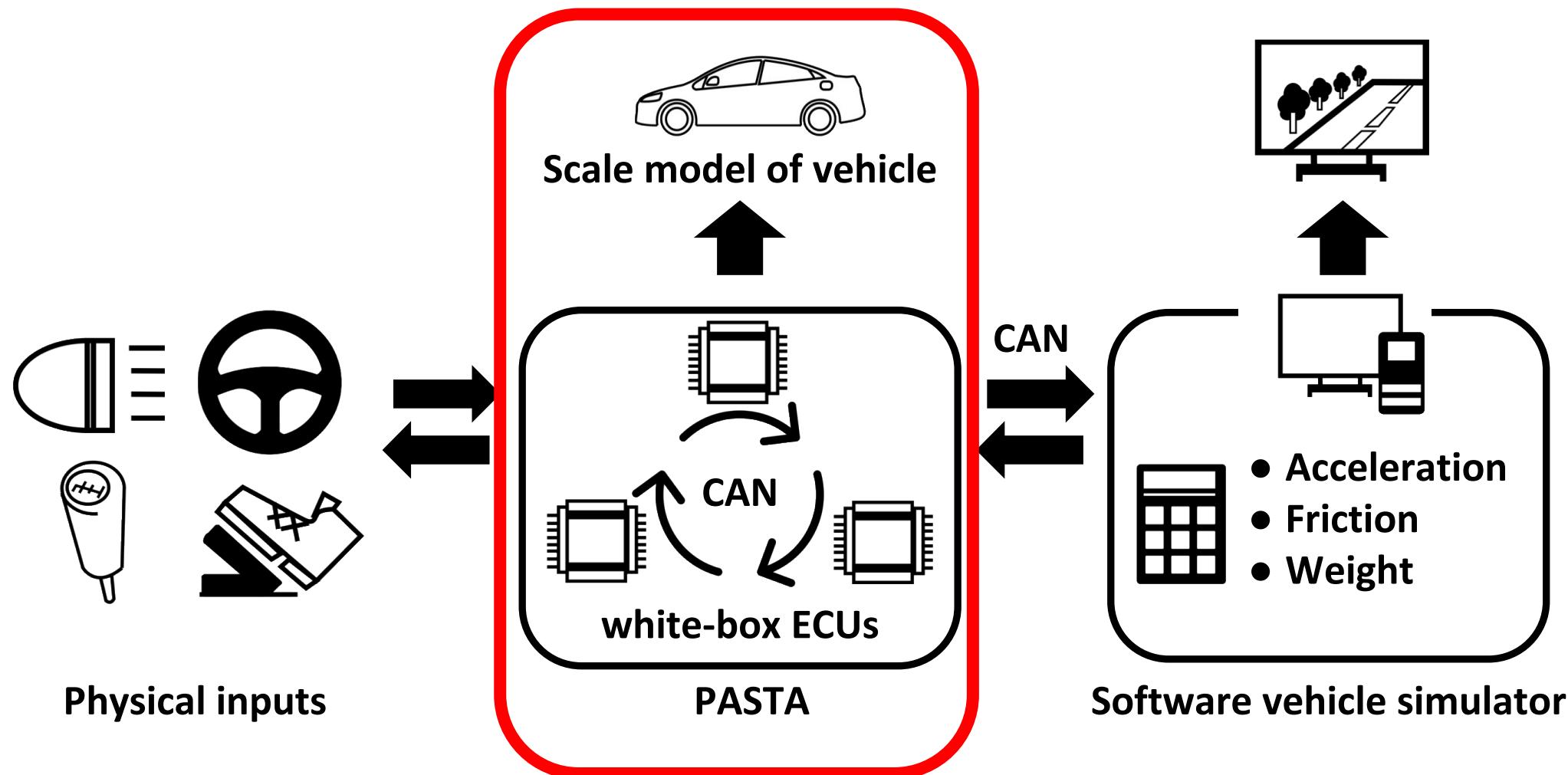
PASTA is adaptable





Demo

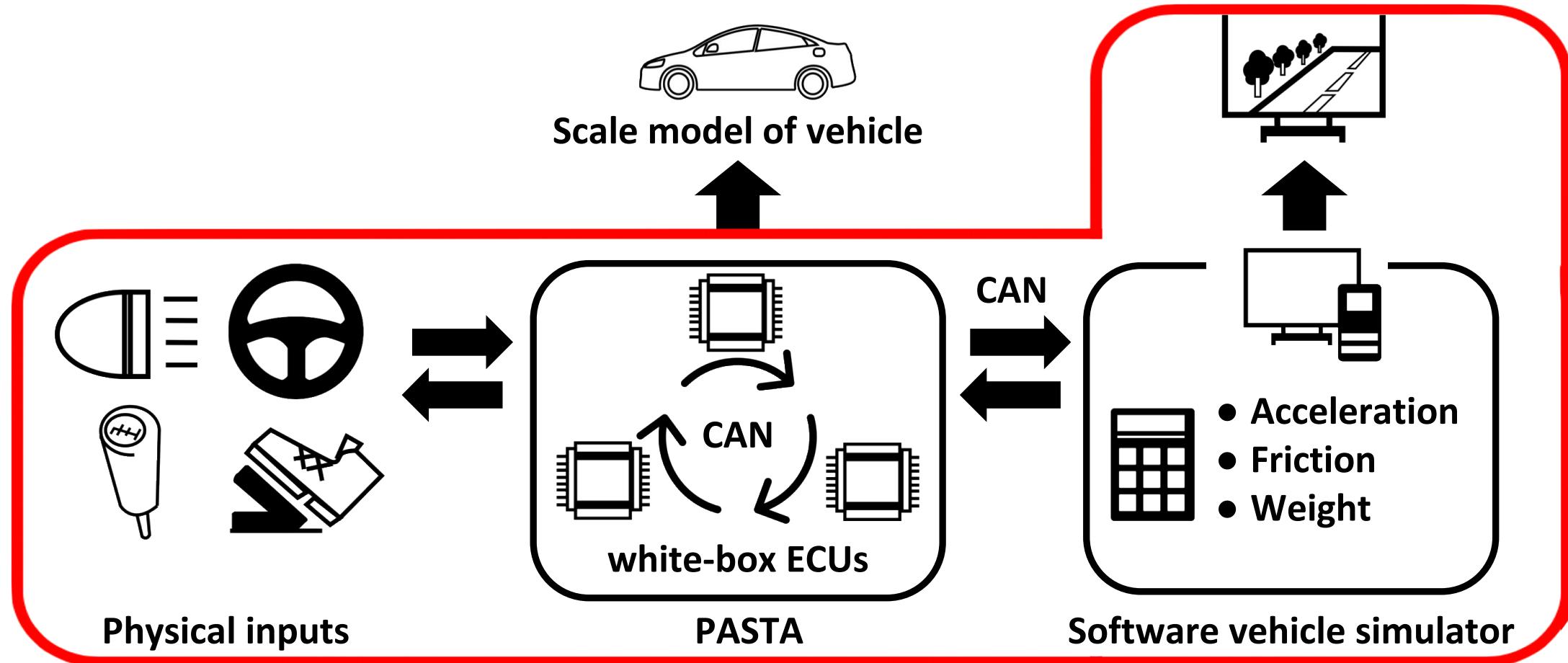
Demo of adaptability 1



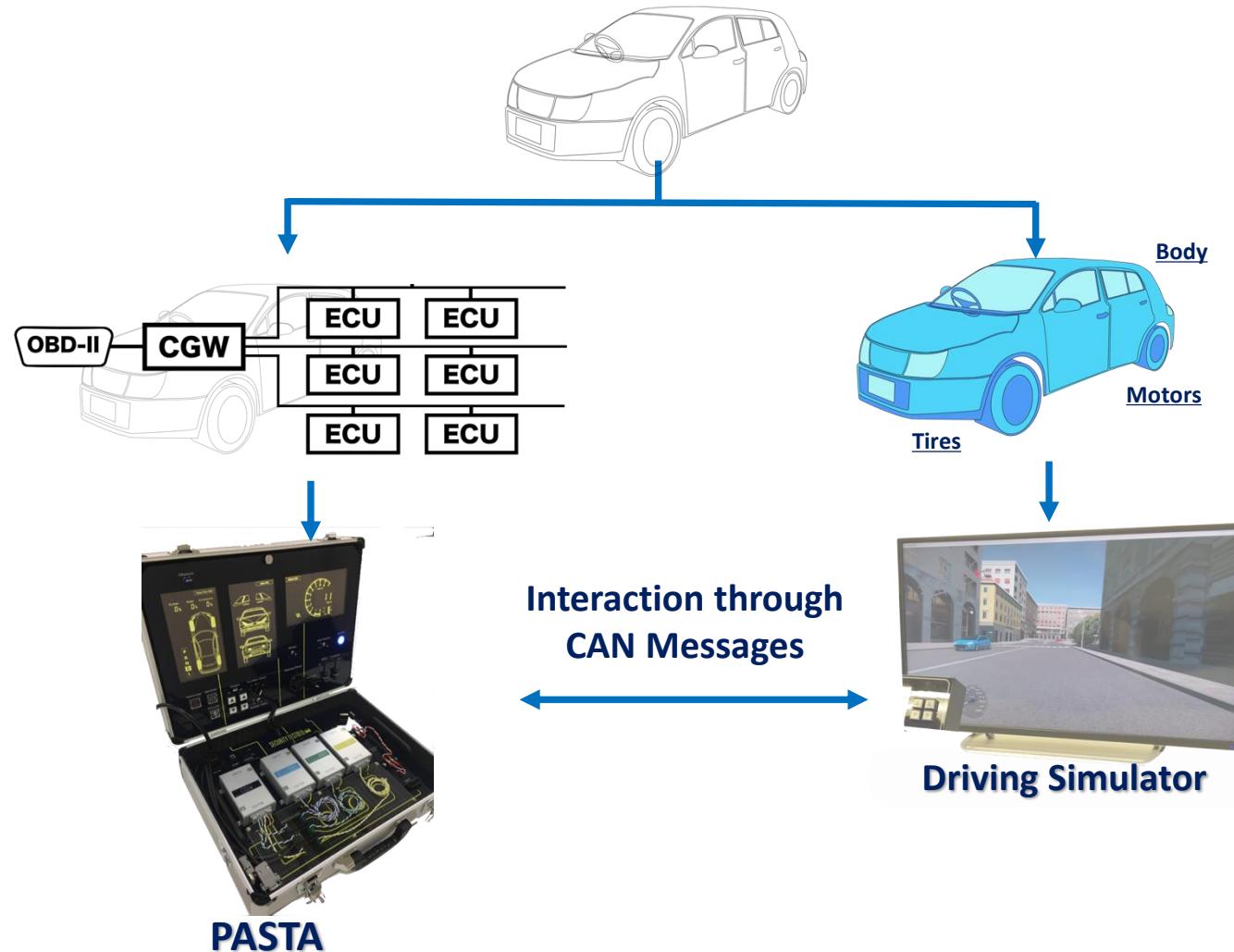
PASTSA with miniature vehicle



Demo of adaptability 2



Integration of drive simulator with PASTA



Real behavior by connection with a drive simulator



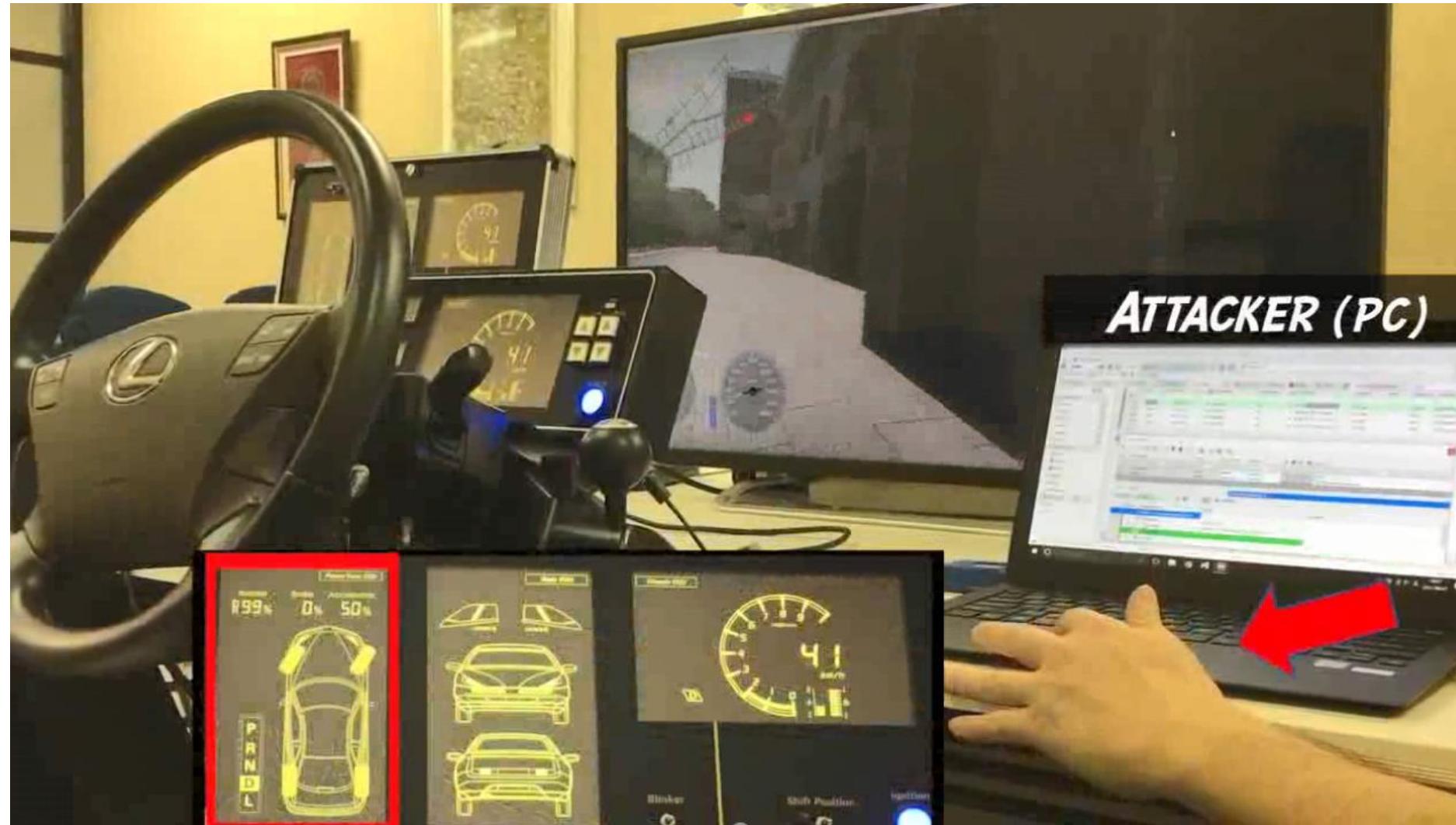
Demo: Incident...

Demo and CAUTION!!!

- Typical attack demonstration via OBD-II port: an attacker injects malicious CAN packets via OBD-II port.
- The effect of attack is noticeable, because, we have not implemented enough safety function in software of ECUs in PASTA.
- However, real vehicles have security and safety functions, it is difficult to reproduce the result of following demo.

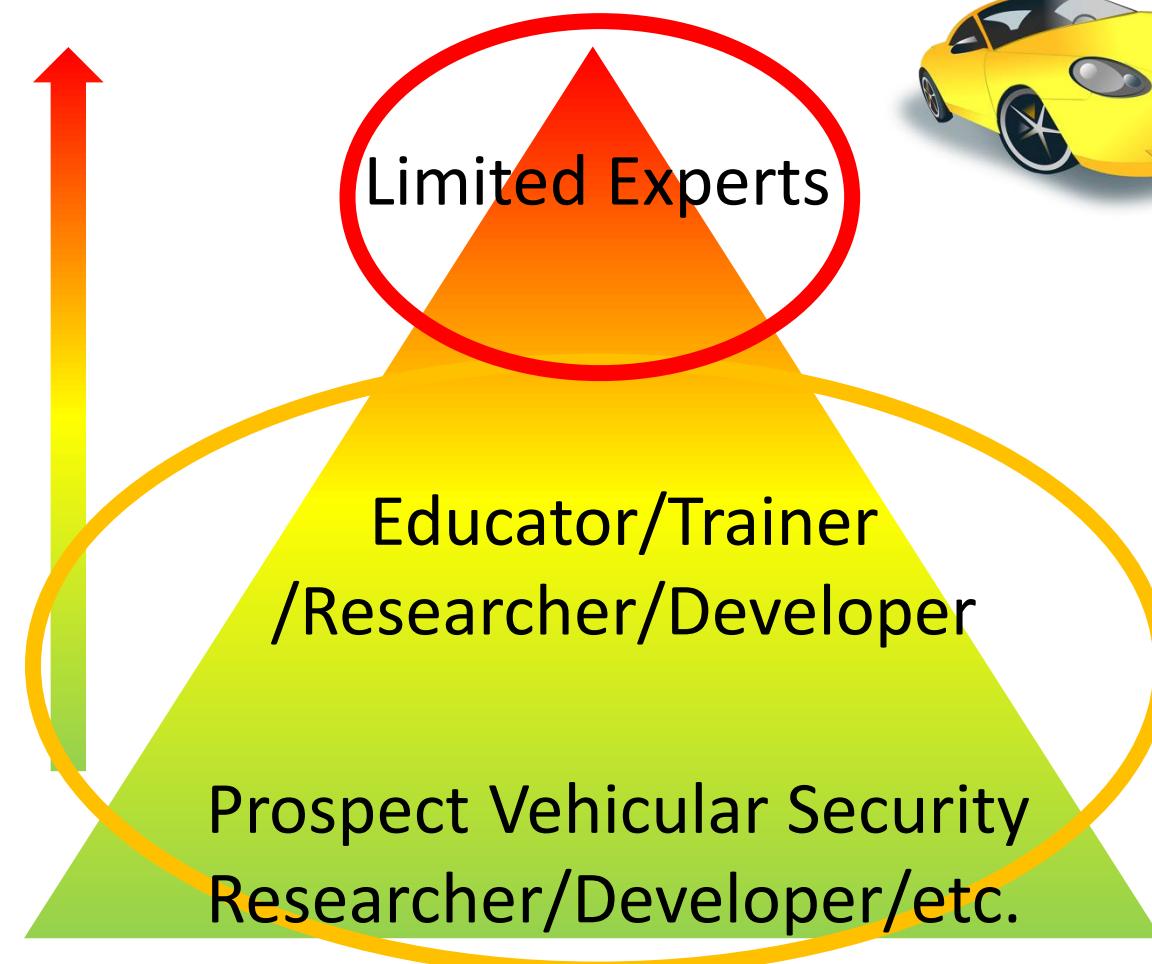


Demo: Incident...



Use Cases

Use Cases



Real Vehicle



WIRED
ANDY GREENBERG SECURITY 07.24.15 12:30 PM
AFTER JEEP HACK, CHRYSLER RECALLS 1.4M VEHICLES FOR BUG FIX



DANGER!



NOT for Everyone ...

PASTA



You can start if you have:
- Some space on desk
- An outlet

Open

Safe

Adaptable

Portable

Use Cases: Education/Training

TARGET



OBJECTIVE

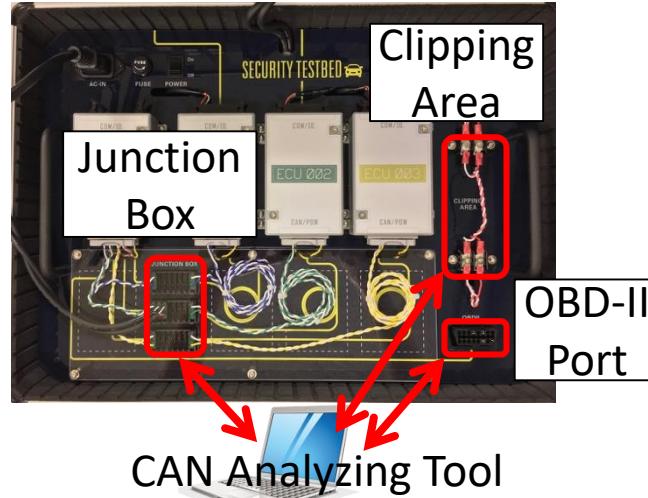
- Educate or learn vehicle security

REQUIREMENTS

- Open (e.g. known answers)
- Flexibility (e.g. intentionally embed vulnerabilities)
- Typical architecture
- Typical attack surfaces

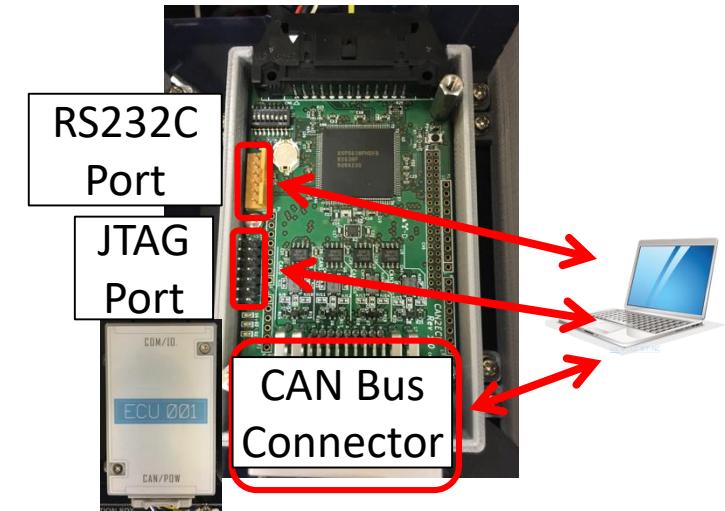
EXAMPLES

Hacking CAN bus messages



- Wire-tap, analyze, and inject CAN messages

Hacking ECU/CGW



- Read, analyze, and reprogram firmware

NOTES

- More to come:
 - LIN, CAN FD, IVI, Wireless I/F, etc.
 - Joint work with YNU

Use Cases: Research

TARGET



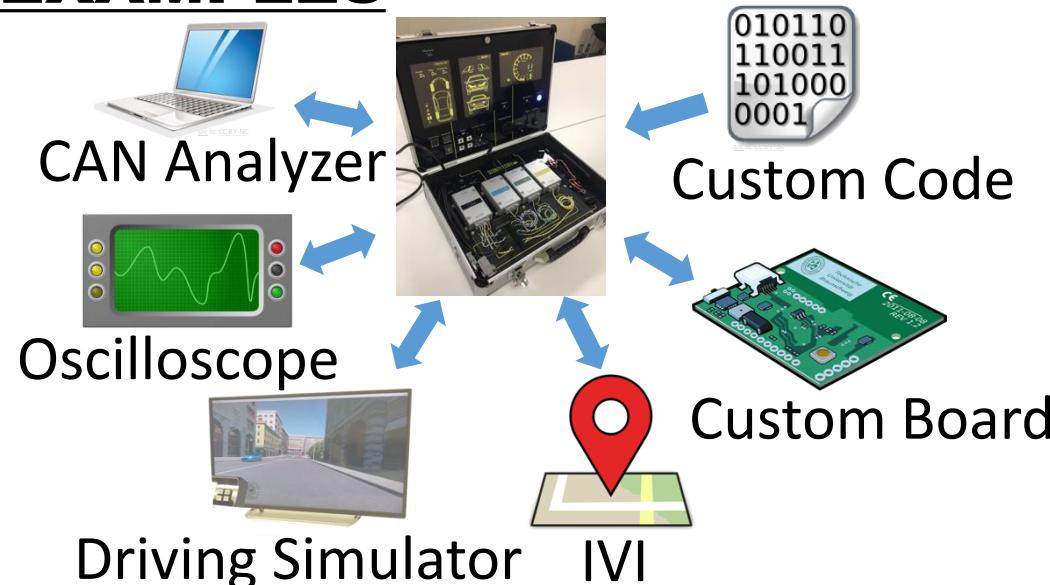
OBJECTIVE

- Open research
from various perspective

REQUIREMENTS

- Open
 - Publish the results
 - Reproduce environments and results

EXAMPLES



RESULTS

- “Real-time Electrical Data Forgery in In-vehicle Controller Area Network Bus”
@ escar Asia 2018
by K. Shirai, T. Kiyokawa, J. Sakamoto, T. Toyama, T. Matsumoto
<https://tech.nikkeibp.co.jp/cp/2018/escar2018e/>

Submitted lecture 3
Real-Time Electrical Data Forgery in In-vehicle Controller Area Network Bus

A Controller Area Network (CAN) is a bus standard for embedded devices that is widely used in-vehicle networks. CANs are equipped with a bit monitoring mechanism that determines if intended data are transmitted. Therefore, CANs are difficult to attack, such as rewriting data in real-time. However, attacks on analog signals carrying digital data (i.e., attacks that manipulate the potential difference on CAN Bus) are possible. We show the theory of Real-Time Electrical Data Forgery in CAN Bus where the transmitted data can be manipulated by some attacker and the resultant data is received as the attacker intended while the sending side recognizes that the transmitted data arrives at the receiving side as it is. In addition, we demonstrate that this attack is possible on an in-vehicle CAN bus. Furthermore, we discuss replacement type electrical data falsification, which is a more advanced attack with high attack success probability, and highlight the need for improved security measures.

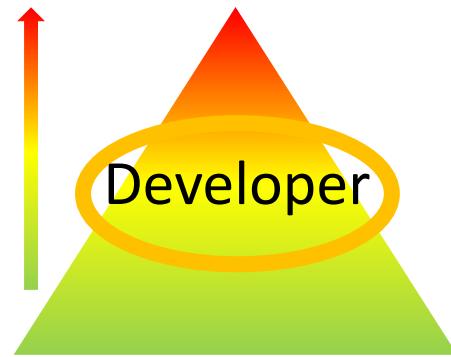


Yokohama National University
Graduate School of Environment and Information Sciences

Mr. Kazuki Shirai

Use Cases: Development

TARGET



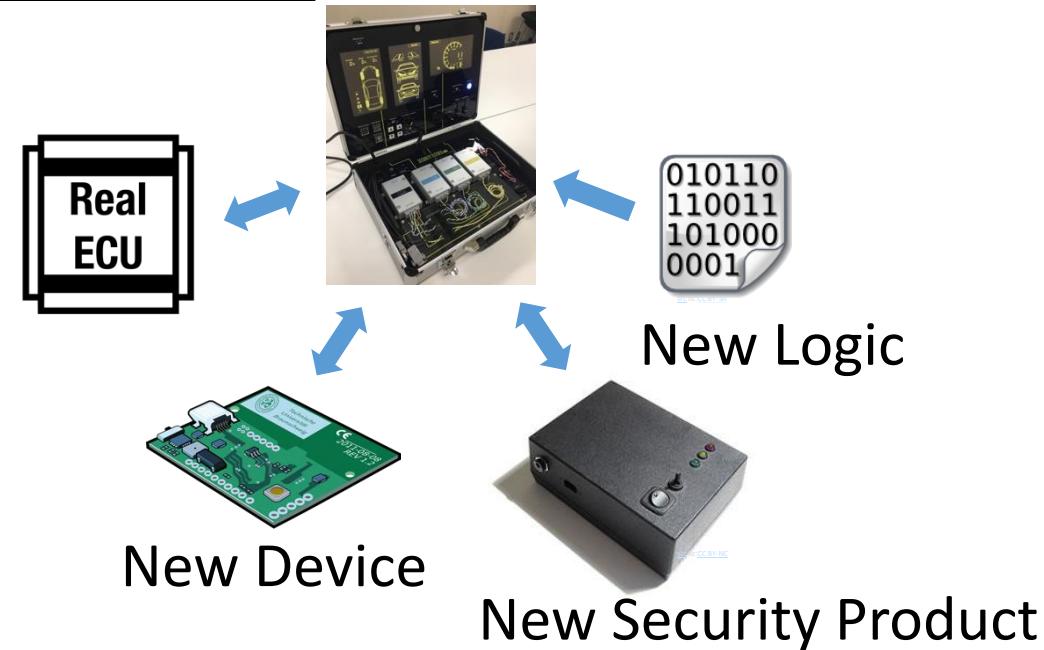
OBJECTIVE

- Prototyping and PoC
of new technologies and products

REQUIREMENTS

- Simulates real vehicle
- Verify the effect
- Support various devices
- Adaptability

EXAMPLES



NOTES

- Require real vehicle in final process
- PASTA can be used for evaluation or validation
of technologies and products

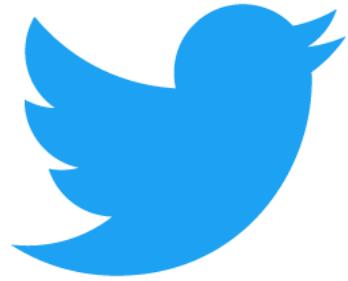
Roadmap

- For more advanced and realistic architecture:
 - Support more protocols
 - LIN, CAN FD, Ethernet, etc.
 - Support wireless interfaces
 - Wi-Fi, Bluetooth, Cellular
 - IVI
 - More domains
 - In-Vehicle Network of vehicles currently available are more complicated and have more domains.
 - Support AUTOSAR system
 - The ECUs in PASTA do not support any OS for vehicles and AUTOSAR system.
- OPEN specifications on GitHub

Take away

- In spite of vehicular security importance, any common platform for research has not been developed.
- PASTA is open, safe, adaptable and portable!
 - Apparently portable!
 - The design of PASTA is open; anyone can program and change the ECUs behavior.
 - PASTA is harmless for students, researchers, hackers, and so on because actuators are simulated in software.
- PASTA can be a common platform for...
 - Automotive cyber security research and development.
 - Educational tools.
 - etc...

For more information



@pasta_auto

GitHub <https://github.com/pasta-auto>

mail pasta_auto@jp.toyota-itc.com