

```
import json
```

```
from typing import List, Optional, Tuple
```

```
import numpy as np
```

```
from pydantic import BaseModel, Field
```

```
from tenacity import retry, stop_after_attempt, wait_exponential
```

```
from swarms.utils.auto_download_check_packages import (
```

```
    auto_check_and_download_package,
```

```
)
```

```
from swarms.utils.lazy_loader import lazy_import_decorator
```

```
from swarms.utils.loguru_logger import initialize_logger
```

```
logger = initialize_logger(log_folder="swarm_matcher")
```

```
class SwarmType(BaseModel):
```

```
    name: str
```

```
    description: str
```

```
    embedding: Optional[List[float]] = Field(
```

```
        default=None, exclude=True
```

```
)
```

```
class SwarmMatcherConfig(BaseModel):
```

```
    model_name: str = "sentence-transformers/all-MiniLM-L6-v2"
```

```
embedding_dim: int = (  
    512 # Dimension of the sentence-transformers model  
)
```

```
@lazy_import_decorator
```

```
class SwarmMatcher:
```

```
    """  
  
    A class for matching tasks to swarm types based on their descriptions.  
  
    It utilizes a transformer model to generate embeddings for task and swarm type descriptions,  
    and then calculates the dot product to find the best match.  
  
    """
```

```
def __init__(self, config: SwarmMatcherConfig):
```

```
    """  
  
    Initializes the SwarmMatcher with a configuration.
```

```
    Args:
```

```
        config (SwarmMatcherConfig): The configuration for the SwarmMatcher.
```

```
    """
```

```
    logger.add("swarm_matcher_debug.log", level="DEBUG")
```

```
    logger.debug("Initializing SwarmMatcher")
```

```
    try:
```

```
        import torch
```

```
    except ImportError:
```

```
auto_check_and_download_package(  
    "torch", package_manager="pip", upgrade=True  
)  
  
import torch
```

```
try:
```

```
    import transformers
```

```
except ImportError:
```

```
    auto_check_and_download_package(  
        "transformers", package_manager="pip", upgrade=True  
    )  
  
    import transformers
```

```
self.torch = torch
```

```
try:
```

```
    self.config = config
```

```
    self.tokenizer = (  
        transformers.AutoTokenizer.from_pretrained(  
            config.model_name  
        )  
    )
```

```
    self.model = transformers.AutoModel.from_pretrained(  
        config.model_name  
    )
```

```
self.swarm_types: List[SwarmType] = []
```

```
logger.debug("SwarmMatcher initialized successfully")
```

except Exception as e:

logger.error(f"Error initializing SwarmMatcher: {str(e)}")

raise

@retry(

stop=stop_after_attempt(3),

wait=wait_exponential(multiplier=1, min=4, max=10),

)

def get_embedding(self, text: str) -> np.ndarray:

"""

Generates an embedding for a given text using the configured model.

Args:

text (str): The text for which to generate an embedding.

Returns:

np.ndarray: The embedding vector for the text.

"""

logger.debug(f"Getting embedding for text: {text[:50]}...")

try:

inputs = self.tokenizer(

text,

return_tensors="pt",

padding=True,

truncation=True,

max_length=512,

```

)

with self.torch.no_grad():

    outputs = self.model(**inputs)

    embedding = (

        outputs.last_hidden_state.mean(dim=1)

        .squeeze()

        .numpy()

    )

    logger.debug("Embedding generated successfully")

    return embedding

except Exception as e:

    logger.error(f"Error generating embedding: {str(e)}")

    raise


def add_swarm_type(self, swarm_type: SwarmType):
    """
    Adds a swarm type to the list of swarm types, generating an embedding for its description.

    Args:
        swarm_type (SwarmType): The swarm type to add.
    """
    logger.debug(f"Adding swarm type: {swarm_type.name}")

    try:

        embedding = self.get_embedding(swarm_type.description)

        swarm_type.embedding = embedding.tolist()

        self.swarm_types.append(swarm_type)

```

```
logger.info(f"Added swarm type: {swarm_type.name}")
```

except Exception as e:

```
logger.error(
```

```
    f"Error adding swarm type {swarm_type.name}: {str(e)}"
```

```
)
```

```
raise
```

```
def find_best_match(self, task: str) -> Tuple[str, float]:
```

```
    """
```

Finds the best match for a given task among the registered swarm types.

Args:

task (str): The task for which to find the best match.

Returns:

Tuple[str, float]: A tuple containing the name of the best matching swarm type and the score.

```
    """
```

```
logger.debug(f"Finding best match for task: {task[:50]}...")
```

```
try:
```

```
    task_embedding = self.get_embedding(task)
```

```
    best_match = None
```

```
    best_score = -float("inf")
```

```
    for swarm_type in self.swarm_types:
```

```
        score = np.dot(
```

```
            task_embedding, np.array(swarm_type.embedding)
```

```
)
```

```

        if score > best_score:

            best_score = score

            best_match = swarm_type

    logger.info(

        f"Best match for task: {best_match.name} (score: {best_score})"

    )

    return best_match.name, float(best_score)
except Exception as e:

    logger.error(

        f"Error finding best match for task: {str(e)}"

    )

    raise

```

```

def auto_select_swarm(self, task: str) -> str:

```

```

    """

```

Automatically selects the best swarm type for a given task based on their descriptions.

Args:

task (str): The task for which to select a swarm type.

Returns:

str: The name of the selected swarm type.

```

    """

```

```

    logger.debug(f"Auto-selecting swarm for task: {task[:50]}...")

```

```

    best_match, score = self.find_best_match(task)

```

```

    logger.info(f"Task: {task}")

```

```
logger.info(f"Selected Swarm Type: {best_match}")

logger.info(f"Confidence Score: {score:.2f}")

return best_match
```

```
def run_multiple(self, tasks: List[str], *args, **kwargs) -> str:

    swarms = []

    for task in tasks:

        output = self.auto_select_swarm(task)

        # Append

        swarms.append(output)

    return swarms
```

```
def save_swarm_types(self, filename: str):
```

```
    """
```

Saves the registered swarm types to a JSON file.

Args:

filename (str): The name of the file to which to save the swarm types.

```
    """
```

```
    try:
```

```
        with open(filename, "w") as f:
```

```
            json.dump([st.dict() for st in self.swarm_types], f)
```

```
        logger.info(f"Saved swarm types to {filename}")
```


except Exception as e:

logger.error(f"Error saving swarm types: {str(e)}")

raise

def load_swarm_types(self, filename: str):

"""

Loads swarm types from a JSON file.

Args:

filename (str): The name of the file from which to load the swarm types.

"""

try:

with open(filename, "r") as f:

swarm_types_data = json.load(f)

self.swarm_types = [

SwarmType(**st) for st in swarm_types_data

]

logger.info(f"Loaded swarm types from {filename}")

except Exception as e:

logger.error(f"Error loading swarm types: {str(e)}")

raise

def initialize_swarm_types(matcher: SwarmMatcher):

logger.debug("Initializing swarm types")

swarm_types = [

```
SwarmType(  
    name="AgentRearrange",  
    description="Optimize agent order and rearrange flow for multi-step tasks, ensuring efficient  
task allocation and minimizing bottlenecks. Keywords: orchestration, coordination, pipeline  
optimization, task scheduling, resource allocation, workflow management, agent organization,  
process optimization",  
),  
SwarmType(  
    name="MixtureOfAgents",  
    description="Combine diverse expert agents for comprehensive analysis, fostering a  
collaborative approach to problem-solving and leveraging individual strengths. Keywords:  
multi-agent system, expert collaboration, distributed intelligence, collective problem solving, agent  
specialization, team coordination, hybrid approaches, knowledge synthesis",  
),  
SwarmType(  
    name="SpreadSheetSwarm",  
    description="Collaborative data processing and analysis in a spreadsheet-like environment,  
facilitating real-time data sharing and visualization. Keywords: data analysis, tabular processing,  
collaborative editing, data transformation, spreadsheet operations, data visualization, real-time  
collaboration, structured data",  
),  
SwarmType(  
    name="SequentialWorkflow",  
    description="Execute tasks in a step-by-step, sequential process workflow, ensuring a logical  
and methodical approach to task execution. Keywords: linear processing, waterfall methodology,  
step-by-step execution, ordered tasks, sequential operations, process flow, systematic approach,
```

staged execution",

),

SwarmType(

name="ConcurrentWorkflow",

description="Process multiple tasks or data sources concurrently in parallel, maximizing productivity and reducing processing time. Keywords: parallel processing, multi-threading, asynchronous execution, distributed computing, concurrent operations, simultaneous tasks, parallel workflows, scalable processing",

),

SwarmType(

name="HierarchicalSwarm",

description="Organize agents in a hierarchical structure with clear reporting lines and delegation of responsibilities. Keywords: management hierarchy, organizational structure, delegation, supervision, chain of command, tiered organization, structured coordination",

),

SwarmType(

name="AdaptiveSwarm",

description="Dynamically adjust agent behavior and swarm configuration based on task requirements and performance feedback. Keywords: dynamic adaptation, self-optimization, feedback loops, learning systems, flexible configuration, responsive behavior, adaptive algorithms",

),

SwarmType(

name="ConsensusSwarm",

description="Achieve group decisions through consensus mechanisms and voting protocols among multiple agents. Keywords: group decision making, voting systems, collective intelligence, agreement protocols, democratic processes, collaborative decisions",

```
# ),  
]
```

```
for swarm_type in swarm_types:  
    matcher.add_swarm_type(swarm_type)  
  
logger.debug("Swarm types initialized")
```

```
@lazy_import_decorator
```

```
def swarm_matcher(task: str, *args, **kwargs):
```

```
    """
```

```
    Runs the SwarmMatcher example with predefined tasks and swarm types.
```

```
    """
```

```
    config = SwarmMatcherConfig()
```

```
    matcher = SwarmMatcher(config)
```

```
    initialize_swarm_types(matcher)
```

```
    # matcher.save_swarm_types(f"swarm_logs/{uuid4().hex}.json")
```

```
    swarm_type = matcher.auto_select_swarm(task)
```

```
    logger.info(f"{swarm_type}")
```

```
    return swarm_type
```

```
# from typing import List, Tuple, Dict

# from pydantic import BaseModel, Field

# from loguru import logger

# from uuid import uuid4

# import chromadb

# import json

# from tenacity import retry, stop_after_attempt, wait_exponential


# class SwarmType(BaseModel):

#     """A swarm type with its name, description and optional metadata"""

#     id: str = Field(default_factory=lambda: str(uuid4()))

#     name: str

#     description: str

#     metadata: Dict = Field(default_factory=dict)


# class SwarmMatcherConfig(BaseModel):

#     """Configuration for the SwarmMatcher"""

#     collection_name: str = "swarm_types"

#     distance_metric: str = "cosine" # or "l2" or "ip"

#     embedding_function: str = (

#         "sentence-transformers/all-mpnet-base-v2" # Better model than MiniLM

#     )
```

```
# persist_directory: str = "./chroma_db"

# class SwarmMatcher:

#     """

#     An improved swarm matcher that uses ChromaDB for better vector similarity search.

#     Features:

#     - Persistent storage of embeddings

#     - Better vector similarity search with multiple distance metrics

#     - Improved embedding model

#     - Metadata filtering capabilities

#     - Batch operations support

#     """

#     def __init__(self, config: SwarmMatcherConfig):

#         """Initialize the improved swarm matcher"""

#         logger.add("swarm_matcher.log", rotation="100 MB")

#         self.config = config

#         # Initialize ChromaDB client with persistence

#         self.chroma_client = chromadb.Client()

#         # Get or create collection

#         try:

#             self.collection = self.chroma_client.get_collection(

#                 name=config.collection_name,
```

```

#     )

#     except ValueError:

#         self.collection = self.chroma_client.create_collection(
#             name=config.collection_name,
#             metadata={"hnsw:space": config.distance_metric},
#         )

#     logger.info(
#         f"Initialized SwarmMatcher with collection '{config.collection_name}'"
#     )


#     def add_swarm_type(self, swarm_type: SwarmType) -> None:
#         """Add a single swarm type to the collection"""
#         try:
#             self.collection.add(
#                 ids=[swarm_type.id],
#                 documents=[swarm_type.description],
#                 metadatas=[
#                     {"name": swarm_type.name, **swarm_type.metadata}
#                 ],
#             )
#             logger.info(f"Added swarm type: {swarm_type.name}")
#         except Exception as e:
#             logger.error(
#                 f"Error adding swarm type {swarm_type.name}: {str(e)}"
#             )

```

```

#         raise

#     def add_swarm_types(self, swarm_types: List[SwarmType]) -> None:
#         """Add multiple swarm types in batch"""
#         try:
#             self.collection.add(
#                 ids=[st.id for st in swarm_types],
#                 documents=[st.description for st in swarm_types],
#                 metadatas=[
#                     {"name": st.name, **st.metadata}
#                     for st in swarm_types
#                 ],
#             )
#             logger.info(f"Added {len(swarm_types)} swarm types")
#         except Exception as e:
#             logger.error(
#                 f"Error adding swarm types in batch: {str(e)}"
#             )
#         raise

#     @retry(
#         stop=stop_after_attempt(3),
#         wait=wait_exponential(multiplier=1, min=4, max=10),
#     )
#     def find_best_matches(
#         self,

```



```

#     task: str,

#     n_results: int = 3,

#     score_threshold: float = 0.7,

# ) -> List[Tuple[str, float]]:

#     """

#     Find the best matching swarm types for a given task

#     Returns multiple matches with their scores

#     """

#     try:

#         results = self.collection.query(

#             query_texts=[task],

#             n_results=n_results,

#             include=["metadatas", "distances"],

#         )

#

#         matches = []

#         for metadata, distance in zip(

#             results["metadatas"][0], results["distances"][0]

#         ):

#             # Convert distance to similarity score (1 - normalized_distance)

#             score = 1 - (

#                 distance / 2

#             ) # Normalize cosine distance to [0,1]

#             if score >= score_threshold:

#                 matches.append((metadata["name"], score))

```

```

#         logger.info(f"Found {len(matches)} matches for task")

#         return matches


#     except Exception as e:

#         logger.error(f"Error finding matches for task: {str(e)}")

#         raise


#     def auto_select_swarm(self, task: str) -> str:

#         """

#         Automatically select the best swarm type for a task

#         Returns only the top match

#         """

#         matches = self.find_best_matches(task, n_results=1)

#         if not matches:

#             logger.warning("No suitable matches found for task")

#             return "SequentialWorkflow" # Default fallback


#         best_match, score = matches[0]

#         logger.info(

#             f"Selected swarm type '{best_match}' with confidence {score:.3f}"

#         )

#         return best_match


#     def run_multiple(self, tasks: List[str]) -> List[str]:

#         """Process multiple tasks in batch"""

#         return [self.auto_select_swarm(task) for task in tasks]

```

```

# def save_swarm_types(self, filename: str) -> None:
#     """Export swarm types to JSON"""
#     try:
#         all_data = self.collection.get(
#             include=["metadatas", "documents"]
#         )
#         swarm_types = [
#             SwarmType(
#                 id=id_,
#                 name=metadata["name"],
#                 description=document,
#                 metadata={
#                     k: v
#                     for k, v in metadata.items()
#                     if k != "name"
#                 },
#             )
#             for id_, metadata, document in zip(
#                 all_data["ids"],
#                 all_data["metadatas"],
#                 all_data["documents"],
#             )
#         ]

#         with open(filename, "w") as f:

```

```

#         json.dump(
#             [st.dict() for st in swarm_types], f, indent=2
#         )
#         logger.info(f"Saved swarm types to {filename}")
#     except Exception as e:
#         logger.error(f"Error saving swarm types: {str(e)}")
#         raise

# def load_swarm_types(self, filename: str) -> None:
#     """Import swarm types from JSON"""
#     try:
#         with open(filename, "r") as f:
#             swarm_types_data = json.load(f)
#             swarm_types = [SwarmType(**st) for st in swarm_types_data]
#             self.add_swarm_types(swarm_types)
#             logger.info(f"Loaded swarm types from {filename}")
#     except Exception as e:
#         logger.error(f"Error loading swarm types: {str(e)}")
#         raise

# def initialize_default_swarm_types(matcher: SwarmMatcher) -> None:
#     """Initialize the matcher with default swarm types"""
#     swarm_types = [
#         SwarmType(
#             name="AgentRearrange",

```

```
#         description=""

#         Optimize agent order and rearrange flow for multi-step tasks, ensuring efficient task
allocation

#         and minimizing bottlenecks. Specialized in orchestration, coordination, pipeline
optimization,

#         task scheduling, resource allocation, workflow management, agent organization, and
process optimization.

#         Best for tasks requiring complex agent interactions and workflow optimization.

#         "",

#         metadata={

#             "category": "optimization",

#             "complexity": "high",

#         },

#     ),

#     SwarmType(

#         name="MixtureOfAgents",

#         description=""

#         Combine diverse expert agents for comprehensive analysis, fostering a collaborative
approach

#         to problem-solving and leveraging individual strengths. Focuses on multi-agent systems,

#         expert collaboration, distributed intelligence, collective problem solving, agent
specialization,

#         team coordination, hybrid approaches, and knowledge synthesis. Ideal for complex
problems

#         requiring multiple areas of expertise.

#         "",
```

```
#      metadata={
#          "category": "collaboration",
#          "complexity": "high",
#      },
#  ),
#  SwarmType(
#      name="SpreadSheetSwarm",
#      description="""
#          Collaborative data processing and analysis in a spreadsheet-like environment, facilitating
#          real-time data sharing and visualization. Specializes in data analysis, tabular processing,
#          collaborative editing, data transformation, spreadsheet operations, data visualization,
#          real-time collaboration, and structured data handling. Perfect for data-intensive tasks
#          requiring structured analysis.
#      """,
#      metadata={
#          "category": "data_processing",
#          "complexity": "medium",
#      },
#  ),
#  SwarmType(
#      name="SequentialWorkflow",
#      description="""
#          Execute tasks in a step-by-step, sequential process workflow, ensuring a logical and
#          methodical
#          approach to task execution. Focuses on linear processing, waterfall methodology,
#          step-by-step
```

```

#         execution, ordered tasks, sequential operations, process flow, systematic approach, and
staged

#         execution. Best for tasks requiring strict order and dependencies.

#         "",

#         metadata={"category": "workflow", "complexity": "low"},

#     ),

#     SwarmType(

#         name="ConcurrentWorkflow",

#         description=""

#         Process multiple tasks or data sources concurrently in parallel, maximizing productivity
#         and reducing processing time. Specializes in parallel processing, multi-threading,

#         asynchronous execution, distributed computing, concurrent operations, simultaneous
tasks,

#         parallel workflows, and scalable processing. Ideal for independent tasks that can be

#         processed simultaneously.

#         "",

#         metadata={"category": "workflow", "complexity": "medium"},

#     ),

# ]

# matcher.add_swarm_types(swarm_types)

# logger.info("Initialized default swarm types")


# def create_swarm_matcher(

#     persist_dir: str = "./chroma_db",

```

```
# collection_name: str = "swarm_types",

# ) -> SwarmMatcher:

# """Convenience function to create and initialize a swarm matcher"""

# config = SwarmMatcherConfig(

#     persist_directory=persist_dir, collection_name=collection_name

# )

# matcher = SwarmMatcher(config)

# initialize_default_swarm_types(matcher)

# return matcher
```

```
# # Example usage
```

```
# def swarm_matcher(task: str) -> str:
```

```
#     # Create and initialize matcher
```

```
#     matcher = create_swarm_matcher()
```

```
#     swarm_type = matcher.auto_select_swarm(task)
```

```
#     print(f"Task: {task}\nSelected Swarm: {swarm_type}\n")
```

```
#     return swarm_type
```

```
# # # Example usage
```

```
# # if __name__ == "__main__":
```

```
# #     # Create and initialize matcher
```

```
# #     matcher = create_swarm_matcher()
```



```
# # # Example tasks

# # tasks = [

# #     "Analyze this spreadsheet of sales data and create visualizations",
# #     "Coordinate multiple AI agents to solve a complex problem",
# #     "Process these tasks one after another in a specific order",
# #     "Write multiple blog posts about the latest advancements in swarm intelligence all at once",
# #     "Write a blog post about the latest advancements in swarm intelligence",
# # ]

# # # Process tasks

# # for task in tasks:

# #     swarm_type = matcher.auto_select_swarm(task)

# #     print(f"Task: {task}\nSelected Swarm: {swarm_type}\n")
```