```
import queue
import threading
from typing import List
from swarms.structs.agent import Agent
from pydantic import BaseModel
import os
from swarms.utils.loguru_logger import logger
from swarms.structs.base_swarm import BaseSwarm
import time
class AgentOutput(BaseModel):
  agent_name: str
  task: str
  result: str
  timestamp: str
class SwarmRunMetadata(BaseModel):
  run_id: str
  name: str
  description: str
  agents: List[str]
  start_time: str
  end_time: str
  tasks_completed: int
```

outputs: List[AgentOutput]

class TaskQueueSwarm(BaseSwarm):

....

A swarm that processes tasks from a queue using multiple agents on different threads.

Args:

agents (List[Agent]): A list of agents of class Agent.

name (str, optional): The name of the swarm. Defaults to "Task-Queue-Swarm".

description (str, optional): The description of the swarm. Defaults to "A swarm that processes tasks from a queue using multiple agents on different threads.".

autosave_on (bool, optional): Whether to automatically save the swarm metadata. Defaults to True.

save_file_path (str, optional): The file path to save the swarm metadata. Defaults to "swarm_run_metadata.json".

workspace_dir (str, optional): The directory path of the workspace. Defaults to os.getenv("WORKSPACE_DIR").

return_metadata_on (bool, optional): Whether to return the swarm metadata after running.

Defaults to False.

max_loops (int, optional): The maximum number of loops to run the swarm. Defaults to 1.

Attributes:

agents (List[Agent]): A list of agents of class Agent.

task_queue (queue.Queue): A queue to store the tasks.

lock (threading.Lock): A lock for thread synchronization.

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autosave_on (bool): Whether to automatically save the swarm metadata.
     save_file_path (str): The file path to save the swarm metadata.
     workspace_dir (str): The directory path of the workspace.
     return metadata on (bool): Whether to return the swarm metadata after running.
     max_loops (int): The maximum number of loops to run the swarm.
     metadata (SwarmRunMetadata): The metadata of the swarm run.
  11 11 11
  def __init__(
     self,
     agents: List[Agent],
     name: str = "Task-Queue-Swarm",
        description: str = "A swarm that processes tasks from a queue using multiple agents on
different threads.",
     autosave_on: bool = True,
     save_file_path: str = "swarm_run_metadata.json",
    workspace_dir: str = os.getenv("WORKSPACE_DIR"),
     return_metadata_on: bool = False,
     max loops: int = 1,
     *args,
     **kwargs,
  ):
    super().__init__(
       name=name,
       description=description,
       agents=agents,
```

```
*args,
  **kwargs,
)
self.agents = agents
self.task_queue = queue.Queue()
self.lock = threading.Lock()
self.autosave_on = autosave_on
self.save_file_path = save_file_path
self.workspace_dir = workspace_dir or os.getenv(
  "WORKSPACE_DIR", "agent_workspace"
)
self.return_metadata_on = return_metadata_on
self.max_loops = max_loops
current_time = time.strftime("%Y%m%d%H%M%S")
self.metadata = SwarmRunMetadata(
  run_id=f"swarm_run_{current_time}",
  name=name,
  description=description,
  agents=[agent.agent_name for agent in agents],
  start_time=current_time,
  end_time="",
  tasks_completed=0,
  outputs=[],
)
```

```
def reliability_checks(self):
  logger.info("Initializing reliability checks.")
  if not self.agents:
     raise ValueError(
       "You must provide a non-empty list of Agent instances."
     )
  if self.max_loops <= 0:
     raise ValueError("max_loops must be greater than zero.")
  logger.info(
     "Reliability checks successful. Swarm is ready for usage."
  )
def add_task(self, task: str):
  """Adds a task to the queue."""
  self.task_queue.put(task)
def _process_task(self, agent: Agent):
  """Processes tasks from the queue using the provided agent."""
  while True:
     try:
       task = self.task_queue.get_nowait()
     except queue.Empty:
       break
```

```
try:
  logger.info(
    f"Agent {agent.agent_name} is running task: {task}"
  )
  result = agent.run(task)
  with self.lock:
    self.metadata.tasks_completed += 1
    self.metadata.outputs.append(
       AgentOutput(
         agent_name=agent.agent_name,
         task=task,
         result=result,
         timestamp=time.strftime(
            "%Y-%m-%d %H:%M:%S"
         ),
    )
  logger.info(
    f"Agent {agent.agent_name} completed task: {task}"
  )
  logger.debug(f"Result: {result}")
except Exception as e:
  logger.error(
    f"Agent {agent_agent_name} failed to complete task: {task}"
  )
  logger.exception(e)
```

```
finally:
       self.task_queue.task_done()
def run(self):
  """Runs the swarm by having agents pick up tasks from the queue."""
  logger.info(f"Starting swarm run: {self.metadata.run_id}")
  threads = [
    threading.Thread(
       target=self._process_task, args=(agent,), daemon=True
    )
    for agent in self.agents
  ]
  for thread in threads:
     thread.start()
  self.task_queue.join()
  for thread in threads:
    thread.join()
  self.metadata.end_time = time.strftime("%Y%m%d%H%M%S")
  if self.autosave_on:
    self.save_json_to_file()
```

```
# if self.return_metadata_on:
      return self.metadata.model_dump_json(indent=4)
  #
  return self.export_metadata()
def save_json_to_file(self):
  json_string = self.export_metadata()
  file_path = os.path.join(
    self.workspace_dir, self.save_file_path
  )
  os.makedirs(os.path.dirname(file_path), exist_ok=True)
  with open(file_path, "w") as f:
    f.write(json_string)
  logger.info(f"Metadata saved to {file_path}")
def export_metadata(self):
  return self.metadata.model_dump_json(indent=4)
```