

Name Leg	Shoulder ID	Hip ID	Knee ID
FR Forward Right	1	5	9
BR Behind Right	2	6	10
FL Forward Left	3	7	11
BL Behind Left	4	8	12

Send data Arduino to Python

	Len	Position Hip				Position Knee					Load Knee			
oxff oxff	ox19	FR	BR	FL	BL	FR	BR	FL	BL	FR	BR	FL	BL	sum

Send data Python to Arduino

	Len		ositio	п нір	Position Knee					
oxFF oxF	ox11	FR	BR	FL	BL	FR	BR	FL	BL	sum