

$\delta = h(x, y)$

ans.  $\delta = h(T, P)$

$\therefore$  @  $\Delta m$   $P_3$  w/ pos  $T_i$

overall error:

$$\frac{1}{2} \sum_{i=1}^m \sum_{j=1}^n \|e_{ij}\|^2$$

$$= \frac{1}{2} \sum_{i=1}^m \sum_{j=1}^n \|S_{ij} - h(T_i, P_j)\|^2$$

$\rightarrow$  we are adjusting the pos  $T$

at the same time

$\rightarrow$  Bundle Adjustment

$\therefore$  in the dual problem:

$$x = [T_1, \dots, T_m, P_1, \dots, P_n]^T$$

$\therefore$  when  $x \leftarrow x + \Delta x$

$$\frac{1}{2} \|S(x) - y\|^2$$

$$\approx \frac{1}{2} \sum_{i=1}^m \sum_{j=1}^n \|e_{ij}\|^2 + F_j \Delta f_j + E_{ij} \Delta p_j$$

$\uparrow$  Bundle Adjustment  $\uparrow$  Bundle Adjustment  
 $\text{w.r.t. } T_i$   $\text{w.r.t. } P_j$

we then stack all variables together:

$$x_0 = [f, f_1, \dots, f_m]^T \in \mathbb{R}^m$$

$$x_p = [P_1, P_2, \dots, P_n]^T \in \mathbb{R}^{3n}$$

$$\rightarrow \frac{1}{2} \|f(x) + \Delta x\|^2 = \frac{1}{2} \|f_0 + F \Delta x + E \Delta p\|^2$$

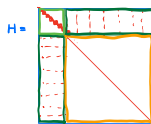
$$\rightarrow H \Delta x = g$$

$$H = J^T J \text{ or } J^T J + \lambda I$$

$$J = [F \ E]$$

$$J^T J = \begin{bmatrix} F^T F & F^T E \\ E^T F & E^T E \end{bmatrix}$$

Schur Trick



$$H = \begin{bmatrix} B & E \\ E^T & C \end{bmatrix}$$

$$\Rightarrow H \Delta x = g \Leftrightarrow \begin{bmatrix} B & E \\ E^T & C \end{bmatrix} \begin{bmatrix} \Delta x_c \\ \Delta x_p \end{bmatrix} = \begin{bmatrix} v \\ w \end{bmatrix}$$