

```
import threading
```

```
import time
```

```
import uuid
```

```
from typing import Any, Callable, Dict, List, Optional
```

```
from swarms.utils.any_to_str import any_to_str
```

```
from swarms.utils.loguru_logger import initialize_logger
```

```
logger = initialize_logger(log_folder="swarm_arange")
```

```
def swarm_id():
```

```
    return uuid.uuid4().hex
```

```
class SwarmArrangeInput:
```

```
    id: str = uuid.uuid4().hex
```

```
    time_stamp: str = time.strftime("%Y-%m-%d %H:%M:%S")
```

```
    name: str
```

```
    description: str
```

```
    swarms: List[Callable] = []
```

```
    output_type: str
```

```
    flow: str = ""
```

```
class SwarmArrangeOutput:
```

input_config: SwarmArrangeInput = None

class SwarmRearrange:

"""

A class representing a swarm of swarms for rearranging tasks.

Attributes:

id (str): Unique identifier for the swarm arrangement

name (str): Name of the swarm arrangement

description (str): Description of what this swarm arrangement does

swarms (dict): A dictionary of swarms, where the key is the swarm's name and the value is the swarm object

flow (str): The flow pattern of the tasks

max_loops (int): The maximum number of loops to run the swarm

verbose (bool): A flag indicating whether to log verbose messages

human_in_the_loop (bool): A flag indicating whether human intervention is required

custom_human_in_the_loop (Callable[[str], str], optional): A custom function for human-in-the-loop intervention

return_json (bool): A flag indicating whether to return the result in JSON format

swarm_history (dict): A dictionary to keep track of the history of each swarm

lock (threading.Lock): A lock for thread-safe operations

Methods:

__init__(id: str, name: str, description: str, swarms: List[swarm], flow: str, max_loops: int, verbose: bool,

human_in_the_loop: bool, custom_human_in_the_loop: Callable, return_json: bool):

Initializes the SwarmRearrange object

add_swarm(swarm: swarm): Adds an swarm to the swarm

remove_swarm(swarm_name: str): Removes an swarm from the swarm

add_swarms(swarms: List[swarm]): Adds multiple swarms to the swarm

validate_flow(): Validates the flow pattern

run(task): Runs the swarm to rearrange the tasks

"""

```
def __init__(
    self,
    id: str = swarm_id(),
    name: str = "SwarmRearrange",
    description: str = "A swarm of swarms for rearranging tasks.",
    swarms: List[Any] = [],
    flow: str = None,
    max_loops: int = 1,
    verbose: bool = True,
    human_in_the_loop: bool = False,
    custom_human_in_the_loop: Optional[
        Callable[[str], str]
    ] = None,
    return_json: bool = False,
    *args,
    **kwargs,
):
```

"""

Initializes the SwarmRearrange object.

Args:

id (str): Unique identifier for the swarm arrangement. Defaults to generated UUID.

name (str): Name of the swarm arrangement. Defaults to "SwarmRearrange".

description (str): Description of what this swarm arrangement does.

swarms (List[swarm]): A list of swarm objects. Defaults to empty list.

flow (str): The flow pattern of the tasks. Defaults to None.

max_loops (int): Maximum number of loops to run. Defaults to 1.

verbose (bool): Whether to log verbose messages. Defaults to True.

human_in_the_loop (bool): Whether human intervention is required. Defaults to False.

custom_human_in_the_loop (Callable): Custom function for human intervention. Defaults to

None.

return_json (bool): Whether to return results as JSON. Defaults to False.

"""

self.id = id

self.name = name

self.description = description

self.swarms = {swarm.name: swarm for swarm in swarms}

self.flow = flow if flow is not None else ""

self.max_loops = max_loops if max_loops > 0 else 1

self.verbose = verbose

self.human_in_the_loop = human_in_the_loop

self.custom_human_in_the_loop = custom_human_in_the_loop

self.return_json = return_json

```
self.swarm_history = {swarm.name: [] for swarm in swarms}
```

```
self.lock = threading.Lock()
```

```
self.id = uuid.uuid4().hex if id is None else id
```

```
# Run the reliability checks
```

```
self.reliability_checks()
```

```
# Logging configuration
```

```
if self.verbose:
```

```
    logger.add("swarm_rearrange.log", rotation="10 MB")
```

```
def reliability_checks(self):
```

```
    logger.info("Running reliability checks.")
```

```
    if not self.swarms:
```

```
        raise ValueError("No swarms found in the swarm.")
```

```
    if not self.flow:
```

```
        raise ValueError("No flow found in the swarm.")
```

```
    if self.max_loops <= 0:
```

```
        raise ValueError("Max loops must be a positive integer.")
```

```
    logger.info(
```

```
        "SwarmRearrange initialized with swarms: {}".format(
```

```
            list(self.swarms.keys())
```

```
        )
```

)

```
def set_custom_flow(self, flow: str):
```

```
    self.flow = flow
```

```
    logger.info(f"Custom flow set: {flow}")
```

```
def add_swarm(self, swarm: Any):
```

```
    """
```

```
    Adds an swarm to the swarm.
```

```
    Args:
```

```
        swarm (swarm): The swarm to be added.
```

```
    """
```

```
    logger.info(f"Adding swarm {swarm.name} to the swarm.")
```

```
    self.swarms[swarm.name] = swarm
```

```
def track_history(
```

```
    self,
```

```
    swarm_name: str,
```

```
    result: str,
```

```
):
```

```
    self.swarm_history[swarm_name].append(result)
```

```
def remove_swarm(self, swarm_name: str):
```

```
    """
```

```
    Removes an swarm from the swarm.
```

Args:

swarm_name (str): The name of the swarm to be removed.

"""

del self.swarms[swarm_name]

def add_swarms(self, swarms: List[Any]):

"""

Adds multiple swarms to the swarm.

Args:

swarms (List[swarm]): A list of swarm objects.

"""

for swarm in swarms:

self.swarms[swarm.name] = swarm

def validate_flow(self):

"""

Validates the flow pattern.

Raises:

ValueError: If the flow pattern is incorrectly formatted or contains duplicate swarm names.

Returns:

bool: True if the flow pattern is valid.

"""

```

if "->" not in self.flow:

    raise ValueError(

        "Flow must include '->' to denote the direction of the task."

    )

swarms_in_flow = []

# Arrow

tasks = self.flow.split("->")

# For the task in tasks

for task in tasks:

    swarm_names = [name.strip() for name in task.split(",")]

    # Loop over the swarm names

    for swarm_name in swarm_names:

        if (

            swarm_name not in self.swarms

            and swarm_name != "H"

        ):

            raise ValueError(

                f"swarm '{swarm_name}' is not registered."

            )

            swarms_in_flow.append(swarm_name)

# If the length of the swarms does not equal the length of the swarms in flow

```



```
if len(set(swarms_in_flow)) != len(swarms_in_flow):  
    raise ValueError(  
        "Duplicate swarm names in the flow are not allowed."  
    )
```

```
logger.info("Flow is valid.")  
return True
```

```
def run(  
    self,  
    task: str = None,  
    img: str = None,  
    custom_tasks: Optional[Dict[str, str]] = None,  
    *args,  
    **kwargs,  
):
```

```
    """
```

Runs the swarm to rearrange the tasks.

Args:

task: The initial task to be processed.

img: An optional image input.

custom_tasks: A dictionary of custom tasks for specific swarms.

Returns:

str: The final processed task.

```
"""
```

```
try:
```

```
    if not self.validate_flow():
```

```
        return "Invalid flow configuration."
```

```
tasks = self.flow.split("->")
```

```
current_task = task
```

```
# Check if custom_tasks is a dictionary and not empty
```

```
if isinstance(custom_tasks, dict) and custom_tasks:
```

```
    c_swarm_name, c_task = next(
```

```
        iter(custom_tasks.items())
```

```
    )
```

```
# Find the position of the custom swarm in the tasks list
```

```
if c_swarm_name in tasks:
```

```
    position = tasks.index(c_swarm_name)
```

```
# If there is a previous swarm, merge its task with the custom tasks
```

```
if position > 0:
```

```
    tasks[position - 1] += "->" + c_task
```

```
else:
```

```
    # If there is no previous swarm, just insert the custom tasks
```

```
    tasks.insert(position, c_task)
```

```
# Set the loop counter
```

```

loop_count = 0

while loop_count < self.max_loops:

    for task in tasks:

        swarm_names = [

            name.strip() for name in task.split(",")

        ]

        if len(swarm_names) > 1:

            # Parallel processing

            logger.info(

                f"Running swarms in parallel: {swarm_names}"

            )

            results = []

            for swarm_name in swarm_names:

                if swarm_name == "H":

                    # Human in the loop intervention

                    if (

                        self.human_in_the_loop

                        and self.custom_human_in_the_loop

                    ):

                        current_task = (

                            self.custom_human_in_the_loop(

                                current_task

                            )

                        )

                    else:

                        current_task = input(

```

"Enter your response: "

)

else:

swarm = self.swarms[swarm_name]

result = swarm.run(

current_task, img, *args, **kwargs

)

result = any_to_str(result)

logger.info(

f"Swarm {swarm_name} returned result of type: {type(result)}"

)

if isinstance(result, bool):

logger.warning(

f"Swarm {swarm_name} returned a boolean value: {result}"

)

result = str(

result

) # Convert boolean to string

results.append(result)

current_task = "; ".join(

str(r) for r in results if r is not None

)

else:

Sequential processing

logger.info(

```

        f"Running swarms sequentially: {swarm_names}"
    )
    swarm_name = swarm_names[0]
    if swarm_name == "H":
        # Human-in-the-loop intervention
        if (
            self.human_in_the_loop
            and self.custom_human_in_the_loop
        ):
            current_task = (
                self.custom_human_in_the_loop(
                    current_task
                )
            )
        else:
            current_task = input(
                "Enter the next task: "
            )
        else:
            swarm = self.swarms[swarm_name]
            result = swarm.run(
                current_task, img, *args, **kwargs
            )
            result = any_to_str(result)
            logger.info(
                f"Swarm {swarm_name} returned result of type: {type(result)}"
            )

```

```

    )

    if isinstance(result, bool):

        logger.warning(

            f"Swarm {swarm_name} returned a boolean value: {result}"

        )

        result = str(

            result

        ) # Convert boolean to string

    current_task = (

        result

        if result is not None

        else current_task

    )

    loop_count += 1

return current_task

```

```

except Exception as e:

    logger.error(f"An error occurred: {e}")

    return str(e)

```

```

def swarm_arrange(

    name: str = "SwarmArrange-01",

    description: str = "Combine multiple swarms and execute them sequentially",

    swarms: List[Callable] = None,

```

```

output_type: str = "json",

flow: str = None,

task: str = None,

*args,

**kwargs,

):
    """

```

Orchestrates the execution of multiple swarms in a sequential manner.

Args:

name (str, optional): The name of the swarm arrangement. Defaults to "SwarmArrange-01".

description (str, optional): A description of the swarm arrangement. Defaults to "Combine multiple swarms and execute them sequentially".

swarms (List[Callable], optional): A list of swarm objects to be executed. Defaults to None.

output_type (str, optional): The format of the output. Defaults to "json".

flow (str, optional): The flow pattern of the tasks. Defaults to None.

task (str, optional): The task to be executed by the swarms. Defaults to None.

*args: Additional positional arguments to be passed to the SwarmRearrange object.

**kwargs: Additional keyword arguments to be passed to the SwarmRearrange object.

Returns:

Any: The result of the swarm arrangement execution.

```

    """

```

try:

```

swarm_arrangement = SwarmRearrange(
    name,

```

```
        description,
        swarms,
        output_type,
        flow,
    )
    result = swarm_arrangement.run(task, *args, **kwargs)
    result = any_to_str(result)
    logger.info(
        f"Swarm arrangement {name} executed successfully with output type {output_type}."
    )
    return result
except Exception as e:
    logger.error(
        f"An error occurred during swarm arrangement execution: {e}"
    )
    return str(e)
```