```
from dataclasses import dataclass, field
from typing import Dict, List, Optional, Union
from swarms.structs.agent import Agent
from swarms.structs.base_swarm import BaseSwarm
from swarms.utils.loguru_logger import initialize_logger
logger = initialize_logger("company-swarm")
@dataclass
class Company(BaseSwarm):
  ....
  Represents a company with a hierarchical organizational structure.
  ....
  org_chart: List[List[Agent]]
  shared instructions: str = None
  ceo: Optional[Agent] = None
  agents: List[Agent] = field(default_factory=list)
  agent_interactions: Dict[str, List[str]] = field(
     default_factory=dict
  )
  def __post_init__(self):
```

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self._parse_org_chart(self.org_chart)
def add(self, agent: Agent) -> None:
  Adds an agent to the company.
  Args:
    agent (Agent): The agent to be added.
  Raises:
     ValueError: If an agent with the same ID already exists in the company.
  try:
    if any(
       existing_agent.id == agent.id
       for existing_agent in self.agents
    ):
       raise ValueError(
          f"Agent with id {agent.id} already exists in the"
          " company."
       )
    self.agents.append(agent)
  except Exception as error:
    logger.error(
       f"[ERROR][CLASS: Company][METHOD: add] {error}"
```

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)
     raise error
def get(self, agent_name: str) -> Agent:
  Retrieves an agent from the company by name.
  Args:
    agent_name (str): The name of the agent to retrieve.
  Returns:
    Agent: The retrieved agent.
  Raises:
     ValueError: If an agent with the specified name does not exist in the company.
  try:
    for agent in self.agents:
       if agent.name == agent_name:
          return agent
     raise ValueError(
       f"Agent with name {agent_name} does not exist in the"
       " company."
    )
  except Exception as error:
     logger.error(
```

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f"[ERROR][CLASS: Company][METHOD: get] {error}"
     )
     raise error
def remove(self, agent: Agent) -> None:
  ....
  Removes an agent from the company.
  Args:
     agent (Agent): The agent to be removed.
  111111
  try:
     self.agents.remove(agent)
  except Exception as error:
     logger.error(
       f"[ERROR][CLASS: Company][METHOD: remove] {error}"
     )
     raise error
def _parse_org_chart(
  self, org_chart: Union[List[Agent], List[List[Agent]]]
) -> None:
  Parses the organization chart and adds agents to the company.
  Args:
```

```
org_chart (Union[List[Agent]], List[List[Agent]]): The organization chart
  representing the hierarchy of agents.
```

```
Raises:
  ValueError: If more than one CEO is found in the org chart or if an invalid
     agent is encountered.
.....
try:
  for node in org_chart:
     if isinstance(node, Agent):
       if self.ceo:
          raise ValueError("1 CEO is only allowed")
        self.ceo = node
       self.add(node)
     elif isinstance(node, list):
       for agent in node:
          if not isinstance(agent, Agent):
             raise ValueError(
               "Invalid agent in org chart"
             )
          self.add(agent)
       for i, agent in enumerate(node):
          if i == len(node) - 1:
             continue
```

```
for other_agent in node[i + 1]:
               self.__init_task(agent, other_agent)
  except Exception as error:
     logger.error(
       "[ERROR][CLASS: Company][METHOD: _parse_org_chart]"
       f" {error}"
     )
     raise error
def _init_interaction(
  self,
  agent1: Agent,
  agent2: Agent,
) -> None:
  Initializes the interaction between two agents.
  Args:
     agent1 (Agent): The first agent involved in the interaction.
     agent2 (Agent): The second agent involved in the interaction.
  Returns:
     None
  ....
  if agent1.ai_name not in self.agents_interactions:
```

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self.agents_interactions[agent1.ai_name] = []
  self.agents_interactions[agent1.ai_name].append(
     agent2.ai_name
  )
def run(self):
  111111
  Run the company
  for (
     agent_name,
     interaction_agents,
  ) in self.agents_interactions.items():
     agent = self.get(agent_name)
     for interaction_agent in interaction_agents:
       task_description = (
          f"Task for {agent_name} to interact with"
          f" {interaction_agent}"
       )
       print(f"{task_description} is being executed")
       agent.run(task_description)
```