

As an example, let's write the pseudo code for PIC Activity 2:

```
Initialization (this runs only once when the code starts)
  - Configure TRISA, ANSELA, and LATA (or PORTA) registers
while(1)
{
  - Toggle RAO
  - Wait 250ms
}
```

Draw or write out a program design for this activity. The counter should start at 0 and count to the maximum value, then rollover back to 0. The delay between counts should be about 250ms.

This design is the second deliverable for this activity.

## Pseudocode

Initialization

- configure TRISA, ANSELA, and LATA registers

- Digital >> ANSELA = 0×00

- need to tum on RA7 -> LATA = 1000 0000 = 0×80

- need to Set pins 0 to 8 as outputs -> TRISA = 0×00

while (1)

- toggle each LED such that it represent

a binary counter

- wait 250 ms