## Uczenie ze wzmocnieniem w środowisku Robocode

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#### Obserwacja

```
private static final int HEADING_BUCKETS = 6;
private static final int GUN_HEADING_BUCKETS = 10;
private static final int ENEMY_BEARING_BUCKETS = 6;
public Observation(double enemyDistance, double energy, double heading, double relativeGunHeading, double enemyBearing,
                   boolean enemyEnergyLoss) {
    this.energy = bucket( min: 0, max: 100, ENERGY_BUCKETS, energy);
    this.heading = bucket( min: 0, max: 360, HEADING_BUCKETS, heading);
    this.enemyBearing = bucket( min: -180, max: 180, ENEMY_BEARING_BUCKETS, enemyBearing);
    this.enemyEnergyLoss = enemyEnergyLoss;
    this.zeroBearing = Math.abs(relativeGunHeading) < 3;
```

#### Losowe akcje

```
if (obs.getZeroBearing() && random.nextDouble() < 0.5) {</pre>
    return new Fire( value: 1 + random.nextInt( bound: 4) * 0.5);
if (random.nextDouble() < experimentRate || rewards == null || rewards.isEmpty()) {
    return switch (random.nextInt( bound: 7)) {
        case 0 -> new GoAhead( value: random.nextInt( bound: 10) * 5);
        case 1 -> new TurnGunLeft( value: random.nextInt( bound: 9) * 5);
        case 2 -> new TurnGunRight( value: random.nextInt( bound: 9) * 5);
        case 3 -> new TurnLeft( value: random.nextInt( bound: 9) * 5);
        case 4 -> new TurnRight( value: random.nextInt( bound: 9) * 5);
        case 5 -> new GoBack( value: random.nextInt( bound: 10) * 5);
        case 6 -> new Fire( value: 1 + random.nextInt( bound: 4) * 0.5);
```

#### Nagrody

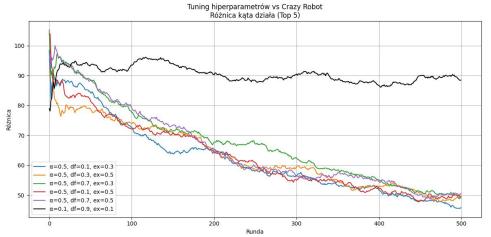
- Nagroda za zadanie obrażeń
- Kara za otrzymanie obrażeń
- Duża nagroda za wygraną
- Kara za przegraną
- Nagroda za przeciwnika w polu widzenia
- Kara za brak przeciwnika w polu widzenia
- Kąt jaki musi wykonać działko by trafić w przeciwnika im mniejszy tym większa nagroda
- Kara za liczbę rund

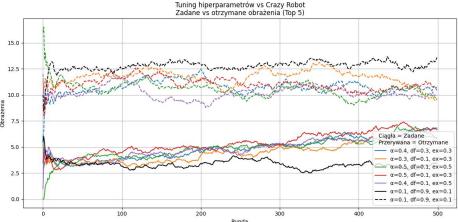
- rozmiar planszy 400x400
- na wykresach przedstawiono średnią kroczącą
- losowość crazy bota pozwala sprawdzić wiele różnych przypadków

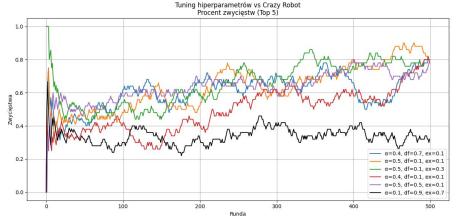
## Tuning hiperparametrów

#### GridSearch:

- alpha  $\in \{0.1, 0.2, 0.3, 0.4, 0.5\}$
- discountFactor  $\in \{0.1, 0.3, 0.5, 0.7, 0.9\}$
- experimentRate  $\in \{0.1, 0.3, 0.5, 0.7\}$



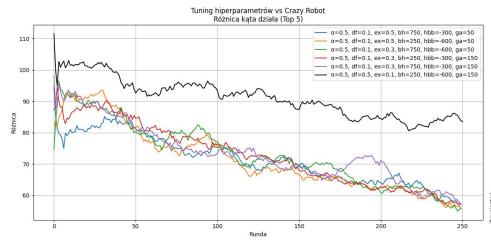


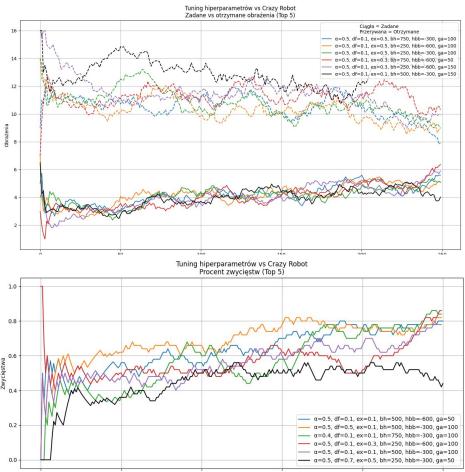


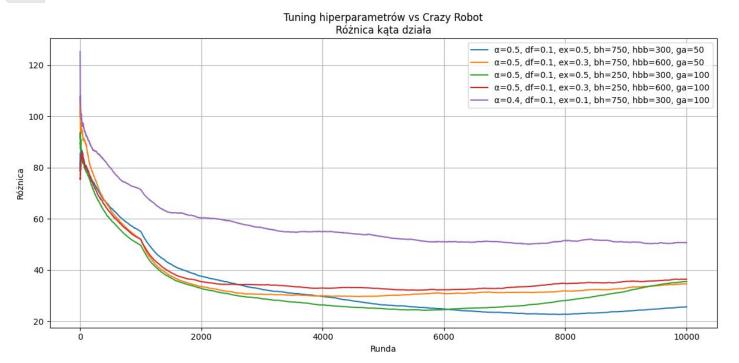
### Tuning hiperparametrów

#### GridSearch:

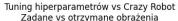
- bulletHitReward ∈ {250, 500, 750}
- hitByBulletPenalty ∈ {-300, -600}
- gunAlignmentReward ∈ {50, 100, 150}

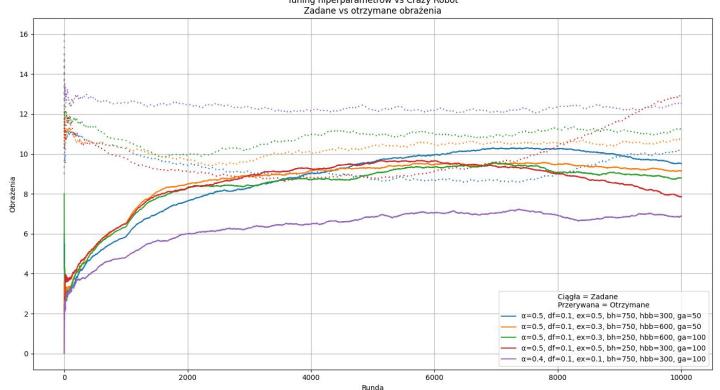


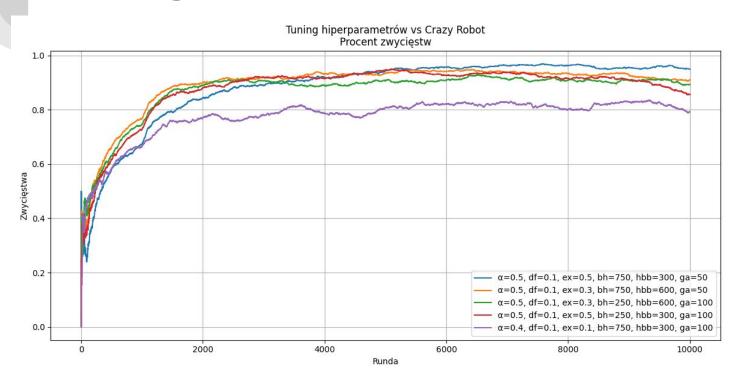




Najlepszy zestaw hiperparametrów niebieska linia alpha=0.5, df=0.1, ex=0.5, bh=750, hbb=300, ga=50







Końcowy procent zwycięstw około 95%

## Demo

### Wyniki bitew

#### vs Crazy Robot - 949/1000 wygranych

Rank	Robot Name	Total Score	Survival	Surv Bonus	Bullet Dmg	Bullet Bonus	Ram Dmg * 2	Ram Bonus	1sts	2nds
1st	agh.reinforced.ReinforcedLearningRobotLoa	114366 (68%)	47350	9470	49537	7703	270	35	949	51
2nd	sample.Crazy	53505 (32%)	2550	510	44287	668	5318	171	53	947

#### vs Corners Robot - 352/1000 wygranych

Rank	Robot Name	Total Score	Survival	Surv Bonus	Bullet Dmg	Bullet Bonus	Ram Dmg * 2	Ram Bonus	1sts	2nds
1st	sample.Corners	160138 (58%)	32400	6480	106235	14958	65	0	648	352
2nd	agh.reinforced.ReinforcedLearningRobotLoa	116052 (42%)	17600	3520	85421	9410	101	0	352	648

#### vs Fire Robot - 300/1000 wygranych

Rank	Robot Name	Total Score	Survival	Surv Bonus	Bullet Dmg	Bullet Bonus	Ram Dmg * 2	Ram Bonus	1sts	2nds
1st	sample.Fire	164295 (57%)	35000	7000	106096	16196	2	0	701	299
2nd	agh.reinforced.ReinforcedLearningRobotLoa	121985 (43%)	14950	2990	95547	8432	66	0	300	700

#### vs Veloci Robot - 36/1000 wygranych

Rank	Robot Name	Total Score	Survival	Surv Bonus	Bullet Dmg	Bullet Bonus	Ram Dmg * 2	Ram Bonus	1sts	2nds
1st	sample.VelociRobot	181190 (83%)	48200	9640	84818	16724	19572	2237	964	36
2nd	agh.reinforced.ReinforcedLearningRobotLoa	37071 (17%)	1800	360	33779	525	606	0	36	964

#### vs Spin Bot - 1/1000 wygranych

Rank	Robot Name	Total Score	Survival	Surv Bonus	Bullet Dmg	Bullet Bonus	Ram Dmg * 2	Ram Bonus	1sts	2nds
1st	sample.SpinBot	177739 (87%)	49950	9990	97109	19472	1159	59	999	1
2nd	agh.reinforced.ReinforcedLearningRobotLoa	25581 (13%)	50	10	25359	27	134	0	1	999

# Dziękuję za uwagę