## Project 1

## February 23, 2018

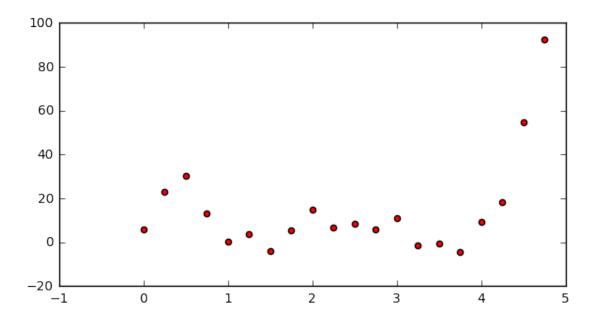
## 1 Problem: Find the best degree 5 polynomial that fits the data from the file datafile.npy.

Let

$$C(a_0,\ldots,a_5) = \sum_{i=0}^{N} (y_i - p(x_i))^2 =$$

where

$$p(x_i) = a_0 + a_1 x_i + a_2 x_i^2 + a_3 x_i^3 + a_4 x_i^4 + a_5 x_i^5$$



The partial derivatives of *C* is as follows:

 $\nabla C = \left(\frac{\partial C}{\partial a_0}, \frac{\partial C}{\partial a_1}, \frac{\partial C}{\partial a_2}, \frac{\partial C}{\partial a_3}, \frac{\partial C}{\partial a_4}, \frac{\partial C}{\partial a_5}\right)$ 

length = norm(vec)

unitVec = np.zeros(len(vec))
for i in range(len(unitVec)):

$$\frac{\partial C}{\partial a_0} = \sum_{i=0}^{N} -2(y_i - p(x_i)) \cdot 1$$

$$\frac{\partial C}{\partial a_1} = \sum_{i=0}^{N} -2(y_i - p(x_i)) \cdot x_i$$

$$\frac{\partial C}{\partial a_2} = \sum_{i=0}^{N} -2(y_i - p(x_i)) \cdot x_i^2$$

$$\frac{\partial C}{\partial a_3} = \sum_{i=0}^{N} -2(y_i - p(x_i)) \cdot x_i^3$$

$$\frac{\partial C}{\partial a_4} = \sum_{i=0}^{N} -2(y_i - p(x_i)) \cdot x_i^4$$

$$\frac{\partial C}{\partial a_5} = \sum_{i=0}^{N} -2(y_i - p(x_i)) \cdot x_i^5$$

Or simply

$$= \left(\sum_{i=0}^{N} -2 \cdot (y_i - p(x_i)), \sum_{i=0}^{N} -2x_i \cdot (y_i - p(x_i)), \sum_{i=0}^{N} -2x_i^2 \cdot (y_i - p(x_i)), \sum_{i=0}^{N} -2x_i^3 \cdot (y_i - p(x_i)), \sum_{i=0}^{N} -2x_i^4 \cdot (y_i - p(x_i)), \sum_{i=0}^{N} -2x_i^5 \cdot (y_i - p(x_i))\right)$$
In [7]: def cost\_gradient(constants):
 mygrad = np.zeros(len(constants))
 for j in range(len(constants)):
 summation = 0
 for point in data:
 summation += (p(point[0], constants) - point[1])\*point[0]\*\*j
 mygrad[j] = summation
 return mygrad

In [8]: def norm(vec):
 length = 0
 for i in range(len(vec)):
 length += vec[i]\*\*2
 return length\*\*(1.0/2)

In [9]: def normalized(vec):

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unitVec[i] = vec[i] / length
           return unitVec
In [10]: def multSeq(h,vec):
            newVec = np.zeros(6)
            for i in range(len(newVec)):
                newVec[i] = vec[i] * h
            return newVec
In [11]: \#x_{old} is the list of constants
        x_old = np.zeros(6)
        h = 0.01 \# step size
        tolerance = 0.001
        maxIterations = 5000
        t = 1
        x_new = np.zeros(6)
In [12]: for i in range(len(x_new)):
            x_new[i] = x_old[i] + multSeq(-h,normalized(cost_gradient(x_old)))[i]
In [13]: while t < maxIterations and</pre>
        (abs(x_new[0] - x_old[0]) + abs(x_new[1] - x_old[1]) + abs(x_new[2] - x_old[2]) +
         abs(x_new[3] - x_old[3]) + abs(x_new[4] - x_old[4]) + abs(x_new[5] - x_old[5])
        ) > tolerance:
            for i in range(len(x_new)):
                x_old[i] = x_new[i]
            for j in range(len(x_new)):
                x_new[j] = x_old[j] - multSeq(h, normalized(cost_gradient(x_old)))[j]
            t += 1
        print(x_new)
In [14]: if i == maxIterations:
            print("Maximum iteration was reached.")
        print("The best degree 5 polynomial has coefficients: ")
        for i in range(len(x_new)):
            print("a" + str(i) + ": " + str(x_new[i]))
        x = np.linspace(0,5,1001)
        y = p(x, x_new)
        fig = plt.figure()
        axes = fig.add_axes([0.1, 0.1, 0.9, 0.7])
        axes.plot(x,y)
        axes.scatter(data[:,0],data[:,1],c="r");
```

The best degree 5 polynomial has coefficients:

a0: 0.0803225404923 a1: 0.0645872156651 a2: 0.0470622772964 a3: -0.0668432941729 a4: -0.383896909967 a5: 0.11123817405

## Out[14]:

