

Game Development

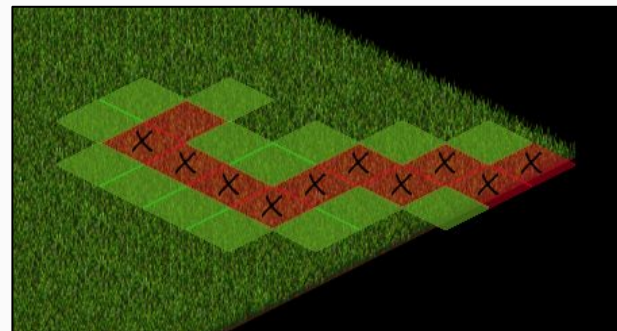
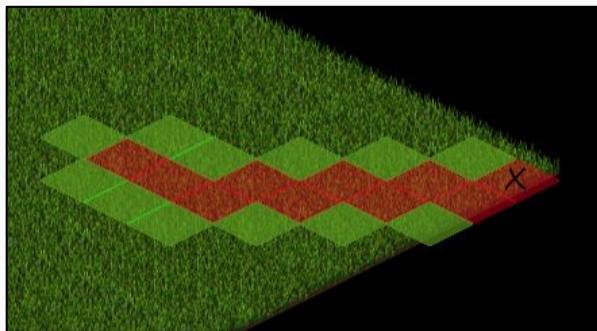
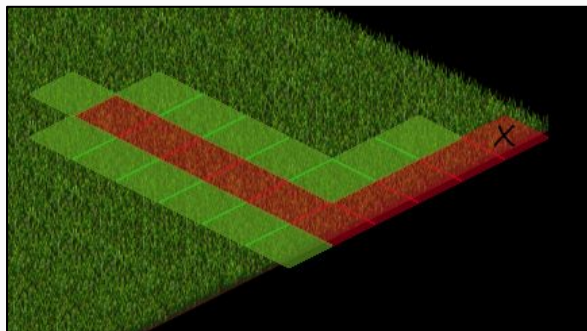
Dijkstra to A*

Solution A*



A*

- A* is like Dijkstra, but it will take in account distance to goal
- It is considered a [Greedy Algorithm](#) (focus only on the local problem)
- Just by adding a distance heuristic to priority we are done:
 - Manhattan distance / Squared distance / Distance



TODO (before)

- Make sure you finish Dijkstra and that you understand it 100%
- Concept of “Cost so far” must be implemented since A* can revisit nodes
 - And unlike Dijkstra in A* it is quite a common case!

TODO 1

- We want to stop propagation as soon as we find the goal tile
- When clicked remember in a property the goal position in tile coordinates
- Stop propagation as soon as goal is found
- You can test with Dijkstra

TODO 2

- Create a `PropagateAStar()` as a copy from `Dijkstra`
- Now to add a neighbor in the frontier:
 - Add the distance to the final cost
- The distance heuristic should be one of three:
 - Manhattan distance
 - Square root distance
 - Distance

Homework

- Adapt A* to take in account diagonals
 - The movement cost must be higher!