Patrick Li-Yu Lo

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Research Dr, Durham NC

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https://pattylo.github.io/
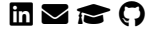
BACKGROUND

Duke University *Aug '25 - Present*
PhD Student (MEMS)

The Hong Kong Polytechnic University *Sep '22 - Mar '25*
MPhil in Robotics & Control (Presidential Fellow) GPA: 4.0/4.3

Hong Kong Center for Construction Robotics (HKCRC) *Jul '21 - Jul '22*
Research Assistant

The Hong Kong Polytechnic University *Sep '17 - Jun '21*
BEng (1st Hons) in Aeronautical and Aviation Engineering (APEC Entry Scholarship)
Exchange: University of Queensland, Australia GPA: 3.75/4.3

PUBLICATIONS & PATENTS (SLIDES)

- **L.-Y. Lo**, B. Li, C.-Y. Wen, and C.-W. Chang, "Experimental Non-Robocentric Dynamic Landing of Quadrotor UAVs with On-Ground Sensor Suite," *IEEE Transactions on Instrumentation and Measurement (TIM)*, vol. 73, 2024. *Links*: pdf, code.

- **L.-Y. Lo**, Y. Hu, B. Li, C.-Y. Wen, and Y. Yang, "An Adaptive Model Predictive Control for Unmanned Underwater Vehicles Subject to External Disturbances and Measurement Noise," in *2024 14th Asian Control Conference (ASCC)*. IEEE, 2024, pp. 01–07. *Links*: pdf, code.

- Y. Yang, K. Liu, **L.-Y. Lo**, T. Huang, Y. Fu, and C.-Y. Wen, "Fixed-Time Adaptive Consensus Control for Multi-Quadrotor Subject to External Disturbances via Deep Reinforcement Learning," submitted to *IEEE Transactions on Automation and Science Engineering (TASE)*, 2024.

- W. Yang, Z. Tan, Y. Xue, **L.-Y. Lo**, K. Liu, and C.-Y. Wen, "Hierarchical 3D Scene Graph Based Metric Semantic SLAM for Object Mapping and Counting," submitted to *IEEE Transactions on Circuits and Systems II: Express Briefs*, 2024.

- **L.-Y. Lo**, B. Li, C.-Y. Wen, and C.-W. Chang, "Landing a Quadrotor on a Ground Vehicle Without Exteroceptive Airborne Sensors: A Non-Robocentric Framework and Implementation," in *2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC)*. IEEE, 2023, pp. 6080–6087. *Links*: pdf.

- C.-W. Chang, L.K. Chung, W.-C. Hung, and **L.-Y. Lo**, "An Integrated Auxiliary System for Construction Precast Components Installation," Patent Pending, Application No.: 202310478194.5, *CN Patent*, [Filing Date: 2023-08-29].

- **L.-Y. Lo**, C. H. Yiu, Y. Tang, A.-S. Yang, B. Li, and C.-Y. Wen, "Dynamic Object Tracking on Autonomous UAV System for Surveillance Applications," *Sensors*, vol. 21, no. 23, p. 7888, 2021. Editor's Choice Article. *Links*: pdf, code.

AWARDS & SCHOLARSHIP

- First Runner-up of UAV Challenge, '23, '24, & '25 IEEE International Conference on Unmanned Aircraft Systems (ICUAS). *Links*: web '23, web '24 web '25.

- PolyU Presidential Postgraduate Fellowship Scheme ('22 - '24).

- Dean's List of PolyU Faculty of Engineering: '17/18, '18/19 & '20/21.

- PolyU Undergraduate APEC Entry Scholarship ('17 - '21).

- Wong Tit-shing Student Exchange Scholarship '19/20.

- Dr. Y.K. Ching Memorial Scholarship.

CORE SKILLS & EXPERIENCES

Languages & Tools: C++, Python, ROS 1/2, Matlab, Docker, PX4/Ardu, Arduino, PyTorch, & OpenCV.
Robotic Subjects: Dynamic Analysis with Data, Optimal Control, Nonlinear Control Theory, Convex Optimization, Deep Learning, Reinforcement Learning, Optimization-based SLAM.
Robotic Platforms: AgileX Scout-Mini, BlueROV2, CrazyFly, UniTree Go1.
Links: Project Pages, Learning Notes.

OTHERS

- **Languages**: English (IELTS 7.5), Mandarin (Native), Cantonese (Proficient), Taiwanese (Proficient).

- **Services**: Reviewer for IEEE Transactions on Instrumentation and Measurement; IEEE Transactions on Mechatronics; IEEE Transactions on Vehicular Technology; IEEE Sensors Journal; 2023 IEEE International Conference on Intelligent Transportation Systems.

- **Volunteering**: Student Ambassador at HKPolyU ('19-'21); Teaching Assistant at HeartFire Education Service, China (Dec '19), African Evangelistic Enterprise, Rwanda (Jun '19), Royal University of Phnom Penh, Cambodia (May - Jun '18).

REFERENCES

Prof. Chih-Yung Wen	Dr. Boyang Li	Dr. Li-Ta Hsu	Dr. Ching-Wei Chang
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