

```
from clusterops import (
    list_available_gpus,
    execute_on_gpu,
)

from swarms import Agent, AgentRearrange

from swarm_models import OpenAIChat

import os

import logging


from dotenv import load_dotenv


load_dotenv()


# Get the OpenAI API key from the environment variable

api_key = os.getenv("OPENAI_API_KEY")


# Create an instance of the OpenAIChat class

model = OpenAIChat(
    openai_api_key=api_key,
    model_name="gpt-4o-mini",
    temperature=0.1,
    max_tokens=2000,
)


# Function for the director agent
```

```
def director_task(task: str):

    logging.info(f"Running Director agent for task: {task}")

    director = Agent(

        agent_name="Director",

        system_prompt="Directs the tasks for the workers",

        llm=model,

        max_loops=1,

        dashboard=False,

        streaming_on=True,

        verbose=True,

        stopping_token="<DONE>",

        state_save_file_type="json",

        saved_state_path="director.json",

    )

    return director.run(task)
```

Function for worker 1

```
def worker1_task(task: str):

    logging.info(f"Running Worker1 agent for task: {task}")

    worker1 = Agent(

        agent_name="Worker1",

        system_prompt="Generates a transcript for a youtube video on what swarms are",

        llm=model,

        max_loops=1,

        dashboard=False,
```

```
streaming_on=True,  
verbose=True,  
stopping_token="<DONE>",  
state_save_file_type="json",  
saved_state_path="worker1.json",  
)  
  
return worker1.run(task)
```

Function for worker 2

```
def worker2_task(task: str):  
  
    logging.info(f"Running Worker2 agent for task: {task}")  
  
    worker2 = Agent(  
  
        agent_name="Worker2",  
  
        system_prompt="Summarizes the transcript generated by Worker1",  
  
        llm=model,  
  
        max_loops=1,  
  
        dashboard=False,  
  
        streaming_on=True,  
  
        verbose=True,  
  
        stopping_token="<DONE>",  
  
        state_save_file_type="json",  
  
        saved_state_path="worker2.json",  
  
    )  
  
    return worker2.run(task)
```

```
# GPU Assignment Example
```

```
def assign_tasks_to_gpus():
```

```
    # List available GPUs
```

```
    gpus = list_available_gpus()
```

```
    logging.info(f"Available GPUs: {gpus}")
```

```
    # Example: Assign Director to GPU 0
```

```
    logging.info("Executing Director task on GPU 0")
```

```
    execute_on_gpu(
```

```
        0, director_task, "Direct the creation of swarm video format"
```

```
    )
```

```
    # Example: Assign Worker1 to GPU 1
```

```
    logging.info("Executing Worker1 task on GPU 1")
```

```
    execute_on_gpu(
```

```
        1,
```

```
        worker1_task,
```

```
        "Generate transcript for youtube video on swarms",
```

```
    )
```

```
    # Example: Assign Worker2 to GPU 2
```

```
    logging.info("Executing Worker2 task on GPU 2")
```

```
    execute_on_gpu(
```

```
        2,
```

```
        worker2_task,
```

"Summarize the transcript generated by Worker1",

)

Flow Management using AgentRearrange (optional)

def run_agent_flow():

Initialize the agents

director = Agent(

agent_name="Director",

system_prompt="Directs the tasks for the workers",

llm=model,

max_loops=1,

dashboard=False,

streaming_on=True,

verbose=True,

stopping_token="<DONE>",

state_save_file_type="json",

saved_state_path="director.json",

)

worker1 = Agent(

agent_name="Worker1",

system_prompt="Generates a transcript for a youtube video on what swarms are",

llm=model,

max_loops=1,

dashboard=False,

```
streaming_on=True,  
verbose=True,  
stopping_token="<DONE>",  
state_save_file_type="json",  
saved_state_path="worker1.json",  
)
```

```
worker2 = Agent(  
    agent_name="Worker2",  
    system_prompt="Summarizes the transcript generated by Worker1",  
    llm=model,  
    max_loops=1,  
    dashboard=False,  
    streaming_on=True,  
    verbose=True,  
    stopping_token="<DONE>",  
    state_save_file_type="json",  
    saved_state_path="worker2.json",  
)
```

```
# Define agent list and flow pattern
```

```
agents = [director, worker1, worker2]
```

```
flow = "Director -> Worker1 -> Worker2"
```

```
# Use AgentRearrange to manage the flow
```

```
agent_system = AgentRearrange(agents=agents, flow=flow)
```

```
output = agent_system.run(
    "Create a format to express and communicate swarms of llms in a structured manner for
youtube"
)
print(output)

if __name__ == "__main__":
    logging.info(
        "Starting the GPU-based task assignment for agents..."
    )
    assign_tasks_to_gpus()

    logging.info("Starting the AgentRearrange task flow...")
    run_agent_flow()
```