

Tidy_Data Code Book

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Original Source & Script

This data set was created using data originally collected from <http://archive.isc.uci.edu/ml/datasets/Human+Activity+Recognition+Using+Smartphones>. For this project, it was downloaded from <https://d396qusza40orc.cloudfront.net/getdata%2Fprojectfiles%2FUCI%20HAR%20Dataset.zip>. The script `run_analysis.R` was run to tidy, subset, and aggregate the data.

Data Characteristics

The data have 180 rows and 82 columns and is 263 KB in size.

Data Variables

“subject” (numeric values 1-30) is the id of the person from whom the data row was collected.

“activity_code” (numeric values 1-6) is the activity id for the action performed while the data row was collected.

“activity_desc” (string values, 6 options) is a descriptive entry of the action performed while the data row was collected. Values can be: LAYING, SITTING, STANDING, WALKING, WALKING_DOWNSTAIRS, WALKING_UPSTAIRS

The remaining columns are considered features.

The features selected for this database come from the accelerometer and gyroscope 3-axial raw signals `tAcc-XYZ` and `tGyro-XYZ`. These time domain signals (prefix ‘t’ to denote time) were captured at a constant rate of 50 Hz. Then they were filtered using a median filter and a 3rd order low pass Butterworth filter with a corner frequency of 20 Hz to remove noise. Similarly, the acceleration signal was then separated into body and gravity acceleration signals (`tBodyAcc-XYZ` and `tGravityAcc-XYZ`) using another low pass Butterworth filter with a corner frequency of 0.3 Hz.

Subsequently, the body linear acceleration and angular velocity were derived in time to obtain Jerk Signals (`tBodyAccJerk-XYZ` and `tBodyGyroJerk-XYZ`). Also the magnitude of these three-dimensional signals were calculated using the Euclidean norm (`tBodyAccMag`, `tGravityAccMag`, `tBodyAccJerkMag`, `tBodyGyroMag`).

Finally, a Fast Fourier Transform (FFT) was applied to some of these signals producing `fBodyAcc-XYZ`, `fBodyAccJerk-XYZ`, `fBodyGyro-XYZ`, `fBodyAccJerkMag`, `fBodyGyroMag`, `gBodyGyroJerkMag`. (Note the ‘f’ to indicate frequency domain signals).

These signals were used to estimate variables of the feature vector for each pattern: ‘-XYZ’ is used to denote 3-axial signals in the X, Y, and Z directions.

`tBodyAcc-XYZ`
`tGravityAcc-XYZ`
`tBodyAccJerk-XYZ`
`tBodyGyro-XYZ`
`tBodyGyroJerk-XYZ`
`tBodyAccMag`
`tGravityAccMag`
`tBodyAccJerkMag`
`tBodyGyroMag`

tBodyGyroJerkMag
fBodyAcc-XYZ
fBodyAccJerk-XYZ
fBodyGyro-XYZ
fBodyAccMag
fBodyAccJerkMag
fBodyGyroMag
fBodyGyroJerkMag

The set of variables that were estimated from the signals are:

mean(): Mean value

std(): Standard deviation

Lastly, the mean of each feature was aggregated to each subject and each activity.