

```
import json

import os

from typing import Dict, Optional

from loguru import logger

from pydantic import BaseModel

import importlib

import subprocess


# Define a Pydantic model to handle JSON output format

class AnnotationResult(BaseModel):

    image_name: str

    annotated_image_path: Optional[str] = None

    detections: list


class GroundedSAMTwo:

    def __init__(

        self,

        ontology_dict: Dict[str, str],

        model_name: str = None,

        grounding_dino_box_threshold: float = 0.25,

        extension: str = "jpg",

        output_dir: Optional[str] = None,

    ):

        """
```

Initialize the GroundedSAMTwo class with a caption ontology and load the model.

:param ontology\_dict: Dictionary for mapping captions to classes, e.g., {"shipping container": "container"}.

:param model\_name: Name of the model to use (default: "Grounding DINO").

:param grounding\_dino\_box\_threshold: Threshold for the bounding box confidence (default: 0.25).

```
"""
```

```
self.ontology_dict = ontology_dict
```

```
self.model_name = model_name
```

```
self.grounding_dino_box_threshold = (  
    grounding_dino_box_threshold
```

```
)
```

```
self.extension = extension
```

```
self.output_dir = output_dir
```

```
self.base_model = None # Model will be loaded lazily
```

```
logger.info(  
    "GroundedSAMTwo initialized with model: {}, box threshold: {}",
```

```
    model_name,
```

```
    grounding_dino_box_threshold,
```

```
    )
```

```
def _install_and_import(self):
```

```
    """
```

```
    Install and import the necessary packages at runtime.
```

```
"""
```

```
try:
```

```
    # Dynamically import required modules
```

```
    global cv2, sv, CaptionOntology, GroundedSAM2
```

```
    cv2 = importlib.import_module("cv2")
```

```
    sv = importlib.import_module("supervision")
```

```
    CaptionOntology = importlib.import_module(
```

```
        "autodistill.detection"
```

```
    ).CaptionOntology
```

```
    GroundedSAM2 = importlib.import_module(
```

```
        "autodistill_grounded_sam_2"
```

```
    ).GroundedSAM2
```

```
except ImportError:
```

```
    logger.warning(
```

```
        "Some packages are missing. Installing required packages: supervision, autodistill,
```

```
autodistill-grounded-sam-2"
```

```
    )
```

```
    subprocess.check_call(
```

```
        [
```

```
            "python",
```

```
            "-m",
```

```
            "pip",
```

```
            "install",
```

```
            "-U",
```

```
            "supervision",
```

```

        "autodistill",
        "autodistill-grounded-sam-2",
    ]
)

# Retry imports after installation
self._install_and_import()

def _load_model(self):
    """
    Lazily load the GroundedSAM2 model.
    """
    if self.base_model is None:
        self._install_and_import() # Install and import required packages
        self.base_model = GroundedSAM2(
            ontology=CaptionOntology(self.ontology_dict),
            # grounding_dino_box_threshold=self.grounding_dino_box_threshold,
        )
        logger.info("GroundedSAM2 model loaded.")

def run(self, input_path: str) -> Optional[str]:
    """
    Annotate an image or label a dataset directory.

    :param input_path: Path to an image or directory of images.
    :return: JSON string output of the annotation results or None.
    """

```

```
self._load_model() # Load the model if not already loaded
```

```
if os.path.isdir(input_path):
```

```
    logger.info("Processing directory: {}", input_path)
```

```
    return self._label_dataset(input_path, self.extension)
```

```
else:
```

```
    logger.info("Processing single image: {}", input_path)
```

```
    return self._annotate_single_image(
```

```
        input_path, self.output_dir
```

```
    )
```

```
def _label_dataset(
```

```
    self, image_dir: str, extension: str = "jpg"
```

```
) -> str:
```

```
    """
```

```
    Label all images in the provided directory.
```

```
:param image_dir: Directory containing images to label.
```

```
:param extension: Image file extension (default: "jpg").
```

```
:return: JSON string of the annotated results for the dataset.
```

```
    """
```

```
    self._load_model()
```

```
    logger.info(
```

```
        "Labeling dataset in directory: {} with extension: {}",
```

```
        image_dir,
```

```
        extension,
```

)

```
self.base_model.label(image_dir, extension=extension)
```

```
# Output results (could be adjusted to store or handle annotations)
```

```
result = {"directory": image_dir, "status": "Labeled"}
```

```
return json.dumps(result, indent=4)
```

```
def _annotate_single_image(
```

```
    self, image_path: str, output_dir: Optional[str] = None
```

```
) -> str:
```

```
    """
```

```
    Annotate a single image and optionally save the annotated image.
```

```
:param image_path: Path to the image.
```

```
:param output_dir: Optional directory to save the annotated image.
```

```
:return: JSON string of the annotation result.
```

```
    """
```

```
    self._load_model()
```

```
    logger.info("Annotating image: {}", image_path)
```

```
    try:
```

```
        # Make predictions and apply non-max suppression
```

```
        results = self.base_model.predict(image_path).with_nms()
```

```
        results = results[results.confidence > 0.3]
```

```
    # Read the image and annotate
```

```

image = cv2.imread(image_path)

mask_annotator = sv.BoxAnnotator()

annotated_image = mask_annotator.annotate(
    image.copy(), detections=results
)

# Display the annotated image
sv.plot_image(image=annotated_image, size=(8, 8))

# Save the annotated image if an output directory is provided
annotated_image_path = None

if output_dir:
    os.makedirs(output_dir, exist_ok=True)
    annotated_image_path = os.path.join(
        output_dir, os.path.basename(image_path)
    )
    cv2.imwrite(annotated_image_path, annotated_image)
    logger.info(
        "Annotated image saved to: {}",
        annotated_image_path,
    )

# Prepare the JSON result using Pydantic
annotation_result = AnnotationResult(
    image_name=os.path.basename(image_path),
    annotated_image_path=annotated_image_path,

```

```
        detections=results.to_dict(
            orient="records"
        ), # Assuming the results object supports conversion to dict
    )
```

```
    # Return the result as a JSON string
```

```
    return annotation_result.json(indent=4)
```

```
except Exception as e:
```

```
    logger.error("Error during image annotation: {}", e)
```

```
    return json.dumps({"error": str(e)})
```

```
# Example usage:
```

```
# ontology = {"shipping container": "container"}
```

```
# runner = GroundedSAMTwo(ontology)
```

```
#
```

```
# # Run on a single image
```

```
# image_path = "path/to/your/image.jpg"
```

```
# json_output = runner.run(image_path, output_dir="annotated_images")
```

```
# logger.info("Annotation result: \n{}", json_output)
```

```
#
```

```
# # Run on a dataset (directory)
```

```
# image_dir = "path/to/your/dataset"
```

```
# json_output = runner.run(image_dir)
```

```
# logger.info("Dataset labeling result: \n{}", json_output)
```