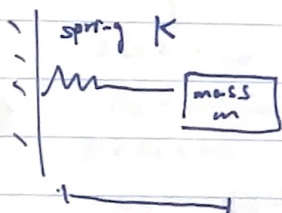


second ODE

- ① Harmonic Oscillator
 - Taylor Series
 - guess
- ② Damped Harmonic Oscillator
- ③ Higher order Linear ODEs

Guess.



$$m\ddot{x} = -kx \Rightarrow \ddot{x} = -X$$

$m=1$
 $k=1$

Guess :

$$X(t) = \cos(t) \underbrace{X(0)}_{\text{I.C.}} \quad \dot{X}(0)=0$$

$$\dot{X}(t) = -\sin(t) X(0) \quad \checkmark$$

$$\ddot{X}(t) = -\cos(t) X(0) \quad \checkmark$$

natural frequency

$$\omega_n = \sqrt{\frac{k}{m}}$$

for general $m, k \Rightarrow X(t) = \cos\left(\sqrt{\frac{k}{m}}t\right) X(0)$

$\cos \lambda t$

Taylor Series

$$X(t) = \underline{C_0} + \underline{C_1 t} + \underline{C_2 t^2} + \underline{C_3 t^3} + \underline{C_4 t^4} + \dots + \textcircled{0} (t^5) \quad (\text{assume } t \text{ is continuous})$$

$$\dot{X}(t) = C_1 + 2C_2 t + 3C_3 t^2 + 4C_4 t^3 + \dots$$

$$\ddot{X}(t) = \underline{2C_2} + \underline{3 \cdot 2 \cdot C_3 t} + \underline{4 \cdot 3 \cdot C_4 t^2} + \underline{5 \cdot 4 \cdot C_5 t^3} + \dots$$

$$\ddot{X} = -X$$

I.C.

$$C_2 = \frac{-1}{2} C_0 = -\frac{1}{2} X(0)$$

$$C_3 = \frac{-1}{3/2} C_1 = -\frac{1}{3!} \dot{X}(0)$$

$$C_4 = \frac{-1}{4 \cdot 3} C_2 = \frac{-1}{4 \cdot 3} \frac{-1}{2} C_0 = \frac{1}{4!} C_0 = \frac{1}{4!} X(0)$$

$C_0 = X(0)$ initial position
 $C_1 = \dot{X}(0)$ initial velocity.

odd $\rightarrow X(0)$
 even $\rightarrow \dot{X}(0)$

(2) $\ddot{x} = -x$

$$x(t) = C_0 + C_1 t + C_2 t^2 + C_3 t^3 + C_4 t^4 + \dots + O(t^5)$$

$$\dot{x}(t) = C_1 + 2C_2 t + 3C_3 t^2 + 4C_4 t^3 + \dots$$

$$\ddot{x}(t) = 2C_2 + 3 \cdot 2 \cdot C_3 t + 4 \cdot 3 C_4 t^2 + 5 \cdot 4 C_5 t^3 + \dots$$

$$\ddot{x} = -x$$

$$\begin{aligned} C_0 &= -2C_2 \\ C_2 &= -\frac{1}{2}C_0 \end{aligned}$$

$$2C_2 = -C_0$$

$$C_2 = -\frac{1}{2}C_0 \quad (1) \rightarrow C_2 = -\frac{1}{2}x(0)$$

$$3 \cdot 2 \cdot C_3 = -C_1$$

$$C_3 = -\frac{1}{3 \cdot 2}C_1 \quad (2) \rightarrow C_3 = -\frac{1}{3!}\dot{x}(0)$$

$$4 \cdot 3 \cdot C_4 = -C_2$$

$$C_4 = -\frac{1}{4 \cdot 3}C_2 \quad (3) \rightarrow C_4 = \frac{1}{4!}x(0)$$

$$(1) \rightarrow (3)$$

$$\begin{aligned} C_4 &= \frac{-1}{4 \cdot 3} \cdot -\frac{1}{2}C_0 \\ &= \frac{1}{4 \cdot 3 \cdot 2}C_0 \\ &= \frac{1}{4!}C_0 \end{aligned}$$

I.C. (initial condition)

$C_0 = x(0)$ initial position

$C_1 = \dot{x}(0)$ initial velocity

$$5 \cdot 4 \cdot C_5 = -C_3$$

$$C_5 = \frac{-1}{5 \cdot 4}C_3$$

$$= \frac{-1}{5 \cdot 4} \cdot -\frac{1}{3!}\dot{x}(0)$$

$$= \frac{1}{5!}\dot{x}(0)$$

Assume $\dot{x}(0) = 0$ or sth else

$$x(t) = \underbrace{\left[1 - \frac{1}{2!}t^2 + \frac{1}{4!}t^4 - \frac{1}{6!}t^6 + \dots\right]}_{\cos(t)} x(0) + \underbrace{\left[t - \frac{t^3}{3!} + \frac{t^5}{5!} - \frac{t^7}{7!} + \dots\right]}_{\sin(t)} \dot{x}(0)$$

e.g.

$$\ddot{x} + 2\dot{x} + x = 0$$

step 1: assume Taylor

step 2: express x , \dot{x} , \ddot{x} in terms of Taylor series

step 3: match the coefficients

$$\Rightarrow x(t) = \cos(t)x(0) \quad \left[\text{when } \sin(t) = 0 \right]$$

(3) Guess again

$$\left. \begin{aligned} x(t) &= e^{\lambda t} \\ \dot{x}(t) &= \lambda e^{\lambda t} = \lambda x(t) \\ \ddot{x}(t) &= \lambda^2 e^{\lambda t} \end{aligned} \right\} \ddot{x} = -x \Rightarrow \lambda^2 e^{\lambda t} = -e^{\lambda t}$$

$$\lambda^2 = -1 \quad \lambda = \pm i$$

$$\star x(t) = k_1 e^{it} + k_2 e^{-it} \star$$

$$k_1 e^{\lambda_1 t} + k_2 e^{\lambda_2 t}$$

$$x(0) = k_1 + k_2$$

$$\dot{x}(0) = i k_1 e^{it} - i k_2 e^{-it} \xrightarrow{t=0} i(k_1 - k_2) \quad \text{set } \dot{x}(0) = 0$$

$$\therefore k_1 = k_2$$

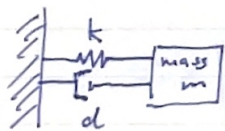
$$\dot{x}(0) = 0 \rightarrow k_1 = k_2$$

$$x(0) = 2k_1 \rightarrow k_1 = k_2 = \frac{x(0)}{2}$$

$$x(t) = \frac{x(0)}{2} [\cos(t) + i \sin(t)] + \frac{x(0)}{2} [\cos(t) - i \sin(t)]$$

$$= x(0) \cos(t)$$

e.g.



$$m\ddot{x} + d\dot{x} + kx = 0$$

$$\omega = \sqrt{\frac{k}{m}}$$

$$\ddot{x} + \zeta \dot{x} + \omega^2 x = 0$$

$$\ddot{x} + \zeta \dot{x} + \omega^2 x = 0$$

linear ODE

$$\text{let } x(t) = e^{\lambda t}$$

$$\dot{x}(t) = \lambda e^{\lambda t}$$

$$\ddot{x}(t) = \lambda^2 e^{\lambda t}$$

$$\lambda^2 e^{\lambda t} + \zeta \lambda e^{\lambda t} + \omega^2 e^{\lambda t} = 0$$

$$\Rightarrow [\lambda^2 + \zeta \lambda + \omega^2] e^{\lambda t} = 0$$

$$\underbrace{\quad}_{=0} \quad \underbrace{\quad}_{\neq 0}$$

$$\lambda^2 + \zeta \lambda + \omega^2 = 0 \quad \frac{b \pm \sqrt{b^2 - 4ac}}{-2a}$$

$$\lambda_{1,2} = \frac{-\zeta \pm \sqrt{\zeta^2 - 4\omega^2}}{2}$$

$$\frac{d}{dt} \begin{bmatrix} x \\ v \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -\omega^2 & -\zeta \end{bmatrix} \begin{bmatrix} x \\ v \end{bmatrix}$$

$$x(t) = k_1 e^{\lambda_1 t} + k_2 e^{\lambda_2 t}$$

now plug in I.C.
solve in Matlab.

$$\ddot{x} + \zeta \dot{x} + \omega^2 x = 0$$

$$\dot{x} = v$$

$$\dot{v} = -\zeta v - \omega^2 x$$