from typing import List, Optional

self.name = name

```
from griptape.structures import Agent as GriptapeAgent
from griptape.tools import FileManager, TaskMemoryClient, WebScraper
from swarms import Agent
class GriptapeAgentWrapper(Agent):
  11 11 11
  A wrapper class for the GriptapeAgent from the griptape library.
  def __init__(
     self, name: str, tools: Optional[List] = None, *args, **kwargs
  ):
     Initialize the GriptapeAgentWrapper.
     Parameters:
     - name: The name of the agent.
     - tools: A list of tools to be used by the agent. If not provided, default tools will be used.
     - *args, **kwargs: Additional arguments to be passed to the parent class constructor.
     super().__init__(*args, **kwargs)
```

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self.tools = tools or [
     WebScraper(off_prompt=True),
     TaskMemoryClient(off_prompt=True),
     FileManager(),
  ]
  self.griptape_agent = GriptapeAgent(
     input=f"I am {name}, an AI assistant. How can I help you?",
    tools=self.tools,
  )
def run(self, task: str, *args, **kwargs) -> str:
  Run a task using the GriptapeAgent.
  Parameters:
  - task: The task to be performed by the agent.
  Returns:
  - The response from the GriptapeAgent as a string.
  .....
  response = self.griptape_agent.run(task, *args, **kwargs)
  return str(response)
def add_tool(self, tool) -> None:
  ....
  Add a tool to the agent.
```

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Parameters:
     - tool: The tool to be added.
     self.tools.append(tool)
     self.griptape_agent = GriptapeAgent(
       input=f"I am {self.name}, an Al assistant. How can I help you?",
       tools=self.tools,
     )
# Usage example
griptape_wrapper = GriptapeAgentWrapper("GriptapeAssistant")
result = griptape_wrapper.run(
  "Load https://example.com, summarize it, and store it in a file called example_summary.txt."
print(result)
```

)