

Recall

$$s = f(x; W) = Wx \quad \text{score function}$$

$$L_i = \sum_j y_j \max(0, s_j - s_{y_j} + 1) \quad \text{SVM loss}$$

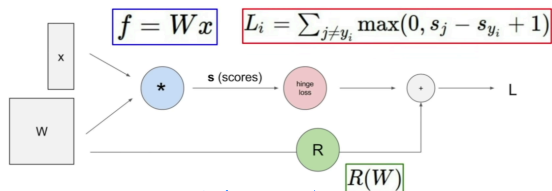
$$L = \frac{1}{N} \sum_{i=1}^N L_i + \sum_k W_k^2 \quad \text{data loss + regularization}$$

want $\nabla W L$

→ solve it with optimization $\left(\begin{array}{l} \text{analytic gradient} \\ \text{numerical gradient} \end{array} \right)$

analytic gradient (thru computational graphs)

Computational graphs



- important to calculate gradient for neural network (complex function)

- e.g. find gradient

$$f(x, y, z) = (x+y)z$$

$$\textcircled{a} x=-2, y=5, z=-4$$

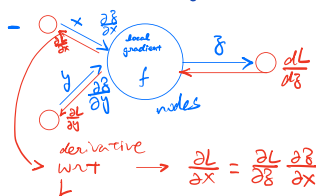
$$g = x+y \quad \frac{\partial g}{\partial x} = 1 \quad \frac{\partial g}{\partial y} = 1$$

$$f = g \times z \quad \frac{\partial f}{\partial g} = z \quad \frac{\partial f}{\partial z} = g$$

$$\text{find } \frac{df}{dx} \quad \frac{df}{dy} \quad \frac{df}{dz}$$

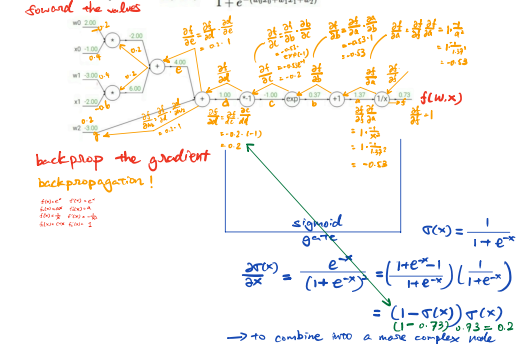
$$\text{chain rule} \quad \frac{\partial f}{\partial x} = \frac{\partial f}{\partial g} \frac{\partial g}{\partial x} \quad \frac{\partial f}{\partial y} = \frac{\partial f}{\partial g} \frac{\partial g}{\partial y} \quad \frac{\partial f}{\partial z} = \frac{\partial f}{\partial z} \frac{\partial z}{\partial z}$$

$$\text{back-propagation} \quad \frac{\partial f}{\partial x} = \frac{\partial f}{\partial g} \frac{\partial g}{\partial x} \quad \frac{\partial f}{\partial y} = \frac{\partial f}{\partial g} \frac{\partial g}{\partial y} \quad \frac{\partial f}{\partial z} = \frac{\partial f}{\partial z} \frac{\partial z}{\partial z}$$

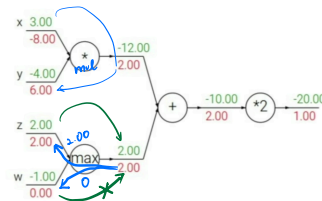


Another example:

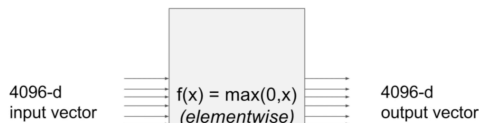
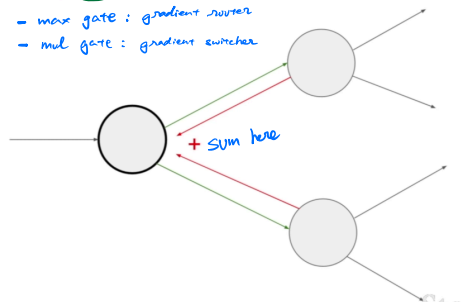
$$f(w, x) = \frac{1}{1 + e^{-(w_0 + w_1 x_1 + w_2 x_2)}}$$



other nodes (more complex ones)



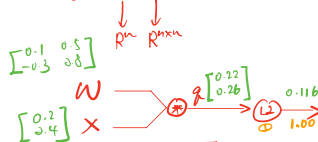
- max gate: gradient router
- mul gate: gradient splitter



Q: what is the size of the Jacobian matrix?
[4096 x 4096!]

in practice we process an entire minibatch (e.g. 100) of examples at one time:
i.e. Jacobian would technically be a [409,600 x 409,600] matrix!
(very sparse)

$$\text{e.g. } f(x, W) = \|W \cdot x\|^2 = \sum_{i=1}^n (W_i \cdot x_i)^2$$



$$g = W \cdot x = \begin{bmatrix} W_{11}x_1 + \dots + W_{1n}x_n \\ W_{21}x_1 + \dots + W_{2n}x_n \\ \vdots \\ W_{m1}x_1 + \dots + W_{mn}x_n \end{bmatrix}$$

$$f(g) = \|g\|^2 = g_1^2 + \dots + g_n^2$$

$$\nabla_g f = 2g = \begin{bmatrix} 2g_1 \\ 2g_2 \\ \vdots \\ 2g_n \end{bmatrix} \in \mathbb{R}^2$$

$$\frac{\partial f}{\partial W_{ij}} = \frac{\partial f}{\partial g_k} \frac{\partial g_k}{\partial W_{ij}} = \sum_k \frac{\partial f}{\partial g_k} \frac{\partial g_k}{\partial W_{ij}}$$

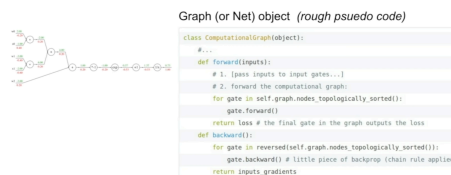
$$= \sum_k (2g_k) (\delta_{ki} x_j) = 2g_i x_j$$

$$\nabla_W f = 2g \cdot x^T$$

$$\frac{\partial f}{\partial x_i} = \sum_k \frac{\partial f}{\partial g_k} \frac{\partial g_k}{\partial x_i} = \sum_k 2g_k W_{ki} = 2W^T g$$

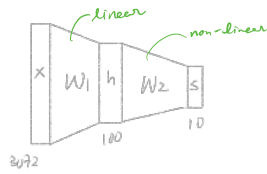
Note that: the gradient with respect to a variable should be the same shape as the variable

Modularized implementation: forward / backward API



• Neural Network

- Before Linear score function : $f = Wx$
- after 2-layer Neural Network: $f = W_2 \max(0, W_1 x)$

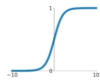


or even 3-layer ...

Activation functions

Sigmoid

$$\sigma(x) = \frac{1}{1+e^{-x}}$$



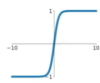
Leaky ReLU

$$\max(0.1x, x)$$



tanh

$$\tanh(x)$$



Maxout

$$\max(w_1^T x + b_1, w_2^T x + b_2)$$

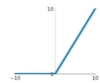
ELU

$$\begin{cases} x & x \geq 0 \\ \alpha(e^x - 1) & x < 0 \end{cases}$$



ReLU

$$\max(0, x)$$



Neural networks: Architectures

