

# CPSC 340 – Tutorial 9

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Slides courtesy of Nam Hee Kim

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## **Agenda**

- 1. Robust PCA
- 2. Gradient for Robust PCA

#### **Robust PCA**

Very similar objective function but we use L1 distance rather than L2

$$f(Z, W) = \sum_{i=1}^{n} \sum_{j=1}^{d} |\langle w^{j}, z_{i} \rangle - x_{ij}|,$$

Like the PCA you've seen before we need to optimize W and Z!

## **Approximating Robust PCA**

Very similar objective function but we use L1 distance rather than L2

$$f(Z, W) = \sum_{i=1}^{n} \sum_{j=1}^{d} |\langle w^{j}, z_{i} \rangle - x_{ij}|,$$

But we want a smooth approximation using:

$$|\alpha| \approx \sqrt{\alpha^2 + \epsilon}$$

## **Evaluating Robust PCA**

Given the definition of f and the smooth approximation we have to compute f

$$f(Z, W) = \sum_{i=1}^{n} \sum_{j=1}^{d} |\langle w^j, z_i \rangle - x_{ij}|, \qquad |\alpha| \approx \sqrt{\alpha^2 + \epsilon},$$

Putting these together we get:

$$f(Z,W) = \sum_{i=1}^n \sum_{j=1}^d \sqrt{(\langle w^j, z_i \rangle - x_{ij})^2 + \epsilon}$$

## **Evaluating Robust PCA**

Given the definition of f and the smooth approximation we have to compute f

$$f(Z,W) = \sum_{i=1}^{n} \sum_{j=1}^{d} |\langle w^j, z_i \rangle - x_{ij}|, \qquad |\alpha| \approx \sqrt{\alpha^2 + \epsilon},$$

(SLIDE 6 of Lecture "More PCA")

The 3 different ways to write the PCA objective function:

$$f(W,Z) = \sum_{i=1}^{2} \sum_{j=1}^{d} (\langle w_{j}^{i} z_{i}^{j} - x_{ij}^{j} \rangle^{2}$$

$$= \sum_{i=1}^{d} ||W^{T} z_{i} - x_{i}^{j}||^{2}$$

$$= ||ZW - X||_{F}^{2}$$
(approximating  $X_{i}$  by  $W_{Z_{i}}^{T}$ )
$$= ||ZW - X||_{F}^{2}$$
(approximating  $X_{i}$  by  $ZW_{Z_{i}}$ )

## **Evaluating Robust PCA**

Given the definition of f and the smooth approximation we have to compute f

$$f(Z,W) = \sum_{i=1}^{n} \sum_{j=1}^{d} |\langle w^j, z_i \rangle - x_{ij}|,$$
  $|\alpha| \approx \sqrt{\alpha^2 + \epsilon},$ 

Putting these together we get (with some abuse of notation):

$$f(Z,W) = \sum \sqrt{(ZW-X)^2 + \epsilon}$$

Combining the equations we already have:

$$f(Z,W) = \sum_{i=1}^{n} \sum_{j=1}^{d} |\langle w^j, z_i \rangle - x_{ij}|, \qquad |\alpha| \approx \sqrt{\alpha^2 + \epsilon},$$

We get:

$$f(Z,W) = \sum_{i=1}^n \sum_{j=1}^d \sqrt{(lpha)^2 + \epsilon} \ lpha = \left\langle w^j, z_i 
ight
angle - x_{ij}$$

If we were to take the gradient w.r.t w^j

$$f(Z,W) = \sum_{i=1}^n \sum_{j=1}^d \sqrt{(lpha)^2 + \epsilon} \hspace{0.5cm} lpha = \langle w^j, z_i 
angle - x_{ij}$$

$$lpha = \langle w^j, z_i 
angle - x_{ij}$$

We get:

$$egin{aligned} rac{df(lpha)}{dw^j} &= \sum_{i=1}^n rac{1}{2} (lpha^2 + \epsilon)^{-rac{1}{2}} \cdot 2lpha \cdot rac{dlpha}{dw^j} \ rac{df(lpha)}{dw^j} &= \sum_{i=1}^n rac{lpha}{\sqrt{lpha^2 + \epsilon}} \cdot rac{dlpha}{dw^j} \end{aligned}$$

What is da/dw^j?

If we were to take the gradient w.r.t W\_i

$$f(Z,W) = \sum_{i=1}^n \sum_{j=1}^d \sqrt{(lpha)^2 + \epsilon} \qquad lpha = \langle w^j, z_i 
angle - x_{ij}$$

We get:

$$egin{aligned} rac{df(lpha)}{dw^j} = \sum_{i=1}^n rac{1}{2} (lpha^2 + \epsilon)^{-rac{1}{2}} \cdot 2lpha \cdot rac{dlpha}{dw^j} \ rac{df(lpha)}{dw^j} = \sum_{i=1}^n rac{lpha}{\sqrt{lpha^2 + \epsilon}} \cdot rac{dlpha}{dw^j} \end{aligned}$$

How does this formula change when we take the derivative w.r.t z\_i?

Again we can see that this scenario is similar to what we've seen in class before

**HINT** (slide 36 of More PCA lecture)

#### PCA Computation: Alternating Minimization

With centered data, the PCA objective is:

$$f(W,z) = \hat{\mathcal{L}} \hat{\mathcal{L}} (\langle w_j^2 \rangle^2 - \chi_{ij})^2$$

$$\nabla_{W} f(w_j z) = Z^T Z W - Z^T X$$

$$(writing fradient as a matrix)$$

$$\nabla_{Z} f(W_j Z) = Z W W^T - X W^T$$

Again we can see that this scenario is similar to what we've seen in class before

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### Demo

**Eigenfaces**