

**Government College of Engineering, Amravati**  
(An Autonomous Institute of Government of Maharashtra)

**B. Tech. (Computer Science & Engineering)**

**Summer – 2017**

**Course Code: CSU802**

**Course Name: Digital Signal Processing**

**Time: 2 Hr. 30min.**

**Max. Marks: 60**

**Instructions to Candidate**

- 1) All questions are compulsory.
- 2) Assume suitable data wherever necessary and clearly state the assumptions made.
- 3) Diagrams/sketches should be given wherever necessary.
- 4) Use of logarithmic table, drawing instruments and non-programmable calculators is permitted.
- 5) Figures to the right indicate full marks.

**1 Solve any Two**

- a What do u understand the by the term signal and signal processing? Explain the basic element of DSP system **6M**
- b Determine the given system are causal or non-causal, linear or non-linear, time variant or time-invariant **6M**

i.  $Y(n)=x(-n+2)$

ii.  $Y(n)=x(2n)$

*Contd..*



- c Determine the convolution sum of two sequence 6M  
 $X(n)=\{3,3,1,2\}$  and  $h(n)=\{1,2,1,2\}$  using  
 mathematical method

- 2 a Determine the response  $y(n), n \geq 0$  of the system 6M  
 describe by the second order difference equation  
 $Y(n)-3y(n-1)-4y(n-2)=x(n)+2x(n-1)$  when input  
 sequence  $x(n)=4^n u(n)$

- b Determine the cross correlation sequence  $r_{xy}(l)$  of 6M  
 the sequence

$$X(n)=\{\dots, 0, 0, 2, -1, 3, 7, 1, 2, -3, 0, 0, \dots\} \text{ and}$$

$$Y(n)=\{\dots, 0, 0, 1, -1, 2, -2, 4, 1, -2, 5, 0, 0, \dots\}$$

- 3 a State and prove the following property of Discrete 4M  
 Fourier transform

1. Circular time shift of a sequence

- b Given  $x(n)=\{0, 1, 2, 3, 4, 5, 6, 7\}$  find  $x(k)$  using DIT 8M  
 FFT algorithm

**Solve any Two**

- 4 a What is ROC ? determine the z transform of 6M  
 following signal

i.  $X(n)=(\cos \omega_0 n) u(n)$

ii.  $X(n)=(\sin \omega_0 n) u(n)$

- b Determine the zero state response of the system 6M

$$X(n)=1/2 y(n-1)+4x(n)+3x(n-1) \text{ to the input}$$

ence 6M  
ising

$X(n) = e^{j\omega_0 n} u(n)$  what is steady-state response of the system

- c Determine the inverse z transform of the following system using partial fraction expansion 6M

$$X(z) = \frac{1}{1 - 1.5z^{-1} + 0.5z^{-2}}$$

Solve any Two

- 5 a Differentiate between FIR and IIR filter with example. 6M

- b Convert the analog filter with the system function. 6M

$$H_a(s) = \frac{s + 0.1}{(s + 0.1)^2 + 9}$$

Into digital IIR filter by means of impulse invariance method

- c Draw the Direct form I and Direct Form II structure for IIR filter 6M

$$H(Z) = \frac{b_0 + b_1 z^{-1} + b_2 z^{-2}}{1 + \alpha_1 z^{-1} + \alpha_2 z^{-2}}$$

rete 4M

IT 8M

6M

n 6M