

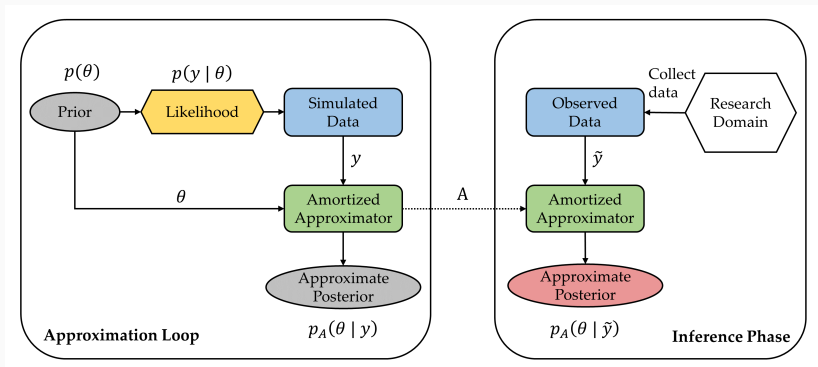
# Robust Amortized Bayesian Inference with Self-Consistency Losses on Unlabeled Data

<https://arxiv.org/abs/2501.13483>

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# Amortized Bayesian Inference



In the following, I use  $x$  for data and  $q(\theta | x)$  for the neural approximator

# Standard neural posterior estimation (NPE)

General form of (standard) NPE losses in SBI:

$$\text{NPELoss}(q) = \mathbb{E}_{(\theta, x) \sim p(\theta, x)} [S(q(\theta \mid x), \theta)]$$

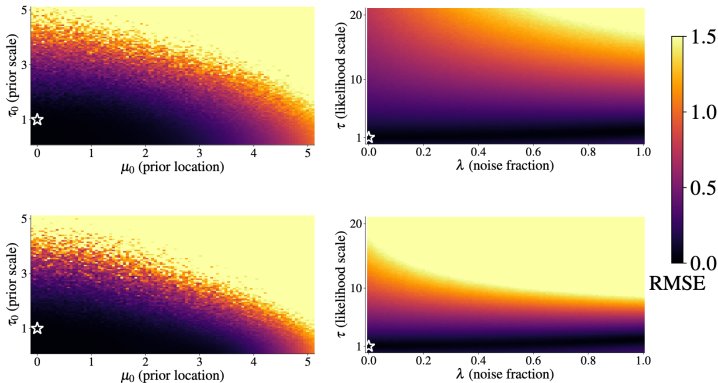
For normalizing flows with invertible neural networks:

$$\text{NPELoss}(q) = \mathbb{E}_{(\theta, x) \sim p(\theta, x)} [-\log q(\theta \mid x)]$$

# Standard NPE on misspecified models fails

Summary Network  
minimal  
overcomplete

## Model Misspecification Prior Simulator & noise



Source: <https://arxiv.org/abs/2406.03154>

# Bayesian Self-consistency

For any set of parameter values  $\theta^{(1)}, \dots, \theta^{(L)}$ , the following holds:

$$p(x) = \frac{p(x \mid \theta^{(1)}) p(\theta^{(1)})}{p(\theta^{(1)} \mid x)} = \dots = \frac{p(x \mid \theta^{(L)}) p(\theta^{(L)})}{p(\theta^{(L)} \mid x)}.$$

This implies that the variance of the log-ratios must be zero:

$$\text{Var}_{l=1}^L \left[ \log \left( \frac{p(x \mid \theta^{(l)}) p(\theta^{(l)})}{p(\theta^{(l)} \mid x)} \right) \right] = 0$$

Our initial paper on Bayesian self-consistency:

<https://arxiv.org/abs/2310.04395>

# Bayesian self-consistency loss

Replace the true posterior  $p(\theta \mid x)$  with the neural approximate posterior  $q(\theta \mid x)$ .

For any (**unlabeled**) dataset  $x^*$  and any parameter generating distribution  $p_C(\theta)$ , we define:

$$\text{SCLoss}(q) = \text{Var}_{\theta \sim p_C(\theta)} [\log p(x^* \mid \theta) + \log p(\theta) - \log q(\theta \mid x^*)]$$

The SC-Loss alone doesn't work well most of the time so we combine it with the standard NPE loss:

$$\text{SemiSupervisedLoss}(q) = \text{NPELoss}(q) + \lambda \cdot \text{SCLoss}(q).$$

# Bayesian Self-Consistency losses a strictly proper

Let  $C$  be a score that is globally minimized if and only if its functional argument is constant across the support of the posterior  $p(\theta | x)$  almost everywhere. Then,  $C$  applied to the Bayesian self-consistency ratio with known likelihood

$$C \left( \frac{p(x | \theta) p(\theta)}{q(\theta | x)} \right)$$

is a strictly proper loss: It is globally minimized if and only if  $q(\theta | x) = p(\theta | x)$  almost everywhere.

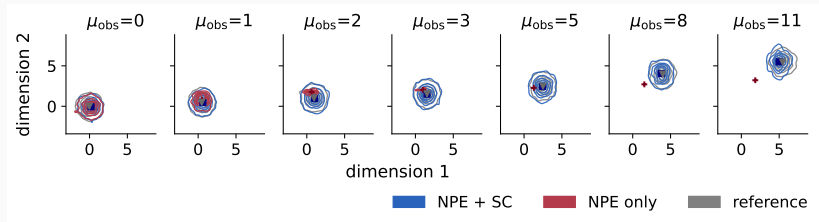
This implies that also the semi-supervised loss is strictly proper.

# Case Study 1: Multivariate normal model

$$\theta \sim \text{Normal}(\mu_{\text{prior}}, I_D), \quad x \sim \text{Normal}(\theta, I_D)$$

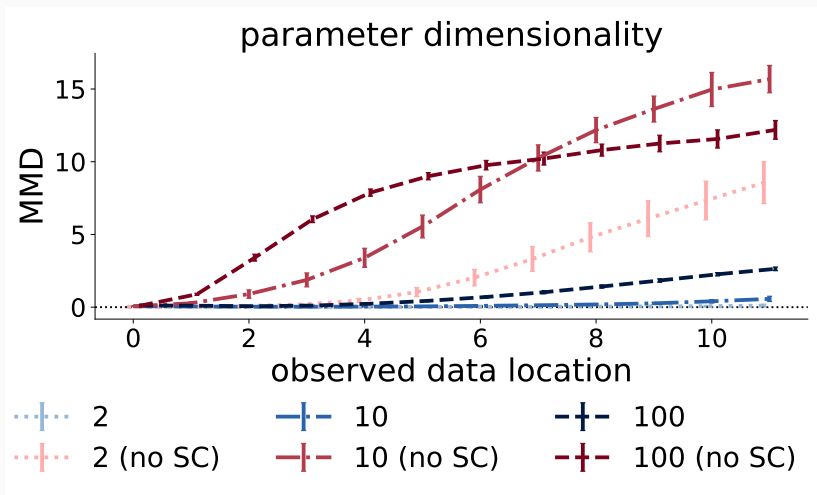
- For the NPE loss, we simulate from the model with  $\mu_{\text{prior}} = 0$
- For the SC loss, we simulate **few unlabeled datasets** from the model with  $\mu_{\text{prior}} = 2$

Illustrative results:

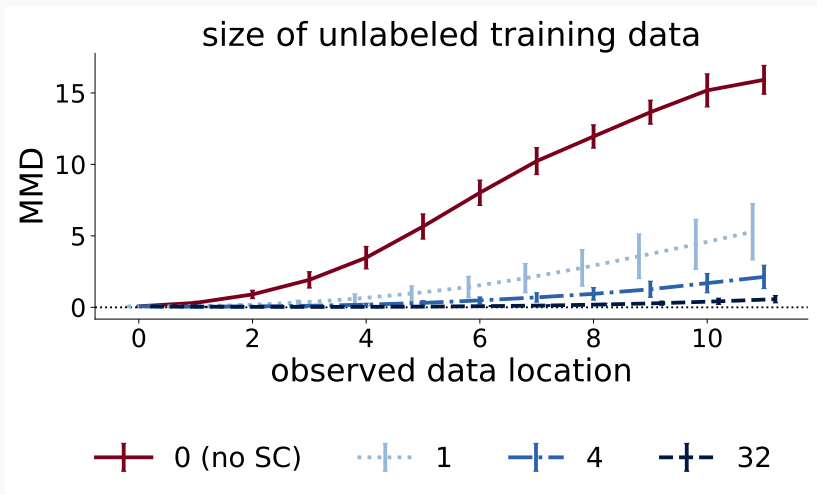




## Case Study 1: More Results



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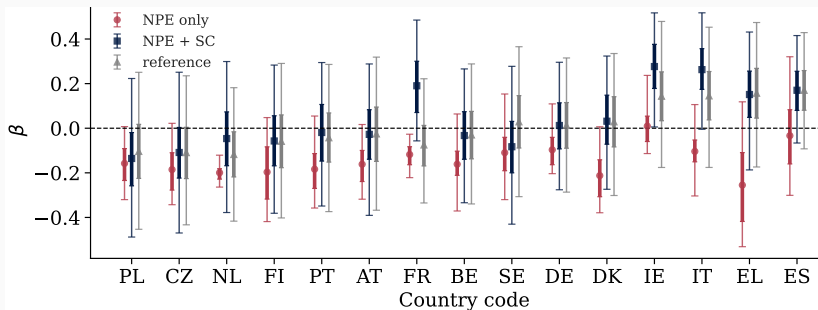
## Case Study 2: Time Series of Air Traffic data

Predicting the change in air traffic for different European countries

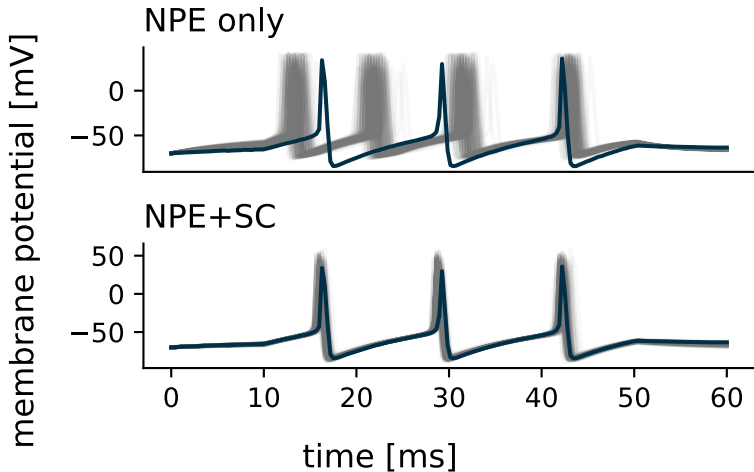
$$y_{j,t+1} \sim \text{Normal}(\alpha_j + \beta_j y_{j,t} + \dots, \sigma_j)$$

- $y_{j,t}$  number of passengers for country  $j$  at year  $t$
- $\alpha_j$  intercept parameter
- $\beta_j$  auto-correlation parameter
- $\sigma_j$  residual standard deviation

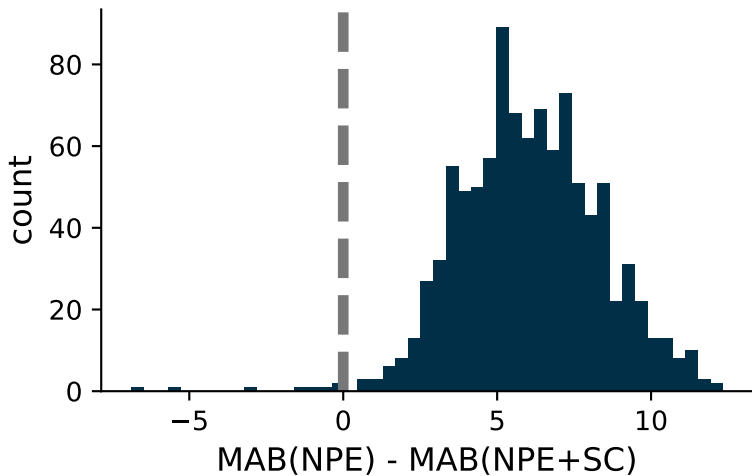
## Case Study 2: Results



## Case Study 3: Hodgkin-Huxley model of neuron activation



### Case Study 3: More results



# Conclusion

- The SC loss can strongly improve robustness to model misspecification if the SC data  $x^*$  are outside of the typical set of the simulator  $p(x, \theta)$  used in the NPE loss
- The SC loss is strictly proper so it has the same target (the true posterior) as the NPE loss
- Challenge 1: The SC loss requires a known or estimated likelihood density: stronger robustness if the likelihood density is known
- Challenge 2: We need neural approximators that have fast density evaluation (currently excludes flow matching or diffusion models)