

# Assignment 3: Part 1

COMP SCI 2ME3 and SFWR ENG 2AA4

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# Constants Module

## Module

Constants

## Uses

N/A

## Syntax

### Exported Constants

MAX\_X = 180 *//dimension in the x-direction of the problem area*

MAX\_Y = 160 *//dimension in the y-direction of the problem area*

TOLERANCE = 5 *//space allowance around obstacles*

VELOCITY\_LINEAR = 15 *//speed of the robot when driving straight*

VELOCITY\_ANGULAR = 30 *//speed of the robot when turning rad*

### Exported Access Programs

none

## Semantics

### State Variables

none

### State Invariant

none

# Point ADT Module

## Template Module

PointT

## Uses

Constants

## Syntax

### Exported Types

PointT = ?

### Exported Access Programs

Routine name	In	Out	Exceptions
PointT	real, real	PointT	InvalidPointException
xcrd		real	
ycrd		real	
dist	PointT	real	

## Semantics

### State Variables

*xc*: real

*yc*: real

### State Invariant

none

### Assumptions

The constructor PointT is called for each abstract object before any other access routine is called for that object. The constructor cannot be called on an existing object.

## Access Routine Semantics

PointT( $x, y$ ):

- transition:  $xc, yc := x, y$
- output:  $out := self$
- exception  $exc := ((\neg(0 \leq x \leq \text{Constants.MAX\_X}) \vee \neg(0 \leq y \leq \text{Constants.MAX\_Y})) \Rightarrow \text{InvalidPointException})$

xcrd():

- output:  $out := xc$
- exception: none

ycrd():

- output:  $out := yc$
- exception: none

dist( $p$ ):

- output:  $out := \sqrt{(self.xc - p.xc)^2 + (self.yc - p.yc)^2}$
- exception: none

## Region Module

### Template Module

RegionT

### Uses

PointT, Constants

### Syntax

#### Exported Types

RegionT = ?

#### Exported Access Programs

Routine name	In	Out	Exceptions
RegionT	PointT, real, real	RegionT	InvalidRegionException
pointInRegion	PointT	boolean	

### Semantics

#### State Variables

*lower\_left*: PointT //coordinates of the lower left corner of the region

*width*: real //width of the rectangular region

*height*: real //height of the rectangular region

#### State Invariant

None

#### Assumptions

The RegionT constructor is called for each abstract object before any other access routine is called for that object. The constructor can only be called once.

## Access Routine Semantics

RegionT( $p, w, h$ ):

- transition:  $lower\_left, width, height := p, w, h$
- output:  $out := self$
- exception  $exc := ((\neg(p.xcrd() + w \leq \text{Constants.MAX\_X}) \vee \neg(p.ycrd() + h \leq \text{Constants.MAX\_X})) \Rightarrow \text{InvalidRegionException})$

pointInRegion( $p$ ):

- output:  $out := \exists(i : \mathbb{N}, j : \mathbb{N} \mid i \in [0..w] \wedge j \in [0..h] : p.dist(pointT(i, j)) \leq \text{Constants.TOLERANCE})$
- exception: none

## Generic List Module

### Generic Template Module

GenericList(T)

### Uses

N/A

### Syntax

#### Exported Types

GenericList(T) = ?

#### Exported Constants

MAX\_SIZE = 100

#### Exported Access Programs

Routine name	In	Out	Exceptions
GenericList		GenericList	
add	integer, T		FullSequenceException, InvalidPositionException
del	integer		InvalidPositionException
setval	integer, T		InvalidPositionException
getval	integer	T	InvalidPositionException
size		integer	

### Semantics

#### State Variables

$s$ : sequence of T

#### State Invariant

$|s| \leq \text{MAX\_SIZE}$

## Assumptions

The `GenericList()` constructor is called for each abstract object before any other access routine is called for that object. The constructor can only be called once.

## Access Routine Semantics

`GenericList()`:

- transition:  $self.s := \langle \rangle$
- output:  $out := self$
- exception: none

`add( $i, p$ )`:

- transition:  $s := s[0..i-1] || \langle p \rangle || s[i..|s|-1]$
- exception:  $exc := (|s| = \text{MAX\_SIZE} \Rightarrow \text{FullSequenceException} \mid i \notin [0..|s|] \Rightarrow \text{InvalidPositionException})$

`del( $i$ )`:

- transition:  $s := s[0..i-1] || s[i+1..|s|-1]$
- exception:  $exc := (i \notin [0..|s|-1] \Rightarrow \text{InvalidPositionException})$

`setval( $i, p$ )`:

- transition:  $s[i] := p$
- exception:  $exc := (i \notin [0..|s|-1] \Rightarrow \text{InvalidPositionException})$

`getval( $i$ )`:

- output:  $out := s[i]$
- exception:  $exc := (i \notin [0..|s|-1] \Rightarrow \text{InvalidPositionException})$

`size()`:

- output:  $out := |s|$
- exception: none



## **Path Module**

### **Template Module**

PathT is GenericList(PointT)

## **Obstacles Module**

### **Template Module**

Obstacles is GenericList(RegionT)

## **Destinations Module**

### **Template Module**

Destinations is GenericList(RegionT)

## **SafeZone Module**

### **Template Module**

SafeZone extends GenericList(RegionT)

### **Exported Constants**

MAX\_SIZE = 1

# Map Module

## Module

Map

## Uses

Obstacles, Destinations, SafeZone

## Syntax

### Exported Access Programs

Routine name	In	Out	Exceptions
init	Obstacles, Destinations, SafeZone		
get_obstacles		Obstacles	
get_destinations		Destinations	
get_safeZone		SafeZone	

## Semantics

### State Variables

*obstacles* : Obstacles

*destinations* : Destinations

*safeZone* : SafeZone

### State Invariant

none

### Assumptions

The access routine `init()` is called for the abstract object before any other access routine is called. If the map is changed, `init()` can be called again to change the map.

### Access Routine Semantics

`init(o, d, sz):`

- transition: *obstacles*, *destinations*, *safeZone* := *o*, *d*, *sz*

- exception: none

get\_obstacles():

- output: *out := obstacles*
- exception: none

get\_destinations():

- output: *out := destinations*
- exception: none

get\_safeZone():

- output: *out := safeZone*
- exception: none

# Path Calculation Module

## Module

PathCalculation

## Uses

Constants, PointT, RegionT, PathT, Obstacles, Destinations, SafeZone, Map

## Syntax

### Exported Access Programs

Routine name	In	Out	Exceptions
is_validSegment	PointT, PointT	boolean	
is_validPath	PathT	boolean	
is_shortestPath	PathT	boolean	
totalDistance	PathT	real	
totalTurns	PathT	integer	
estimatedTime	PathT	real	

## Semantics

### State Variables

none

### State Invariant

none

### Assumptions

none

### Access Routine Semantics

is\_validSegment ( $p1, p2$ ):

- output:  $out := \forall(i : \mathbb{N} | i \in [0..Map.get\_obstacles.size-1] : Map.getval(i).pointInRegion(p1..p2))$

- exception: none

is\_validPath ( $p_1, p_2$ ):

- output:
- exception: none

is\_shortestPath ( $p$ ):

- output:  $out := \forall (i : \mathbb{N} | i \in [0..Map.get\_destinations.size-1] \wedge Map.get\_destinations[i].is\_validPath : p.dist(Map.get\_destinations[i].getval) < p.dist(Map.get\_destinations[i+1].getval))$
- exception: none

totalDistance ( $p$ ):

- output:  $out := +(i : \mathbb{Z} | 0 \leq i \leq (p.size() - 1) : p.getval(i).dist(p.getval(i+1)))$
- exception: none

totalTurns ( $p$ ):

- output:  $out := +(i : \mathbb{N} | i \in [0..p.size] \wedge (p[i].ycrd - p[i-1].ycrd)/(p[i].xcrd - p[i-1].xcrd) \neq 0 : 1)$
- exception: none

estimatedTime ( $p$ ):

- output:  $out := +(i : \mathbb{N} | i \in [0..p.size-1] \wedge (p[i].ycrd - p[i-1].ycrd)/(p[i].xcrd - p[i-1].xcrd) = 0 : 1) + p.totalTurns$
- exception: none

# 1 Critique of Module Interface