

## • Term project:

- project proposal
- term project report
- online/offline project presentation

### - vector $X$

$$X \in \mathbb{R}^n$$

$$X = [x_1, x_2, \dots, x_n]^T = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

### - Matrix $X$

$$X \in \mathbb{R}^{m \times n}$$

$$X = \begin{bmatrix} x_{11} & x_{12} & \dots & x_{1n} \\ x_{21} & x_{22} & \dots & x_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ x_{m1} & x_{m2} & \dots & x_{mn} \end{bmatrix} = \begin{bmatrix} x_1^T \\ x_2^T \\ \vdots \\ x_m^T \end{bmatrix} \in \mathbb{R}^{m \times n}$$

$$X_{i:} \Rightarrow i^{\text{th}} \text{ row of } X$$

( $X_{:j}$  column)

$$X_{:j} \Rightarrow j^{\text{th}} \text{ col of } X$$

### - Tensor > 2 axis

element-wise product

$$C_{ij} = A_{ij} B_{ij}$$

### - matrix product

$$C_{ij} = \sum_k A_{ik} B_{kj}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a & c \\ b & d \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

### - Inverse

$$A^{-1}A = I$$

### - norm

vector norm  $L_p$   $p \geq 1$

$$\|X\|_p = \left( \sum_i |x_i|^p \right)^{1/p}$$

e.g.  $p=1$

$$\|X\|_1 = \sum_i |x_i|$$

$$\|X\|_2 = \sqrt{\sum_i x_i^2}$$

$$\|X\|_\infty = \max_i |x_i|$$

not valid but used in ML  
e.g.  $X = [0, 1, 0, 3, 2, 0]^T$

$$\|X\|_0 = 3$$

e.g. 2 dimension vector

$L_1$  norm = 1

$$\|X\|_1 = 1$$

$$x_1 + x_2 = 1$$

$$x_1 > 0$$

$$x_2 > 0$$

$$x_1 > 0$$

$$x_2 < 0$$

$$L_2 \text{ norm} = 1$$

$$\|X\|_2 = 1$$

### FACT

$$\|X\|_\infty \leq \|X\|_2 \leq \|X\|_1 \leq \sqrt{n} \|X\|_2 \leq n \|X\|_\infty$$

Proof

$$\|X\|_\infty = \max_i |x_i| = \max_i \sqrt{|x_i|^2} = \sqrt{\sum_i |x_i|^2} = \|X\|_2$$

## • Matrix Norm

$$\|A\|_F = \sqrt{\sum_{i,j} A_{i,j}^2} \neq L_2 \text{ norm matrix}$$

(Frobenius norm)

$\lambda$  = largest eigen value

$L_2$  norm matrix

$$\|A\|_2 = \sqrt{\lambda_{\max}(A)}$$

## • vector inner product

$$\langle x, y \rangle = \|x\|_2 \|y\|_2 \cos \theta$$

if  $\|y\|_2 = 1$

$$\langle x, y \rangle = \|x\|_2 \cos \theta \quad (\text{projection on } y \text{ space})$$

## • Holder's inequality

$$|\langle x, y \rangle| \leq \|x\|_p \|y\|_q \quad \text{s.t. } \frac{1}{p} + \frac{1}{q} = 1$$

e.g.  $p=2, q=2$   
 $p=1, q=\infty$

• remark:  
norm will be frequently used for regularization

## • Linear combination

$$Ax$$

## • Linear dependence, span

• orthogonal / orthonormal: all column vector are in "inner-product = 0" relations:

$$\text{orthogonal: } x^T y = 0$$

$$\|x\|_2 = \|y\|_2 = 1$$

$$\text{orthogonal: } A^T A = I$$

$$A^T = A^{-1}$$

## • eigenvalue decomposition

$$A = Q \Lambda Q^T \quad Q, Q^T \text{ are orthogonal}$$

(square matrix)

$\Lambda$  is diagonal w/  $\lambda$  values

## • quadratic form:

$$\begin{aligned} x^T A x &= x^T Q \Lambda Q^T x \\ &= (Q^T x)^T \Lambda (Q^T x) \\ &= \sum_{i=1}^n \lambda_i (z_i^T x)^2 \leq \lambda_i \sum_{i=1}^n (z_i^T x)^2 \\ &= \lambda_i \|x\|_2^2 \end{aligned}$$

(computational approach: QR decomposition)

## • Positive definite

$$\forall x, x^T A x > 0$$

$$\text{SPD}$$

$$\forall x, x^T A x \geq 0$$

quadratic form w/ PD or SPD:

$$0 \leq x^T A x \leq \lambda_1 \|x\|_2^2$$

$\hookrightarrow$  helpful sometimes

## • SVD (singular vector decomposition)

don't hv to be square matrix

$$A = U \Sigma V^T \rightarrow \begin{bmatrix} \cdot & \cdot \\ \cdot & \cdot \end{bmatrix} \text{ diagonal}$$

$$U U^T = I$$

$$V V^T = I$$

could be used in more cases

- Derivative

- chain rule

$$f(x) = h(g(x))$$

$$\frac{df}{dx} = \frac{dh}{dg} \frac{dg}{dx}$$

- $f(x) \in \mathbb{R}^1$

$$x \in \mathbb{R}^n$$

$$\frac{df(x)}{dx} = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{bmatrix}$$

- trace =

$$\sum_{i,j}^n A_{ij} \quad (\text{tr}(A))$$

- Jacobian

- $f(x) \in \mathbb{R}^{n \times 1}$

$$x \in \mathbb{R}^1$$

$$\frac{\partial f(x)}{\partial x} = \begin{bmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_2}{\partial x} & \dots & \frac{\partial f_n}{\partial x} \end{bmatrix}$$

$$df = \sum_{i=1}^n \frac{\partial f}{\partial x_i} dx_i$$

$$\text{eg } f = a^T x b$$

$$\frac{\partial f}{\partial x} = ?$$

$$df = (da^T) x b + a^T (dx) b + a^T x (db)$$

$$df = \text{tr}(df)$$

$$df = a^T (dx) b$$

$$= \text{tr}(a^T (dx) b)$$

$$= \text{tr}(b a^T (dx))$$

$$= \text{tr}[(b a^T)^T dx]$$

$$\therefore \frac{df}{dx} = a b^T$$

- Probability

- random variable

Discrete: PMF (mass-function)

PDF (density-function)

- marginal probability

- conditional probability

- independence

- expectation variance covariance

- different kinds distribution

- Bayes Rules