# **Model Based Design Training**

### **COURSE CONTENT:**

### 1. Introduction to MATLAB/Simulink

- a. History and Introduction
- b. Applications in different domains
- c. Overall Architecture and System Requirements

#### Simulink:

Configuration setting:

- Solver

**Basic Blocks:** 

Saturation block

Deadzone block

Relay/hysterias

Detect change/detect increase/decrease

Wrap to zero

Edge detection /rising/falling/either/function call

**Rate Limiter** 

Mux/demux

Bus creater/bus selector

Multiport switch

On delay/off delay

Lookup Tables & etc.

Simulink.parameter

Simulink.signal

Mpt.parameter and Mpt.signal

### **Subsytems:**

Atomic/non automic

Conditionally executed Subsystem (enable ,triggered ,enable triggered)

Variant subsystem

#### **Stateflow:**

Truth table

Temporal logic

Decomposition

History junction

Stateflow junction

Connective junction

Decision patterns

Model Advisor (MAAB, MISRA, ISO 26262)

**Code Generation**: Embedded Codder

## 2. User Interface and Basics

- a. MATLAB UI
- b. Basic Commands and usage
- c. Simulink UI
- d. Basic Simulink Usage
- e. State Flow and other toolbox. (Real time example assignment's)

### 3. MATLAB Variables

### 4. MATLAB and Sequences

# 5. User Defined Functions and Operators

6. Basic Plotting with MATLAB 7. Vectors and Matrices using MATLAB 8. Debugging with MATLAB 9. Block diagrams of Signal and Systems 11. Problem Solving with Applications using MATLAB/Simulink/StateFlow: i. Engineering Domain (Automotive + Control Systems + Electronics + **Electrical Engg + Computer Science Engineering)** ii. Financial Domain iii. Data Analysis and applications 12. Introduction to Embedded Systems and MATLAB/Simulink. 13. Fixed point Datatype / Flotting type Datatype 14. Testing: a.MIL/SIL b.SLDV(Simulink Design Verifier) c. Coverages (execution, Decision, Condition, MCDC) 15. Basics of Autosar. 16. Polyspace. 17. Basics of communication protocols.