

## Continuous Dynamical Systems<sup>1</sup>

**1.** Represent the phase portrait of the scalar dynamical system  $\dot{x} = 1 - x^2$ . Find  $\varphi(t, 1)$  and justify. Specify the properties of the functions  $\varphi(t, 2)$  and, respectively,  $\varphi(t, 0.5)$ .

**2.** Let  $0 < c < 1$  be a parameter and consider the scalar dynamical system  $\dot{x} = x(1 - x) - cx$ .

- a) Find its equilibria and study their stability using the linearization method.
- b) Represent its phase portrait.
- c) When  $x(t) > 0$  is considered to be the density of fish in a lake, and  $0 < c < 1$  to be the rate of fishing, try to predict the fate of the fish from the lake interpreting the theoretical result obtained at a) and b).  $\diamond$

**3.** Let  $c > 1/4$  be a parameter and consider the scalar dynamical system  $\dot{x} = x(1 - x) - c$ .

- a) Represent its phase portrait.
- b) When  $x(t) \geq 0$  is considered to be the density of fish in a lake, and  $c > 1/4$  to be the rate of fishing, try to predict the fate of the fish from the lake interpreting the theoretical result obtained at a).  $\diamond$

**4.** Represent the phase portrait of the scalar dynamical system  $\dot{x} = 2 - x^2$ . Study the stability of the equilibrium points using the linearization method. Find  $\varphi(t, \sqrt{2})$  and specify the properties of the functions  $\varphi(t, -1.5)$ ,  $\varphi(t, 0)$  and  $\varphi(t, 2)$ .  $\diamond$

**5.** Represent the phase portrait of the scalar dynamical system  $\dot{x} = 2x - x^2$ . Study the stability of the equilibrium points using the linearization method. Find  $\varphi(t, 2)$ ,  $\varphi(t, 0)$  and study the properties of the functions  $\varphi(t, -2)$ ,  $\varphi(t, 1)$  and  $\varphi(t, 3)$ .

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If there is an attractor, specify its basin of attraction.  $\diamond$

**6.** Represent the phase portrait, specify the orbits and emphasize the properties of the solution  $\varphi(\cdot, \eta)$  for any  $\eta \in \mathbb{R}$  for the following equations. Specify the stability of the equilibria.

(a)  $\dot{x} = x - x^2$ , (b)  $\dot{x} = x - x^3 + 1$ , (c)  $\dot{x} = x - x^3 + 0.2$ , (d)  $\dot{x} = -x - x^3 + 1$ ,  
(e)  $\dot{x} = 2 \sin x$ , (f)  $\dot{x} = 1 - 2 \sin x$ , (g)  $\dot{x} = 1 - \sin x$ , (h)  $\dot{x} = 2 - \sin x$ , (i)  $\dot{x} = \tanh x$ .  $\diamond$

**7.** Represent the phase portrait of  $\dot{x} = \lambda - x^2$ . Discuss with respect to the parameter  $\lambda \in \mathbb{R}$ .  $\diamond$

**8.** We consider the following linear planar system

(a)  $\dot{x} = -6x$ ,  $\dot{y} = -3y$ , (b)  $\dot{x} = -6y$ ,  $\dot{y} = -3x$ , (c)  $\dot{x} = 6y$ ,  $\dot{y} = -3x$ , (d)  
 $\dot{x} = x$ ,  $\dot{y} = -3y$ , (e)  $\dot{x} = 2y$ ,  $\dot{y} = -3x$ , (f)  $\dot{x} = -2y$ ,  $\dot{y} = 2x$ .

i) Find its flow.

ii) Specify the type and stability of this linear system.

iii) Find a first integral. There is a global first integral?

iv) Represent its phase portrait.  $\diamond$

**9.** Specify the type and stability of the linear systems

(a)  $\dot{x} = 4x - 5y$ ,  $\dot{y} = x - 2y$ , (b)  $\dot{x} = x + y$ ,  $\dot{y} = -2x + 4y$ , (c)  
 $x' = x + y$ ,  $y' = x - 4y$ .  $\diamond$

**10.** (i) For what values of the real parameter  $a$ , the system  $\dot{x} = ax - 5y$ ,  
 $\dot{y} = x - 2y$  is a center?. In that cases find the general solution of the system.

(ii) For what values of the real parameter  $a$ , the system from (i) has a line filled with equilibrium points?  $\diamond$

**11.** There are uncoupled linear systems which are centers?  $\diamond$

**12.** Find all the equilibrium points of the nonlinear planar system  $\dot{x} = x(1 - x)$ ,  
 $\dot{y} = (y + 1)(y - 2)$ .  $\diamond$

**13\*.** Represent the phase portrait of the following uncoupled (product) systems

(a)  $\dot{x} = x(1 - x)$ ,  $\dot{y} = 0$  , (b)  $\dot{x} = x(1 - x)$ ,  $\dot{y} = y$  , (c)  $\dot{x} = x(1 - x)$ ,  $\dot{y} = (y + 1)(y - 2)$  .  $\diamond$

**14.** Find the equilibrium points and decide whether they are or not hyperbolic, for the nonlinear planar system  $\ddot{\theta} + \dot{\theta} + \theta^3 = 0$ .  $\diamond$

**15.** We consider the following nonlinear planar systems

$$\dot{x} = -x + xy, \quad \dot{y} = -2y + 3y^2.$$

a) Find its equilibrium points and study their stability using the linearization method.

b) Find  $\varphi(t, 0, 2/3)$ ,  $\varphi(t, 4, 0)$  and  $\varphi(t, 1, 2/3)$ .

c) Represent in the phase plane the orbits corresponding to the initial values  $(0, 2/3)$ ,  $(4, 0)$  and  $(1, 2/3)$ .  $\diamond$

**16.** Consider the following planar system

$$\dot{x} = 2x - x^2, \quad \dot{y} = y - xy^2.$$

a) Find the equilibrium points and study their stability.

b) Find  $\varphi(t, 2, 1/2)$ ,  $\varphi(t, 2, 0)$  and  $\varphi(t, 0, 2)$ .  $\diamond$

**17.** Find the polar coordinates of the following points of cartesian coordinates. Represent all these points in the plane.

$(0, 1)$ ,  $(1, 0)$ ,  $(2, 0)$ ,  $(0, 3)$ ,  $(-3, 0)$ ,  $(0, -2)$ ,  $(1, 1)$ ,  $(1, 1/2)$ ,  $(-2, 1)$ ,  $(-6, -3)$ ,  
 $(\eta_1 \cos t - \eta_2 \sin t, \eta_1 \sin t + \eta_2 \cos t)$  where  $t \in \mathbb{R}$  and  $(\eta_1, \eta_2) \in \mathbb{R}^2 \setminus \{(0, 0)\}$ ,  
 $(\eta_1 e^t \cos t - \eta_2 e^t \sin t, \eta_1 e^t \sin t + \eta_2 e^t \cos t)$  where  $t \in \mathbb{R}$  and  $(\eta_1, \eta_2) \in \mathbb{R}^2 \setminus \{(0, 0)\}$ .  
 $\diamond$

**18.** We consider the linear planar system  $\dot{x} = -x + y$ ,  $\dot{y} = -x - y$ . Specify its type and stability. Pass to polar coordinates. Represent its phase portrait.  $\diamond$

**19.** Consider the following planar system

$$\dot{x} = x - 2xy, \quad \dot{y} = x - y.$$

Find the equilibrium points and study their stability.  $\diamond$

**20.** Consider the following planar system

$$\dot{x} = -y(x^2 + y^2), \quad \dot{y} = x(x^2 + y^2).$$

- a) Does this system have other equilibria besides  $(0, 0)$ ? Justify.
- b) Decide whether the equilibrium point  $(0, 0)$  is hyperbolic or not.
- c) Verify that  $\varphi(t, 1, 0) = (\cos t, \sin t)$ ,  $\varphi(t, 2, 0) = (2 \cos 4t, 2 \sin 4t)$  for all  $t \in \mathbb{R}$ . Find  $\varphi(t, 3, 0)$ . Represent the corresponding orbits.
- d) Pass to polar coordinates and represent the phase portrait. Deduce that all the solutions of the system are periodic.  $\diamond$

**21.** We consider the planar system

$$\dot{x} = -y + x(1 - x^2 - y^2), \quad \dot{y} = x + y(1 - x^2 - y^2).$$

- a) Study the stability of the equilibrium point  $(0, 0)$  using the linearization method. There are other equilibrium points?
- b) Check that  $\varphi(t, 1, 0) = (\cos t, \sin t)$  for all  $t \in \mathbb{R}$ . Represent the corresponding orbit.  $\diamond$

**22.** Consider the following planar system

$$\dot{x} = -y - x(x^2 + y^2), \quad \dot{y} = x - y(x^2 + y^2).$$

- a) Does this system have other equilibria besides  $(0, 0)$ ? Justify.
- b) Prove that the equilibrium point  $(0, 0)$  is not hyperbolic.
- c) Use the system obtained by passing to polar coordinates to determine the shape of the orbits.  $\diamond$

**23.** Denote by  $x(t)$  the density of a trout population at time  $t$ . Describe its evolution in each of the following cases.

- (a)  $\dot{x} = 100x$ .
- (b)  $\dot{x} = 100x - x^2$ .

Assume that someone is fishing, first with a constant rate  $k > 0$ , that is,

- (c)  $\dot{x} = 100x - x^2 - k$ ,

and another one, in another basin, with rate proportional to the density,  $kx(t)$ , where  $k > 0$ , that is,

- (d)  $\dot{x} = 100x - x^2 - kx$ .

Discuss with respect to  $k$ .  $\diamond$

**24.** For each  $k > 0$  we consider the differential equation

$$\dot{x} = -k(x - 21),$$

which is the model of Newton for cooling processes, here  $x(t)$  being the temperature of a cup of tea at time  $t$ .

(a) Find its flow. (b) An experiment revealed the following fact. A cup of tea with initial temperature of  $49^\circ C$  has a temperature of  $37^\circ C$  after 10 minutes. Find the initial temperature of a cup of tea such that after 20 minutes the tea has  $37^\circ C$ .  $\diamond$

**25.** Find a global first integral of the following nonlinear planar system  $\ddot{\theta} + \omega^2 \sin \theta = 0$  (where  $\omega > 0$ ).  $\diamond$

**26.** Find a first integral in  $(0, \infty) \times (0, \infty)$  of the following nonlinear planar system  $\dot{x} = N_1x - xy$ ,  $\dot{y} = -N_2y + xy$  (where  $N_1, N_2 > 0$ ).  $\diamond$

**27.** Find a first integral in  $(0, \infty) \times (0, \infty)$  of the following nonlinear planar system  $\dot{x} = x - xy$ ,  $\dot{y} = -0.3y + 0.3xy$ .  $\diamond$

**28.** a) Give an example of a coupled linear planar system which has a node at the origin.

b) Give an example of a coupled linear planar system which has a saddle at the origin.  $\diamond$

**29.** Find the the flow of each of the systems. Decide whether, for every  $\eta \in \mathbb{R}^2$  we have  $\lim_{t \rightarrow \infty} \varphi(t, \eta) = 0$  or we have that  $\varphi(t, \eta)$  is bounded for  $t \in (0, \infty)$ .

a)  $x' = -2x$ ,  $y' = -3y$

b)  $x' = -2x$ ,  $y' = 3y$

c)  $x' = -3x$ ,  $y' = x - 3y$

d)  $x' = y$ ,  $y' = \omega^2 x$  (here  $\omega > 0$  is a parameter)

e)  $x' = -x - y$ ,  $y' = x - y$

f)  $x' = -5x - 9y$ ,  $y' = 2x + y$ .  $\diamond$