

Name Leg	Shoulder ID	Hip ID	Knee ID
FR Forward Right	1	5	9
BR Behind Right	2	6	10
FL Forward Left	3	7	11
BL Behind Left	4	8	12

## Send data Arduino to Python

	Len	Position Hip				Position Knee					Load Knee			
oxff oxff	ox19	FR	BR	FL	BL	FR	BR	FL	BL	FR	BR	FL	BL	sum

## Send data Python to Arduino

Len		Positio	п нір	Position Knee					
oxFF oxFF ox1	9 FR	BR	FL	BL	FR	BR	FL	BL	sum