

# Signals & Systems :-

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## Unit - I (Signal Analysis)

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▷ Signal:- A Signal is a function of independent variables that carry some information.

→ A signal is a physical quantity that varies with time, space (or) any other independent variable by which information can be conveyed.

$$x(t) = f(x_1, x_2, x_3, \dots, x_n)$$

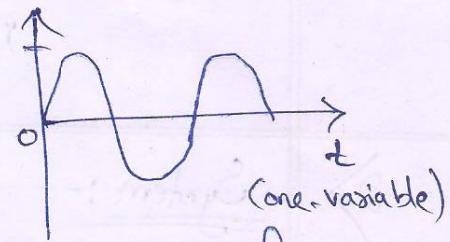
$x_i$  = time, space, temperature ..etc., → (independent variables)

e.g. - Audio, video, ECG (Electrocardiogram), AC Power Supply Signal.

→ One Dimensional Signal:-

If a signal depends on one-variable is called one-dimensional signal.

e.g. - voice, AC signal.



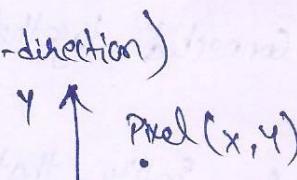
→ Two Dimensional Signal:-

If a signal depends on two variables is called two dimensional

signal depends on two variables (x-direction & y-direction)

e.g. - Pixel has two variable (x-direction & y-direction)

e.g. - Picture, video signal



→ Multi Dimensional Signal:-

If the signal depends 1 (or) more than two variables

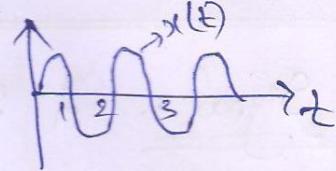
is called multi dimensional signal.

e.g. - speed of the wind.

## 1.1) Classification of Signals:-

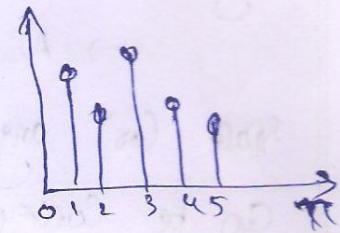
(a) Continuous time signals:- (or) Analog Signal  
 It is defined at every instant of time  $\rightarrow x(t)$   
 (or) at continuous range

e.g. time  
 $A \sin(\omega t)$  and  $a+bt$



(b) Discrete time signals:-  
 defined at discrete instant of time

e.g. Sampling period  
 $x(nT) = x(t) \Big|_{t=nT}$



T = Sampling interval

n = integer range (-∞ to ∞)

(c) Digital signals:-

It is also an discrete time signal with take the infinite values '0' & '1'

Digital signal (or) Binary signal

$x(n) = 0 \text{ (or)} 1 \quad n = (-\infty \text{ to } \infty)$   
 $n = -2, -1, 0, 1, 2 \dots$

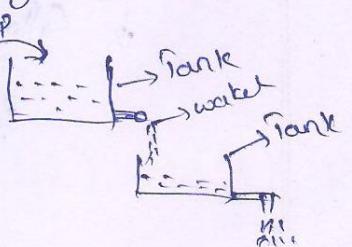
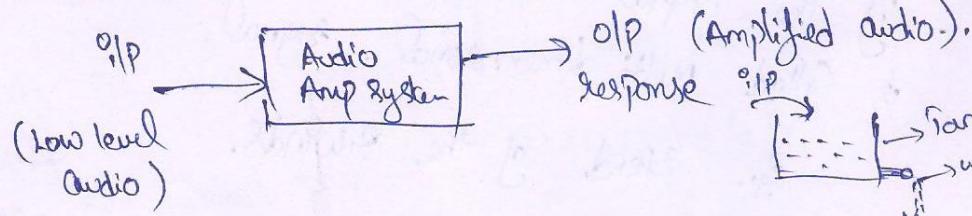
## 2)

### System :-

It is a set of elements (or) functional blocks that are connected together and produce an o/p in response to i/p signal

(or)  
 An Entity that processes a set of i/p signal to yield another set of o/p signal.

e.g. An audio amplifier, Attenuator, TV set etc.



(3)

Analogy:-

→ Signals are represented in terms of orthogonal functions.

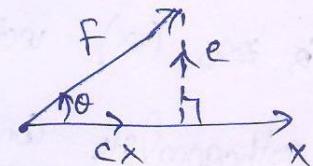
### ① Orthogonality Concept in vectors:-

All signals are basically vectors.

vector is represented in terms of its co-ordinates.

Let us consider vector 'f' and another vector 'x'. Then projection of vector along other vector is

The dot product of vectors f and x is given



$$f \cdot x = |f| |x| \cos \theta. \rightarrow \textcircled{a}$$

$\theta \rightarrow$  angle b/w  $f \& x$

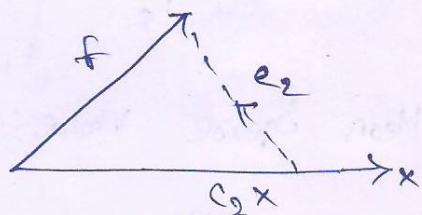
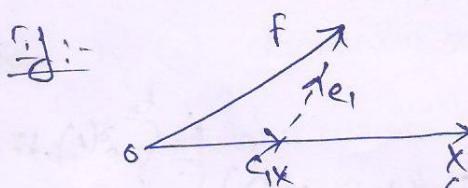
$c_x \rightarrow$  Component of vector f along x (or) projection of 'f' on 'x'

Using vector addition

$$f = c_x + e \rightarrow \textcircled{b}$$

'e' → used vector if it is minimum only when it is perpendicular.

$$\text{to } x. \quad f = c_1 x + e_1$$



(Here  $e_1$  &  $e_2$  are than e)

The component of f along 'x' is  $c_x$  which is given as  $|f| \cos \theta$

$$\therefore c|x| = |f| \cos \theta \rightarrow \textcircled{c}$$

Multiplying both the sides by  $|x|$

$$c|x|^2 = |f| \cdot |x| \cdot \cos \theta \rightarrow \textcircled{d}$$

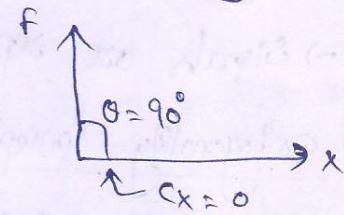
dot product of vector  $f \& x$

$$c = \frac{f \cdot x}{|x|^2} = \frac{f \cdot x}{x \cdot x} \left\{ \begin{array}{l} \because x \cdot x \& f \cdot x \text{ are vector product} \\ x \text{ and } x \text{ cannot get cancelled.} \end{array} \right. \rightarrow \textcircled{e}$$

→ when 'f' is perp to x, f will not have component along x. (i)

x - because  $\theta = 90^\circ$

$$f \cdot x = |f| \cdot |x| \cdot \cos 0^\circ \rightarrow (f) \\ = |f| \cdot |x| \cos 90^\circ \quad \{ \because \cos 90^\circ = 0 \}$$



$$f \cdot x = 0$$

∴ the vector f & x are said to be orthogonal if their dot Product is zero (or) vectors are orthogonal if they are perp.

## ② Orthogonality Concept in Signals :-

Consider a signal  $f(t)$  to be represented in terms of  $x(t)$

over an interval  $t_1 \leq t \leq t_2$

From vector addition :  $c x(t) + e(t) \quad t_1 \leq t \leq t_2 \rightarrow (1)$   
 Eq (1.b)  $\rightarrow f(t) = c x(t) + e(t)$   
 $e(t) = f(t) - c x(t)$

Energy of  $e(t)$  will be

$$E_e = \int_{t_1}^{t_2} e^2(t) \cdot dt \rightarrow (2)$$

Mean Square Value of  $e(t)$  will be

$$\bar{e}^2(t) = \frac{1}{t_2 - t_1} \int_{t_1}^{t_2} e^2(t) \cdot dt \quad (\text{from eq } (1)) \quad (\because \int_{t_1}^{t_2} e^2(t) \cdot dt = E_e)$$

$$\bar{e}(t) = \frac{E_e}{t_2 - t_1}$$

$$\therefore E_e = \int_{t_1}^{t_2} [f(t) - c x(t)]^2 \cdot dt. \rightarrow (3)$$

Value of 'c' should be selected such that  $E_e$  will be minimum

It can be obtained by differentiating  $E_e$  w.r.t to  $c$  and Equating it

to zero

$$\rightarrow \text{for minimum } E_e, \frac{dE_e}{dc} = 0 \rightarrow (4)$$

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From Eq. ③  $\int_{t_1}^{t_2} f(t) \cdot x(t) dt = 0$ 

$$\text{i.e. } \frac{d}{dc} \left[ \int_{t_1}^{t_2} [f(t) - c x(t)]^2 dt \right] = 0$$

$$\rightarrow (a-b)^2 \Rightarrow a^2 - 2ab + b^2$$

$$\Rightarrow \underbrace{\frac{d}{dc} \int_{t_1}^{t_2} f^2(t) dt}_{\text{independent of } c} - \frac{d}{dc} \int_{t_1}^{t_2} 2c f(t) \cdot x(t) dt + \frac{d}{dc} \int_{t_1}^{t_2} c^2 x^2(t) dt = 0 \rightarrow ⑤$$

*'c' to it will be zero*

$$\Rightarrow -2 \int_{t_1}^{t_2} f(t) \cdot x(t) dt + 2c \int_{t_1}^{t_2} x^2(t) dt = 0$$

$$\Rightarrow 2c \int_{t_1}^{t_2} x^2(t) dt = 2 \int_{t_1}^{t_2} f(t) \cdot x(t) dt$$

$$c = \frac{\int_{t_1}^{t_2} f(t) \cdot x(t) dt}{\int_{t_1}^{t_2} x^2(t) dt} \rightarrow ⑥$$

The same expression can be obtained for minimum value of  $\int_{t_1}^{t_2} E(t) dt$ .

from Eq. ⑥ denominator represents Energy of  $x(t)$ , which cannot be zero.

Hence numerator must be zero to make 'c' zero. If 'c' is zero, there

will be no component of  $f(t)$  along  $x(t)$ .

$\rightarrow f(t)$  and  $x(t)$  are said to be orthogonal over interval  $(t_1, t_2)$  i.e.

$$\int_{t_1}^{t_2} f(t) \cdot x(t) dt = 0$$

Similarly if  $f(t)$  and  $x(t)$  are complex signals then they are orthogonal over interval  $[t_1, t_2]$  if.

$$\int_{t_1}^{t_2} f(t) \cdot x^*(t) dt = 0 \quad (\text{or}) \quad \int_{t_1}^{t_2} f^*(t) \cdot x(t) dt = 0$$

Complex Conjugate  
of  $x(t)$

$\hookrightarrow$  Complex conjugate of  $f(x)$ .

Problems:-

(i) Show that the following signals are orthogonal over an interval [0, 1].

$$f(t) = 1 \quad ; \quad x(t) = \sqrt{3}(1-2t)$$

Sol w.r.t. orthogonal if for

$$\int_{t_1}^{t_2} f(t) \cdot x(t) \, dt = 0$$

$$\Rightarrow \int_{t_1}^{t_2} f(t) \cdot x(t) \, dt = \int_{t_1}^{t_2} 1 (\sqrt{3})(1-2t) \, dt$$

$$= \int_0^1 \sqrt{3} \, dt - \int_0^1 2\sqrt{3}t \, dt$$

$$= \sqrt{3} \left[ t \right]_0^1 - 2\sqrt{3} \left[ \frac{t^2}{2} \right]_0^1$$

$$\sqrt{3}[1-0] - 2\sqrt{3}\left[\frac{1}{2}\right]$$

$$\sqrt{3} - \sqrt{3} = 0 \rightarrow \text{orthogonal}$$

(ii) Fig shows a square wave. Represent this signal by sint. Plot an energy in this representation.

Sol. Square wave be  $f(t)$  and Sine wave be

$$x(t) = \sin t \quad \text{then } f(t) = ?$$

$$f(t) = c \cdot x(t) \\ = c \cdot \sin t \rightarrow \textcircled{a}$$

value of 'c' is given by

$$c = \frac{\int_{t_1}^{t_2} f(t) \cdot x(t) \, dt}{\int_{t_1}^{t_2} x^2(t) \, dt}$$

$$\int_{t_1}^{t_2} f(t) \cdot x(t) \, dt = \int_{2\pi}^0 f(t) \cdot \sin t \, dt$$

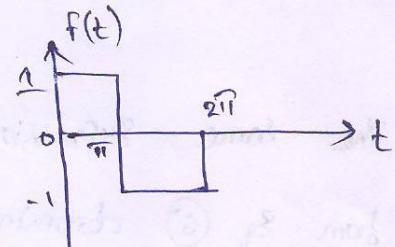
(whole  $f(t) = 1$  to 1)

$$= \int_0^{\pi} 1 \cdot \sin t \, dt + \int_{\pi}^{2\pi} (-1) \cdot \sin t \, dt$$

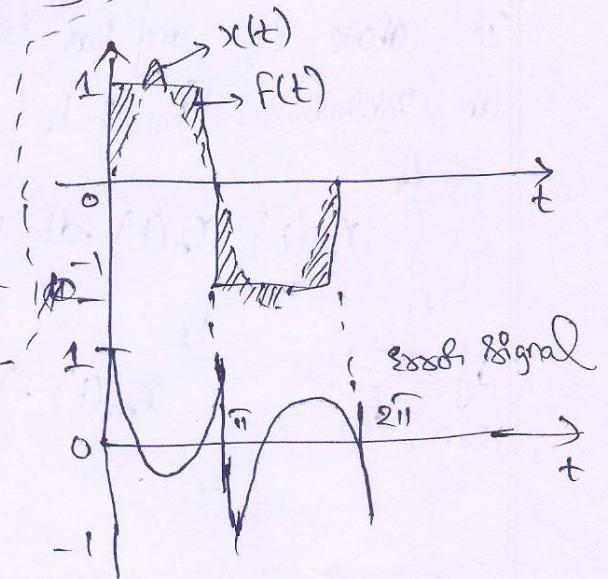
$$= [-\cos t]_0^{\pi} - [-\cos t]_{\pi}^{2\pi} = [\cos 0 - \cos \pi] + [\cos 2\pi - \cos \pi]$$

$$= -(-1-1) + (1-(-1)) = 4$$

$$= 4.$$



$$\begin{aligned}
 & \int_{t_1}^{t_2} x^2(t) dt = \int_0^{2\pi} \sin^2 t dt \quad (\text{where } \sin^2 a = \frac{1-\cos 2a}{2}) \quad (7) \\
 &= \int_0^{2\pi} \left( \frac{1-\cos 2t}{2} \right) dt = \frac{1}{2} \int_0^{2\pi} dt - \frac{1}{2} \int_0^{2\pi} \cos 2t dt \\
 &= \frac{1}{2} [t]_0^{2\pi} - \frac{1}{2} \left[ \frac{\sin 2t}{2} \right]_0^{2\pi} \quad (\text{where } \int_0^{2\pi} \cos 2t dt = \frac{\sin 2t}{2} \Big|_0^{2\pi}) \\
 &= \frac{1}{2} [2\pi - 0] - \frac{1}{2} [\sin 2(2\pi) - \sin 2(0)] \\
 &= \pi - \frac{1}{2} [0 - 0] \\
 \Rightarrow & \pi - 0 \Rightarrow \pi \\
 \therefore C = & \frac{\int_{t_1}^{t_2} f(t) \cdot x(t) dt}{\int_{t_1}^{t_2} x^2(t) dt} = \frac{0}{\pi} \Rightarrow C = 0
 \end{aligned}$$



and ~~each~~  $e(t) = f(t) - C \cdot x(t)$

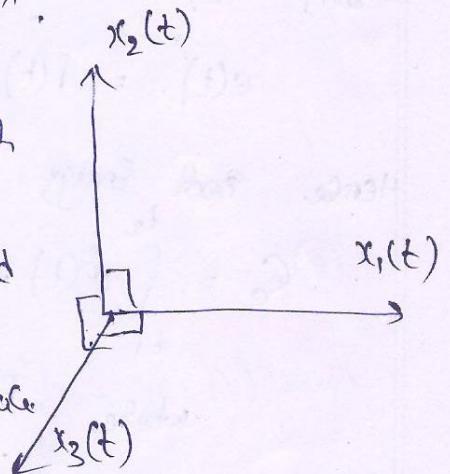
$$e(t) = \cancel{f(t)} - 0 \xrightarrow{\text{cancel}} e(t) = 1$$

### (3) orthogonal signal Space :-

Let  $x_1(t), x_2(t), x_3(t)$  be orthogonal each other

i.e. 3-signals are mutually ~~perp~~ which forms  
3-dimensional signal space which is also called  
orthogonal signal space.

→ which can represent any signal lying in that space.



Note:- There are N-such mutually orthogonal signals i.e.  $x_1(t), x_2(t), \dots, x_n(t)$  then they form N-dimensional orthogonal signal space.

## Signal Approximation using orthogonal functions :-

→ Consider a set of signals which are mutually orthogonal over an interval  $[t_1, t_2]$ ,  $f(t)$  can be given as

$$f(t) \approx c_1 x_1(t) + c_2 x_2(t) + c_3 x_3(t) + \dots + c_N x_N(t)$$

$$f(t) \approx \sum_{n=1}^N c_n x_n(t) \rightarrow (a)$$

In above Eq, any two signal  $x_m(t)$  &  $x_n(t)$  are orthogonal over an interval  $[t_1, t_2]$  i.e.

$$\int_{t_1}^{t_2} x_m(t) \cdot x_n(t) \cdot dt = \begin{cases} 0 & \text{for } m \neq n \\ E_n & \text{for } m = n \end{cases} \rightarrow (b)$$

$$\text{If } \frac{m=n}{E_n} = \int_{t_1}^{t_2} x_m(t) \cdot x_n(t) \cdot dt = \int_{t_1}^{t_2} x_n(t) \cdot x_n(t) \cdot dt$$

$$E_n = \int_{t_1}^{t_2} x_n^2(t) \cdot dt \rightarrow \text{Energy signal.}$$

Error  $e(t)$  in the approximation of Eq is given as

$$e(t) = f(t) - \sum_{n=1}^N c_n x_n(t). \rightarrow (d)$$

Hence error Energy

$$E_e = \int_{t_1}^{t_2} e^2(t) \cdot dt = \int_{t_1}^{t_2} \left[ f(t) - \sum_{n=1}^N c_n x_n(t) \right]^2 \cdot dt \rightarrow (e)$$

where  $E_e$  is sum of  $c_1, c_2, c_3, \dots, c_N$

→ Hence  $E_e$  will be minimized w.r.t to  $c_i$  if

$$\frac{\partial E_e}{\partial c_i} = 0.$$

$$\text{now:- } \frac{\partial}{\partial c_i} \left\{ \int_{t_1}^{t_2} \left[ f(t) - \sum_{n=1}^N c_n x_n(t) \right]^2 \cdot dt \right\} = 0 \rightarrow (f)$$

(9)

$$\frac{\partial}{\partial c_0} \left\{ \int_{t_1}^{t_2} f^2(t) dt - \sum_{n=1}^N c_n f(t) \cdot x_n(t) dt + \int_{t_1}^{t_2} c_n^2 x_n^2(t) dt \right\} = 0 \rightarrow (g)$$

For  $i = 1, 2, 3, \dots, N$  the Eq is executed.  
The first integration term is independent of  $c_i$  so its derivative is zero

$$\frac{\partial}{\partial c_i} \left\{ - \int_{t_1}^{t_2} 2c_i f(t) \cdot x_i(t) dt + \int_{t_1}^{t_2} c_i^2 x_i^2(t) dt \right\} = 0 \rightarrow (h)$$

$$\therefore -2 \int_{t_1}^{t_2} f(t) \cdot x_i(t) dt + 2c_i \int_{t_1}^{t_2} x_i^2(t) dt = 0$$

$$c_i = \frac{\int_{t_1}^{t_2} f(t) \cdot x_i(t) dt}{\int_{t_1}^{t_2} x_i^2(t) dt}$$

where  $i = 1, 2, \dots, N \rightarrow (i)$

w.r.t  $\int_{t_1}^{t_2} x_i^2(t) dt = E_i \rightarrow \text{Energy}$

$$\Rightarrow c_i = \frac{1}{E_i} \int_{t_1}^{t_2} f(t) \cdot x_i(t) dt \quad \rightarrow (j)$$

5) Mean Square Error :- for orthogonal functions :-

The error energy is given by Eq no:- 4.e

$$E_e = \int_{t_1}^{t_2} \left[ f(t) - \sum_{n=1}^N (c_n \cdot x_n(t)) \right]^2 dt \rightarrow (1)$$

$$E_e = \int_{t_1}^{t_2} f^2(t) dt - 2 \sum_{n=1}^N \int_{t_1}^{t_2} f(t) \cdot c_n \cdot x_n(t) dt + \int_{t_1}^{t_2} \sum_{n=1}^N c_n^2 x_n^2(t) dt \rightarrow (2)$$

Integration & Summation interchanged (from  $m=n$ ) concept

$$E_e = \int_{t_1}^{t_2} f^2(t) dt - 2 \sum_{n=1}^N c_n \int_{t_1}^{t_2} f(t) \cdot x_n(t) dt + \sum_{n=1}^N c_n^2 \int_{t_1}^{t_2} x_n^2(t) dt \rightarrow (3)$$

$$E_e = \int_{t_1}^{t_2} f^2(t) dt - 2 \sum_{n=1}^N c_n (f(t) \cdot x_n(t)) dt + \sum_{n=1}^N c_n^2 E_n$$

(because  $\int_{t_1}^{t_2} f(t) \cdot x_n(t) dt = c_n E_n$ )

$$\int_{t_1}^{t_2} x_n^2(t) dt = E_n$$

(4)

$$= \int_{t_1}^{t_2} f^2(t) dt - 2 \sum_{n=1}^N c_n^2 \cdot g_n + \sum_{n=1}^N c_n^2 \cdot g_n$$

$$= \int_{t_1}^{t_2} f^2(t) dt - \sum_{n=1}^N c_n^2 \cdot g_n \rightarrow (5)$$

The mean square error and error energy are related as

$$\overline{e^2(t)} = \frac{E_e}{t_2 - t_1} \Rightarrow \frac{1}{t_2 - t_1} \left[ \int_{t_1}^{t_2} f^2(t) dt - \sum_{n=1}^N c_n^2 g_n \right] \rightarrow (6)$$

$\therefore \sum_{n=1}^N c_n^2 g_n$  is always positive so if  $E_e \rightarrow 0$  as  $N \rightarrow \infty$ ,  $\rightarrow (7)$

### 6) Closed (or) Complete Set of Orthogonal functions:-

→ Mean square error approaches to zero as number of terms  $c_n^2 g_n$  are made infinite under below condition.

with  $\overline{e^2(t)} = 0$  as  $N \rightarrow \infty$

from Eq (5.6)  $\overline{e^2(t)} = \frac{1}{t_2 - t_1} \left[ \int_{t_1}^{t_2} f^2(t) dt - \sum_{n=1}^N c_n^2 g_n \right]$

$$0 = \frac{1}{t_2 - t_1} \left[ \int_{t_1}^{t_2} f^2(t) dt - \sum_{n=1}^N c_n^2 g_n \right] \rightarrow (8)$$

$$\Rightarrow \int_{t_1}^{t_2} f^2(t) dt = \sum_{n=1}^N c_n^2 g_n \rightarrow (9)$$

from  $f(t) = \sum_{n=1}^N c_n x_n(t)$  when  $N \rightarrow \infty \rightarrow (10)$

$$\therefore f(t) = \sum_{n=1}^{\infty} c_n x_n(t) \quad (11) \quad \left\{ \text{Generalized Fourier Series} \right\}$$

→ It is said to be closed (or) complete set if there exists no other function  $P(t)$  for which  $\int_{t_1}^{t_2} P(t) \cdot x_n(t) dt = 0 \rightarrow (12)$

→ If  $P(t)$  exists and above integral is zero then  $P(t)$  must be member of set  $\{x_n(t)\}$   $\rightarrow (13)$

∴ for complete set function  $f(t) = c_1 x_1(t) + c_2 x_2(t) + c_3 x_3(t) + \dots \rightarrow (14)$

$$c_i = \frac{\int_{t_1}^{t_2} f(t) \cdot x_i(t) dt}{\int_{t_1}^{t_2} x_i^2(t) dt} = \frac{1}{E_i} \int_{t_1}^{t_2} f(t) \cdot x_i(t) dt \rightarrow (15)$$

(11)

## 7) Orthogonality in Complex functions:-

Let set of signals  $x_1(t), x_2(t), x_3(t) \dots$  are complex then those signals are mutually orthogonal if

$$\int_{t_1}^{t_2} x_m(t) \cdot x_n^*(t) dt = \int_{t_1}^{t_2} x_m^*(t) \cdot x_n(t) dt = \begin{cases} 0 & \text{for } m \neq n \\ c_n & \text{for } m = n \end{cases}$$

$\therefore f(t)$  can be expressed as

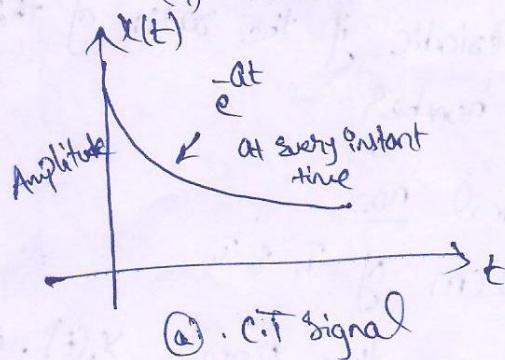
$$f(t) = \sum_{n=1}^{\infty} c_n x_n(t) \quad \text{where } c_n = \frac{1}{f_n} \int_{t_1}^{t_2} f(t) \cdot x_n^*(t) dt$$

$$c_n = \int_{t_1}^{t_2} x_n(t) \cdot x_n^*(t) dt$$

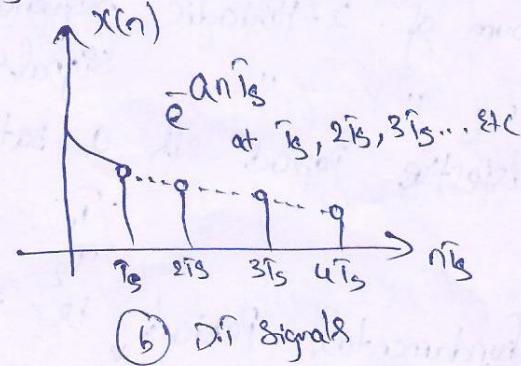
## 8) Classification of Signals :-

2-types depending on independent variable time.

- (i) Continuous time signals (C.T)
- (ii) Discrete time signals (D.T)



(a) C.T Signal



(b) D.T Signal

### ① Periodic & Non-Periodic Signals:-

- A signal is said to be Periodic if it repeats at regular intervals (or) Every time interval  $T$  is called Periodic
- A signal which repeats after

$x(t)$  is called periodic if and only if

$$x(t+T) = x(t) \quad \text{for all } t$$

Time  $\downarrow$  Constant time interval

- The smallest value of  $T$  that satisfies this condition is called fundamental period in sample period of  $x(t)$ .

→ The reciprocal of fundamental Period 'T' is called fundamental

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$$f \text{ of } x(t) \quad f = \frac{1}{T}, \quad ; \text{ angular freq} = \omega = 2\pi f = \frac{2\pi}{T}$$

$$T = \frac{2\pi}{\omega}$$

→ A signal  $x(t)$  for which there is no value of  $T$  satisfying the condition  $x(t+T) = x(t)$  is called non-Periodic (or) aperiodic signal.

Similarly for discrete time signal,  $x(n)$  is said to be Periodic if it satisfies  $x(n+N) = x(n) \quad * \text{integer } N$ .

$$\text{Angular freq} \quad \Omega = \frac{2\pi}{N} \Rightarrow N = \frac{2\pi}{\Omega}$$

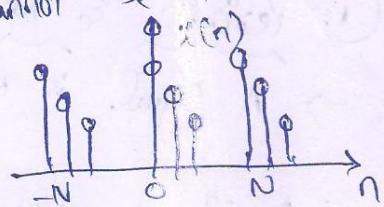
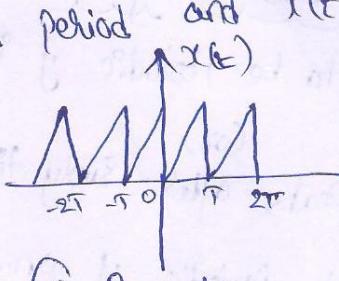
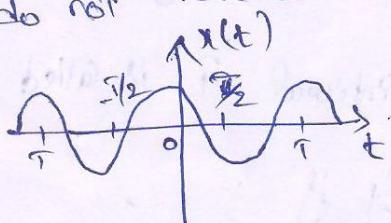
- Note:-
- ① Sum of 2- Continuous time Periodic signals may not be Periodic
  - ② Sum of 2-Periodic sequences is always Periodic
  - ③ " " " signals is Periodic if the ratio of their respective periods is a rational number

$$\frac{T_1}{T_2} = \text{rational no.} \Leftrightarrow$$

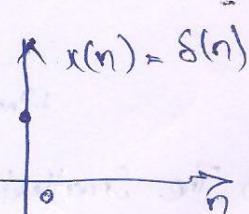
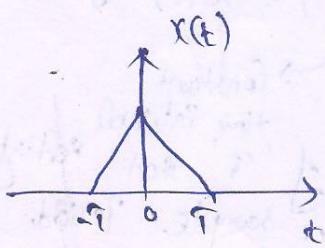
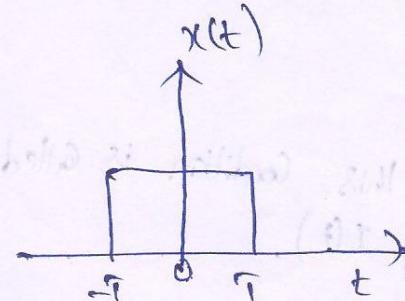
is the LCM of  $T_1$  &  $T_2$

- ④ fundamental period is the LCM of  $T_1$  &  $T_2$

- ⑤ if the ratio  $\frac{T_1}{T_2}$  is an irrational no. then signals  $x_1(t)$  &  $x_2(t)$  do not have a common period and  $x(t)$  cannot be periodic.



a) Periodic



b) Non-Periodic

Even and Odd Signals:-

→ A Signal  $x(t)$  (or)  $x(n)$  is said to be an even signal if

it satisfies the condition

$$x(-t) = x(t) \quad \forall t$$

$$x(-n) = x(n) \quad \forall n$$

→ A Signal  $x(t)$  (or)  $x(n)$  is said to be odd signal if it satisfies

the condition

$$x(-t) = -x(t) \quad \forall t$$

$$x(-n) = -x(n) \quad \forall n$$

→ Even signals are symmetrical about vertical axis (or) time origin while odd signals are asymmetric

↳ Sine

→ A Signal  $x(t)$  (or)  $x(n)$  can be expressed as sum of two signals i.e.

one odd & one even.

$$x(t) = x_e(t) + x_o(t)$$

$$x(n) = x_e(n) + x_o(n)$$

where

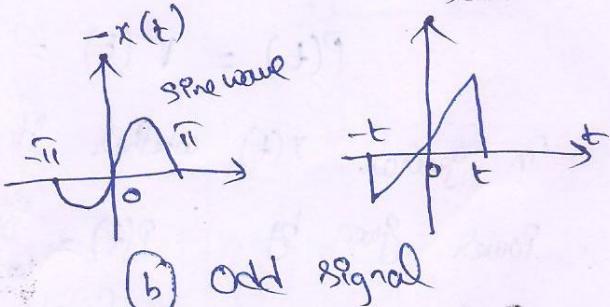
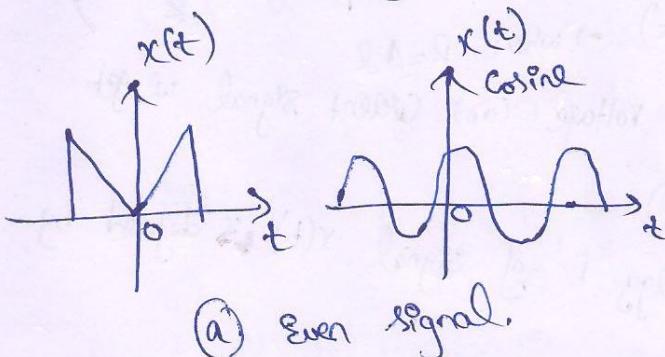
$$x_e(n) = \frac{1}{2} \{ x(n) + x(-n) \} \quad \text{even part}$$

$$x_o(n) = \frac{1}{2} \{ x(n) - x(-n) \} \quad \text{odd part}$$

$$x_e(t) = \frac{1}{2} \{ x(t) + x(-t) \}$$

$$x_o(t) = \frac{1}{2} \{ x(t) - x(-t) \}$$

→ The Product of two even (or) odd signal is an even signal and Product of even signal and odd signal is an odd "



### ③ Deterministic and Random Signals:-

→ A Deterministic signal is the one where no uncertainty occur w.r.t its value at only time

$$x(t) = 100 \sin 50t \text{ (Continuous)}$$

$$x(n) = 100 \sin 50n \text{ (Discrete)}$$

→ Random signal is the one about which there is some degree of uncertainty before it actually occurs.  
e.g. The op of TV/radio receives when tuned to frequency where there is no broadcast.

### ④ Real and Complex Signals:-

→  $x(t)$  is real signal if its value is real number and is a complex signal if its value is a complex number.

Complex signal of  $x(t)$  is  $x_1(t) + j x_2(t)$

$$x(t) = x_1(t) + j x_2(t)$$

$\downarrow$   
real signal and  $j = \sqrt{-1}$

### ⑤ Energy and Power Signal:-

In electrical systems signals may represent current/voltage.

From Power dissipated  $V$  across Resistor 'R' producing current  $i(t)$

Consider a voltage signal  $v(t)$  across resistor is

then Power dissipated in resistor is

$$P(t) = \frac{v^2(t)}{R} = i^2(t) \cdot R$$

$$\left( \because v = iR \right)$$

$$P = \frac{v^2(t)}{R} = \frac{i^2(t) \cdot R^2}{R}$$

$$P(t) = V^2(t) = i^2(t) \rightarrow \text{when } R=1\Omega$$

In general  $x(t)$  whether it is voltage (or) current signal we get

Power given by  $P(t) = x^2(t)$

Total energy (or) normalized energy 'E' of signal  $x(t)$  is defined by

$$E = \lim_{T \rightarrow \infty} \int_{-T/2}^{T/2} |x^2(t)| dt$$

$$\therefore E = \int_{-\infty}^{\infty} |x^2(t)| dt$$

avg Power (or) normalized avg Power  $P$  of signal  $x(t)$  is

$$P = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T/2}^{T/2} |x(t)|^2 dt$$

→ In case of discrete-time signal  $x(n)$  integrals replaced by summation

$$E = \sum_{n=-\infty}^{\infty} |x(n)|^2$$

$$P = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^N |x(n)|^2$$

Note:- The signals for which total energy is finite ( $0 < E < \infty$ ) are called Energy signals. They have zero avg Pow.

e.g. deterministic & non-periodic signals.

→ The signals for which the avg Power is finite ( $0 < P < \infty$ ) are called Power signals. They have infinite energy.

e.g. Random, periodic signal

e.g. Random, periodic signal are mutually exclusive.

→ Both Energy & Power Signal are mutually exclusive.

### Q) Elementary Signals :-

(i) Unit Step function:- Important signal used in many cases.

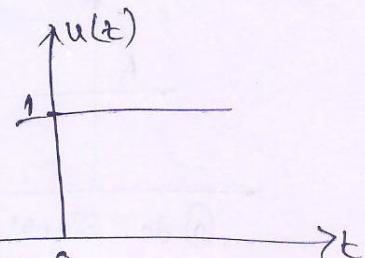
Eg:- Applying brake to an automobile we are applying constant force.

→ If a step function has unity magnitude then it is called unit step

It is defined as  $u(t)$

$$u(t) = 1 \text{ for } t \geq 0$$

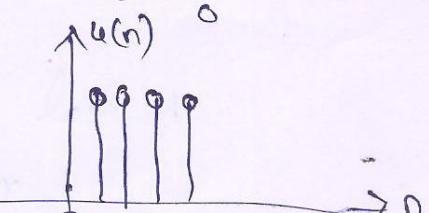
$$u(t) = 0 \text{ for } t < 0$$



### Discrete :-

$$u(n) = 1 \text{ for } n \geq 0$$

$$u(n) = 0 \text{ for } n < 0$$



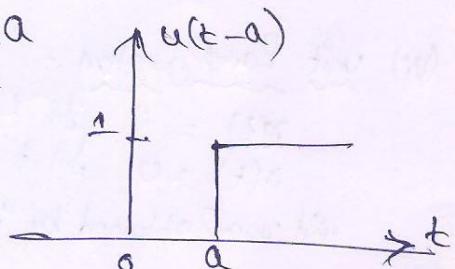
### Shifted Unit Step function :-

$u(t-a)$  is zero if  $t-a < 0$  (or)  $t < a$

$u(t-a)$  is one if  $t-a > 0$  (or)  $t > a$

$$u(t-a) = 1 \text{ for } t > a$$

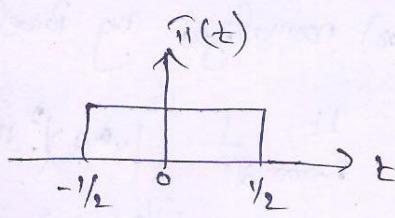
$$u(t-a) = 0 \text{ for } t < a$$



(ii) Rectangular Pulse function:-

$$\Pi(t) = 1 \quad \text{for } |t| \leq \frac{1}{2}$$

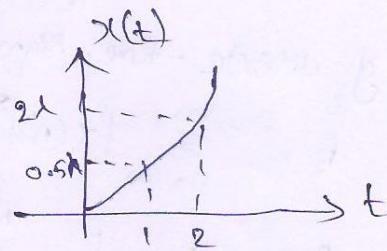
$$= 0 \quad \text{for otherwise}$$



(iii) Parabolic Signal:-

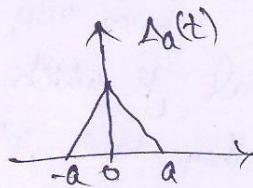
$$x(t) = \frac{1}{2}t^2 \quad \text{for } t > 0$$

$$= 0 \quad ; \quad t < 0$$



(iii) Triangular Pulse function:-

$$\Delta_a(t) = \begin{cases} 1 - \frac{|t|}{a} & |t| \leq a \\ 0 & |t| > a \end{cases}$$



(iv) Sinusoidal Signal:-

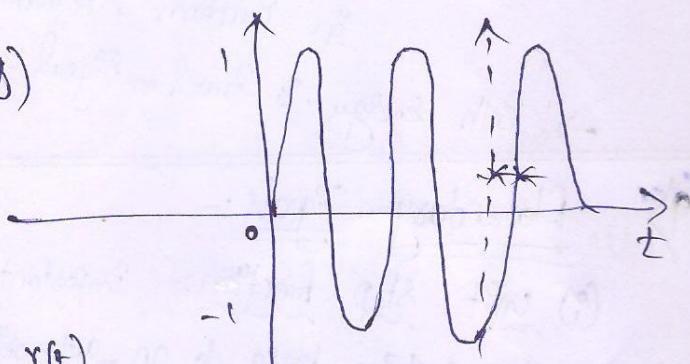
$$x(t) = A \sin(\Omega t + \theta)$$

$\Theta \rightarrow$  phase angle in radians  
 $\Omega \rightarrow$  freq in radians per sec  
 $A \rightarrow$  amplitude.

$$A = 1; \theta = \frac{\pi}{3}$$

Cosinusoidal signal:-

$$x(t) = A \cos(\Omega t + \phi)$$

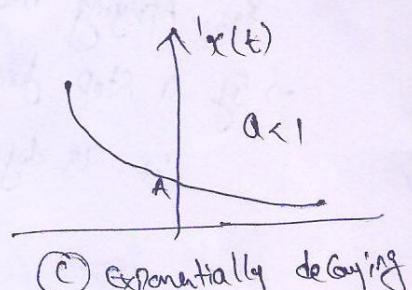
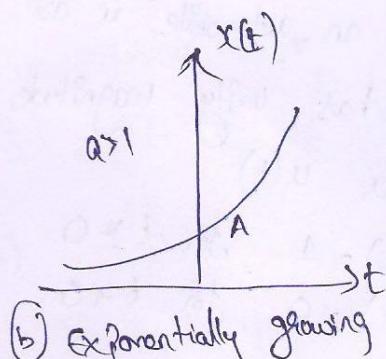


(v) Real Exponential Signal:-

$$x(t) = e^{at}$$

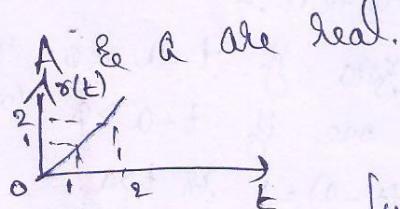
$a = 0$

@ dc - signal



A Real exponential is defined as

$$x(t) = A \cdot e^{at}$$



(vi) Unit Ramp function:-

$$r(t) = t \quad \text{for } t > 0$$

$$= 0 \quad \text{for } t < 0$$

unit ramp obtained by integrating unit step

$$r(t) = \int u(t) dt$$

$$= \int t dt = \frac{t^2}{2}$$

$$r(t) = \frac{t^2}{2}$$

## Complex Exponential Signal:-

General form of complex exponential is

$$x(t) = e^{st} \rightarrow (a) \quad s = \text{complex variable}$$

$$s = \sigma + j\omega$$

$$\Rightarrow x(t) = e^{st} = e^{(\sigma+j\omega)t} = e^{\sigma t} \cdot e^{j\omega t} \rightarrow (b)$$

using Euler's identity

$$e^{j\omega t} = \cos \omega t + j \sin \omega t \rightarrow (c)$$

Substitute (c) in eq (b)

$$x(t) = e^{\sigma t} [\cos \omega t + j \sin \omega t]$$

→ Depending on the values of  $\sigma$  &  $\omega$  we get different signal

(i) If  $\sigma = 0$ ;  $\omega = 0$ ;  $x(t) = 1$ ; pure DC signal

(ii) If  $\sigma = 0$  then  $s = \omega$ ;  $x(t) = e^{\omega t}$  which decay exponentially for  $\sigma < 0$  & grows exponentially for  $\sigma > 0$ .

(iii) If  $\sigma = 0$  then  $s = \pm j\omega$  gives  $x(t) = e^{\pm j\omega t}$  sinusoidal signal

(iv) If  $\sigma > 0$  then finite  $\omega$  we get exponentially decaying sinusoidal.

(v) If  $\sigma < 0$  then finite  $\omega$  we get " growing sinusoidal."

(vi)

(vii) Gaussian signal:-

Defined as

$$x(t) = g_a(t) = e^{-at^2}; -\infty < t < \infty$$

