

# Deep Vector Autoregression for Macroeconomic Data

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# Motivation

*Can we leverage the power of deep learning in VAR models?*

- ▶ We propose **Deep VAR**: a novel approach towards VAR that leverages the power of deep learning in order to model non-linear relationships.
- ▶ By modelling each equation of the VAR system as a deep neural network, our proposed extension outperforms modern benchmarks in terms of in-sample fit, out-of-sample fit and point forecasting accuracy.
- ▶ Performance is particularly striking during period economic uncertainty and recession.
- ▶ By staying methodologically as close as possible to the original benchmark, we hope that our approach is more likely to find acceptance in the economics domain.

## Key contributions

- ▶ Simple methodology close in spirit to conventional benchmark.
- ▶ Significant improvement in predictive performance.
- ▶ Open source R package to facilitate reproducibility.

### **Work-in-progress:**

- ▶ Master's thesis was selected for publication by Universitat Pompeu Fabra.
- ▶ Feedback rounds with Eddie Gerba (Bank of England, LSE) and Chiara Osbat (ECB)
- ▶ Presented an updated version of the paper at NeurIPS 2021 MLECON workshop in December.

## Previous literature

- ▶ Non-linear dependencies are likely to form part of the data generating process of variables commonly used to model the monetary transmission mechanism (Brock et al. 1991).
- ▶ A range of machine learning models has previously been used in the context of time series forecasting Kihoro, Otieno, and Wafula (2004). Deep learning has been shown to be particularly successful at capturing non-linearities G. P. Zhang (2003).
- ▶ Joseph et al. (2021) review both machine learning and deep learning methods for forecasting inflation and find that neural networks in particular are useful for forecasting especially at a longer horizon.

## Methodology

- Relax the assumption of linearity and instead model the process as system of potentially highly non-linear equations:

$$y_{it} = f_i(\mathbf{y}_{t-1:t-p}; \theta) + v_{it} \quad , \quad \forall i = 1, \dots, K \quad (1)$$

- Each single variable in model is modelled as a recurrent neural network:

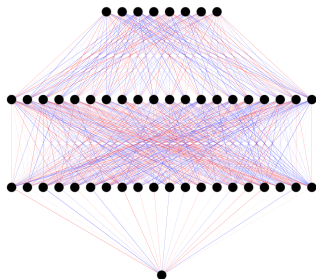


Figure 1: Neural Network Architecture.

# Data

- ▶ To evaluate our proposed methodology empirically we use the FRED-MD data base to collect a sample of monthly US data on:
  - ▶ output (IP)
  - ▶ unemployment (UR)
  - ▶ inflation (CPI)
  - ▶ interest rates (FFR)
- ▶ Our sample spans the period from January 1959 through March 2021.

# Model fit

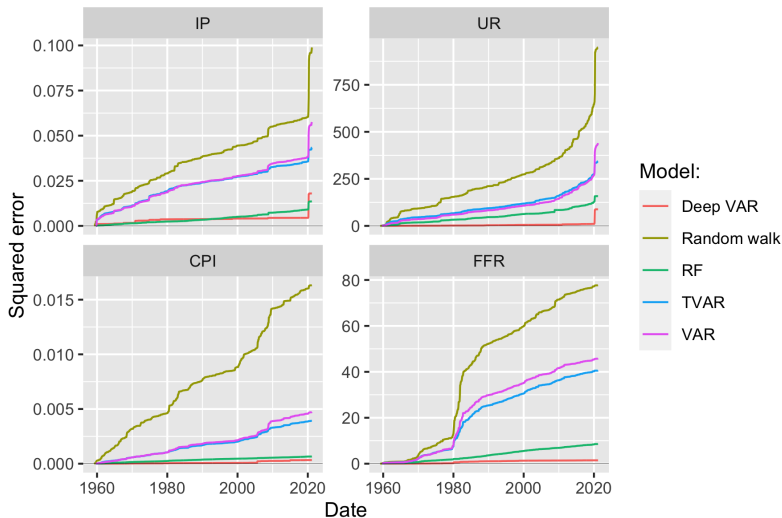


Figure 2: Comparison of cumulative loss over the entire sample period for Deep VAR and benchmarks.

# Forecasting accuracy

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## Concluding remarks

- ▶ Simple framework that relies on the premise of minimal intervention in the conventional and trusted framework.
- ▶ Deep learning appears to do a good job at capturing non-linear dependencies.

### **But...**

- ▶ Added complexity is (often) coupled with lack of interpretability:
  - ▶ No analytical expressions for impulse response functions and variance decompositions
  - ▶ Verstyuk (2020) manages to recover IRFs numerically; should be readily applicable to our Deep VAR framework.
- ▶ Uncertainty estimation can be done through Bayesian methods: deep ensemble, MC dropout, Variational Inference:
  - ▶ All of the above entail an added layer (layers really!) of computational complexity.
  - ▶ Laplace Redux for effortless Bayesian Deep Learning (Daxberger et al. 2021) holds promise, but not yet implemented.

Your questions and comments

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Hiddens

# Long Short-Term Memory

- ▶ The most common choice of neural networks architectures for modelling persistent time series is the LSTM:

*“The LSTM [has] the ability to remove or add information to the cell state, carefully regulated by structures called gates. Gates are a way to optionally let information through.” — Olah (2015)*

$$\begin{aligned}\mathbf{f}_t &= \sigma(\mathbf{b}_f + \mathbf{W}_f \mathbf{h}_{t-1} + \mathbf{U}_f \mathbf{h}_{-1}) \\ \mathbf{i}_t &= \sigma(\mathbf{b}_i + \mathbf{W}_i \mathbf{h}_{t-1} + \mathbf{U}_i \mathbf{h}_{-1}) \\ \mathbf{o}_t &= \sigma(\mathbf{b}_o + \mathbf{W}_o \mathbf{h}_{t-1} + \mathbf{U}_o \mathbf{h}_{-1}) \\ \mathbf{C}_t &= \mathbf{f}_t \odot \mathbf{C}_{t-1} + \mathbf{i}_t \odot \tanh(\mathbf{b}_C + \mathbf{W}_C \mathbf{h}_{t-1} + \mathbf{U}_C \mathbf{h}_{-1}) \\ \mathbf{h}_t &= \mathbf{o}_t \odot \tanh(\mathbf{C}_t) \\ \hat{y}_{it} &= c + \mathbf{v}^T \mathbf{h}_t\end{aligned}\tag{2}$$