

```
from typing import List, Callable
```

```
from swarms.structs.agent import Agent
```

```
from swarms.utils.loguru_logger import logger
```

```
from swarms.structs.base_swarm import BaseSwarm
```

```
from swarms.structs.conversation import Conversation
```

```
# def select_next_speaker_bid(
```

```
#     step: int,
```

```
#     agents: List[Agent],
```

```
# ) -> int:
```

```
#     """Selects the next speaker."""
```

```
#     bids = []
```

```
#     for agent in agents:
```

```
#         bid = ask_for_bid(agent)
```

```
#         bids.append(bid)
```

```
#     max_value = max(bids)
```

```
#     max_indices = [i for i, x in enumerate(bids) if x == max_value]
```

```
#     idx = random.choice(max_indices)
```

```
#     return idx
```

```
def select_next_speaker_roundtable(
```

```
    step: int, agents: List[Agent]
```

```
) -> int:
```

```
"""Selects the next speaker."""
```

```
return step % len(agents)
```

```
def select_next_speaker_director(
```

```
    step: int, agents: List[Agent], director: Agent
```

```
) -> int:
```

```
    # if the step is even => director
```

```
    # => director selects next speaker
```

```
    if step % 2 == 1:
```

```
        idx = 0
```

```
    else:
```

```
        idx = director.select_next_speaker() + 1
```

```
    return idx
```

```
def run_director(self, task: str):
```

```
    """Runs the multi-agent collaboration with a director."""
```

```
    n = 0
```

```
    self.reset()
```

```
    self.inject("Debate Moderator", task)
```

```
    print("(Debate Moderator): \n")
```

```
    while n < self.max_loops:
```

```
        name, message = self.step()
```

```
        print(f"({name}): {message}\n")
```

n += 1

# [MAYBE]: Add type hints

class MultiAgentCollaboration(BaseSwarm):

"""

Multi-agent collaboration class.

Attributes:

agents (List[Agent]): The agents in the collaboration.

selection\_function (callable): The function that selects the next speaker.

Defaults to select\_next\_speaker.

max\_loops (int): The maximum number of iterations. Defaults to 10.

autosave (bool): Whether to autosave the state of all agents. Defaults to True.

saved\_file\_path\_name (str): The path to the saved file. Defaults to

"multi\_agent\_collab.json".

stopping\_token (str): The token that stops the collaboration. Defaults to

"<DONE>".

results (list): The results of the collaboration. Defaults to [].

logger (logging.Logger): The logger. Defaults to logger.

logging (bool): Whether to log the collaboration. Defaults to True.

Methods:

reset: Resets the state of all agents.

inject: Injects a message into the collaboration.

inject\_agent: Injects an agent into the collaboration.

step: Steps through the collaboration.

ask\_for\_bid: Asks an agent for a bid.

select\_next\_speaker: Selects the next speaker.

run: Runs the collaboration.

format\_results: Formats the results of the run method.

#### Usage:

```
>>> from swarm_models import OpenAIChat

>>> from swarms.structs import Agent

>>> from swarms.swarms.multi_agent_collab import MultiAgentCollaboration

>>>

>>> # Initialize the language model

>>> llm = OpenAIChat(

>>>     temperature=0.5,

>>> )

>>>

>>>

>>> ## Initialize the workflow

>>> agent = Agent(llm=llm, max_loops=1, dashboard=True)

>>>

>>> # Run the workflow on a task

>>> out = agent.run("Generate a 10,000 word blog on health and wellness.")

>>>

>>> # Initialize the multi-agent collaboration
```

```

>>> swarm = MultiAgentCollaboration(
>>>     agents=[agent],
>>>     max_loops=4,
>>> )
>>>
>>> # Run the multi-agent collaboration
>>> swarm.run()
>>>
>>> # Format the results of the multi-agent collaboration
>>> swarm.format_results(swarm.results)

```

```

"""

```

```

def __init__(
    self,
    name: str = "MultiAgentCollaboration",
    description: str = "A multi-agent collaboration.",
    director: Agent = None,
    agents: List[Agent] = None,
    select_next_speaker: Callable = None,
    max_loops: int = 10,
    autosave: bool = True,
    saved_file_path_name: str = "multi_agent_collab.json",
    stopping_token: str = "<DONE>",
    logging: bool = True,
    *args,

```

```
    **kwargs,
):
    super().__init__(
        name=name,
        description=description,
        agents=agents,
        *args,
        **kwargs,
    )

    self.name = name

    self.description = description

    self.director = director

    self.agents = agents

    self.select_next_speaker = select_next_speaker

    self._step = 0

    self.max_loops = max_loops

    self.autosave = autosave

    self.saved_file_path_name = saved_file_path_name

    self.stopping_token = stopping_token

    self.results = []

    self.logger = logger

    self.logging = logging

    # Conversation

    self.conversation = Conversation(
        time_enabled=True, *args, **kwargs
```

)

```
def default_select_next_speaker(  
    self, step: int, agents: List[Agent]
```

```
) -> int:
```

```
    """Default speaker selection function."""  
    return step % len(agents)
```

```
def inject(self, name: str, message: str):
```

```
    """Injects a message into the multi-agent collaboration."""  
    for agent in self.agents:  
        self.conversation.add(name, message)  
        agent.run(self.conversation.return_history_as_string())  
    self._step += 1
```

```
def step(self) -> str:
```

```
    """Steps through the multi-agent collaboration."""  
    speaker_idx = self.select_next_speaker(  
        self._step, self.agents  
    )  
    speaker = self.agents[speaker_idx]  
    message = speaker.send()
```

```
    for receiver in self.agents:
```

```
        self.conversation.add(speaker.name, message)  
        receiver.run(self.conversation.return_history_as_string())
```

```
self._step += 1
```

```
if self.logging:
```

```
    self.log_step(speaker, message)
```

```
return self.conversation.return_history_as_string()
```

```
def log_step(self, speaker: str, response: str):
```

```
    """Logs the step of the multi-agent collaboration."""
```

```
    self.logger.info(f"{speaker.name}: {response}")
```

```
def run(self, task: str, *args, **kwargs):
```

```
    """Runs the multi-agent collaboration."""
```

```
    for _ in range(self.max_loops):
```

```
        result = self.step()
```

```
        if self.autosave:
```

```
            self.save_state()
```

```
        if self.stopping_token in result:
```

```
            break
```

```
return self.conversation.return_history_as_string()
```

```
# def format_results(self, results):
```

```
#     """Formats the results of the run method"""
```

```
#     formatted_results = "\n".join(
```

```
#         [
```



```

#         f"{result['agent']} responded: {result['response']}"
#
#         for result in results
#
#     ]
#
# )
#
# return formatted_results


# def save(self):
#
#     """Saves the state of all agents."""
#
#     state = {
#
#         "step": self._step,
#
#         "results": [
#
#             {"agent": r["agent"].name, "response": r["response"]}
#
#             for r in self.results
#
#         ],
#
#     }
#
#
#
#     with open(self.saved_file_path_name, "w") as file:
#
#         json.dump(state, file)
#
#
#
# def load(self):
#
#     """Loads the state of all agents."""
#
#     with open(self.saved_file_path_name) as file:
#
#         state = json.load(file)
#
#         self._step = state["step"]
#
#         self.results = state["results"]
#
#     return state

```

```
# def __repr__(self):  
  
#     return (  
  
#         f"MultiAgentCollaboration(agents={self.agents},"  
#         f" selection_function={self.select_next_speaker},"  
#         f" max_loops={self.max_loops}, autosave={self.autosave},"  
#         f" saved_file_path_name={self.saved_file_path_name})"  
#     )
```