

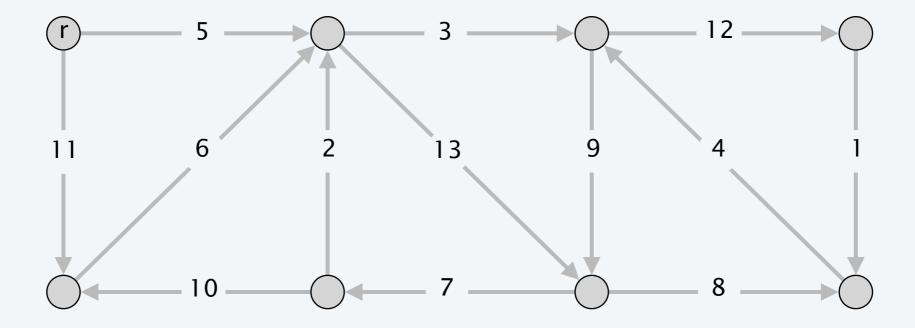
Lecture slides by Kevin Wayne

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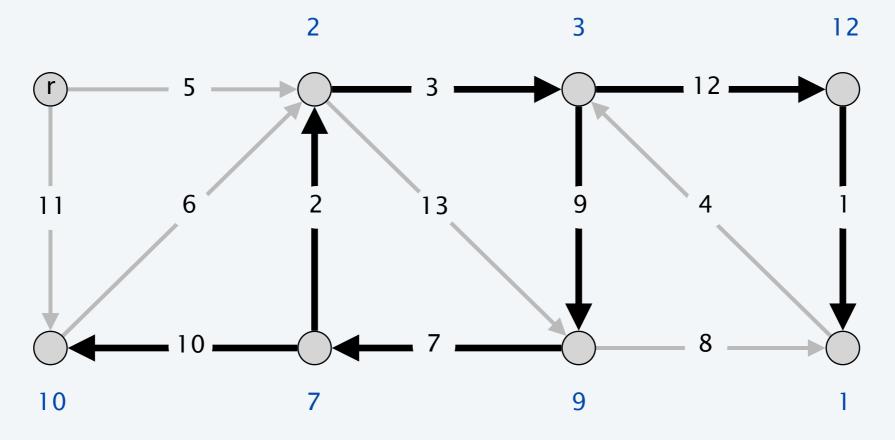
http://www.cs.princeton.edu/~wayne/kleinberg-tardos

#### 4. GREEDY ALGORITHMS II

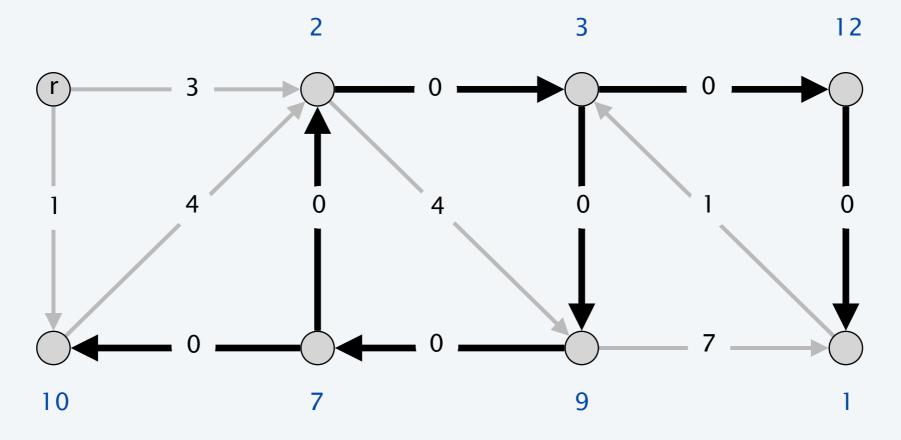
input digraph G = (V, E)



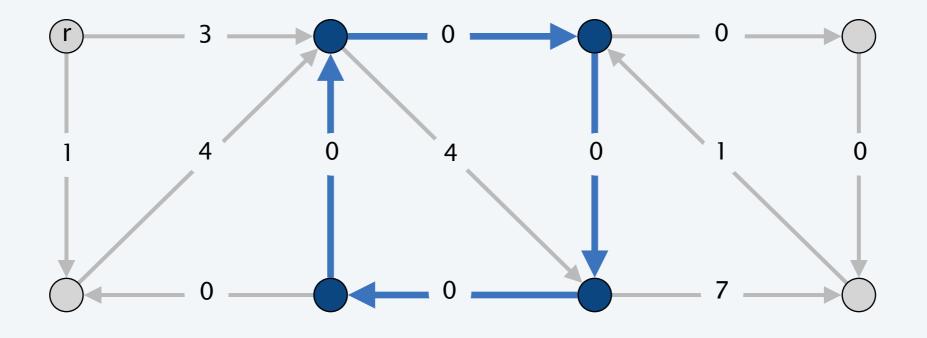
Phase 1: find cheapest edge entering each node

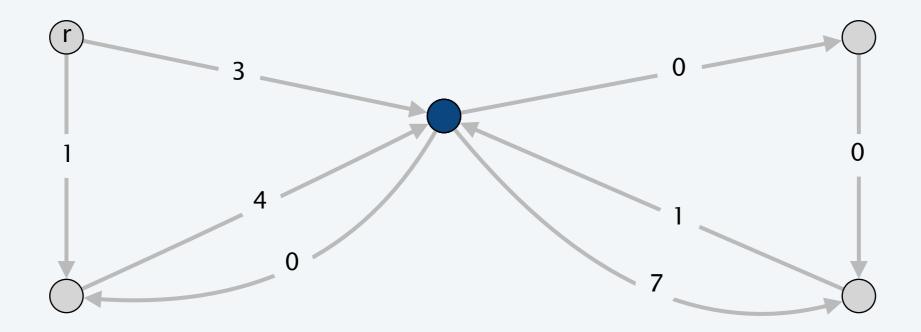


Phase 1: replace costs with reduced costs

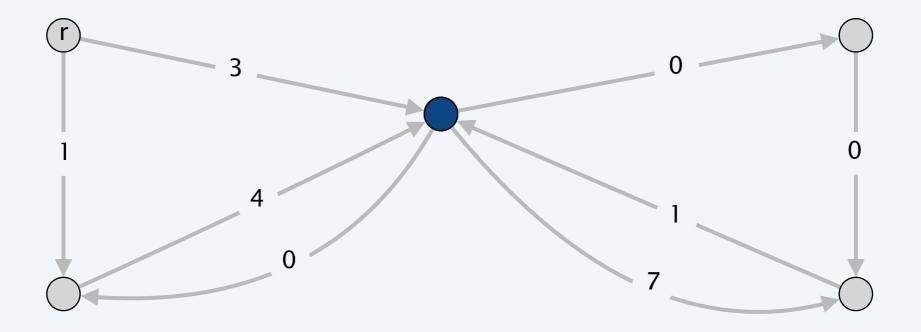


Phase 1: find 0-cost directed cycle C and contract

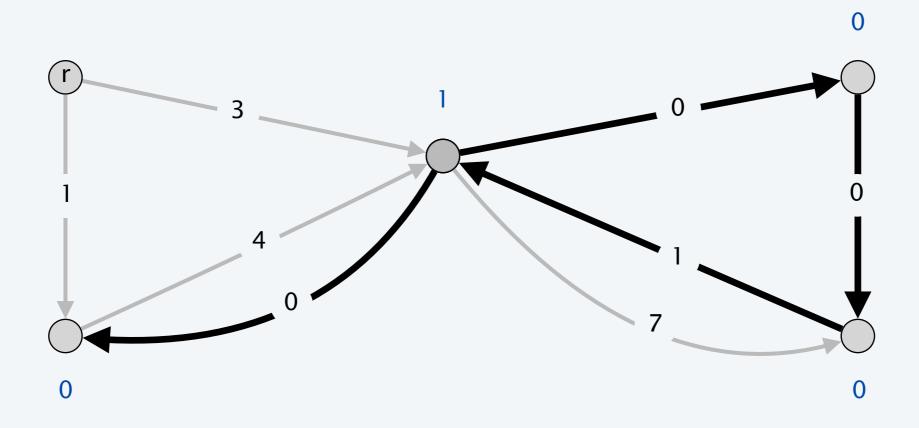




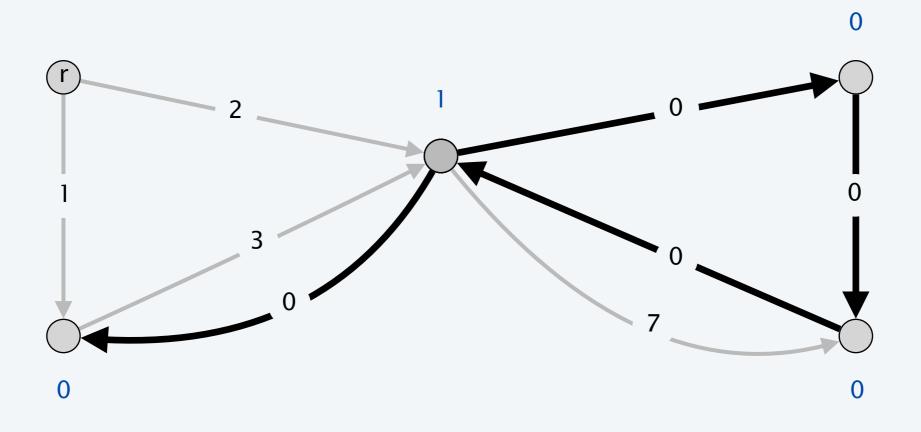
Phase 2: digraph G'



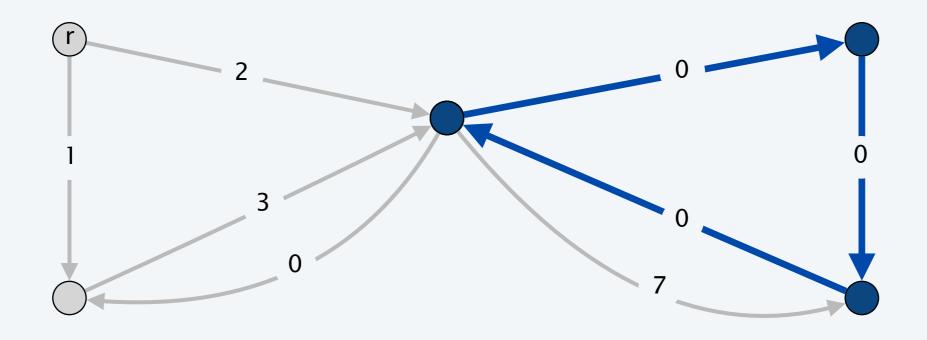
Phase 2: find cheapest edge entering each node

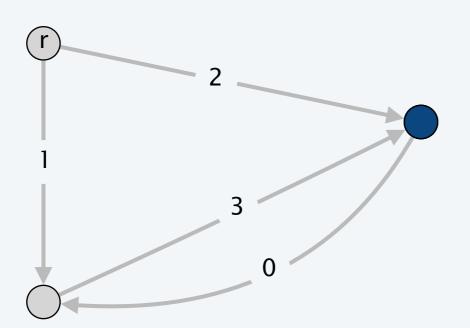


Phase 2: replace cost with reduced costs

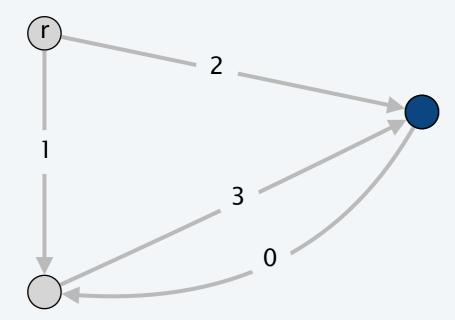


Phase 2: find 0-cost directed cycle and contract

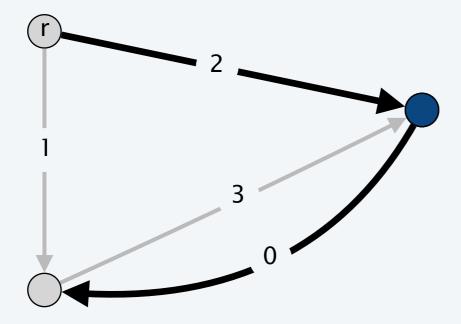




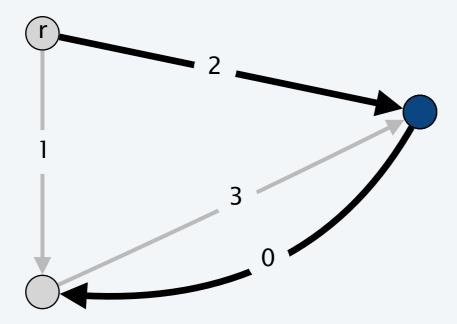
Phase 3: digraph G"



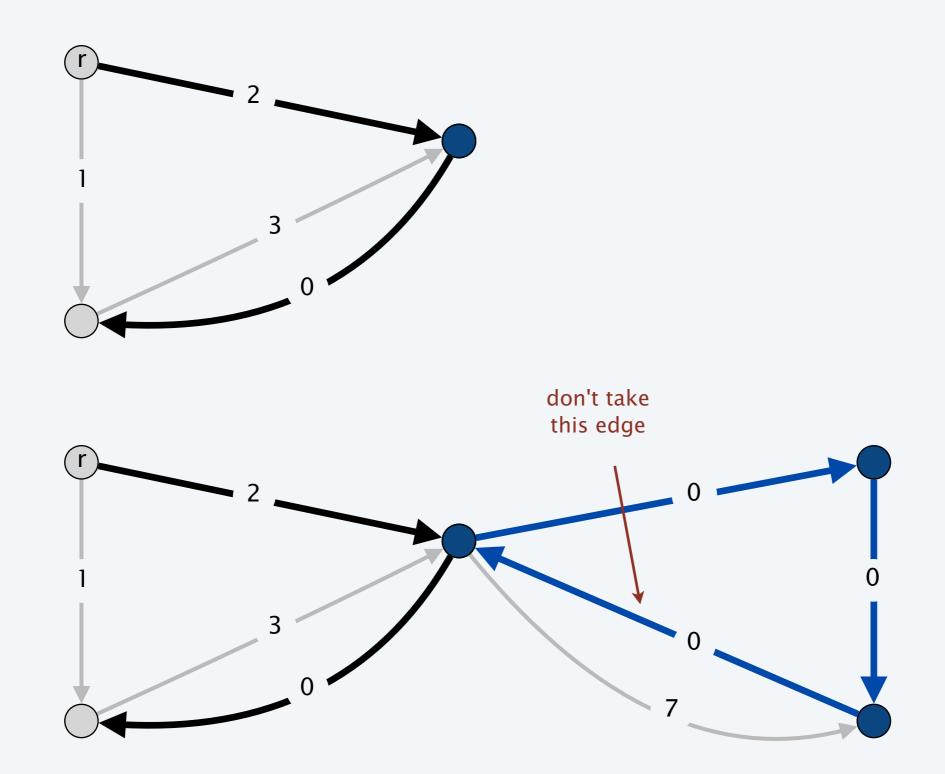
Phase 3: find cheapest edge entering each node



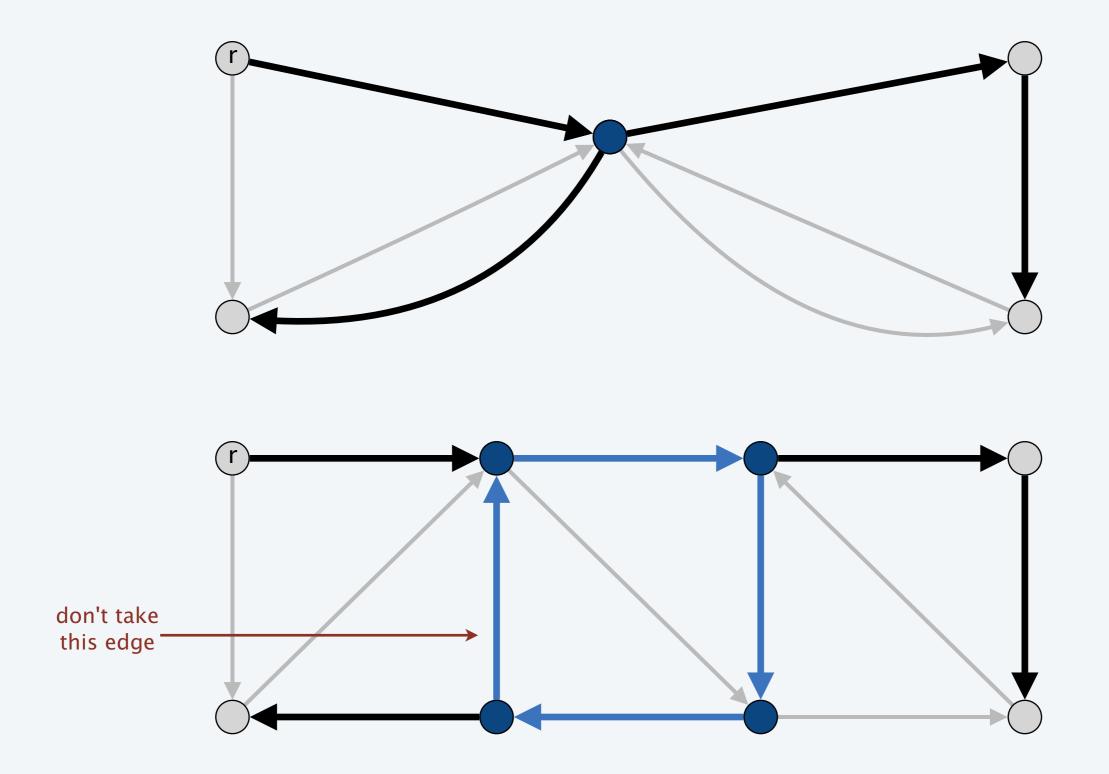
Phase 3: it's an arborescence!



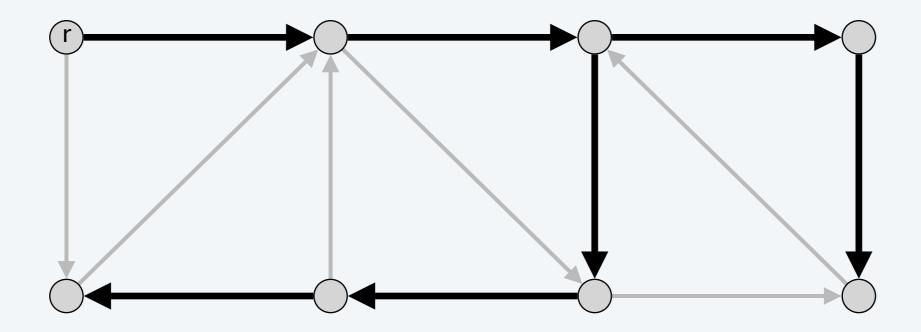
Phase 2': uncontract node and take all but one edge of cycle



Phase 1': uncontract node and take all but one edge of cycle



stop: no more nodes to uncontract



#### min-cost arborescence

