

```
import os
```

```
from dotenv import load_dotenv
```

```
from swarms import (
```

```
    Agent,
```

```
    Edge,
```

```
    GraphWorkflow,
```

```
    Node,
```

```
    NodeType,
```

```
    OpenAIChat,
```

```
)
```

```
load_dotenv()
```

```
api_key = os.environ.get("OPENAI_API_KEY")
```

```
llm = OpenAIChat(
```

```
    temperature=0.5, openai_api_key=api_key, max_tokens=4000
```

```
)
```

```
agent1 = Agent(llm=llm, max_loops=1, autosave=True, dashboard=True)
```

```
agent2 = Agent(llm=llm, max_loops=1, autosave=True, dashboard=True)
```

```
def sample_task():
```

```
    print("Running sample task")
```

```
return "Task completed"
```

```
wf_graph = GraphWorkflow()
```

```
wf_graph.add_node(
```

```
    Node(id="agent1", type=NodeType.AGENT, agent=agent1)
```

```
)
```

```
wf_graph.add_node(
```

```
    Node(id="agent2", type=NodeType.AGENT, agent=agent2)
```

```
)
```

```
wf_graph.add_node(
```

```
    Node(id="task1", type=NodeType.TASK, callable=sample_task)
```

```
)
```

```
wf_graph.add_edge(Edge(source="agent1", target="task1"))
```

```
wf_graph.add_edge(Edge(source="agent2", target="task1"))
```

```
wf_graph.set_entry_points(["agent1", "agent2"])
```

```
wf_graph.set_end_points(["task1"])
```

```
print(wf_graph.visualize())
```

```
# Run the workflow
```

```
results = wf_graph.run()
```

```
print("Execution results:", results)
```