

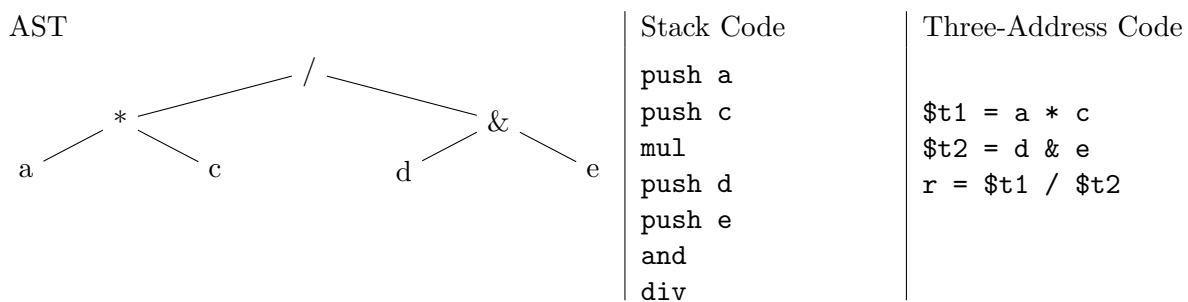
Interpreting Bytecodes, a.k.a. Virtual Machines

Bytecode interpretation trades off compiler complexity for interpreter complexity: the compiler processes the program at greater length, thus enabling a much more direct virtual machine implementation. Later on, we'll talk about just-in-time compilers, where the interpreter actually contains a native code compilation engine. JIT engines, though, are optional; you can always directly interpret the code by simulating the instruction set architecture of the target machine.

What are some examples of bytecode interpreters you know about?

Three-Address Code vs. Stack Code. Most bytecode interpreters are stack-based (like old RPN calculators¹.) Stack code is compact, which is good for transporting code across the network. Internal compiler intermediate representations are usually three-address code, where each statement contains at most one operation and, hence, two operands (in most cases).

Interpreter inputs and state. Implementing a virtual machine is implementing a processor in software. Examples of virtual machine instructions are loads, stores, and arithmetic instructions; note that by this point, we've compiled the AST's expression trees into lower-level instructions.



(There are more instructions in the stack code, but they're shorter to encode.)

The Java virtual machine also includes object-oriented instructions, like virtual invoke instructions, implementing dynamic dispatch, and `instanceof` instructions, implementing dynamic type tests.

¹Reverse Polish Notation is where you enter the operands and then the operation, e.g. `2 3 +`. You can get RPN by doing a postfix traversal of the expression tree. People using RPN calculators are far faster at keying in computations than with the usual infix-notation, and they make fewer mistakes.

Let's compare VM state to AST interpreter state:

AST	VM
locals	registers or stack
heap	heap
PC and implicit call stack	PC and explicit call stack

Unlike the interpreter's implicit call stack, a virtual machine will often maintain an explicit data structure, which keeps return addresses and function parameters. Registers would include:

- general purpose registers;
- a stack pointer `sp` pointing to the top of the stack;
- a frame pointer `fp` pointing to the current stack frame (where the local variables live); and
- a program counter `pc` pointing to the current instruction.

The machine state also includes condition codes, or flags (e.g. bits indicating the results of comparisons).

To execute an instruction, the interpreter:

- reads and decodes the instruction at the program counter;
- executes the instruction, changing the state of the machine (registers, stack, condition codes);
- updates the `pc` by incrementing it; jumping to a new address; or pushing the current address on the stack and jumping to a new address (function call).

Java VM code might look like this:

```
pc = code.start;
while(true)
{
    npc = pc + instruction_length(code[pc]);
    switch (opcode(code[pc]))
    {
        case ILOAD_1: push(local[1]);
                     break;
        case ILOAD:   push(local[code[pc+1]]);
                     break;
        case ISTORE:  t = pop();
                     local[code[pc+1]] = t;
                     break;
        case IADD:    t1 = pop(); t2 = pop();
                     push(t1 + t2);
                     break;
        case IFEQ:    t = pop();
                     if (t == 0) npc = code[pc+1];
                     break;
        ...
    }
    pc = npc;
}
```

Quadratic formula example

Here is the Java code for the quadratic formula example seen in class today.

```
public class Quadratic {

    public static void main(String[] args) {
        double x = positiveRoot(1, 3, -4);
        System.out.println(x);
        double x3 = positiveRoot3AC(1, 3, -4);
        System.out.println(x3);
    }

    static double positiveRoot(int a, int b, int c) {
        return ((-1 * b) + Math.sqrt(b*b - 4*a*c)) / (2*a);
    }

    static double positiveRoot3AC(int a, int b, int c) {
        int negB = -1 * b;
        int b2 = b*b;
        int ac = a * c;
        int fourac = 4 * ac;
        int discriminant = b2 - fourac;
        double sqrt = Math.sqrt(discriminant);
        double numerator = negB + sqrt;
        int denominator = 2 * a;
        double x = numerator / denominator;
        return x;
    }
}
```

and the corresponding Java bytecode:

```
Compiled from "Quadratic.java"
public class Quadratic extends java.lang.Object{
    public Quadratic();
    Code:
        0: aload_0
        1: invokespecial #1; //Method java/lang/Object."<init>":()V
        4: return

    public static void main(java.lang.String[]);
    Code:
        0: iconst_1
        1: iconst_3
        2: bipush -4
        4: invokestatic #2; //Method positiveRoot:(III)D
        7: dstore_1
        8: getstatic #3; //Field java/lang/System.out:Ljava/io/PrintStream;
        11: dload_1
        12: invokevirtual #4; //Method java/io/PrintStream.println:(D)V
        15: iconst_1
        16: iconst_3
        17: bipush -4
        19: invokestatic #5; //Method positiveRoot3AC:(III)D
        22: dstore_3
        23: getstatic #3; //Field java/lang/System.out:Ljava/io/PrintStream;
        26: dload_3
        27: invokevirtual #4; //Method java/io/PrintStream.println:(D)V
        30: return

    static double positiveRoot(int, int, int);
    Code:
        0: iconst_m1          // push -1
```

```

1: iload_1          // push local #1 (b)
2: imul            // integer multiply: -b
3: i2d             // int to double
4: iload_1          // push local #1 (b)
5: iload_1          // push local #1 (b)
6: imul            // integer multiply: b*b
7: iconst_4         // push 4
8: iload_0          // push local #0 (a)
9: imul            // integer multiply: 4*a
10: iload_2         // push local #2 (c)
11: imul            // integer multiply: 4a*c
12: isub           // integer subtract: b2 - 4ac
13: i2d             // integer to double
14: invokestatic #6; //Method java/lang/Math.sqrt:(D)D
17: dadd            // double add: -b + sqrt
18: iconst_2         // push 2
19: iload_0          // push local #0 (a)
20: imul            // integer multiply: 2*a
21: i2d             // integer to double
22: ddiv            // double division: numerator / denominator
23: dreturn         // return x

static double positiveRoot3AC(int, int, int);
Code:
0: iconst_m1
1: iload_1
2: imul
3: istore_3
4: iload_1
5: iload_1
6: imul
7: istore 4
9: iload_0
10: iload_2
11: imul
12: istore 5
14: iconst_4
15: iload 5
17: imul
18: istore 6
20: iload 4
22: iload 6
24: isub
25: istore 7
27: iload 7
29: i2d
30: invokestatic #6; //Method java/lang/Math.sqrt:(D)D
33: dstore 8
35: iload_3
36: i2d
37: dload 8
39: dadd
40: dstore 10
42: iconst_2
43: iload_0
44: imul
45: istore 12
47: dload 10
49: iload 12
51: i2d
52: ddiv
53: dstore 13
55: dload 13
57: dreturn
}

```