

① Eigenvalues, eigenvectors & diagonalize  $\dot{x} = Ax$

② geometry of e-vals, e-vects

③ evals evects in general

④ Examples

⑤ solution to  $\dot{x} = Ax$

Recall to diagonalize ODE  $\dot{x} = Ax$

we need a coord.  $\gamma$ -form  $\dot{x} = T\dot{z}$  s.t.  $\dot{z} = Dz$ .

$$\boxed{AT = TD}$$

eigenvalue equation

cols are diag of D  
e-vects (A) are e-val (A)

"Eigen" = characteristic or latent

$$A\vec{z} = \lambda \vec{z}$$

for special vec  $\vec{z}$   
single column vector

for special val  $\lambda$

Ex:

$$A = \begin{bmatrix} 3 & -1 \\ -1 & 3 \end{bmatrix}$$

$$\text{try } x = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$Ax = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$$

different direction

$$\text{try } x = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$Ax = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$

different direction

$$\text{try } x = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$Ax = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$$

same direction

$\rightarrow$  e-v, w  $\lambda = 2$

$$\text{try } x = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$Ax = \begin{bmatrix} 4 \\ -4 \end{bmatrix}$$

same direction

$\rightarrow$  e-v, w  $\lambda = 4$

$$\vec{z} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$Ax = \lambda x = \lambda I x$$

$$[A - \lambda I]x = 0$$

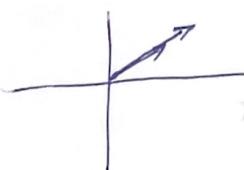
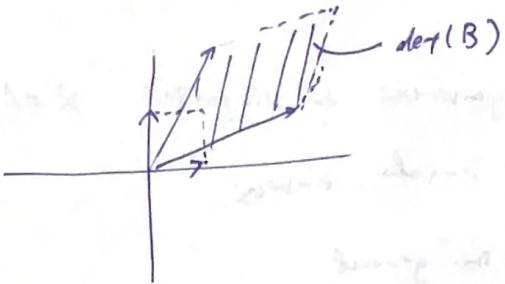
case 1 :  $x = 0$  (boring)

case 2 :  $\det[A - \lambda I] = 0$

is singular

- cannot be invertible
- column co-dependent

characteristic equation



$\det(B)$

$xA = x$  or  $Bx = 0$   
 $Bx \Rightarrow$  the resulted  
vectors collapse  
on the same

dimension lost.

$$QT = T A$$

Step 1

$$A = \begin{bmatrix} 3 & -1 \\ -1 & 3 \end{bmatrix}$$

$$[A - \lambda I]$$

$$= \begin{bmatrix} 3-\lambda & -1 \\ -1 & 3-\lambda \end{bmatrix}$$

$$(3-\lambda)^2 - (-1 \times -1)$$

$$= \lambda^2 - 6\lambda + 8$$

$$= (\lambda-4)(\lambda-2)$$

$$\lambda_1 = 2$$

$$\lambda_2 = 4$$

$$\lambda_1 = 2$$

$$A - 2I = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0$$

$$\begin{cases} x_1 - x_2 = 0 \\ -x_1 + x_2 = 0 \end{cases} \xrightarrow{\text{true if}} x_1 = x_2 \Rightarrow \begin{cases} x_1 = t \\ x_2 = t \end{cases} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\lambda_2 = 4$$

$$A - 4I = \begin{bmatrix} -1 & -1 \\ -1 & -1 \end{bmatrix}$$

$$\begin{bmatrix} -1 & -1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0$$

$$\begin{cases} -x_1 - x_2 = 0 \\ -x_1 - x_2 = 0 \end{cases} \xrightarrow{\text{true iff}} x_1 = -x_2 \Rightarrow \begin{cases} x_1 = t \\ x_2 = -t \end{cases} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$A\vec{x} = \lambda\vec{x}$$

$$(A - \lambda I)\vec{x} = 0$$

~~ANSWER~~

$$\gg [\tau, D] = \text{eig}(A);$$

$$AT = TD$$

$$A = TDT^{-1}$$

$$A^2 = T D^2 T^{-1}$$

$$A^3 = T D^3 T^{-1}$$

:

$$\dot{x} = Ax \Rightarrow x(t) = \underbrace{e^{At}}_{\downarrow} x(0)$$

$$e^{At} = I + At + \frac{1}{2!} A^2 t^2 + \frac{1}{3!} A^3 t^3 + \dots$$

$$= TT^{-1} + TDT^{-1}t + \frac{1}{2!} TD^2 T^{-1} t^2 + \frac{1}{3!} TD^3 T^{-1} t^3 + \dots$$

$$= T \left[ I + Dt + \frac{1}{2!} D^2 t^2 + \frac{1}{3!} D^3 t^3 + \dots \right] T^{-1}$$

$$= T \begin{bmatrix} e^{\lambda_1 t} & & & 0 \\ & e^{\lambda_2 t} & & \\ 0 & & \ddots & \\ & & & e^{\lambda_n t} \end{bmatrix} T^{-1}$$

$$\Rightarrow \boxed{e^{At} = T e^{Dt} T^{-1}}$$

$$x = T \beta$$

$$\gg [\tau, D] = \text{eig}(A);$$

$$T = \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 0 & 1 & 1 & \dots & 1 \\ 0 & 0 & 1 & \dots & 1 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix}$$

$$D = \begin{bmatrix} \lambda_1 & & & 0 \\ & \lambda_2 & & \\ 0 & & \ddots & \lambda_n \end{bmatrix}$$

$$\dot{x} = Ax$$

$$x(t) = T e^{Dt} T^{-1} x(0)$$

$$\beta(t) = e^{Dt} \beta(0)$$

$$x(t) = T \beta(t)$$

