



## Seminar 4

1. For each  $k > 0$  we consider the differential equation

$$\dot{x} = -k(x - 21),$$

which is the model of Newton for cooling processes, here  $x(t)$  being the temperature of a cup of tea at time  $t$ .

(a) Find its flow. (b) An experiment revealed the following fact. A cup of tea with initial temperature of  $49^\circ C$  has a temperature of  $37^\circ C$  after 10 minutes. Find the initial temperature of a cup of tea such that after 20 minutes the tea has  $37^\circ C$ .  $\diamond$

**Theorem 1** Let  $f \in C^1(\mathbb{R})$  and  $\eta^* \in \mathbb{R}$  be such that  $f(\eta^*) = 0$ .

If  $f'(\eta^*) < 0$  then  $\eta^*$  is an attractor equilibrium point of  $\dot{x} = f(x)$ .

If  $f'(\eta^*) > 0$  then  $\eta^*$  is a repeller equilibrium point of  $\dot{x} = f(x)$ .

2. Let  $0 < c < 1$  be a parameter and consider the scalar dynamical system

$$\dot{x} = x(1 - x) - cx.$$

a) Find its equilibria and study their stability using the linearization method.

b) Represent its phase portrait.

c) When  $x(t) > 0$  is considered to be the density of fish in a lake, and  $0 < c < 1$  to be the rate of fishing, try to predict the fate of the fish from the lake interpreting the theoretical result obtained at a) and b).  $\diamond$

3. Represent the phase portrait of the scalar dynamical system

$\dot{x} = x - x^3$ . Find  $\varphi(t, -1)$  and  $\varphi(t, 0)$  and justify. Specify the properties of the functions  $\varphi(t, -2)$ ,  $\varphi(t, 3)$  and, respectively,  $\varphi(t, -0.5)$ .

4. Represent the phase portrait of the scalar dynamical systems

a)  $\dot{x} = x - x^3 + 1$ ; b)  $\dot{x} = -x^3$ ; c)  $\dot{x} = x^3$ ; d)  $\dot{x} = -x^2$ . Try to use the linearization method.

1. For each  $k > 0$  we consider the differential equation

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Flow  $\rightarrow$  multimea tuturor soluțiilor posibile  
 $\varphi(\cdot, \mu)$  is the solution of the  $\begin{cases} x' = f(x) \\ x(0) = \mu \end{cases}$

a) let  $\mu \in \mathbb{R}$  fixed

$$\begin{cases} x' = -k(x - 21) \\ x(0) = 0 \end{cases}$$

$$\frac{x'}{x-21} = -k$$

$$(\ln(x-21))' = -k \quad | \int$$

$$x-21 = e^{-kt} \cdot C$$

$$x(t) = e^{-kt} \cdot C + 21$$

$$\mu = x(0) = 21 + C$$

$$C = \mu - 21$$

$$\Rightarrow x(t) = (\mu - 21) \cdot e^{-kt} + 21$$

$$\varphi(t, \mu) = (\mu - 21) e^{-kt} + 21$$

$x^*$  equilibrium point iff  $(x^*)' = 0$

$$0 = (x^*)' = f(x^*)$$

We find the equilibrium points by solving  $f(x) = 0$

$$-k(x - 21) = 0 \Rightarrow x^* = 21$$

b)  $49^\circ\text{C} \xrightarrow[t=0]{t=10} 37^\circ\text{C}$   
 initial state  $t=0$

$$\varphi(10, 49) = (49 - 21) \cdot e^{-k \cdot 10}$$

$$37 = 28 e^{-10k} + 21$$

$$e^{-10k} = \frac{16}{28} = \frac{4}{7} \Rightarrow k = -\frac{1}{10} \ln \frac{4}{7}$$

$x^\circ \xrightarrow{20'} 37^\circ$

$$\varphi(20, \mu) = 37$$

$$(\mu - 21) e^{-20k} + 21 = 37$$

$$(\mu - 21) (e^{-10k})^2 = 16$$

$$(\mu - 21) \frac{16}{49} = 16$$

$$\mu - 21 = 49$$

$$\mu = 70 \Rightarrow t_* = 70^\circ$$

2. Let  $0 < c < 1$  be a parameter and consider the scalar dynamical system

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a) Find its equilibria and study their stability using the linearization method.

b) Represent its phase portrait.

c) When  $x(t) > 0$  is considered to be the density of fish in a lake, and  $0 < c < 1$  to be the rate of fishing, try to predict the fate of the fish from the lake interpreting the theoretical result obtained at a) and b).  $\diamond$

Problem  $x' = f(x)$ ,  $x^*$  eq. points:  $f(x^*) = 0$

$x^*$   $\begin{cases} \text{attractor} \\ \text{repeller} \end{cases}$

$x^*$  is an attractor if  $\exists \mu > 0$  s.t.  $|\varphi(t, x^*) - \varphi(t, \mu)| \rightarrow 0, t \rightarrow \infty \forall \mu \in B(x^*, \mu)$

$$\begin{cases} x' = 1 - x \\ f(x) = 1 - x \end{cases}$$

$$x^* = 1 \text{ eq. point}$$

$$\varphi(t, \mu) = -e^{-t} \cdot (1 - \mu) + 1 \Rightarrow \varphi(t, 1) = 1$$

$$|\varphi(t, \mu) - \varphi(t, x^*)| = |-e^{-t}(1 - \mu) + 1 - 1| = e^{-t} |1 - \mu| \rightarrow 0 \quad t \rightarrow \infty$$

\* exam

$$x' = f(x)$$

$x^*$  eq. point

if  $f'(x^*) < 0 \Rightarrow x^*$  is an attractor

$f'(x^*) > 0 \Rightarrow x^*$  is a repeller

Phase portrait



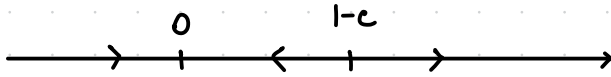
$$x' = x(1 - x) - cx, \quad c \in (0, 1)$$

$$a) \quad \begin{aligned} f(x) &= x(1-x) - cx = 0 \\ x(1-x-c) &= 0 \Rightarrow \begin{cases} x_1^* = 0 \\ x_2^* = 1-c \end{cases} \end{aligned}$$

$$f'(x) = 1 - 2x - c$$

$$f'(0) = 1 - c$$

$$\left. \begin{aligned} f'(1-c) &= 1 - 2 + 2c - c = c - 1 \\ c &\in (0, 1) \end{aligned} \right\} \Rightarrow \begin{aligned} f'(0) &> 0 \text{ - attract.} \\ f'(1-c) &< 0 \text{ - repeller} \end{aligned}$$



3. Represent the phase portrait of the scalar dynamical system

$\dot{x} = x - x^3$ . Find  $\varphi(t, -1)$  and  $\varphi(t, 0)$  and justify. Specify the properties of the functions  $\varphi(t, -2)$ ,  $\varphi(t, 3)$  and, respectively,  $\varphi(t, -0.5)$ .

$$x' = x - x^3$$

$$\varphi(t, \mu) = \begin{cases} x' = f(x) \\ x(0) = \mu \end{cases}$$

Orbits imaginea solutiilor

$$x' = f(x)$$

$\varphi(t, \mu)$  flow

$$\mathcal{O}(\mu) = \{ \varphi(t, \mu) \mid t \in \text{domain} \} \rightarrow \text{orbit}$$

if  $x_1^*, x_2^*$  eq points

$$\Psi(\mu_1) = \Psi(\mu_2) \quad \forall \quad \mu_1, \mu_2 \in (-\infty, x_1^*)$$

$$\mu_1, \mu_2 \in (x_1^*, x_2^*)$$

$$\mu_1, \mu_2 \in (x_2^*, \infty)$$

$$\Psi(\mu_1) = (-\infty, x_1^*), \quad \mu \in (-\infty, x_1^*)$$

$$\Psi(\mu_2) = (x_1^*, x_2^*), \quad \mu \in (x_1^*, x_2^*)$$

$\varphi(t, \mu) \rightarrow$  is increasing in  $\mu$

$$\varphi(t, \mu_1) \leq \varphi(t, \mu_2) \quad \forall \quad \mu_1 \leq \mu_2$$

$$x' = x - x^3$$

$$f(x) = x(1-x^2)$$

$$x(1-x^2) = 0 \Rightarrow \begin{cases} x_1^* = 0 \\ x_2^* = 1 \\ x_3^* = -1 \end{cases}$$

$$\gamma(-\infty, x_3^*) = (-\infty, -1)$$

$$\gamma(x_3^*, x_1^*) = (-1, 0)$$

$$\gamma(x_1^*, x_2^*) = (0, 1)$$

$$\gamma(x_2^*, +\infty) = (1, \infty)$$

4. Represent the phase portrait of the scalar dynamical systems

a)  $\dot{x} = x - x^3 + 1$ ; b)  $\dot{x} = -x^3$ ; c)  $\dot{x} = x^3$ ; d)  $\dot{x} = -x^2$ . Try to use the linearization method.

$$\text{a) } \underline{\dot{x} = x - x^3 + 1 = 0}$$

$$\text{b) } \left. \begin{array}{l} \dot{x} = -x^3 \\ f(x) = 0 \end{array} \right\} \Rightarrow x = 0 \Rightarrow x_1^* = 0 \text{ eq. point}$$

$$f'(x) = -3x^2$$

$$f'(x_1^*) = f'(0) = 0$$

$$\left\{ \begin{array}{l} \dot{x} = -x^3 \\ x_0 = \mu \end{array} \right\} \Rightarrow \frac{\dot{x}}{x^3} = -1$$

$$\frac{x^2}{2} = -t$$

$$\frac{1}{x^2(t)} = 2t - 2c$$

$$x^2(t) = \frac{1}{2t - 2c}$$

$$x(t) = \frac{1}{\sqrt{2t - 2c}} \Rightarrow x(0) = \frac{1}{\sqrt{-2c}} \Rightarrow |c| = \frac{1}{2\mu^2} \left\{ \begin{array}{l} c < 0 \\ \Rightarrow c = -\frac{1}{2\mu^2} \end{array} \right.$$

$$\gamma(t, \mu) = \frac{1}{\sqrt{2t + \frac{1}{\mu^2}}}$$

$$|\gamma(t, \mu) - \gamma(t, 0)|$$

$$\left| \frac{1}{\sqrt{2t + \frac{1}{\mu^2}}} - \frac{1}{\sqrt{2t}} \right| = \left| \frac{\sqrt{2t} - \sqrt{2t + \frac{1}{\mu^2}}}{\sqrt{2t} \cdot \sqrt{2t + \frac{1}{\mu^2}}} \right| \rightarrow 0 \Rightarrow \text{attractor}$$

