**Installation**

1.download folder in git hub

git clone <https://github.com/pattarong-RAE/Cheetah_Cube_Inspire.git>

cd ./Cheetah\_Cube\_Inspire

2.install library and setup env with python

mkdir ./Python\_code

python -m venv ./Python\_code

./Python\_code/Script/activate

pip install -r ./Python\_code /Script/lib.txt

cd ./Script

3.Burn board NODEMCU ESP32 file name “CheetahArduino.ino”



4.Run control robot this file “main.py”

python ./main.py

run in folder terminal

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cd ./Cheetah\_Cube\_Inspire

mkdir ./Python\_code

python -m venv ./Python\_code

./Python\_code/Script/activate

pip install -r ./Python\_code /Script/lib.txt

cd ./Script

python ./main.py