

$$1a) \Delta(\nabla f(x_i)) = \frac{\nabla f(x_{i+1}) - \nabla f(x_i)}{h_{i+1}}$$

$$= \left[\frac{f(x_{i+1}) - f(x_i)}{h_{i+1}} - \frac{f(x_i) - f(x_{i-1}))}{h_i} \right] / h_{i+1}$$

$$\rightarrow h_{i+1} \Delta(\nabla f(x_i)) = \left[\frac{f(x_{i+1}) - f(x_i)}{h_{i+1}} - \frac{f(x_i) - f(x_{i-1}))}{h_i} \right]$$

$$\nabla(\Delta f(x_i)) = \frac{\Delta f(x_i) - \Delta f(x_{i-1}))}{h_i}$$

$$= \left[\frac{f(x_{i+1}) - f(x_i)}{h_{i+1}} - \frac{f(x_i) - f(x_{i-1}))}{h_i} \right] / h_i$$

$$\rightarrow h_i \nabla(\Delta f(x_i)) = \left[\frac{f(x_{i+1}) - f(x_i)}{h_{i+1}} - \frac{f(x_i) - f(x_{i-1}))}{h_i} \right]$$

$$\boxed{h_{i+1} \Delta(\nabla f(x_i))} = \boxed{\Delta f(x_i) - \nabla f(x_i)}$$

$$b) [\Delta f(x_i) - \nabla f(x_i)] \approx \left(f'(x_i) + \frac{h_{i+1}}{2} f''(x_i) + \frac{h_{i+1}^2}{3!} f'''(x_i) + \dots - \left(f'(x_i) - \frac{h_i}{2} f''(x_i) + \frac{h_i^2}{3!} f'''(x_i) - \dots \right) \right)$$

$$\approx \frac{h_{i+1} + h_i}{2!} f''(x_i) + \frac{h_{i+1}^2 - h_i^2}{3!} f'''(x_i) + \dots$$

neither

$\rightarrow h_{i+1} \Delta(\nabla f(x_i))$ nor $h_i \nabla(\Delta f(x_i))$ approximates $f''(x_i)$

unless $h_{i+1} = h_i = h \rightarrow [\Delta f(x_i) - \nabla f(x_i)] \approx \frac{2h}{2!} f''(x_i) + \dots$

$$h \Delta(\nabla f(x_i)) = h \nabla(\Delta f(x_i)) \approx f''(x_i)$$

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2a) $u'(t) = f(u)$ and $u(0) = \phi$

$$u'(t) \approx \frac{u(t_{i+1}) - u(t_i)}{h} = f(u_i) + O(h) \rightarrow \boxed{u_{i+1} = u_i + hf(u_i) \text{ and } u_0 = \phi}$$

b) In fact, $u(t_{i+1}) = u(t_i) + hf(u_i) + O(h^2)$

$$|u(t_{i+1}) - u_{i+1}| = \varepsilon_{i+1}$$

$$= |u(t_i) - u_i| + h|f(u(t_i)) - f(u_i)| + O(h^2)$$

$$\leq \underbrace{|u(t_i) - u_i|}_{\varepsilon_i} + h\lambda \underbrace{|u(t_i) - u_i|}_{\varepsilon_i} + O(h^2)$$

$$\rightarrow \varepsilon_{i+1} \leq (1 + h\lambda)\varepsilon_i + Ch^2 \quad \text{for } i = 0, 1, \dots, M-1$$

$$\text{By MI} \rightarrow \varepsilon_{i+1} \leq \frac{C}{\lambda} h [(1 + h\lambda)^{i+1} - 1]$$

$$\text{F.E.M is convergent} \rightarrow \lim_{M \rightarrow \infty} \varepsilon_{M+1} = 0$$

$$\varepsilon_{M+1} \leq \frac{C\tilde{T}}{\lambda(M+1)} \left[\left(1 + \frac{\tilde{T}\lambda}{M+1}\right)^{M+1} - 1 \right]$$

$$\rightarrow \lim_{M \rightarrow \infty} \varepsilon_{M+1} = \lim_{M \rightarrow \infty} \frac{C\tilde{T}}{\lambda(M+1)} \lim_{M \rightarrow \infty} \left[\left(1 + \frac{\lambda\tilde{T}}{M+1}\right)^{M+1} - 1 \right]$$

$$= 0 \times (e^{\lambda\tilde{T}} - 1) = 0$$

\rightarrow F.E.M is convergent on any uniform mesh.

- Scintillate -

3a) Discretization in time: $\frac{u(s, t_{i+1}) - u(s, t_i)}{2h} = u_t(s, t_i) + O(h^2)$

$u = \begin{bmatrix} u(s, t_1) \\ u(s, t_2) \\ \vdots \\ u(s, t_n) \end{bmatrix} = \begin{bmatrix} u_1(s) \\ u_2(s) \\ \vdots \\ u_n(s) \end{bmatrix} \in \mathbb{R}^n$

$u_{ss} = \begin{bmatrix} u_{ss,1}(s) \\ \vdots \\ u_{ss,n}(s) \end{bmatrix}$

$\frac{u(s_{i+1}, t) - 2u(s_i, t) + u(s_{i-1}, t))}{h^2} = u_{ss}(s_i, t) + O(h^2)$

3) $u_{ss} = \begin{bmatrix} \frac{u(s_2, t) - 2u(s_1, t) + u(s_0, t))}{h^2} \\ \vdots \\ \frac{u(s_n, t) - 2u(s_{n-1}, t) + u(s_{n-2}, t))}{h^2} \end{bmatrix}$

$= \frac{1}{h^2} \begin{bmatrix} 1 & -2 & 1 & & & \\ & 1 & -2 & 1 & & \\ & & \ddots & \ddots & \ddots & \\ 0 & & & 1 & -2 & 1 \\ & & & & 1 & -2 \end{bmatrix} \begin{bmatrix} u(t) \\ u(t) \\ \vdots \\ u_{n-1}(t) \\ u_{n-1}(t) \end{bmatrix}$

$A \in \mathbb{R}^{(n+1) \times (n+1)}$

$\vec{u} \in \mathbb{R}^{n+1}$

$\vec{u} \in \mathbb{R}^{n+1}$

$A \in \mathbb{R}^{(n+1) \times (n+1)}$

$\begin{bmatrix} 5 & n+1-2 \\ 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 1 \end{bmatrix} = n-1$

$\therefore u(t) = \frac{\alpha}{h^2} A \vec{u} \quad \text{with} \quad \vec{u}(0) = \vec{\phi}$

Use forward euler's method.

$u_{i+1} = u_i + \Delta t \cdot \frac{\alpha}{(\Delta x)^2} A u_i \quad \text{with} \quad \vec{u}(0) = \vec{\phi}$

6) $\frac{\alpha \Delta t}{(\Delta x)^2} < \frac{1}{2}$

Forward-Time Central-Space method