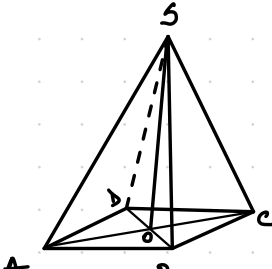


11. Show that  $\vec{SA} + \vec{SB} + \vec{SC} + \vec{SD} = 4\vec{SO}$



$$\begin{aligned}\vec{SA} &= \vec{SO} + \vec{OA} & \vec{OA} &= \frac{1}{3}\vec{OB} + \frac{2}{3}\frac{\vec{OC}}{2} \\ \vec{SB} &= \vec{SO} + \vec{OB} & \vec{OB} &= \frac{1}{3}\vec{OA} + \frac{2}{3}\frac{\vec{OC}}{2} \\ \vec{SC} &= \vec{SO} + \vec{OC} & \vec{OC} &= \frac{1}{3}\vec{OA} + \frac{1}{3}\vec{OB} + \frac{1}{3}\vec{OC} \\ \vec{SD} &= \vec{SO} + \vec{OD} & \vec{OD} &= \frac{1}{3}\vec{OA} + \frac{1}{3}\vec{OB} + \frac{1}{3}\vec{OC}\end{aligned}$$

$$\vec{SA} + \vec{SB} + \vec{SC} + \vec{SD} = 4\vec{SO}$$

2.9. Determine parametric equations for the plane  $\pi$  in the following cases:

- ☒ a)  $\pi$  contains the point  $M(1, 0, 2)$  and is parallel to the vectors  $\mathbf{a}_1(3, -1, 1)$  and  $\mathbf{a}_2(0, 3, 1)$ ,  
☒ b)  $\pi$  contains the points  $A(-2, 1, 1)$ ,  $B(0, 2, 3)$  and  $C(1, 0, -1)$ ,  
☒ c)  $\pi$  contains the point  $A(1, 2, 1)$  and is parallel to  $\mathbf{i}$  and  $\mathbf{j}$ ,  
☒ d)  $\pi$  contains the point  $M(1, 7, 1)$  and is parallel coordinate plane  $Oyz$ ,  
☒ e)  $\pi$  contains the points  $M_1(5, 3, 4)$  and  $M_2(1, 0, 1)$ , and is parallel to the vector  $\mathbf{a}(1, 3, -3)$ ,  
☒ f)  $\pi$  contains the point  $A(1, 5, 7)$  and the coordinate axis  $Ox$ .

a)  $\pi \ni M(1, 0, 2) \quad \vec{n} \parallel \mathbf{a}_1, \mathbf{a}_2$

$$\Rightarrow \vec{r} = \begin{cases} x = x_A + \lambda x_{\vec{v}} + \mu x_{\vec{w}} \\ y = y_A + \lambda y_{\vec{v}} + \mu y_{\vec{w}} \\ z = z_A + \lambda z_{\vec{v}} + \mu z_{\vec{w}} \end{cases}$$

$$\Rightarrow \begin{vmatrix} x - x_A & y - y_A & z - z_A \\ x_{\vec{v}} & y_{\vec{v}} & z_{\vec{v}} \\ x_{\vec{w}} & y_{\vec{w}} & z_{\vec{w}} \end{vmatrix} = 0$$

$$\Rightarrow \vec{r} = \begin{cases} x = 1 + 3\lambda + 0\mu \\ y = 0 - 1\lambda + 3\mu \\ z = 2 + \lambda + \mu \end{cases}$$

$$\Rightarrow \begin{vmatrix} x - 1 & y & z - 2 \\ 3 & -1 & 1 \\ 0 & 3 & 1 \end{vmatrix} = 0 \Rightarrow D(\vec{n}) = \langle (3, -1, 1), (0, 3, 1) \rangle$$

b)  $A(-2, 1, 1) \quad B(0, 2, 3) \quad C(1, 0, -1)$

$$\vec{AB} = (0 - (-2), 2 - 1, 3 - 1) = (2, 1, 2)$$

$$\vec{BC} = (1, -2, -4)$$

$$\Rightarrow \vec{r} = \begin{cases} x = 0 + \lambda \cdot 2 + \mu \cdot 1 \\ y = 2 + \lambda \cdot 1 + \mu \cdot (-2) \\ z = 3 + \lambda \cdot 2 + \mu \cdot (-4) \end{cases}$$

$$\Rightarrow \begin{vmatrix} x & y - 2 & z - 3 \\ 2 & 1 & 2 \\ 1 & -2 & -4 \end{vmatrix} = 0 \Rightarrow D(\vec{n}) = \langle (2, 1, 2), (1, -2, -4) \rangle$$

c)  $A(1, 2, 1) \quad \vec{n} \parallel (1, 0, 0), (0, 1, 0) \Rightarrow \vec{v} = (1, 0, 0) \quad \vec{w} = (0, 1, 0)$

$$\vec{r} = \begin{cases} x = 1 + \lambda \cdot 1 + \mu \cdot 0 \\ y = 2 + \lambda \cdot 0 + \mu \cdot 1 \\ z = 1 + \lambda \cdot 0 + \mu \cdot 0 \end{cases}$$

$$\Rightarrow \begin{vmatrix} x-1 & y-2 & z-1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{vmatrix} = 0 \Rightarrow D(\tilde{\eta}) = \langle (1, 0, 0), (0, 1, 0) \rangle$$

d)  $M(1, 4, 1) \quad \tilde{\eta} \parallel Oyz$

$$\tilde{\eta} = \begin{vmatrix} x-1 & y-2 & z-1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = 0 \Rightarrow D(\tilde{\eta}) = \langle (0, 1, 0), (0, 0, 1) \rangle$$

e)  $M_1(0, 3, 4) \quad M_2(1, 0, 1) \in \tilde{\eta} \quad \tilde{\eta} \parallel a_1(1, 3, -3)$

$$\overrightarrow{M_1 M_2} = (-1, -3, -3)$$

$$\tilde{\eta} = \begin{cases} x = 5 + \lambda - 4\mu \\ y = 3 + 0 - 3\mu \\ z = 4 + \lambda - 3\mu \end{cases}$$

$$\Rightarrow D(\tilde{\eta}) = \langle (1, 0, 1), (-4, -3, -3) \rangle$$

f)  $A(1, 5, 4) \in \tilde{\eta} \quad \tilde{\eta} \parallel O_x \Rightarrow \text{determined by } \begin{cases} O_x = (1, 0, 0) \\ O_A = (1, 5, 4) \end{cases}$

$$\tilde{\eta} = \begin{cases} x = 1 + \lambda + \mu \\ y = 5 + 5\mu \\ z = 4 + 4\mu \end{cases} \Rightarrow D(\tilde{\eta}) = \langle (1, 0, 0), (1, 5, 4) \rangle$$

2.3. With the assumptions in Example 1.20, give parametric equations and Cartesian equations for the lines AB, AC, BC both in the coordinate system  $\mathcal{K}$  and in the coordinate system  $\mathcal{K}'$ .

**Example 1.20** (In dimension 2). Let  $\mathcal{K} = (O, (i, j))$  and  $\mathcal{K}' = (O', (i', j'))$  be two coordinate systems (reference frames) of  $\mathbb{E}^2$ . Suppose that we know  $O', i'$  and  $j'$  relative to  $\mathcal{K}$ :

$$[O']_{\mathcal{K}} = \begin{bmatrix} 7 \\ -1 \end{bmatrix}_{\mathcal{K}}, \quad i' = -2i + j = \begin{bmatrix} -2 \\ 1 \end{bmatrix}_{\mathcal{K}}, \quad j' = i + 2j = \begin{bmatrix} 1 \\ 2 \end{bmatrix}_{\mathcal{K}}.$$

$$A(x_A, y_A)$$

$$K(O, i, j)$$

$$i' = -2i + j$$

$$B(x_B, y_B)$$

$$K'(O', i', j')$$

$$j' = i + 2j$$

$$C(x_C, y_C)$$

$$\mathcal{M}_{\mathcal{K}\mathcal{K}'} = \begin{pmatrix} -2 & 1 \\ 1 & 2 \end{pmatrix}$$

$$\begin{cases} x = i \cdot x_A + j \cdot y_A \\ \vdots \end{cases} \Rightarrow [x]_{\mathcal{K}'} = \begin{pmatrix} -2 & 1 \\ 1 & 2 \end{pmatrix} \cdot \begin{pmatrix} x_A \\ y_A \end{pmatrix} = \begin{pmatrix} -2x_A + y_A \\ x_A + 2y_A \end{pmatrix}$$

$$[x]_{\mathcal{K}'} = (-2x_A + y_A)i' + (x_A + 2y_A)j'$$