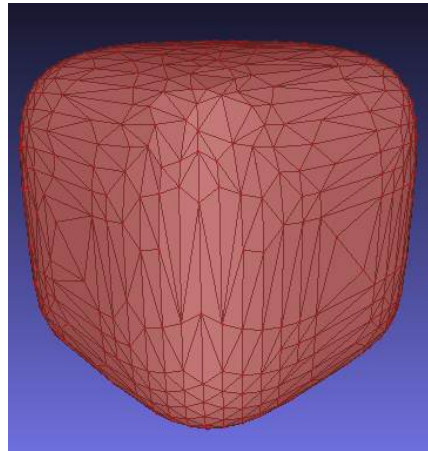
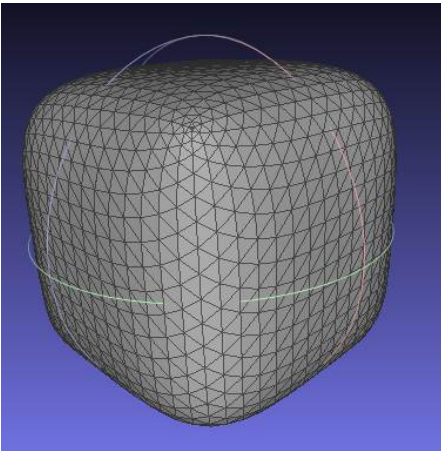


TD 4 - Mesh simplification

(LUCA CASTELLI ALEARDI)

The goal of this TD session is to perform an incremental decimation procedure for simplifying a mesh



Examples of mesh simplification based on quadric error metrics (Garland and Heckbert, 1997).

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1. GETTING STARTED (A PROCESSING FRAME FOR 2D AND 3D RENDERING)

FILES TO DOWNLOAD TODAY

Here are some files to download (and extract to the main folder of your Eclipse project TD4):

- [meshes.zip](#): examples of triangle meshes (OFF format).

Libraries to add (project /LIB):

- [Jcg.jar](#): library for the manipulation of triangle meshes (here are the [sources](#))
- [TC.jar](#): input/output from files.

For the simplification and rendering of meshes (download the file [TD4_src.zip](#)):

- `SurfaceMesh.java`: class defining main methods for drawing the mesh
- `MeshViewer.java`: main drawing class, allowing to rotate the scene in 3D.
- `ArcBall.java`: simple class allowing to rotate the 3D scene with mouse events.
- `MeshSimplification.java`: abstract class defining main methods for mesh simplification (including edge contraction)
- `HalfedgeContraction.java`: skeleton of a simple decimation procedure (based on half-edge contractions)

JAVA DOCUMENTATION

Here is the [javaDoc](#) concerning the packages and classes used today:

- Jcg [documentation](#).
- Processing [documentation](#);

CLASS MESHVIEWER

Class `MeshViewer` provides simple methods for drawing a triangle mesh in a 3D frame; it also provides a simple trackball (allowing to rotate the 3D scene with mouse events).

Method `setup()` allows to select the preferred simplification algorithm.

```
public void setup() {
    size(800,600,P3D);
    ArcBall arcball = new ArcBall(this);

    this.mesh=new SurfaceMesh(this, filename);
    MeshSimplification ms=new HalfedgeContraction(this.mesh.polyhedron3D);

    ms.simplify();
}
```

1. INCREMENTAL DECIMATION BASED ON EDGE CONTRACTION

1.1 RANDOM HALF-EDGE CONTRACTION

Given a triangle mesh (class `Polyhedron_3<Point_3>`), we want to simplify it, by computing **half-edge contractions**: we contract edge (u,v) , by taking as new location the original position of u . Halfedges are randomly chosen.

- complete method `simplify()` of class `HalfedgeContraction` (which extends class `MeshSimplification`).

1.2 CHECK ILLEGAL EDGE CONTRACTIONS

Now we want to make method `simplify()` "safe", in order to preserve the validity of the mesh (which must remain manifold: no loops nor multiple edges).

- add a method `boolean isLegal(Halfedge<Point_3> h)` to class `HalfedgeContraction` which returns true if the contraction of edge h does preserve the combinatorial validity of the mesh.
- modify method `simplify()` of class `HalfedgeContraction` in order to perform only legal edge contractions.

1.3 EDGE CONTRACTION

Now we perform **edge contractions**: we contract edge (u,v) , and we place the new vertex, for example, at the barycenter of u and v . Halfedges are still randomly chosen.

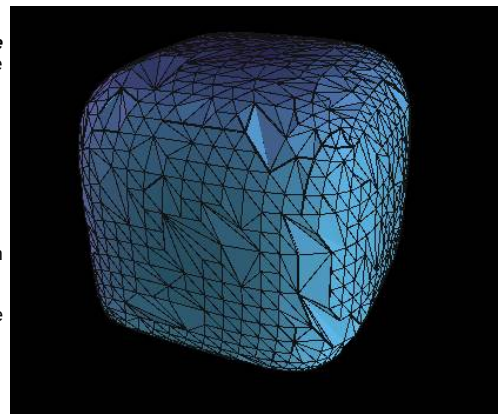
- write class `EdgeContraction` (which extends class `MeshSimplification`).
- complete method `simplify()`: the new position is simply the barycenter of u and v .
- modify method `simplify()`: as new location, take the barycenter of vertices u , v and their neighbors.

1.4 CHOSE EDGES ACCORDING TO GEOMETRIC CRITERIA

In order to improve the quality of the simplified mesh, we choose to select edges according to a geometric criterion: we associate to each edge a cost, defined as its euclidean length. When an edge contraction is performed, the neighboring edges involved in the contraction must be updated (their cost just changed after the edge contraction).

- modify method `simplify()` in order to select edges according to their length.

Remark: you can use a `PriorityQueue` in order to store the edges (sorted according to their cost). After performing the contraction $(u,v) \rightarrow z$, we have to update all edges incident to the new vertex z .



Example of mesh simplification: edges are chosen at random.

2. QUADRIC ERROR METRICS (BONUS)

2.0 OPTIMAL PLACEMENT OF VERTICES BASED ON QUADRIC ERROR METRICS

As mentioned during the Lecture 4, there exists better ways for selecting edges to contract. One solution (sketched today), consists in evaluating a local error based on quadric metrics.

- write class `QuadricErrorMetrics` (which extends class `MeshSimplification`).
- complete method `simplify()`.