

UNIT-IIprocess Synchronization &  
Dead locks

=) Process Synchronization:-

b/w 2 processes mutual understanding at the time of Execution.

=) Critical section:-

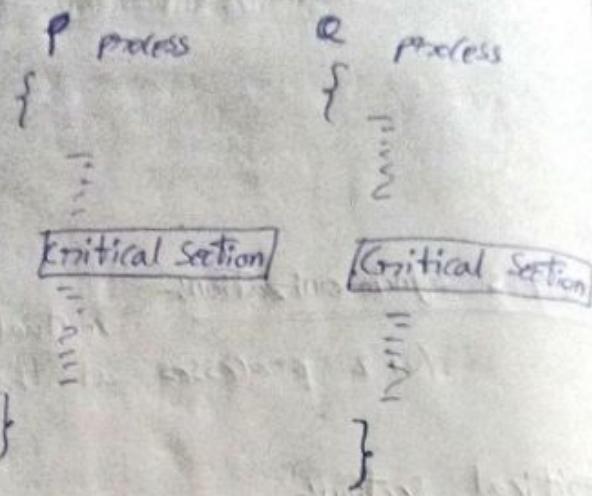
Each & every process will have a small segment of code in it, which is called critical section.

when 1 process executing its critical section, the other processes are not allowed to execute their critical sections, because during the execution of critical section, the following things may happen.

- A variable value may be changed.
- The table may be modified.
- A file may be updated.

If we allow more than one process to execute their critical sections concurrently, then the consistency of data will be affected.

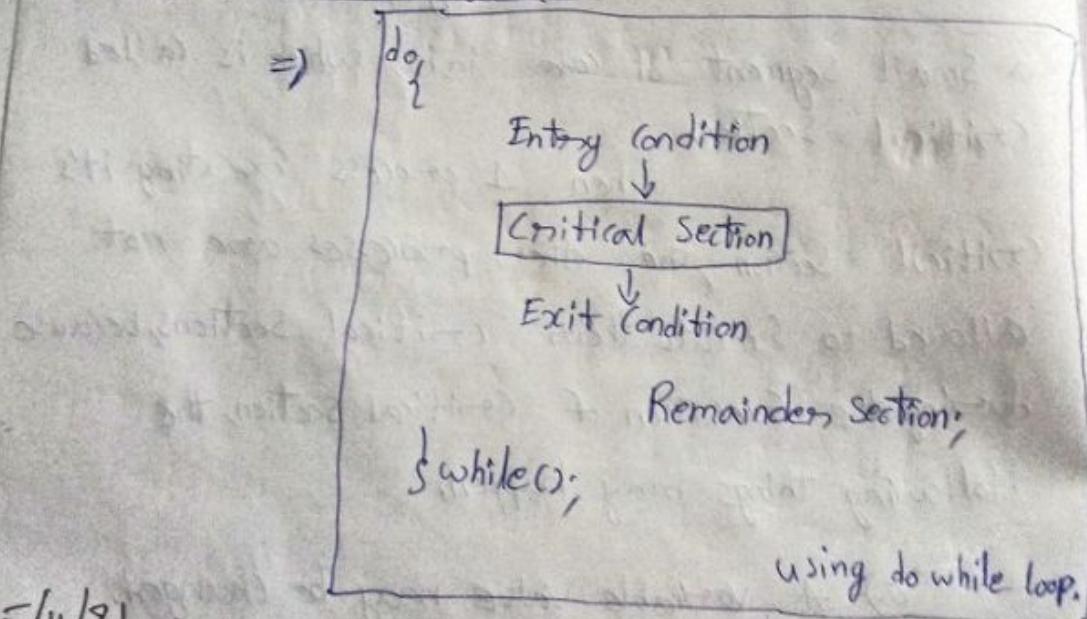
Ex:-



=> peterson's  
Section

2 process can  
is nothing but,  
algorithm ①

=> Critical Section syntax:-



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=> Solution for critical section problem:-

A critical section problem can be solved by the following issues.

- mutual Exclusion
- process
- Bounded Time

The A  
Algorithm:

⇒ peterson's Solution for 2 process critical section problem:-

This peterson's Solution Solves 2 Process critical section problem. It's algorithm is nothing but the combination of the key points of algorithm ① & algorithm ②.

The Algorithm is as follows:-

Algorithm:-

$$\begin{cases} i=0 \\ j=1-1 \end{cases}$$

Boolean flag[2];

int turn;

,

,

,

do

{

flag[i] = true;

turn = i;

while(turn == j && flag[i])

Critical Section

flag[i] = false;

Remainder Section;

} while();

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## => Hardware Synchronization:-

can be solved by using Hardware Synchronization concept.

2 types of Hardware Synchronization's available to solve critical section problem.

- a) Test(), Set() instruction.
- b) Swap Instruction.

### a) Test(), Set() instructions:-

Test() is a fn which checks the status of a process. It returns a boolean value either true (or) false.

Set() is a fn which sets the function process so that one process is allowed to execute Critical Section part & the other process is made wait.

### => Syntax for Test() & Set() Instructions:-

```
do {  
    while( Test and Set(lock))  
        {  
            // Critical Section  
            lock = false;  
            // Remaining Section  
        }  
    } while(1);
```

### b) Swap Instruction

be used for mutual  
declared as

FALSE. And  
as TRUE

=> Syntax

R-T  
S(1,x)  
E-S  
X-

### => Software

-zation, +  
4 tools, AV  
Theme  
tools

## b) Swap Instruction:-

It is a function which can be used for mutual exclusion. A variable (lock) is declared as boolean variable & initialized as FALSE. Another boolean variable 'key' is initialized as TRUE.

## ⇒ Syntax for Swap Instruction:-

```
do
{
    Key = TRUE;
    while(Key == TRUE)
        Swap(lock, key);
    [Critical Section]
    lock = false;
    Remainder Section;
} while();
```

## ⇒ Software Synchronization:-

Like, Hardware Synchronization, there are some Software Synchronization tools, available to solve Critical Section problem.

There are 2 popular Software Synchronization tools available are:-

- Semaphores
- Monitors

## a) Semaphore:-

It is defined as a 'binary variable' which is used to solve Critical Section problem.

It's a Software Synchronization tool, denoted by s.

It uses 2 primitives:-

a) WAIT(s)

b) SIGNAL(s)

The WAIT(s) & SIGNAL(s) primitives can be defined as follows:

WAIT(s): / If  $s = 1$ , then make  $s = 0$ , & allow process to execute its critical section part.  
else

place the process in a queue.

SIGNAL(s):

/ If queue ≠ Empty, remove the process from the queue & allow to execute its critical section part.

/ else

make  $s = 1$ .

Note:-

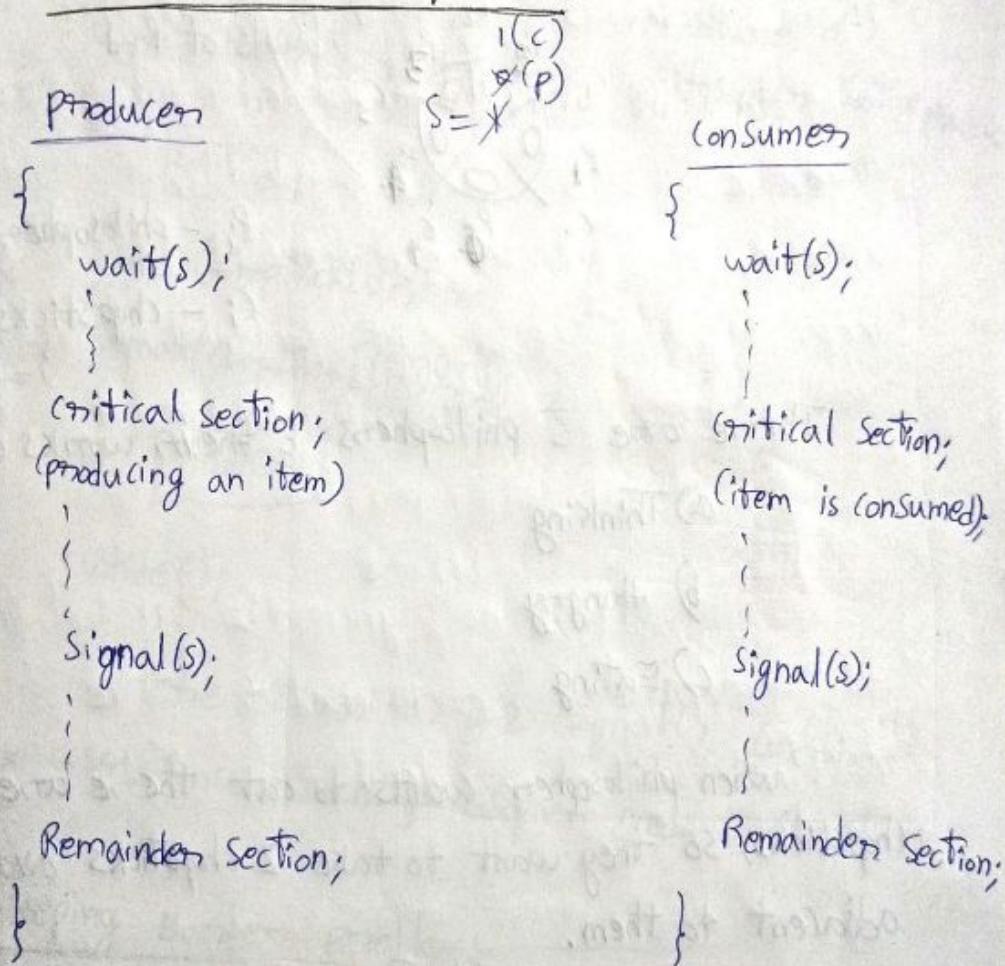
If  $s = 0$ , some process is executing its critical section part.

If  $s = 1$ , no process is executing its critical section part.

## ⇒ Classical problems of Synchronization:-

- Producers - consumers
- Dining - philosophers
- Sleeping Barber

### a) Producers - Consumers problem:-



Producer is a process which produces an item,  
& Consumer is a process which will consume  
the item (called consumer process). In both  
processes, wait(s) is Entry & signal(s) is Exit  
conditions. First, consumer process is ideal.

Scanned By Camera Scanner

Solution for dining philosophers problem using

Semaphore:

Semaphore (chopstick);

for  
f

wait(chopstick[1]);

wait(chopstick[(i+1)%5]);

Eating

Structure of  
philosopher Eating

Signal(chopstick[1]);

Signal(chopstick[(i+1)%5]);

Thinking

}while();

The 2 wait() & 2 signal() conditions  
are used. Since each philosopher needs 2 chopsticks.

9) Sleeping Barbers problem:-

0 0 0

Waiting room

0 1

Barber room

In this problem, there will be a <sup>(inner)</sup> barbers room,  
where only one chair is available.

only one customer at a time. If there is no customer then he will sleep. This works by the Barber shop:-

- a) sleeping
- b) working

If more than one customer comes at a time, if the barber is busy with his work, then others want to wait in a room called waiting room. Hence, the critical section problem is, if customer is there, he will serve, otherwise he will go to sleep. If all chairs are occupied in the waiting room, if a new customer enters, he will leave.

=) monitor:-

It is a <sup>software</sup> synchronization tool, similar to Semaphore, which is used to solve critical section problem.

=) Syntax of a monitor:-

monitors monitor\_name

{ shared variables declarations

procedure1()

{

=====  
body  
=====

procedure2()

{

=====  
body  
=====

procedure\_3()

{

=====  
body  
=====

{ =====

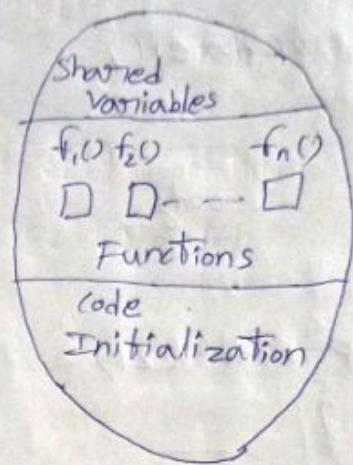
code initialization;

}

A monitor can be divided into 3 parts:-

- shared variables declarations.
- Functions/procedures.
- Code Initialization.

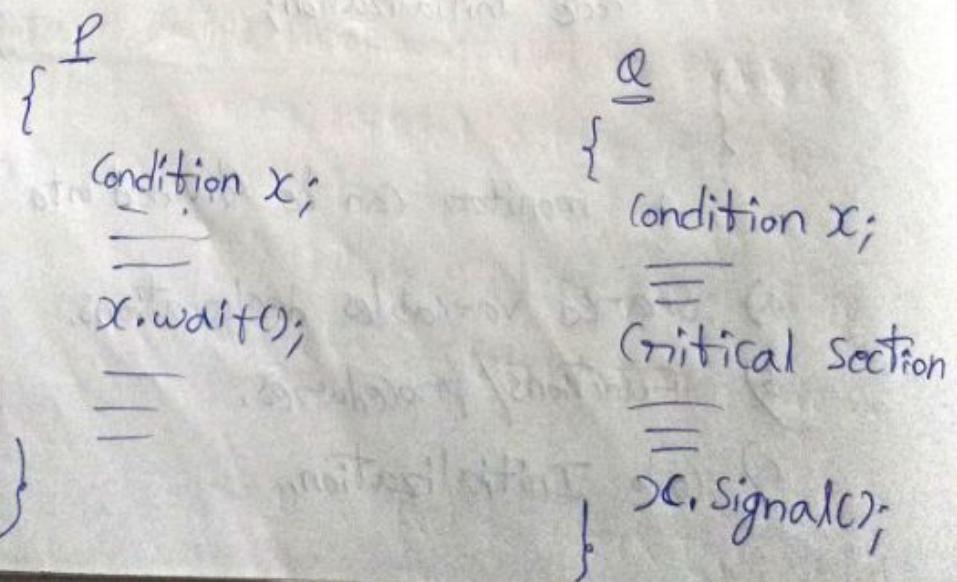
$\Rightarrow$  The schematic view of a monitor.



It uses a special data type called "condition" data type, & the monitor uses 2 primitives to solve the critical section problem.

- a) wait()
- b) signal()

The condition variable will be shared by multiple process.



If a process, for example; "P" executes  
`x.wait()` then the process "P" will be  
Suspended immediately & suspended process  
"P" can be involved when some other  
process executes `x.signal()`

=) Solution for Dining philosophers problem  
using monitors:-

monitor dp

{

enum {thinking, hungry, eating};

enum State[3];

Condition self[5];

Void pick\_up(int i)

{

State[i] = hungry;

test(i);

if(State[i] != eating)

self[i].wait();

}

Void putdown(int i)

{

State[i] = thinking;

test((i+4)%5);

}

test((i+1)%5);

```

void test(int i)
{
    if((state[(i+4)%5] != eating && state[i] == hungry && (state[(i+1)%5] != eat))
    {
        state[i] = eating;
        self[i].signal();
    }
}

void init()
{
    for(i=0; i<5; i++)
    {
        state[i] = thinking;
    }
}

```

⇒ The purpose of above functions are:-

a) pick up():-

This function is used to pickup 2 chopsticks to start(initiate) Eating process.

b) put down():-

This fn is used to put down the chopsticks after eating process.

c) Test():-

This fn is used to check the availability

+ the chop

1/12/21  
⇒

Read

P - Process -

R - Resource -

Each proce

But, R<sub>2</sub>

To complete

R<sub>1</sub> is me

Process

If 'P'

Q. So

But w

Resour

all,

⇒ System

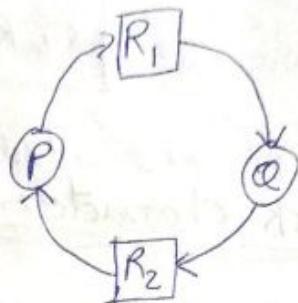
of the chopsticks.

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⇒

### Read locks :-

P - Process - O

R - Resource - □



There are 2 processes for execution.

Each process requires 2 resources  $R_1 \in R_2$ .

But,  $R_2$  is given to  $P \in R_1$  is given to  $Q$ .

To complete the execution of first process  $P$ ,  $R_1$  is required ( $R_2$  is with  $P$ ). To execute the process of  $Q$ ,  $R_2$  is required ( $R_1$  is with  $Q$ ).

If ' $P$ ' completes the execution  $R_2$  can be given to  $Q$ . So,  $Q$  can complete its execution (or) vice versa.

But w/o execution no process will release the resources. So, no process will be executed at all. This situation is called 'dead lock'!

⇒ System models:-

Under normal mode of operation, a process will get resources & use them in

the following way.

- a) Request for Resource
- b, use of Resource
- c, Release of Resource

⇒ dead lock characterization:

Dead lock can be characterized based upon some conditions. Those conditions are called "necessary conditions of a dead lock."

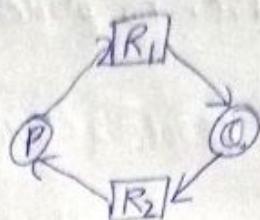
⇒ Necessary conditions of a deadlock:

There are 4 conditions which are called the necessary conditions of a Dead lock.

a) mutual Exclusion:

At least 1 resource should be in non-shareable mode, then mutual understanding b/w 2 processes will not be available, i.e., a hardware resource can't be shared by more processes at a time.

b) Hold & wait:-



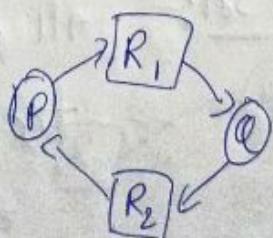
It is a process is holding a resource & is waiting for another resource, this leads to deadlock.

Ex:- 'P' is holding the resource 'R<sub>1</sub>' & waiting for 'R<sub>2</sub>'.

c) No preemption:-

A resource can be released by a process only after completion of its execution.  
At any cost, the process will not preempt the resource before execution.

d) Circular wait:-



$P \rightarrow R_1 \rightarrow Q \rightarrow R_2 \rightarrow P$

There should not be any circular wait in the

System, i.e. no process should wait for other process execution.

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⇒ Resource allocation graph  
(or)

System Resource allocation graph:-

It is a digraph

which is used to find whether a deadlock is available in the system/not.

Resource allocation graph contains

1. A vertex set
2. An Edge set

Again a vertex set contains 2 sets,

a) process set:-

All processes available in the System are available here.

Ex:- Process set: {P<sub>1</sub>, P<sub>2</sub>, P<sub>3</sub>, P<sub>4</sub>}

b) Resource set :-

All resources available in the System are available here.

Ex:- Resource set :  $\{R_1, R_2, R_3\}$

An Edge is made into 2 sets,

a) Assigned Edge:-

Resources allocated to a process is represented in an assigned edge.

Ex:-  $R_1 \rightarrow P_1, R_3 \rightarrow P_4$ , i.e., [Resource  $\rightarrow$  Process]

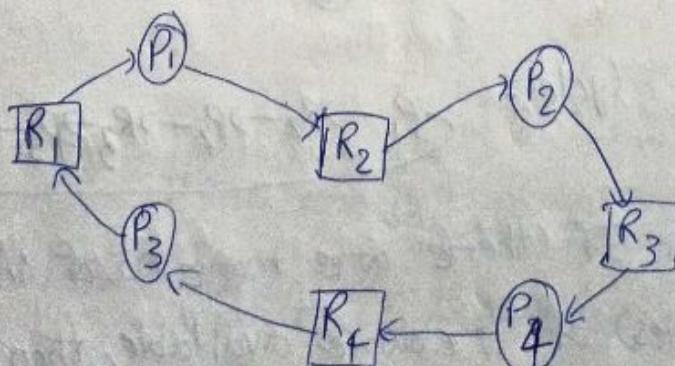
b)

Request Edge:-

Processes waiting for resources are represented in a request edge.

Ex:-  $P \rightarrow R_1, Q \rightarrow R_2$ , i.e., [process  $\rightarrow$  resource]

Example for System Resource Allocation Graph:-



Assigned Edges:-  $R_1 \rightarrow P_1, R_2 \rightarrow P_2, R_3 \rightarrow P_4, R_4 \rightarrow P_3$

Request Edges:-  $P_1 \rightarrow R_2, P_2 \rightarrow R_3, P_4 \rightarrow R_1, P_2 \rightarrow R_1$

Note:-

E P<sub>22</sub>

be E

Sometimes, even there is a cycle,

deadlock may not occur in the Syst.

=> Cycle:-

(P<sub>1</sub> → R<sub>2</sub> → P<sub>2</sub> → R<sub>3</sub> → P<sub>4</sub> → R<sub>4</sub> → P<sub>3</sub> → R<sub>1</sub>)

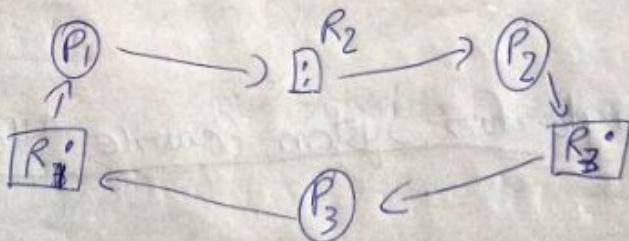
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Dea

If there is a cycle (Combo of assign.

E request edges), then there is a possibility of deadlock available in the System. There is a cycle, so deadlock occurs.

=> A resource allocation graph with cycle but without deadlock:-

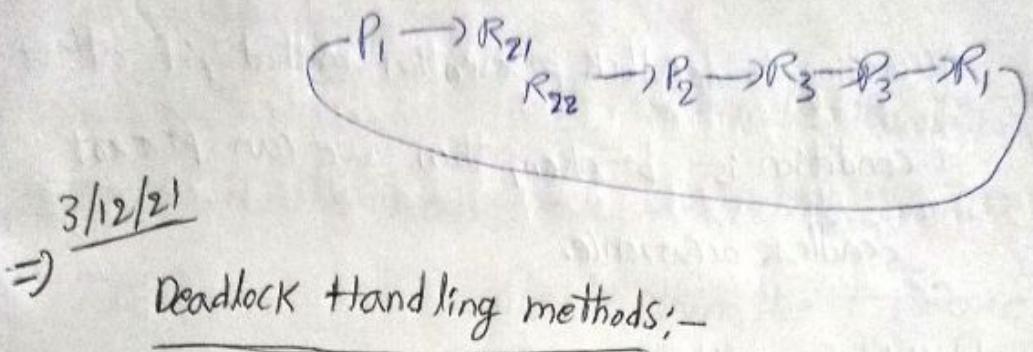


(cycle:-

(P<sub>1</sub> → R<sub>2</sub> → P<sub>2</sub> → R<sub>3</sub> → P<sub>3</sub> → R<sub>1</sub>)

If there are more no. of instances (copies) of resources available, then deadlock can be avoided. Here 2 copies of R<sub>2</sub> i.e. R<sub>21</sub> & R<sub>22</sub>. So, R<sub>21</sub> can be given to P<sub>1</sub>.

$\{ R_{22}$  can be given to  $P_2$  so that cycle can be broken. So, deadlock can be avoided.



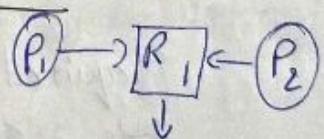
There are 3 popular methods available to handle deadlocks.

The deadlock handling methods are:-

- a) Deadlock prevention
- b) Deadlock Avoidance
- c) Deadlock detection and Recovery

a) Deadlock prevention:-

a) Mutual Exclusion:-



H/W Resource /

Non-shareable

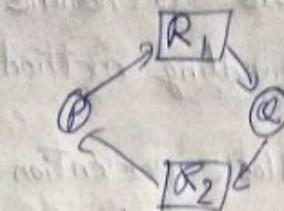
If there are shareable resources like files, mutual understanding b/w 2 processes can exist. If only non-shareable resources are available like printer, then mutual exclusion can't be taken.

Note:-

Deadlock will occur in a system, whenever all 4 conditions exist at a time.

According to deadlock prevention method, if any 1 condition is broken, then we can prevent deadlock occurrence.

b) Hold & wait:-



Hold & wait conditions can be broken by using 2 protocols.

a) Protocol 1:-

This protocol allocates all resources required by a process before it starts its execution.

b) Protocol 2:-

This protocol allocates all resources to a process, when the process is not holding any resource.

### i) No preemption:-

This no preemption condition can be broken by using one protocol.

#### Protocol:-

This protocol allocates to a process, if the resource is available. If the resource is not available, then the resource already given to the process will be taken back.

### d) Circular wait:-

To avoid circular wait, each resource is given a "unique number". Each process is instructed to request for a particular resource in either ascending / descending order. A  $f_n$  may be defined as,

$$F: R_j \rightarrow k$$

$R_i$  - resources

$k$  - integers

If a process requests for a resource with unique number  $z$ , then the next time, the process should request a resource greater than  $z$ .

### Deadlock avoidance:-

#### 1) Safe state:-

dead lock prevention method never allow a deadlock in the system. This deadlock avoidance method will try to avoid the deadlock based on the state of system.

##### a) Safe state:-

System must allocate resources, whenever a process makes a request, then it is in safe state. deadlock never occurs.

##### b) Unsafe state:-

System can't allocate resources, whenever a process makes a request, then the system is in unsafe state. It leads to deadlock, when the system is in unsafe state.

##### c) Safe Sequence:-

The processes in the system can be executed in 1 particular order. So, deadlock won't occur. This sequence is called Safe Sequence.

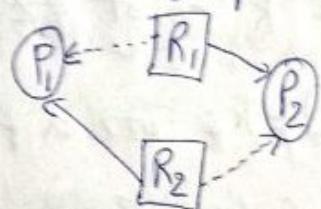
Ex:-  $P_1, P_2, P_3, P_4$  are processes. If they're executed in the order  $P_2, P_3, P_1, P_4$  then

deadlock will not occur. The safe sequence can be represented as  $\langle P_2, P_3, P_1, P_4 \rangle$

There are 2 algorithms for deadlock avoidance method:-

- Resource Allocation graph Algorithm.
- Banker's Algorithm

a) Resource Allocation graph Algorithm:-



Along the assigned edge & Requested Edge, it also have an Edge called "claim edge". This claim edge is represented as

Resource  $\dashrightarrow$  process, i.e.  $R_i \dashrightarrow P_j$ .

meaning of claim edge is now a process is waiting for a resource & in near future, it will be converted into assigned Edge.

b) Banker's Algorithm:-

It requires that a process must inform os that it requires a maximum no. of resources in advance:-

There are 4 different data structures used in Banker's Algorithm:-

- a)  $\text{Available}[j] = k$ ; There are  $k$  no. of resources of type  $R_j$  are available in the system.
- b)  $\text{max}[i,j] = k$ ; A process  $P_i$  requires a maximum of ' $k$ ' no. of resources of type  $R_j$ .
- c)  $\text{Allocated}[i,j] = k$ ; For a process  $P_i$ ,  $k$  no. resources of type  $R_j$  are allocated.
- d)  $\text{Need}[i,j] = k$ ; A process  $P_i$  still needs ' $k$ ' no. of resources of type  $R_j$ .

The need matrix can be calculated as,

$$\text{Need}[i,j] = \text{max}[i,j] - \text{Allocated}[i,j]$$

Banker's Algorithm contains 2 different algorithms:-

- a) Safety Algorithm
- b) Resource Allocation Algorithm

- a) Safety Algorithm:-

Step 1:-

Let  $\text{work} = \text{Available}$  &  
 $\text{Finish}[i] = \text{false}$ , for  $i=0,1,2,\dots$

Step 2:- Find an  $i$  such that

a)  $\text{Finish}[i] = \text{false}$ ;

b)  $\text{Need} \leq \text{work}$ ;

If no such  $i$  exists goto Step 4.

Step 3:-  $\text{work} = \text{work} + \text{allocation};$

$\text{Finish}[i] = \text{true};$

Goto Step 2;

Step 4:- if  $\text{finish}[i] = \text{true}$ , for all  $i$ , then  
System is in Safe State.

This safety algorithm is used to find  
whether System is in Safe/unsafe state.

b) Resource Allocation Algorithm :-

Step 1:- If Request  $\leq$  need goto 2,  
else print error, because  
process exceeds the limit.

Step 2:- If Request  $\leq$  Available goto 3,  
else process has to wait  
because resource isn't available.

Step 3:-  $\text{Available} = \text{Available} - \text{Request}$   
 $\text{Allocation} = \text{Allocation} + \text{Request}$   
 $\text{Need} = \text{Need} - \text{Request}$

Note:- By getting the information Safety algorithm, this resource allocation algorithm will be executed provided Safety Algorithm gives output as "Safe State." ii) Safe sequence P<sub>1</sub>

problem:-

Apply Banker's Algorithm:-

a) Need matrix

b)  $\langle P_1 \ P_3 \ P_4 \ P_2 \ P_0 \rangle$  is safe sequence/na

c) Request from  $P_1$  for  $(1, 0, 2)$

is available immediately/not?

Process	Allocation			max			Available		
	A	B	C	A	B	C	A	B	C
$P_0$	0	1	0	7	5	3	3	3	2
$P_1$	2	0	0	3	2	2			
$P_2$	3	0	2	9	0	2			
$P_3$	2	1	1	2	2	2			
$P_4$	0	0	2	4	3	3			

i) need-matrix:-

$P_0$	7	4	3
$P_1$	1	2	2
$P_2$	6	0	0
$P_3$	0	1	1
$P_4$	4	3	1

ii) Safe Sequence:-

$\langle P_1, P_3, P_4, P_2, P_0 \rangle$

$P_i$	max	A	B	C
		3	2	2
Initial		2	0	0
need		1	2	2

$$\text{need}(P_1) \Rightarrow (1, 2, 2) = \text{request}$$

Available(3, 3, 2)

Satisfied, Request  $\leq$  Available

$P_3$

	A	B	C
max	2	2	1
Initial	2	1	1
need	0	1	1

Available(5, 3, 2)

$$\text{Need}(0, 1, 1) \leq (5, 3, 2)$$

Satisfied

Available(7, 4, 3)

$P_4$

	A	B	C
max	4	3	3
initial	0	0	2
need	4	3	1

$$\text{Request}(4, 3, 1) \leq \text{Available}(7, 4, 3)$$

Satisfied

available(7 4 5).

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dead

P<sub>2</sub>      A    B    C  
max : 9    0    2  
initial : 3    0    2  
need : 6    0    0 (request)

deadlock  
=> Detects

Request(6 0 0) ⊑ available(7 4 5)

Satisfied.

Available(10 4 7)

(a)s

P<sub>0</sub>      A    B    C  
max : 7 5 3  
initial : 0 1 0  
need : 7 4 3 (request)

Request(7 4 3) ⊑ (10 4 7)

Satisfied.

(P<sub>1</sub>, P<sub>3</sub>, P<sub>4</sub>, P<sub>2</sub>, P<sub>0</sub>) is safe resource.

iii)

P<sub>1</sub> : need(1 2 2)

Request(1 0 2)

Request(1 0 2) ⊑ need(1 2 2)

Request(1 0 2) ⊑ Available(3 3 2)

Satisfied. OS will allocate the  
resource immediately.

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## Deadlock detection & Recovery:-

Deadlock

→ Detection:-

2 Algorithms available for deadlock detection,

a) single instance resource Algorithm

b) multiple instance resource Algorithm

a) single instance resource Algorithm:-

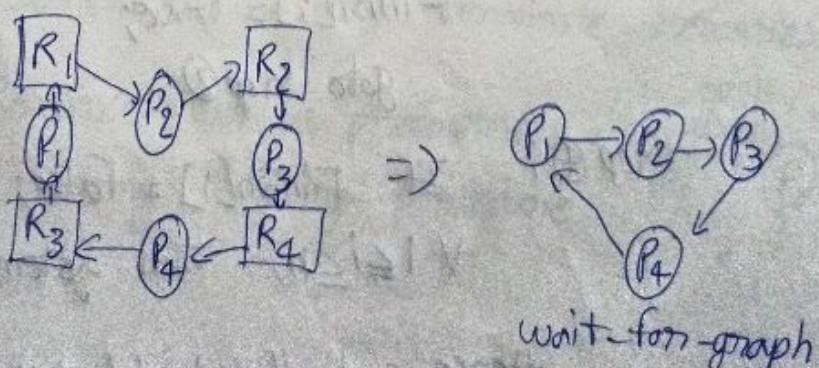
It works

when there is only 1 instance of a resource available we take a resource allocation graph & converted into wait for graph.

wait for graph:-

Resources in the graph once removed, then new graph contains only processes. A graph which contain only (processes) is called wait-for-graph.

If a wait-for-graph consists a cycle then deadlock is detected.



$\rightarrow P_1 \rightarrow P_2 \rightarrow P_3 \rightarrow P_4$

If it contains cycles, then deadlock identified.

b) multiple instance Resource Algorithm:-

when only 1 instance of resource is available,  
Wait-for-graph Algorithm is applicable.

There are 4 data structures available,

- a) Available[i] = k
- b) max[i, j] = k
- c) Allocated[i, j] = k
- d) Need[i, j] = k

Step ①: work = Available

Finish[i] = false; for all 'i'

Step ②: Find an 'i' such that

Finish[i] = false;

Request  $\leq$  work;

If no such i exists, then goto Step ④

Step ③:

work = work + Allocation

Finish[i] = true;

goto step ②

Step ④:

If Finish[i] = false;

$\forall 1 \leq i \leq n$ , then System is in unsafe

Hence, a deadlock is detected.

State.

Deadlock

## Deadlock Recovery:-

from  
2 ways to recover from deadlock,  
once deadlock is detected in the System.

a) process Termination

b) Resource preemption

a) process Termination:-

a) Terminate all processes which cause deadlock occurrence. Disadvantage of this technique is the execution done so far is wasted.

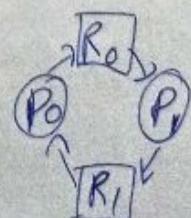
b) Terminate one process at a time till deadlock is removed from the system.

We start deleting 1 process & checked that deadlock is removed. If deadlock is removed, we stop the process. otherwise, we start terminating another process and so on.

b) Resource preemption:-

Instead of terminating processes, sometimes we may terminate resources.

Resources can be preempted using following procedure



a) Identifying a resource:-

out of all resources available  
1 resource will be identified & preempted.

b) Roll back:-

once the identified resource  
(by step 1) is preempted then the process which  
was holding the resource will go to waiting.

c) No starvation:-

If each time, the same  
resource is terminated continuously then process  
will go to waiting state for long time. This  
causes starvation situation. So each time different  
resource should be terminated.

Prevention  
M.F.  
F.I.S.W  
F.R.P  
C.U.C