

# Audrow Nash

Software Engineer & Robotics Enthusiast

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San Antonio, TX

## Summary

Passionate software engineer with expertise in robotics, web development, and open-source contributions. Experienced in creating educational content and fostering community engagement in the robotics field.

## Experience

### Software Engineer

Open Robotics | 2020 - Present

- Develop and maintain core ROS 2 packages
- Create educational content for the robotics community
- Engage with the open-source robotics community

### Robotics Software Engineer

Robotic Materials | 2019 - 2020

- Developed software for robotic manipulation tasks
- Implemented computer vision algorithms for object detection
- Contributed to the company's ROS-based software stack

## Education

### Ph.D. in Mechanical Engineering

University of California, San Diego, 2020

## Skills

Python, C++, ROS/ROS 2, JavaScript, TypeScript, React, Node.js, Git, Docker

## Projects

### ROS 2 Podcast

Host of a podcast discussing Robot Operating System (ROS) 2 and its ecosystem

[Learn more](#)

## Open Robotics Contributions

Significant contributions to various ROS 2 packages and documentation

[Learn more](#)