

```
import os

from typing import Any, Callable, Dict, List, Optional, Tuple, Union


import yaml

from tenacity import (
    retry,
    stop_after_attempt,
    wait_exponential,
    retry_if_exception_type,
)

from pydantic import (
    BaseModel,
    Field,
    field_validator,
)

from swarms.utils.loguru_logger import initialize_logger

from swarms.structs.agent import Agent

from swarms.structs.swarm_router import SwarmRouter

from swarms.utils.litellm_wrapper import LiteLLM


logger = initialize_logger(log_folder="create_agents_from_yaml")


class AgentConfig(BaseModel):
    agent_name: str

    system_prompt: str
```

```
model_name: Optional[str] = None

max_loops: int = Field(default=1, ge=1)

autosave: bool = True

dashboard: bool = False

verbose: bool = False

dynamic_temperature_enabled: bool = False

saved_state_path: Optional[str] = None

user_name: str = "default_user"

retry_attempts: int = Field(default=3, ge=1)

context_length: int = Field(default=100000, ge=1000)

return_step_meta: bool = False

output_type: str = "str"

auto_generate_prompt: bool = False

artifacts_on: bool = False

artifacts_file_extension: str = ".md"

artifacts_output_path: str = ""
```

```
@field_validator("system_prompt")
```

```
@classmethod
```

```
def validate_system_prompt(cls, v):
```

```
    if not v or not isinstance(v, str) or len(v.strip()) == 0:
```

```
        raise ValueError(
```

```
            "System prompt must be a non-empty string"
```

```
        )
```

```
    return v
```

```
class SwarmConfig(BaseModel):

    name: str

    description: str

    max_loops: int = Field(default=1, ge=1)

    swarm_type: str

    task: Optional[str] = None

    flow: Optional[Dict] = None

    autosave: bool = True

    return_json: bool = False

    rules: str = ""

    @field_validator("swarm_type")
    @classmethod
    def validate_swarm_type(cls, v):

        valid_types = {

            "SequentialWorkflow",

            "ConcurrentWorkflow",

            "AgentRearrange",

            "MixtureOfAgents",

            "auto",

        }

        if v not in valid_types:

            raise ValueError(

                f"Swarm type must be one of: {valid_types}"

            )
```

```
return v
```

```
class YAMLConfig(BaseModel):
```

```
    agents: List[AgentConfig] = Field(..., min_length=1)
```

```
    swarm_architecture: Optional[SwarmConfig] = None
```

```
    model_config = {
```

```
        "extra": "forbid" # Prevent additional fields not in the model
```

```
    }
```

```
def load_yaml_safely(
```

```
    yaml_file: str = None, yaml_string: str = None
```

```
) -> Dict:
```

```
    """Safely load and validate YAML configuration using Pydantic."""
```

```
    try:
```

```
        if yaml_string:
```

```
            config_dict = yaml.safe_load(yaml_string)
```

```
        elif yaml_file:
```

```
            if not os.path.exists(yaml_file):
```

```
                raise FileNotFoundError(
```

```
                    f"YAML file {yaml_file} not found."
```

```
                )
```

```
            with open(yaml_file, "r") as file:
```

```
                config_dict = yaml.safe_load(file)
```

else:

raise ValueError(

"Either yaml_file or yaml_string must be provided"

)

Validate using Pydantic

YAMLConfig(**config_dict)

return config_dict

except yaml.YAMLError as e:

raise ValueError(f"Error parsing YAML: {str(e)}")

except Exception as e:

raise ValueError(f"Error validating configuration: {str(e)}")

@retry(

stop=stop_after_attempt(3),

wait=wait_exponential(multiplier=1, min=4, max=10),

retry=retry_if_exception_type((ConnectionError, TimeoutError)),

before_sleep=lambda retry_state: logger.info(

f"Retrying after error: {retry_state.outcome.exception()}")

),

)

def create_agent_with_retry(

agent_config: Dict, model: LiteLLM

) -> Agent:

"""Create an agent with retry logic for handling transient failures."""

try:

```
validated_config = AgentConfig(**agent_config)
```

```
agent = Agent(
```

```
    agent_name=validated_config.agent_name,
```

```
    system_prompt=validated_config.system_prompt,
```

```
    llm=model,
```

```
    max_loops=validated_config.max_loops,
```

```
    autosave=validated_config.autosave,
```

```
    dashboard=validated_config.dashboard,
```

```
    verbose=validated_config.verbose,
```

```
    dynamic_temperature_enabled=validated_config.dynamic_temperature_enabled,
```

```
    saved_state_path=validated_config.saved_state_path,
```

```
    user_name=validated_config.user_name,
```

```
    retry_attempts=validated_config.retry_attempts,
```

```
    context_length=validated_config.context_length,
```

```
    return_step_meta=validated_config.return_step_meta,
```

```
    output_type=validated_config.output_type,
```

```
    auto_generate_prompt=validated_config.auto_generate_prompt,
```

```
    artifacts_on=validated_config.artifacts_on,
```

```
    artifacts_file_extension=validated_config.artifacts_file_extension,
```

```
    artifacts_output_path=validated_config.artifacts_output_path,
```

```
)
```

```
return agent
```

except Exception as e:

```
    logger.error(
```

```
        f"Error creating agent {agent_config.get('agent_name', 'unknown')}: {str(e)}"
```

)

raise

```
def create_agents_from_yaml(
```

```
    model: Callable = None,
```

```
    yaml_file: str = "agents.yaml",
```

```
    yaml_string: str = None,
```

```
    return_type: str = "auto",
```

```
) -> Union[
```

```
    SwarmRouter,
```

```
    Agent,
```

```
    List[Agent],
```

```
    Tuple[Union[SwarmRouter, Agent], List[Agent]],
```

```
    List[Dict[str, Any]],
```

```
]:
```

```
    """
```

```
    Create agents and/or SwarmRouter based on configurations defined in a YAML file or string.
```

```
    """
```

```
    agents = []
```

```
    task_results = []
```

```
    swarm_router = None
```

```
    try:
```

```
        # Load and validate configuration
```

```
        config = load_yaml_safely(yaml_file, yaml_string)
```

```
# Create agents with retry logic

for agent_config in config["agents"]:

    logger.info(

        f"Creating agent: {agent_config['agent_name']}"

    )

    if "model_name" in agent_config:

        model_instance = LiteLLM(

            model_name=agent_config["model_name"]

        )

    else:

        model_name = "gpt-4o"

        model_instance = LiteLLM(model_name=model_name)

    agent = create_agent_with_retry(

        agent_config, model_instance

    )

    logger.info(

        f"Agent {agent_config['agent_name']} created successfully."

    )

    agents.append(agent)
```

```
# Create SwarmRouter if specified
```

```
if "swarm_architecture" in config:
```

```
    try:
```



```

swarm_config = SwarmConfig(
    **config["swarm_architecture"]
)

swarm_router = SwarmRouter(
    name=swarm_config.name,
    description=swarm_config.description,
    max_loops=swarm_config.max_loops,
    agents=agents,
    swarm_type=swarm_config.swarm_type,
    task=swarm_config.task,
    flow=swarm_config.flow,
    autosave=swarm_config.autosave,
    return_json=swarm_config.return_json,
    rules=swarm_config.rules,
)

logger.info(
    f"SwarmRouter '{swarm_config.name}' created successfully."
)

except Exception as e:
    logger.error(f"Error creating SwarmRouter: {str(e)}")
    raise ValueError(
        f"Failed to create SwarmRouter: {str(e)}"
    )

# Handle return types with improved error checking
valid_return_types = {

```

```

    "auto",
    "swarm",
    "agents",
    "both",
    "tasks",
    "run_swarm",
}

if return_type not in valid_return_types:

    raise ValueError(

        f"Invalid return_type. Must be one of: {valid_return_types}"

    )

if return_type == "run_swarm" or "swarm":

    if not swarm_router:

        raise ValueError(

            "Cannot run swarm: SwarmRouter not created."

        )

    try:

        return swarm_router.run(

            config["swarm_architecture"]["task"]

        )

    except Exception as e:

        logger.error(f"Error running SwarmRouter: {str(e)}")

        raise

# Return appropriate type based on configuration

```

```
if return_type == "auto":
    return (
        swarm_router
        if swarm_router
        else (agents[0] if len(agents) == 1 else agents)
    )
elif return_type == "swarm":
    return (
        swarm_router
        if swarm_router
        else (agents[0] if len(agents) == 1 else agents)
    )
elif return_type == "agents":
    return agents[0] if len(agents) == 1 else agents
elif return_type == "both":
    return (
        swarm_router
        if swarm_router
        else agents[0] if len(agents) == 1 else agents
    ), agents
elif return_type == "tasks":
    return task_results

except Exception as e:
    logger.error(
        f"Critical error in create_agents_from_yaml: {str(e)}"
```

)

raise