Structured Neural Networks

In this homework, we train a collection of neural networks including a convolutional neural network on the MNIST dataset, and a graph neural network on some graph classification task.

In [1]:

```
import torch
import torch.nn as nn

import torchvision
import torchvision.transforms as transforms
import utils
import numpy

import matplotlib
%matplotlib inline
from matplotlib import pyplot as plt
```

We first consider the convolutional neural network, which we apply in the following to the MNIST data.

In [2]:

We consider for this dataset a convolution network made of four convolutions and two pooling layers.

In [3]:

```
torch.manual_seed(0)
cnn = utils.NNClassifier(nn.Sequential(
    nn.Conv2d( 1, 8, 5), nn.ReLU(), nn.MaxPool2d(2),
    nn.Conv2d( 8, 24, 5), nn.ReLU(), nn.MaxPool2d(2),
    nn.Conv2d( 24, 72, 4), nn.ReLU(),
    nn.Conv2d( 72, 10, 1)
))
```

The network is wrapped in the class utils.NNClassifier, which exposes scikit-learn-like functions such as fit() and predict(). To evaluate the convolutional neural network, we also consider two simpler baselines: a one-layer linear network, and standard fully-connected network composed of two layers.

In [4]:

Evaluating the convolutional neural network (15 P)

יים ווטאי אוטטפפט אונון נוופ טטווואמווסוטון טו נוופספ נווופפ טומססווופוס.

Task:

Train each classifier for 5 epochs and print the classification accuracy on the training and test data (i.e. the fraction of
the examples that are correctly classified). To avoid running out of memory, predict the training and test accuracy only
based on the 2500 first examples of the training and test set respectively.

```
In [5]:
```

```
import numpy as np
In [6]:
Xr.shape, Tr.shape, Xt.shape, Tt.shape
Out[6]:
(torch.Size([60000, 1, 28, 28]),
 torch.Size([60000]),
 torch.Size([10000, 1, 28, 28]),
 torch.Size([10000]))
In [7]:
for name,cl in [('linear',lin),('full',fc),('conv',cnn)]:
    cl.fit(Xr,Tr,epochs=5)
    preds_train = np.argmax(cl.predict(Xr[:2500]), axis=1)
    preds_test = np.argmax(cl.predict(Xt[:2500]), axis=1)
    errtr = np.mean(preds_train.numpy() == Tr[:2500].numpy())
    errtt = np.mean(preds_test.numpy() == Tt[:2500].numpy())
    print('%10s train: %.3f test: %.3f'%(name,errtr,errtt))
    linear train: 0.910 test: 0.878
      full train: 0.967 test: 0.951
```

We observe that the convolutional neural network reaches the higest accuracy with less than 2% of misclassified digits on the test data.

Confidently predicted digits (15 P)

conv train: 0.990 test: 0.982

We now ask whether some digits are easier to predict than others for the convolutional neural network. For this, we observe that the neural network produces at its output scores y_c for each class c. These scores can be converted to a class probability using the softargmax (also called softmax) function:

$$p_{c} = \frac{\exp(y_{c})}{\sum_{c'=1}^{10} \exp(y_{c'})}$$

Task:

 Find for the convolutional network the data points in the test set that are predicted with the highest probability (the lowest being random guessing). To avoid numerical unstability, your implementation should work in the log-probability domain and make use of numerically stable functions of numpy/scipy such as logsumexp.

In [8]:

```
preds = cnn.predict(Xt).numpy()
highest_prob_per_sample = np.amax(preds, axis=1)
idxs_highest_probs = np.argsort(highest_prob_per_sample)
highest = Xt[idxs_highest_probs[-24:]]
lowest = Xt[idxs_highest_probs[:24]]
```

```
for digits in [highest,lowest]:
    plt.figure(figsize=(8,3))
    plt.axis('off')
    plt.imshow(digits.numpy().reshape(3,8,28,28).transpose(0,2,1,3).reshape(28*3,28*8),cmap='gray')
    plt.show()
```





We observe that the most confident digits are thick and prototypical. Interestingly, the highest confidence digits are all from the class "3". The low-confidence digits are on the other hand thiner, and are often also more difficult to predict for a human.

Graph Neural Network (20 P)

We consider a graph neural network (GNN) that takes as input graphs of size m given by their adjacency matrix A and which is composed of the following four layers:

$$H_0 = U$$

$$H_1 = \rho(\Lambda H_0 W)$$

$$H_2 = \rho(\Lambda H_1 W)$$

$$H_3 = \rho(\Lambda H_2 W)$$

$$y = \mathbf{1}^\top H_3 V$$

U is a matrix of size $m \times h$, W is a matrix of size $h \times h$, V is a matrix of size $h \times 3$ and Λ is the normalized Laplacian associated to the graph adjacency matrix A (i.e. $\Lambda = D^{-0.5}AD^{-0.5}$ where D is a diagonal matrix containing the degree of each node), and $\rho(t) = \max$ is the rectified linear unit that applies element-wise.

Task:

• Implement the forward function of the GNN. It should take as input a minibatch of adjacency matrices A (given as a 3-dimensional tensor of dimensions (minibatch_size \times number_nodes \times number_nodes)) and return a matrix of size minibatch_size \times 3 representing the scores for each example and predicted class.

(Note: in your implementation use array operations instead of looping over all individual examples of the minibatch.)

In [9]:

```
class GNN(torch.nn.Module):
    def __init__(self,nbnodes,nbhid,nbclasses):
        torch.nn.Module.__init__(self)
        self.m = nbnodes
        self.h = nbhid
        self.c = nbclasses

        self.U = torch.nn.Parameter(torch.FloatTensor(numpy.random.normal(0,nbnodes**-.5,[nbnodes,nbhid])))
        self.W = torch.nn.Parameter(torch.FloatTensor(numpy.random.normal(0,nbhid**-.5,[nbhid,nbhid])))
        self.W = torch.nn.Parameter(torch.FloatTensor(numpy.random.normal(0,nbhid**-.5,[nbhid,nbhid])))
```

```
def forward(self,A):
    degrees_sqrt = torch.pow(torch.sum(A, dim=1),-0.5)
    D = torch.diag_embed(degrees_sqrt)

lapl = torch.matmul(torch.matmul(D, A), D)

H1 = torch.nn.ReLU()(torch.matmul(torch.matmul(lapl,self.U),self.W))
    H2 = torch.nn.ReLU()(torch.matmul(torch.matmul(lapl,H1),self.W))
    H3 = torch.nn.ReLU()(torch.matmul(torch.matmul(lapl,H2),self.W))

Y = torch.matmul(torch.sum(H3,dim=1), self.V)

return Y
```

The graph neural network is now tested on a simple graph classification task where the three classes correspond to star-shaped, chain-shaped and random-shaped graphs. Because the GNN is more difficult to optimize and the dataset is smaller, we train the network for 500 epochs. We compare the GNN with a simple fully-connected network built directly on the adjacency matrix.

In [10]:

```
Ar,Tr,At,Tt = utils.graphdata()
# A=Ar[:100]
# degrees = torch.sum(A, dim=1)
# D = torch.diag embed(degrees)
# lapl = torch.matmul(torch.matmul(torch.pow(D, -0.5), A), torch.pow(D, -0.5))
# print(lapl[0])
# print(csgraph.laplacian(Ar[0].numpy(), normed=True))
torch.manual_seed(0)
dnn = utils.NNClassifier(nn.Sequential(nn.Linear( 225,512), nn.ReLU(),nn.Linear(512,3)),flat=True)
torch.manual seed(0)
gnn = utils.NNClassifier(GNN(15,25,3))
for name,net in [('DNN',dnn),('GNN',gnn)]:
    net.fit(Ar,Tr,lr=0.01,epochs=500)
    Yr = net.predict(Ar)
   Yt = net.predict(At)
    acctr = (Yr.max(dim=1)[1] == Tr).data.numpy().mean()
    acctt = (Yt.max(dim=1)[1] == Tt).data.numpy().mean()
    print('name: %10s train: %.3f test: %.3f'%(name,acctr,acctt))
             DNN train: 1.000 test: 0.829
name:
```

We observe that both networks are able to perfectly classify the training data, however, due to its particular structure, the graph

GNN train: 0.945 test: 0.901

neural network generalizes better to new data points.

In []:

name: