

CPSC 340: Machine Learning and Data Mining

Principal Component Analysis

Fall 2021

Last Time: MAP Estimation

- MAP estimation maximizes posterior:

$$p(w | X, y) \propto p(y | X, w) p(w)$$

"posterior" "likelihood" "prior"

- Likelihood measures probability of labels 'y' given parameters 'w'.
- Prior measures probability of parameters 'w' before we see data.
- For IID training data and independent priors, equivalent to using:

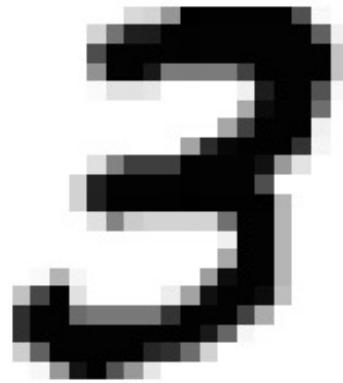
$$f(w) = -\sum_{i=1}^n \log(p(y_i | x_i, w)) - \sum_{j=1}^d \log(p(w_j))$$

- So log-likelihood is an error function, and log-prior is a regularizer.
 - Squared error comes from Gaussian likelihood.
 - L2-regularization comes from Gaussian prior.

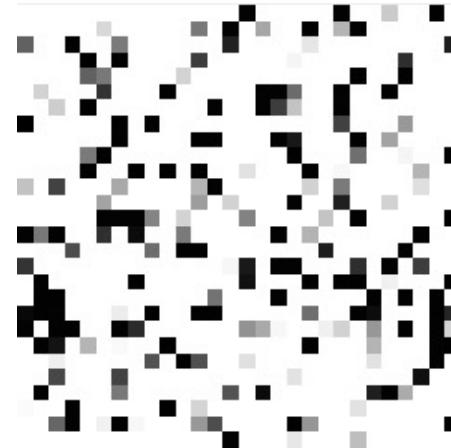
Motivation: Human vs. Machine Perception

- Huge difference between what we see and what computer sees:

What we see:



What the computer “sees”:



- But maybe images shouldn't be written as combinations of pixels.
 - Can we learn a better representation?
 - In other words, can we learn good features?

Motivation: Pixels vs. Parts

- Can view 28x28 image as **weighted sum** of “single pixel on” images:

$$\begin{matrix} 3 \end{matrix} = 1 \begin{matrix} \cdot \\ \end{matrix} + 0 \begin{matrix} & \cdot \\ & \end{matrix} + 1 \begin{matrix} & \\ \cdot \end{matrix} + 0.6 \begin{matrix} & \\ \cdot \end{matrix} + 0 \begin{matrix} \cdot \\ \end{matrix} + \dots$$

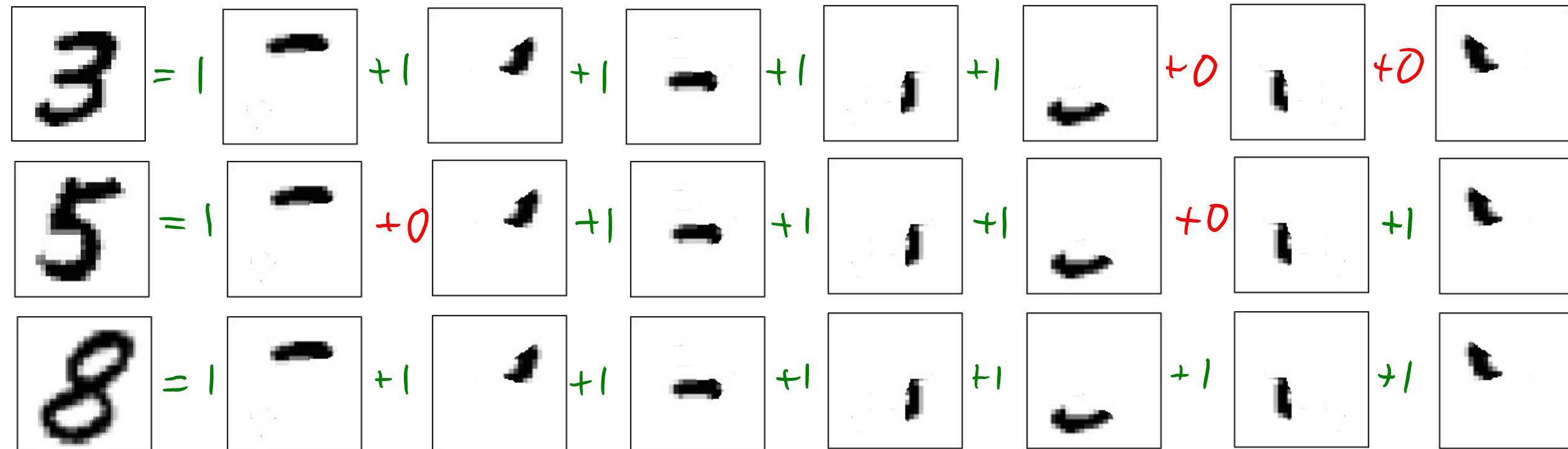
- We have one image/feature for each pixel.
- The **weights** specify “how much of this pixel is in the image”.
 - A weight of zero means that pixel is white, a weight of 1 means it’s black.
- This is **non-intuitive**, isn’t a “3” made of **small number of “parts”**?

$$\begin{matrix} 3 \end{matrix} = 1 \begin{matrix} \text{---} \\ \end{matrix} + 1 \begin{matrix} \text{---} \\ 1 \end{matrix} + 1 \begin{matrix} \text{---} \\ \text{---} \end{matrix} + 1 \begin{matrix} & \\ \text{---} \end{matrix} + 1 \begin{matrix} & \\ 1 \end{matrix} + 1 \begin{matrix} \text{---} \\ \text{---} \end{matrix}$$

- Now the weights are “**how much of this part is in the image**”.

Motivation: Pixels vs. Parts

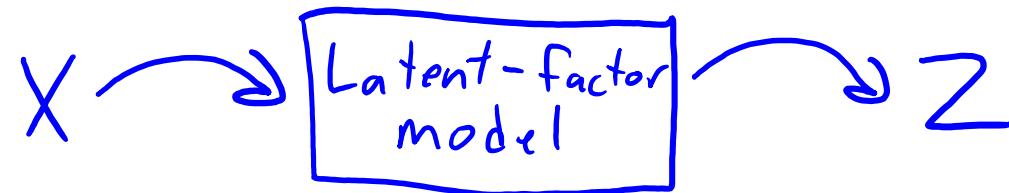
- We could represent other digits as different combinations of “parts”:



- Consider replacing images x_i by the weights z_i of the different parts:
 - The 784-dimensional x_i for the “5” image is replaced by 7 numbers: $z_i = [1 \ 0 \ 1 \ 1 \ 1 \ 0 \ 1]$.
 - Features like this could make learning much easier.

Part 4: Latent-Factor Models

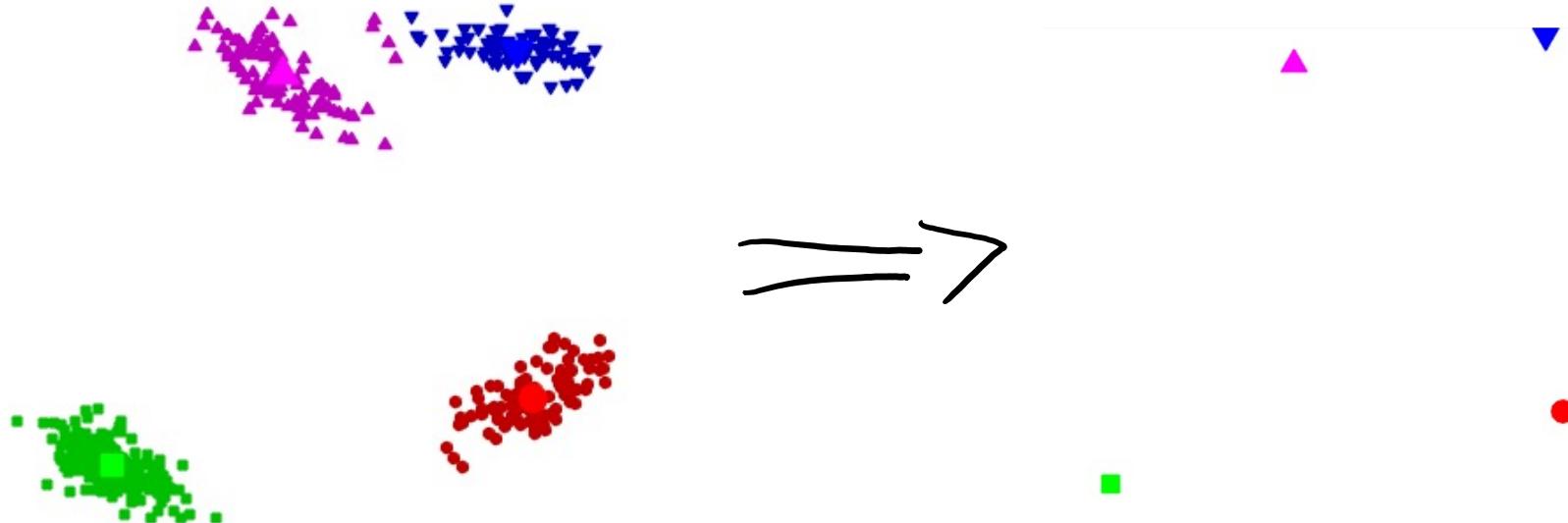
- The “part weights” are a change of basis from x_i to some z_i .
 - But in high dimensions, it can be hard to find a good basis.
- Part 4 is about learning the basis from the data.



- Why?
 - Supervised learning: we could use “part weights” as our features.
 - Outlier detection: it might be an outlier if isn’t a combination of usual parts.
 - Dimension reduction: compress data into limited number of “part weights”.
 - Visualization: if we have only 2 “part weights”, we can view data as a scatterplot.
 - Interpretation: we can try and figure out what the “parts” represent.

Previously: Vector Quantization

- Recall using **k-means** for vector quantization:
 - Run k-means to find a set of “means” w_c .
 - This gives a cluster \hat{y}_i for each object ‘i’.
 - Replace features x_i by mean of cluster: $\hat{x}_i \approx w_{\hat{y}_i}$



- This can be viewed as a (really bad) latent-factor model.

Vector Quantization (VQ) as Latent-Factor Model

- When $d=3$, we could write x_i exactly as:

$$x_i = \begin{bmatrix} x_{i1} \\ x_{i2} \\ x_{i3} \end{bmatrix} = z_{i1} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + z_{i2} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + z_{i3} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

(this is like "one pixel on" representation of images)

"part 1" "part 2" "part 3"

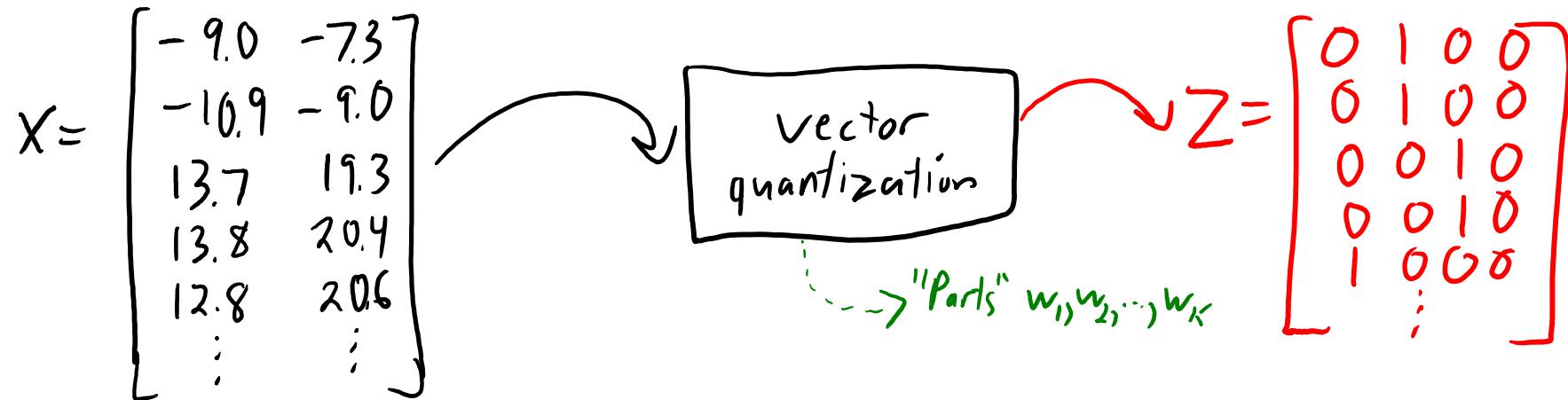
- In this “pointless” latent-factor model we have $z_i = [x_{i1} \ x_{i2} \ x_{i3}]$.
- If x_i is in cluster 2, VQ approximates x_i by mean w_2 of cluster 2:

$$x_i \approx w_2 = \textcolor{red}{0}w_1 + \textcolor{green}{1}w_2 + \textcolor{red}{0}w_3 + \textcolor{red}{0}w_4$$

- So in this example we would have $z_i = [\textcolor{red}{0} \ 1 \ 0 \ 0]$.
 - The “parts” are the means from k-means.
 - VQ only uses one part (the “part” from the cluster).

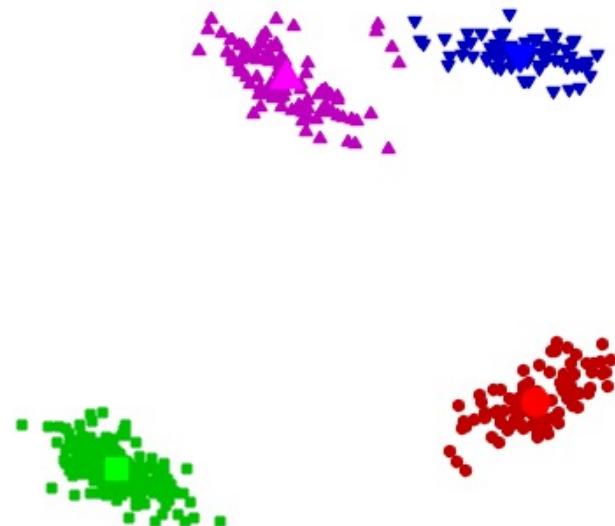
Vector Quantization vs. PCA

- Viewing vector quantization as a **latent-factor model**:



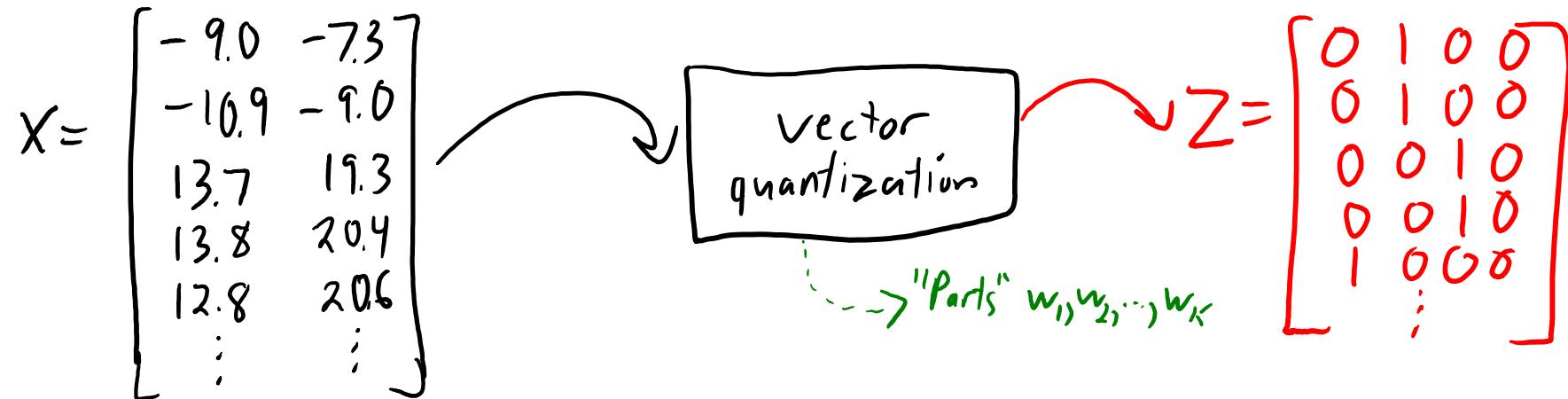
- Suppose we're doing supervised learning, and the colours are the true labels 'y':

- Classification would be really easy with this "k-means basis" 'Z'.



Vector Quantization vs. PCA

- Viewing vector quantization as a **latent-factor model**:



- But it **only uses 1 part**, it's just memorizing 'k' points in x_i space.
 - What we want is **combinations of parts**.
- PCA is a generalization that allows continuous ' z_i ':**
 - It can have more than 1 non-zero.
 - It can use fractional weights and negative weights.

$$Z = \begin{bmatrix} 0.2 & 1.6 \\ 0.3 & 1.5 \\ 0.1 & -2.7 \\ 0.3 & -2.7 \\ \vdots & \vdots \end{bmatrix}$$

Principal Component Analysis (PCA) Applications

- Principal component analysis (PCA) has been invented many times:

PCA was invented in 1901 by [Karl Pearson](#),^[1] as an analogue of the [principal axis theorem](#) in mechanics; it was later independently developed (and named) by [Harold Hotelling](#) in the 1930s.^[2] Depending on the field of application, it is also named the discrete [Kosambi–Karhunen–Loève transform](#) (KLT) in signal processing, the [Hotelling transform](#) in multivariate quality control, proper orthogonal decomposition (POD) in mechanical engineering, [singular value decomposition](#) (SVD) of \mathbf{X} (Golub and Van Loan, 1983), [eigenvalue decomposition](#) (EVD) of $\mathbf{X}^T \mathbf{X}$ in linear algebra, [factor analysis](#) (for a discussion of the differences between PCA and factor analysis see Ch. 7 of ^[3]), [Eckart–Young theorem](#) (Harman, 1960), or [Schmidt–Mirsky theorem](#) in psychometrics, [empirical orthogonal functions](#) (EOF) in meteorological science, [empirical eigenfunction decomposition](#) (Sirovich, 1987), [empirical component analysis](#) (Lorenz, 1956), [quasiharmonic modes](#) (Brooks et al., 1988), [spectral decomposition](#) in noise and vibration, and [empirical modal analysis](#) in structural dynamics.

standard deviation of 3 in roughly the (0.878, 0.478) direction and of 1 in the orthogonal direction. The vectors shown are the eigenvectors of the [covariance matrix](#) scaled by the square root of the corresponding eigenvalue, and shifted so their tails are at the mean.

PCA Notation (MEMORIZE)

- PCA takes in a matrix 'X' and an input 'k', and outputs two matrices:

$$Z = \left[\begin{array}{c} z_1^T \\ z_2^T \\ \vdots \\ z_n^T \end{array} \right] \Big\}_n \quad W = \left[\begin{array}{c} w_1^T \\ w_2^T \\ \vdots \\ w_k^T \end{array} \right] \Big\}_k = \left[\begin{array}{cccc} 1 & 1 & \dots & 1 \\ w_1 & w_2 & \dots & w_d \end{array} \right] \Big\}_d$$

- For row 'c' of W, we use the notation w_c .
 - Each w_c is a “part” (also called a “factor” or “principal component”).
- For row 'i' of Z, we use the notation z_i .
 - Each z_i is a set of “part weights” (or “factor loadings” or “features”).
- For column 'j' of W, we use the notation w^j .
 - Index 'j' of all the 'k' “parts” (value of pixel 'j' in all the different parts).

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- With this notation, we can write our approximation of one x_{ij} as:

$$\hat{x}_{ij} = z_{i1}w_{1j} + z_{i2}w_{2j} + \dots + z_{ik}w_{kj} = \sum_{c=1}^k z_{ic}w_{cj} = (w^j)^T z_i = \langle w^j, z_i \rangle$$

- K-means: “take index ‘j’ of closest mean”.
- PCA: “ z_i gives weights for index ‘j’ of all means”.

- We can write approximation of the vector x_i as:

$$\hat{x}_i = \begin{bmatrix} \langle w_1^T, z_i \rangle \\ \langle w_2^T, z_i \rangle \\ \vdots \\ \langle w_d^T, z_i \rangle \end{bmatrix} = W^T z_i$$

$d \times 1 \quad d \times k \quad k \times 1$

Different views (MEMORIZE)

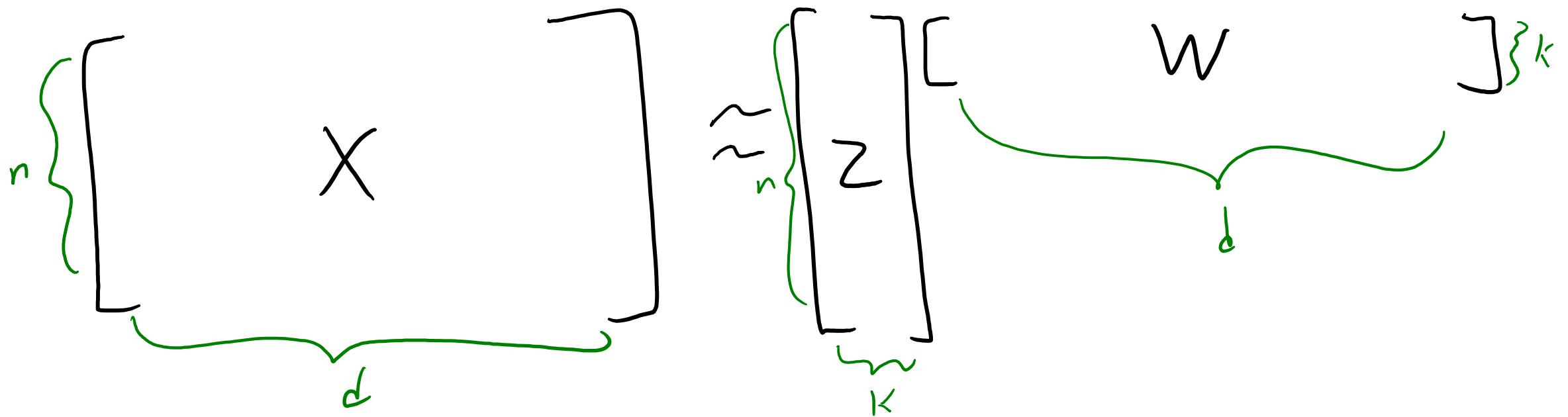
- PCA approximates each x_{ij} by the inner product $\langle w^j, z_i \rangle$.
- PCA approximates each x_i by the matrix-vector product $W^T z_i$.
- PCA approximates matrix ‘X’ by the matrix-matrix product ZW .

$$\overset{n \times d}{X} \approx \overset{n \times k}{Z} \overset{k \times d}{W}$$

- PCA is also called a “matrix factorization” model.
- Both ‘Z’ and ‘W’ are variables.
- This can be viewed as a “change of basis” from x_i to z_i values.
 - The “basis vectors” are the rows of W , the w_c .
 - The “coordinates” in the new basis of each x_i are the z_i .

PCA Applications

- Applications of PCA:
 - Dimensionality reduction: replace ‘X’ with lower-dimensional ‘Z’.
 - If $k \ll d$, then compresses data.
 - Often better approximation than vector quantization.



PCA Applications

- Applications of PCA:

- Dimensionality reduction: replace 'X' with lower-dimensional 'Z'.

- If $k \ll d$, then compresses data.

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$$\begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ 2 & 4 & 6 & 8 & 10 & 12 & 14 & 16 \\ 3 & 6 & 9 & 12 & 15 & 18 & 21 & 24 \\ 4 & 8 & 12 & 16 & 20 & 24 & 28 & 32 \\ 5 & 10 & 15 & 20 & 25 & 30 & 35 & 40 \\ 6 & 12 & 18 & 24 & 30 & 36 & 42 & 48 \\ 7 & 14 & 21 & 28 & 35 & 42 & 49 & 56 \\ 8 & 16 & 24 & 32 & 40 & 48 & 56 & 64 \end{bmatrix} \underset{\approx}{\sim} \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \\ 7 \\ 8 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \end{bmatrix}$$

X *Z* *W*

Compresses 64 elements
of 'X' down to 16 elements
of 'Z' and 'W'
(can predict all x_i values from one z_i value)

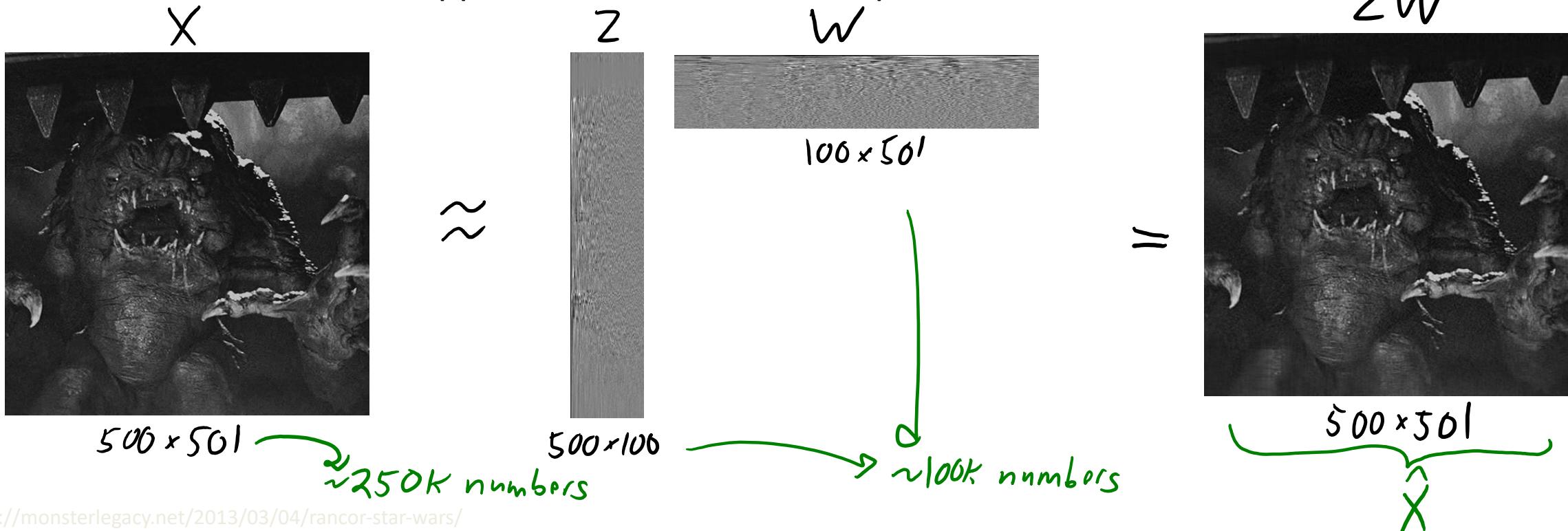
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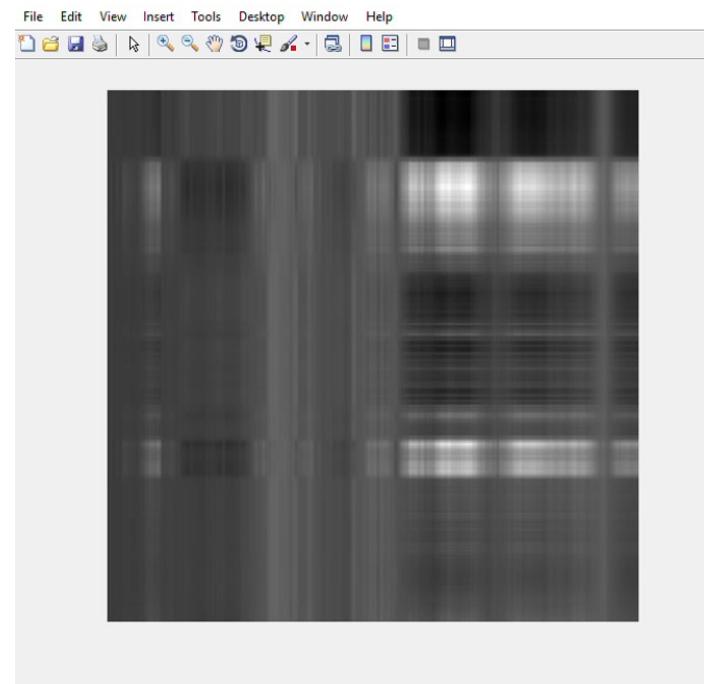
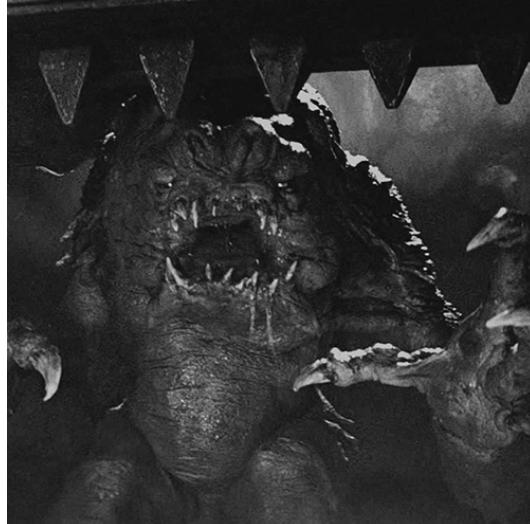
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- Often better approximation than vector quantization.



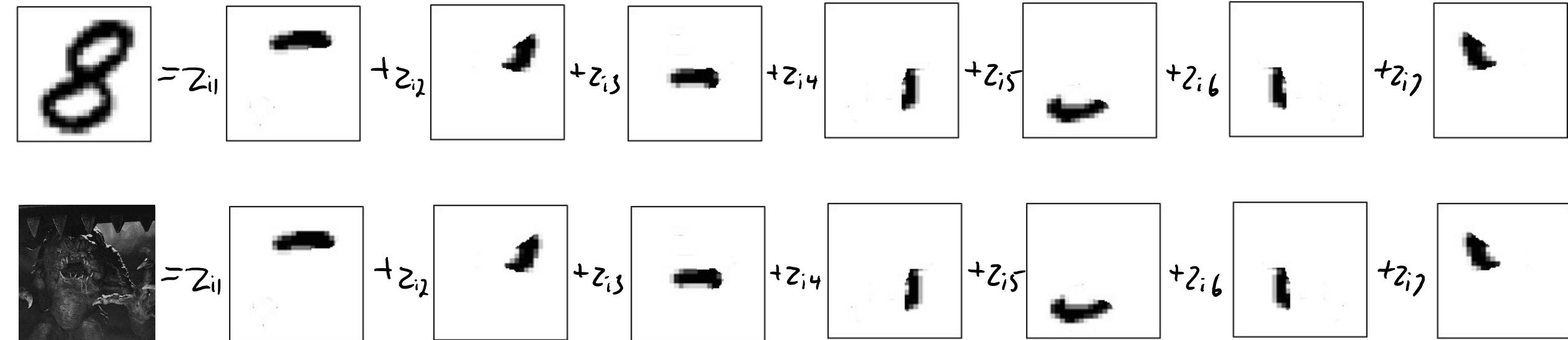
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PCA Applications

- Applications of PCA:
 - **Outlier detection:** if PCA gives poor approximation of x_i , could be ‘outlier’.
 - Though due to squared error **PCA is sensitive to outliers.**



PCA Applications

- Applications of PCA:
 - Partial least squares: uses PCA features as basis for linear model.

Compute approximation $X \approx ZW$

Now use Z as features in a linear model:

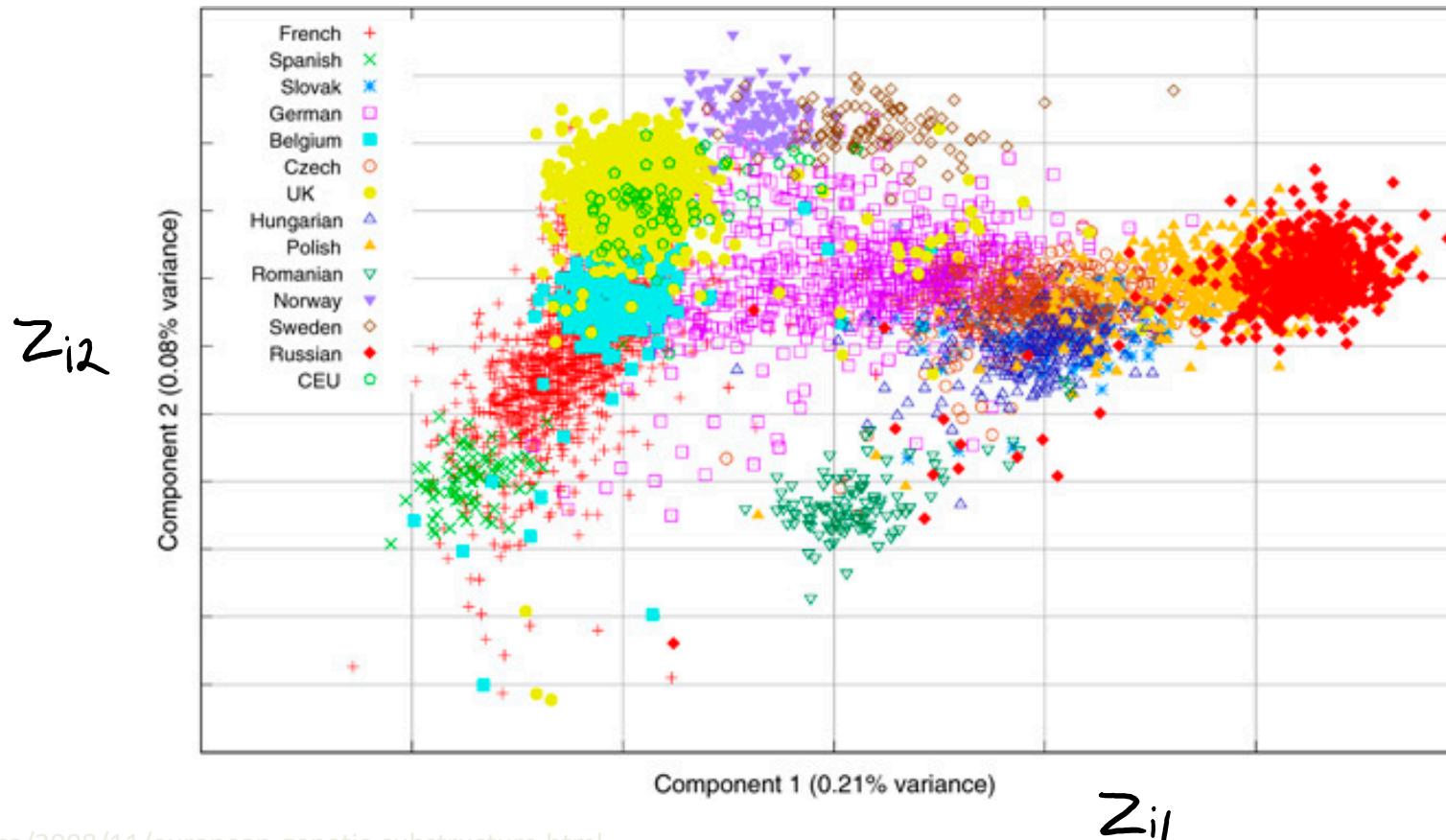
$$y_i = v^T z_i$$

linear regression
weights 'v' trained
under this change
of basis.

lower-dimensional than original features so less overfitting

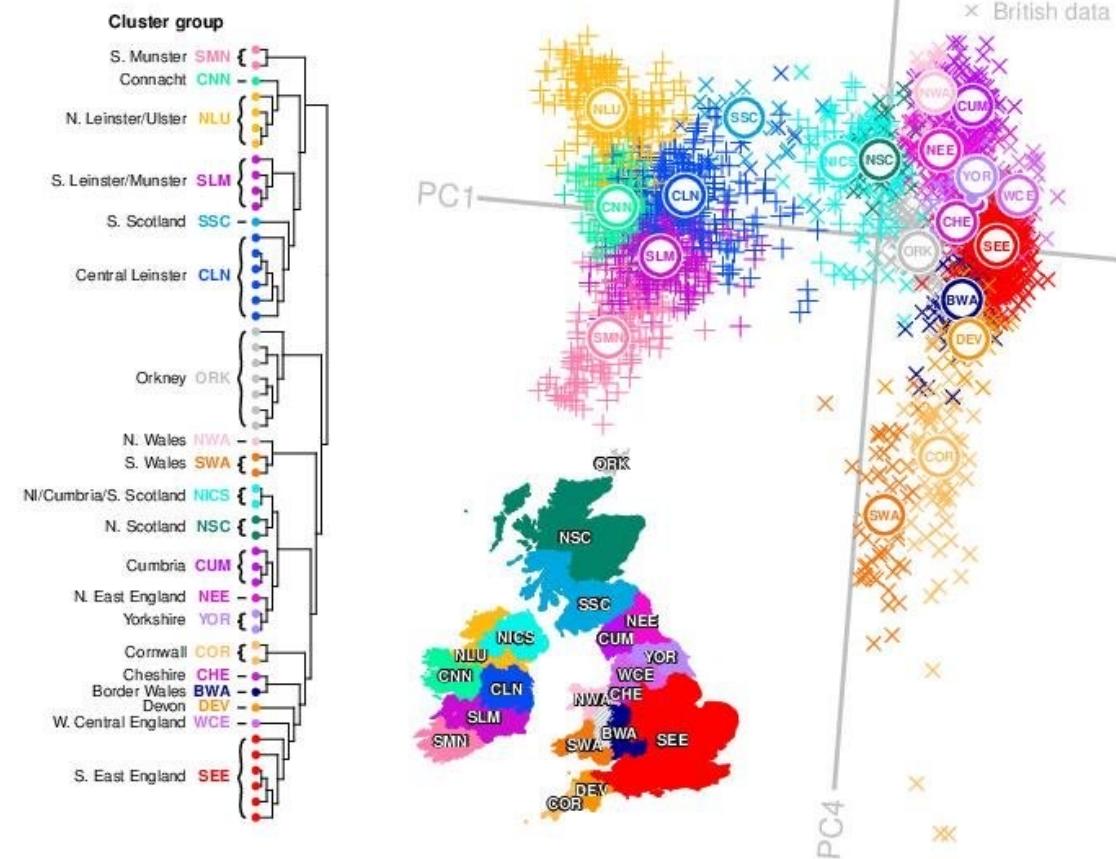
PCA Applications

- Applications of PCA:
 - Data visualization: plot z_i with $k = 2$ to visualize high-dimensional objects.



PCA Applications

- Applications of PCA:
 - **Data visualization:** plot z_i with $k = 2$ to visualize high-dimensional objects.
 - Can augment other visualizations: A



PCA Applications

- Applications of PCA:
 - Data interpretation: we can try to assign meaning to latent factors w_c .
 - Hidden “factors” that influence all the variables.

Trait	Description
O penness	Being curious, original, intellectual, creative, and open to new ideas.
C onscientiousness	Being organized, systematic, punctual, achievement-oriented, and dependable.
E xtraversion	Being outgoing, talkative, sociable, and enjoying social situations.
A greeableness	Being affable, tolerant, sensitive, trusting, kind, and warm.
N euroticism	Being anxious, irritable, temperamental, and moody.

["Most Personality Quizzes Are Junk Science. I Found One That Isn't."](#)

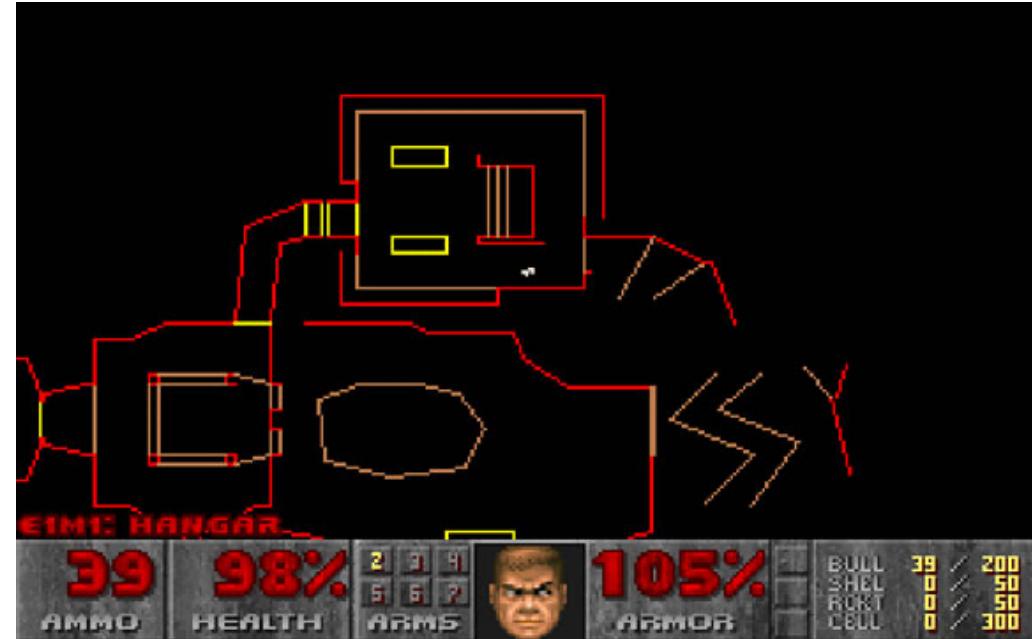
What is PCA actually doing?

When should PCA work well?

Today I just want to show geometry,
we'll talk about implementation next time.

Doom Overhead Map and Latent-Factor Models

- Original “Doom” video game included an “overhead map” feature:



- This map can be viewed as a latent-factor model of player location.

[https://en.wikipedia.org/wiki/Doom_\(1993_video_game\)](https://en.wikipedia.org/wiki/Doom_(1993_video_game))

<https://forum.minetest.net/viewtopic.php?f=5&t=9666>

Overhead Map and Latent-Factor Models

- Actual player location at time 'i' can be described by 3 coordinates:

$$x_i = \begin{bmatrix} x_{i1} \\ x_{i2} \\ x_{i3} \end{bmatrix}$$

← "x" coordinate
← "y" coordinate
← "z" coordinate

- The overhead map approximates these 3 coordinates with only 2:

$$z_i = \begin{bmatrix} z_{i1} \\ z_{i2} \end{bmatrix}$$

← "x" coordinate
← "y" coordinate

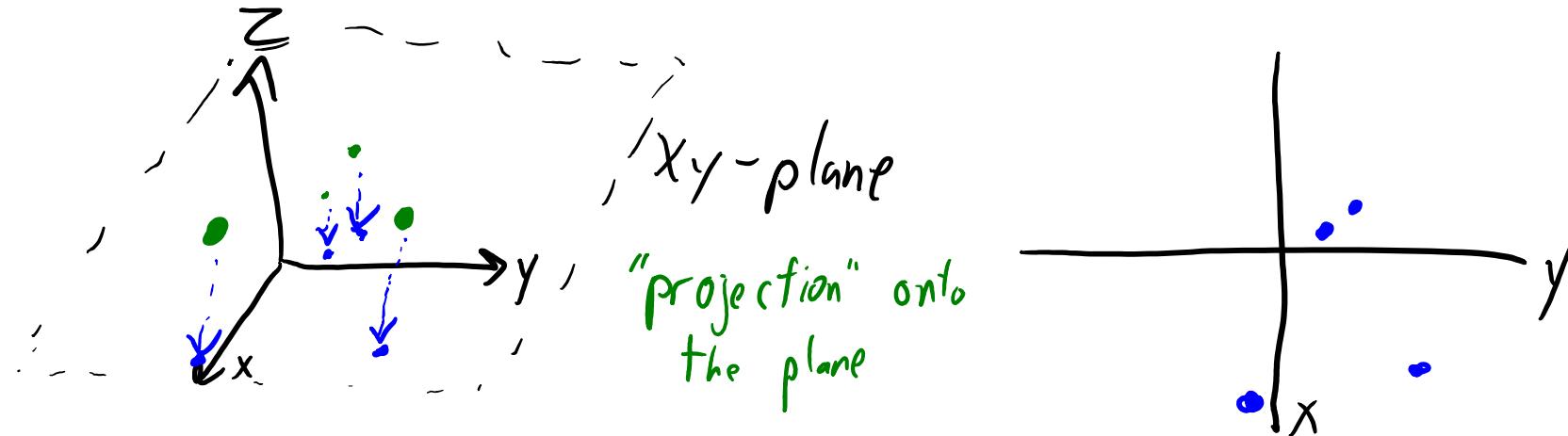
- Our k=2 latent factors are the following:

$$W = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

- So our approximation of x_i is: $\hat{x}_i = z_{i1} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + z_{i2} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$

Overhead Map and Latent-Factor Models

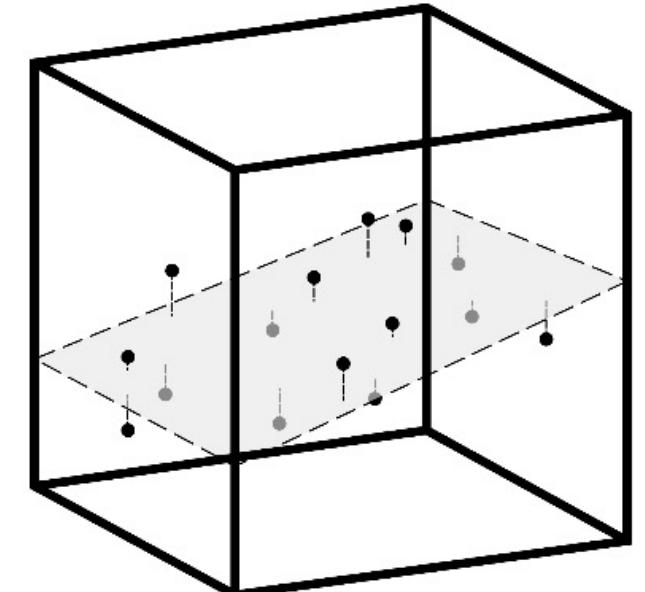
- The “overhead map” approximation just **ignores the “height”**.



- This is a **good approximation** if the world is flat.
 - Even if the character jumps, the first two features will approximate location.
- But it's a **poor approximation** if heights are different.

Overhead Map and Latent-Factor Models

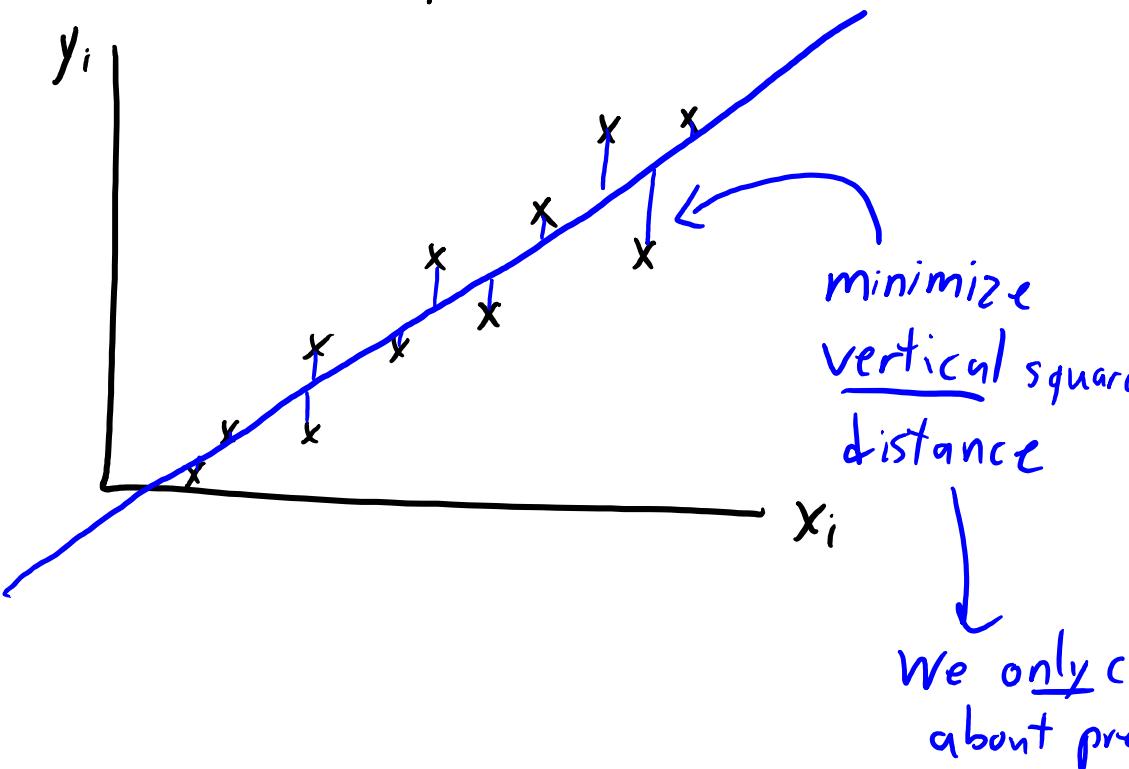
- Consider these crazy goats trying to get some salt:
 - Ignoring height gives poor approximation of goat location.



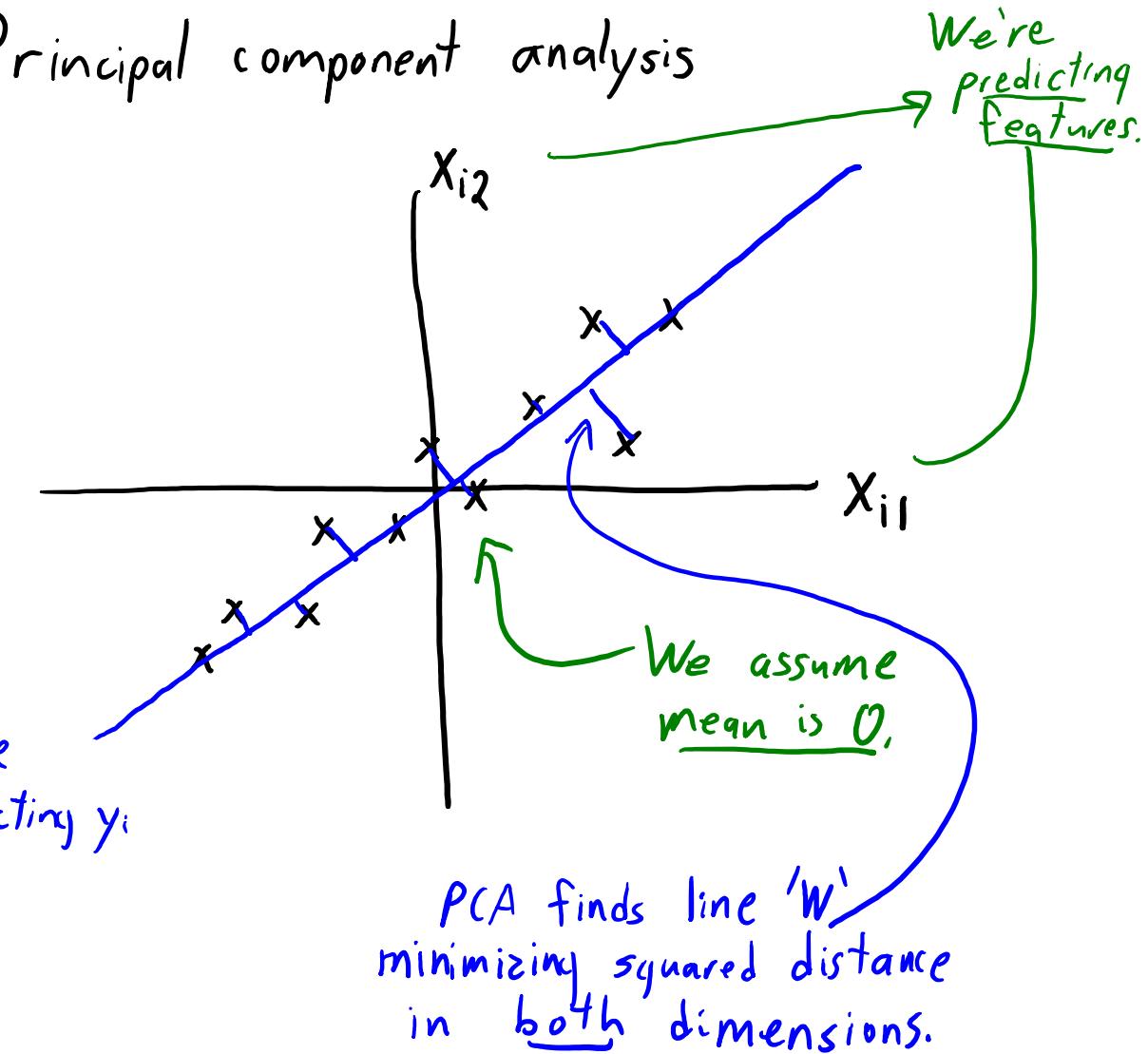
- But the “goat space” is basically a **two-dimensional plane**.
 - Better k=2 approximation: define ‘W’ so that combinations give the plane.

PCA with $d=2$ and $k=1$

Least squares

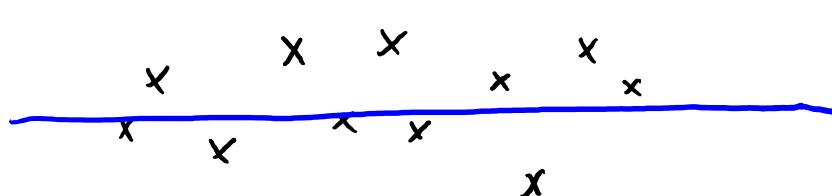


Principal component analysis

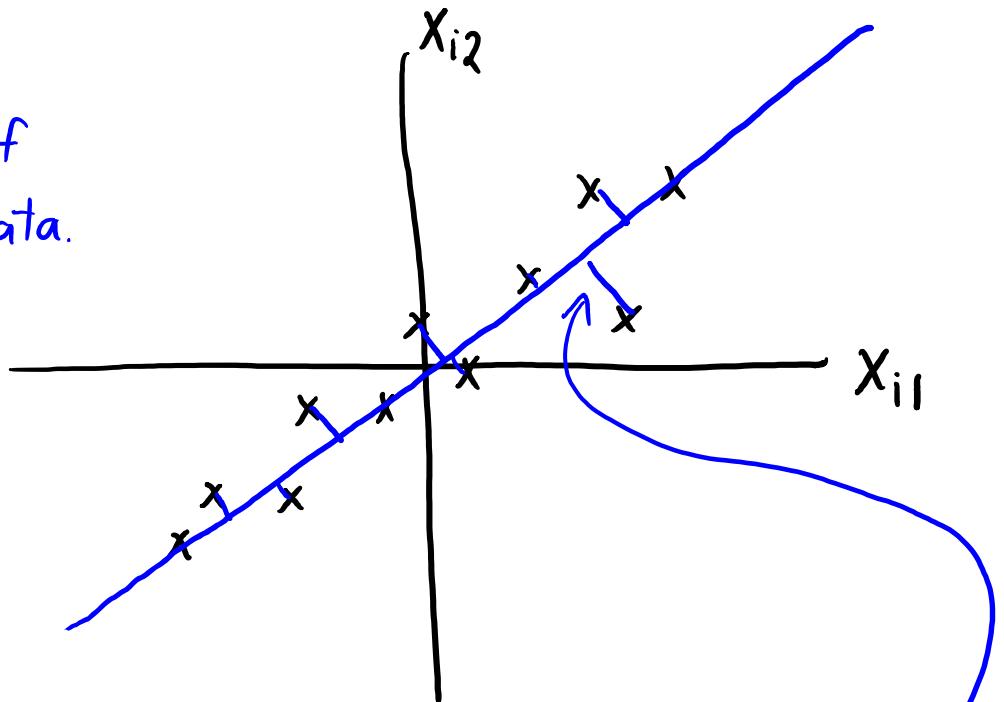


PCA with d=2 and k =1

Principal component analysis



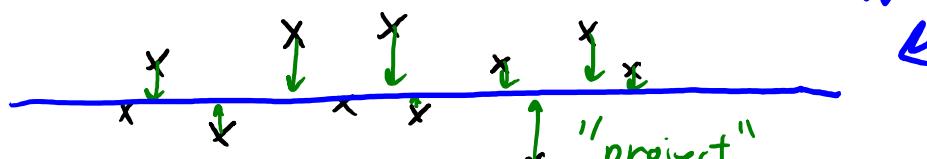
You can think of
'W' as rotating data.



PCA finds line 'W'
minimizing squared distance
in both dimensions.

PCA with $d=2$ and $k=1$

Principal component analysis

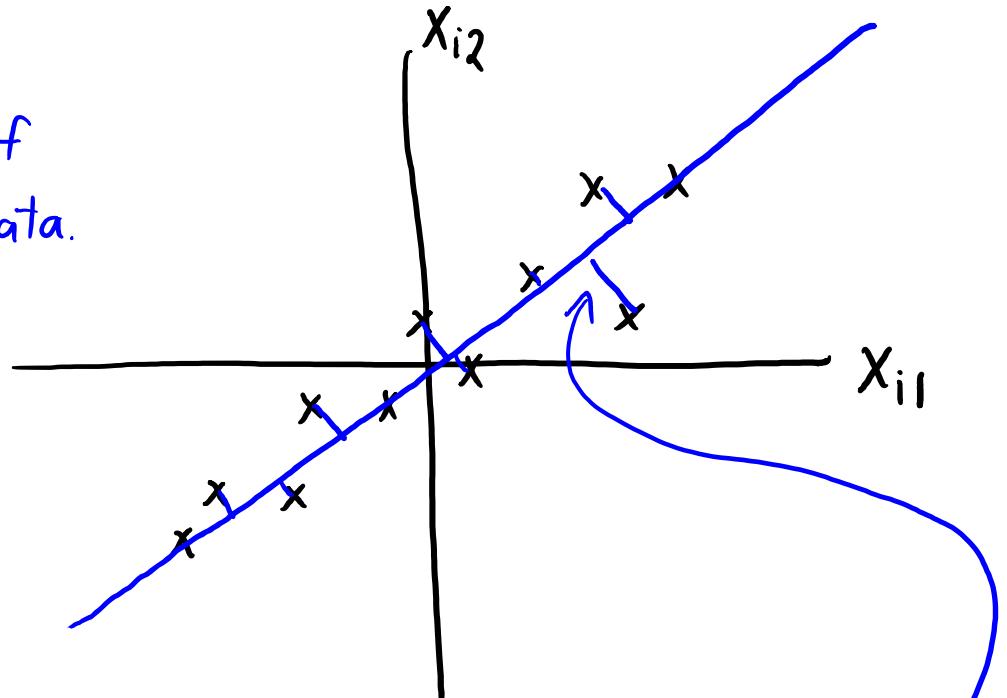


You can think of
'W' as rotating data.

Z_i

Z_i can be interpreted as
position along the line.

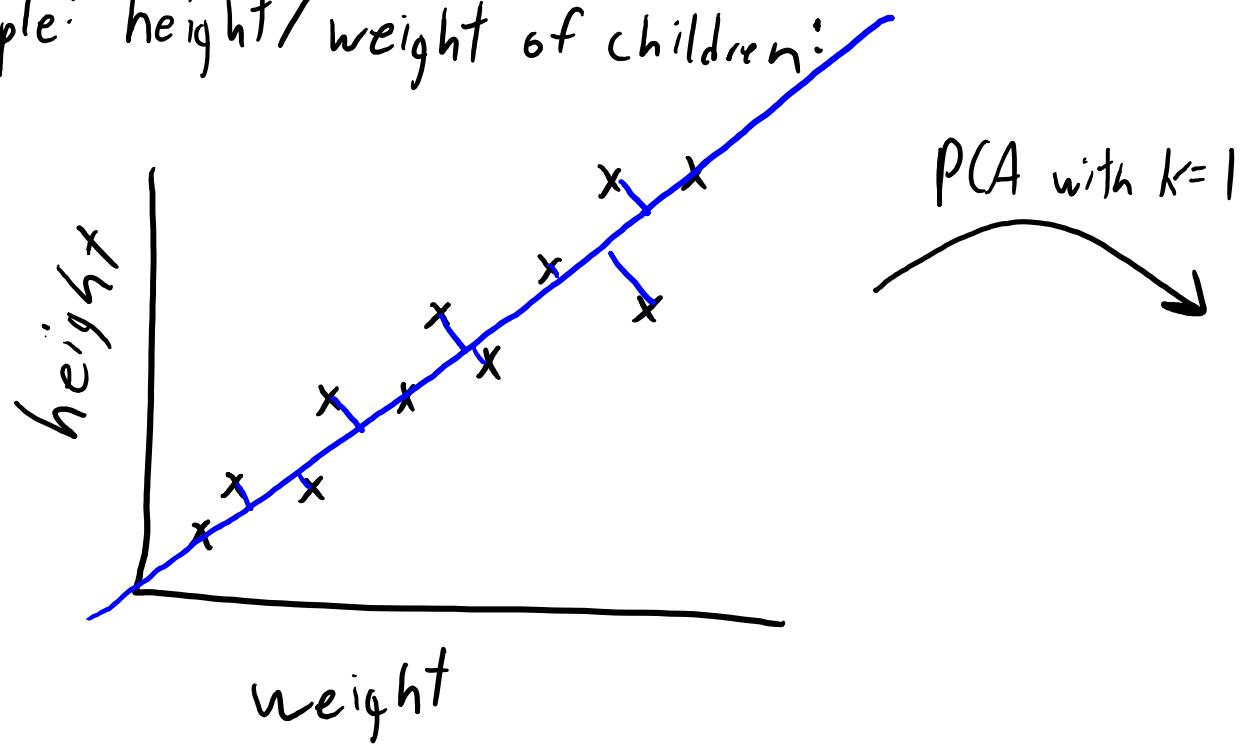
(turned a 2d dataset
into a 1d dataset)



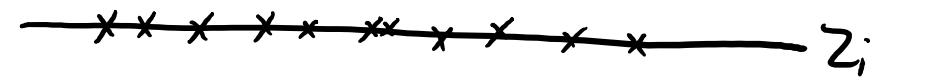
PCA finds line 'W'
minimizing squared distance
in both dimensions.

PCA with $d=2$ and $k=1$

Example: height/weight of children:



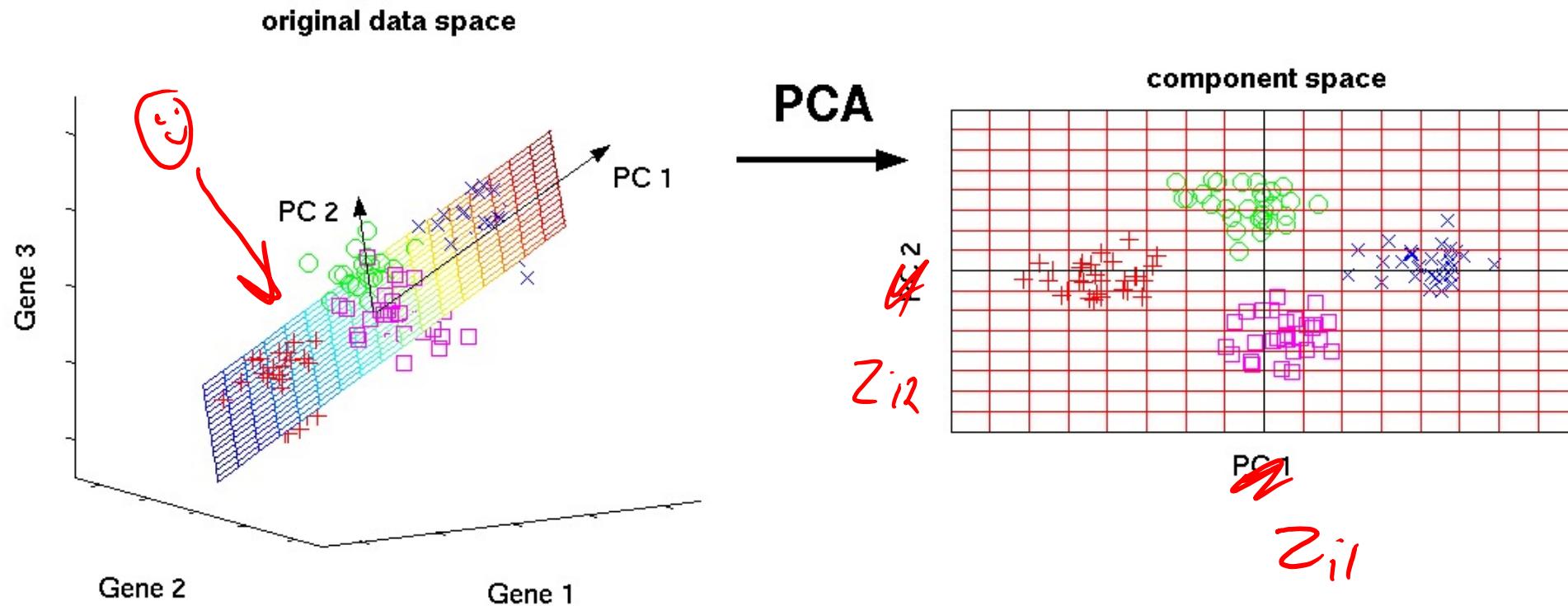
PCA with $k=1$



Latent factor could be viewed as measure of size.

PCA with d=3 and k=2.

- With $d=3$, PCA ($k=1$) finds line minimizing squared distance to x_i .
- With $d=3$, PCA ($k=2$) finds plane minimizing squared distance to x_i .



Summary

- Latent-factor models:
 - Try to learn basis Z from training examples X.
 - Usually, the z_i are “part weights” for “parts” w_c .
 - Useful for dimensionality reduction, visualization, factor discovery, etc.
- Principal component analysis:
 - Writes each training examples as linear combination of parts.
 - We learn both the “parts” ‘W’ and the “features” Z.
 - We can view ‘W’ as best lower-dimensional hyper-plane.
 - We can view ‘Z’ as the coordinates in the lower-dimensional hyper-plane.
- Next time: PCA in 4 lines of code.