

Ex4_2

February 10, 2019

1 Exercise 2

1.1 a)

Analoger Filter:

$$H(s) = \frac{1}{1 + \frac{s}{\omega_c}} \quad (1)$$

Bilineare transformation mit:

$$s = 2f_s \frac{z-1}{z+1} \quad (2)$$

Einsetzen ergibt die generelle Form:

$$H_d(z) = \frac{1}{1 + \frac{2f_s}{\omega_c} \frac{z-1}{z+1}} = \frac{1 + z^{-1}}{(1 + \frac{2f_s}{\omega_c}) + (1 - \frac{2f_s}{\omega_c})z^{-1}} \quad (3)$$

Analoger Tiefpassfilter kann geschrieben werden als:

$$H(s) = \frac{1}{1 + a_1 \frac{s}{\omega_c} + b_1 (\frac{s}{\omega_c})^2} \quad (4)$$

Unser gegebener Tiefpassfilter erster Ordnung:

$$H(s) = \frac{1}{1 + \frac{s}{\omega_c}} \quad (5)$$

Normale Notation für die Transferfunktion von Analogen Filtern zweiter Ordnung:

$$H(s) = \frac{B_0 s^2 + B_1 s + B_2}{A_0 s^2 + A_1 s + A_2} \quad (6)$$

Durch den Vergleich der normalen Notation und unserem gegeben Filter ergibt sich:

$$B_0 = 0, B_1 = 0, B_2 = 1, A_0 = \frac{b_1}{\omega_c^2} = 0, A_1 = \frac{a_1}{\omega_c} = \frac{1}{\omega_c}, A_2 = 1 \quad (7)$$

Nach der Substitution von $s = 2f_s \frac{z-1}{z+1}$ wollen wir folgende Form erhalten:

$$H(z) = \frac{b_0 + b_1 z^{-1} + b_2 z^{-2}}{1 + a_1 z^{-1} + a_2 z^{-2}} \quad (8)$$

Rechenweg:

$$\frac{B_0(2f_s \frac{z-1}{z+1})^2 + B_1(2f_s \frac{z-1}{z+1}) + B_2}{A_0(2f_s \frac{z-1}{z+1})^2 + A_1(2f_s \frac{z-1}{z+1}) + A_2} = \dots = \frac{\frac{B_0 4f_s^2 + B_1 2f_s + B_2}{A_0 4f_s^2 + A_1 2f_s + A_2} + \frac{-B_0 8f_s^2 + 2B_2}{A_0 4f_s^2 + A_1 2f_s + A_2} z^{-1} + \frac{B_0 4f_s^2 - B_1 2f_s + B_2}{A_0 4f_s^2 + A_1 2f_s + A_2} z^{-2}}{1 + \frac{-A_0 8f_s^2 + 2A_2}{A_0 4f_s^2 + A_1 2f_s + A_2} z^{-1} + \frac{A_0 4f_s^2 - A_1 2f_s + A_2}{A_0 4f_s^2 + A_1 2f_s + A_2} z^{-2}} \quad (9)$$

Die Koeffizienten des digitalen Filters sind daher:

$$b_0 = \frac{B_2 + 2B_1 f_s + 4B_0 f_s^2}{A_2 + 2A_1 f_s + 4A_0 f_s^2} = \frac{1}{1 + \frac{2f_s}{\omega_c}} b_1 = \frac{2B_2 - 8B_0 f_s^2}{A_2 + 2A_1 f_s + 4A_0 f_s^2} = \frac{2}{1 + \frac{2f_s}{\omega_c}} b_2 = \frac{B_2 + 2B_1 f_s - 4B_0 f_s^2}{A_2 + 2A_1 f_s + 4A_0 f_s^2} = \frac{1}{1 + \frac{2f_s}{\omega_c}} a_1 = \dots \quad (10)$$

1.2 b)

$$b_0 = \frac{B_2 + 2B_1 f_s + 4B_0 f_s^2}{A_2 + 2A_1 f_s + 4A_0 f_s^2} = \frac{1}{1 + \frac{1}{\tan(\pi \frac{f_c}{f_s})}} b_1 = \frac{2B_2 - 8B_0 f_s^2}{A_2 + 2A_1 f_s + 4A_0 f_s^2} = \frac{2}{1 + \frac{1}{\tan(\pi \frac{f_c}{f_s})}} b_2 = \frac{B_2 + 2B_1 f_s - 4B_0 f_s^2}{A_2 + 2A_1 f_s + 4A_0 f_s^2} = \frac{1}{1 + \frac{1}{\tan(\pi \frac{f_c}{f_s})}} a_1 = \dots \quad (11)$$

1.3 c), d), e)

c) calculate the coefficients

```
In [1]: import numpy as np
import matplotlib.pyplot as plt
import scipy.signal as sig

fs = 48000 #Hz
fc = 10000 #Hz

omc = 2*np.pi*fc
omc_wrapped = 2*fs *np.tan(np.pi * fc / fs)

#Coefficients without pre-wrapping:
b0 = 1 / ( 1 + 2 *fs / omc)
b1 = 2 / ( 1 + 2 *fs / omc)
b2 = 1 / ( 1 + 2 *fs / omc)
b = [b0, b1, b2]

a1 = 2 / ( 1 + 2 *fs / omc)
#a2 = (1 - 2 * fs / omc) / ( 1 + 2 *fs / omc)
a2 = (omc - 2 * fs) / (omc + 2 *fs)
a = ([1, a1, a2])

#Coefficients with pre-wrapping
b0_w = 1 / ( 1 + 2 *fs / omc_wrapped)
b1_w = 2 / ( 1 + 2 *fs / omc_wrapped)
```

```

b2_w = 1 / ( 1 + 2 *fs / omc_wrapped)
b_wrapped = [b0_w, b1_w, b2_w]

a1_w = 2 / ( 1 + 2 *fs / omc_wrapped)
a2_w = (1 - 2 * fs / omc_wrapped) / ( 1 + 2 *fs / omc_wrapped)
a_wrapped = [1, a1_w, a2_w]

print("Coefficients of the digital filter in biquad structure:\n")
print("a = ", a)
print("b = ",b)

print("\nCoefficients of the digital filter in biquad structure with pre-wrapping:\n")
print("a = ",a_wrapped)
print("b = ",b_wrapped)

```

Coefficients of the digital filter in biquad structure:

```

a = [1, 0.7911744635176464, -0.2088255364823536]
b = [0.3955872317588232, 0.7911744635176464, 0.3955872317588232]

```

Coefficients of the digital filter in biquad structure with pre-wrapping:

```

a = [1, 0.8683475024126042, -0.13165249758739586]
b = [0.4341737512063021, 0.8683475024126042, 0.4341737512063021]

```

d) visualise magnitude transfer function

```

In [18]: # Analog Filter
A = [0, 1/omc, 1]
B = [0, 0, 1]

#bilinear transform without pre-wrapping
Om, Hd = sig.freqz(b, a, whole=True)
temp, Ha = sig.freqs(B, A, worN=fs*Om)
#Compute the frequency response of a digital filter and Analog Filter

#bilinear transform with pre-wrapping
Om_w, Hd_wrapped = sig.freqz(b_wrapped, a_wrapped, whole=True)

#freuquency vector
#f = np.arange(0,fs,1) #frquency range
f = Om * fs / (2*np.pi)
#Plot Magnitude
plt.figure(figsize=(10,3))
plt.semilogx(f, 20*np.log10(np.abs(Ha)), label=r'analogue prototype')
plt.semilogx(f, 20*np.log10(np.abs(Hd)), label=r'bilinear transform without pre-wrapping')

```

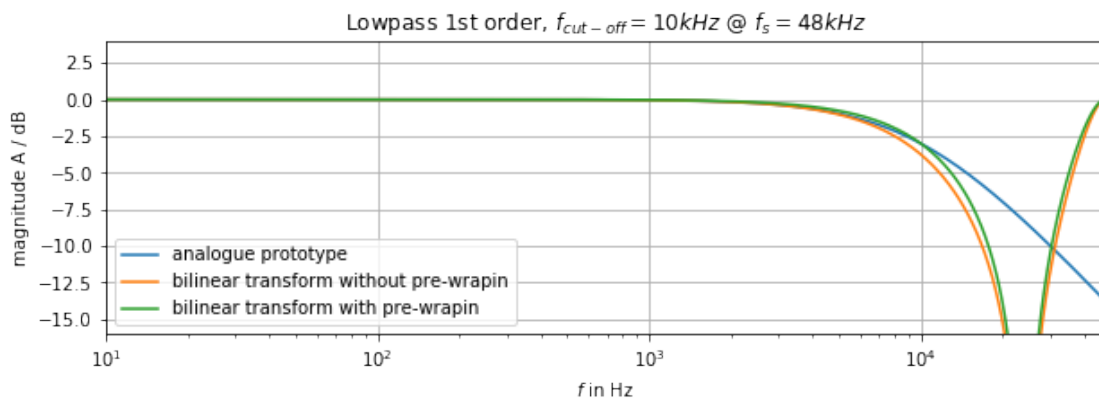
```

plt.semilogx(f, 20*np.log10(np.abs(Hd_wrapped)), label=r'bilinear transform with pre-wrapping')
plt.xlabel(r'$f$ in Hz')
plt.ylabel(r'magnitude A / dB')
plt.grid()
plt.title(r'Lowpass 1st order, $f_{cut-off} = 10$ kHz$ @ $f_s = 48$ kHz$')
plt.legend()
plt.axis([10, fs, -16, 4])

```

/home/max/anaconda3/lib/python3.7/site-packages/ipykernel_launcher.py:19: RuntimeWarning: divide by zero encountered in log10
/home/max/anaconda3/lib/python3.7/site-packages/ipykernel_launcher.py:20: RuntimeWarning: divide by zero encountered in log10

Out[18]: [10, 48000, -16, 4]



Die bilineare Transformation der Frequenzantwort ist verschieden zu der des analogen Filters, durch die first-order approximation während des Mappings von der s-plane zur z-plane. Unter anderem verschiebt sich die corner frequency. Dieser Effekt wird als frequency wrapping bezeichnet. Durch das pre-wrapping, bei der die corner frequency ersetzt, sodass die Frequenz an dieser Stelle korrigiert wird.

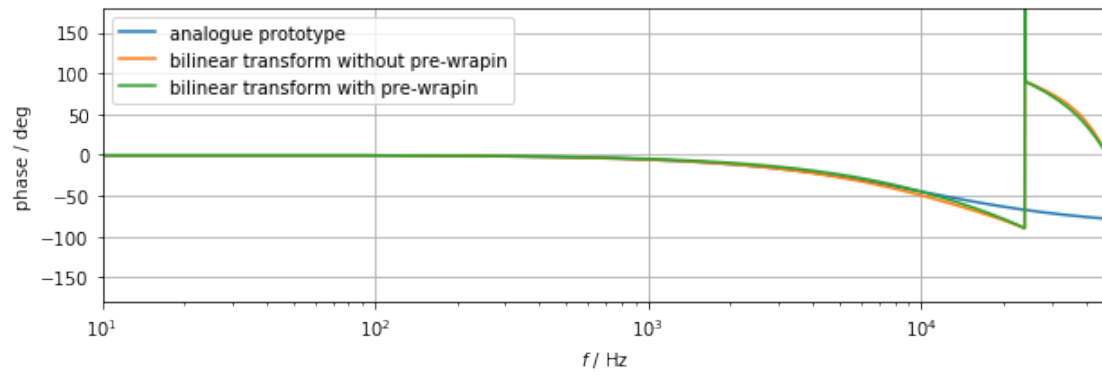
e)

```

In [14]: #Plot Angle
plt.figure(figsize=(10,3))
plt.semilogx(f, (180 / np.pi) * np.angle(Ha), label=r'analogue prototype') # transform
plt.semilogx(f, (180 / np.pi) * np.angle(Hd), label=r'bilinear transform without pre-wrapping')
plt.semilogx(f, (180 / np.pi) * np.angle(Hd_wrapped), label=r'bilinear transform with pre-wrapping')
plt.xlabel(r'$f$ / Hz')
plt.ylabel(r'phase / deg')
plt.grid()
plt.legend()
#plt.title(r'Lowpass 1st order, $f_{cut-off} = 10$ kHz$ @ $f_s = 48$ kHz$')
plt.axis([10, fs, -180, 180])

```

Out[14]: [10, 48000, -180, 180]



Die Stabilität und minimale phase des Systems sind durch die bilineare Transformation erhalten geblieben.