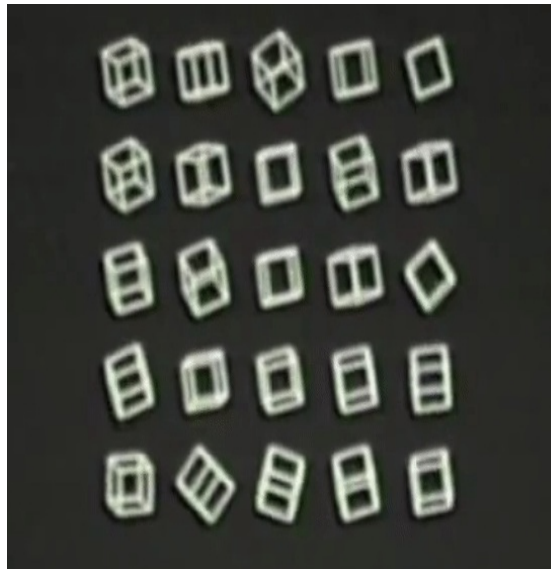
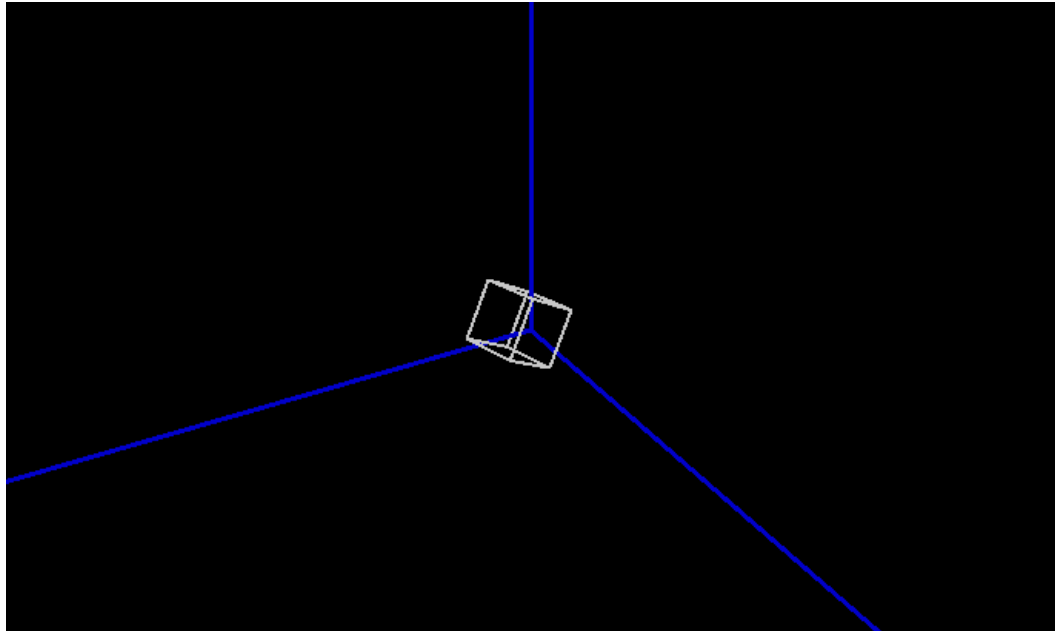


# TD 1 - Homogeneous coordinates linear transformations

## (with an introduction to Processing)

(LUCA CASTELLI ALEARDI, 18TH SEPT 2018)

How to create a simple screen saver? The goal of this TD is to provide a simple applet animating 3D cube screen saver, as in the video below on the right (by Manfred Mohr, 1973-74, Cubic Limit)



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### 0. GETTING STARTED WITH ECLIPSE AND PROCESSING

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[Processing](#) is a java based programming language providing an easy and nice environment for dealing with computer graphics, image processing, geometric modelling, ...

In order to correctly configure Processing and Eclipse, please follow these [procedures](#).

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### 1. PERFORMING SIMPLE TRANSFORMATIONS ON POINTS IN THE PLANE

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#### FILES TO DOWNLOAD TODAY

Here two Java libraries to install (in a "general Eclipse Project", use a LIB directory):

- [Jama](#) library (for matrix computations)
- [Processing](#) (for 2d rendering)

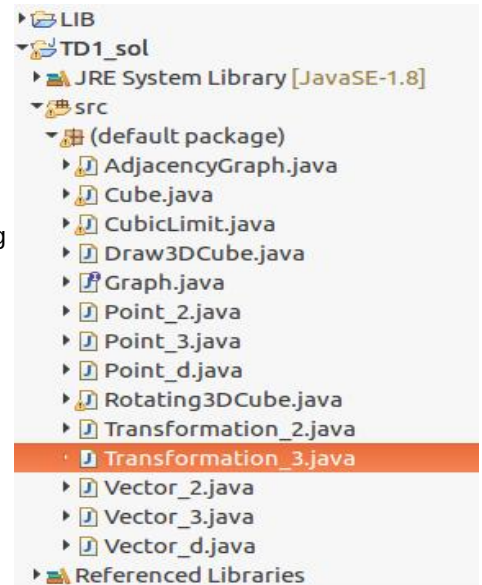
Here are some files to download (and extract to the /src folder of your Eclipse project):

- [src.zip](#): contains a number of classes for representing and manipulating geometric objects (such as points, vectors, graphs, ...).
- [Rotating3DCube.java](#): this class provided main methods for drawing graphs (to be completed today)
- [Transformation\\_3](#): allows to describe projective transformations in 3D space, using matrix representation involving homogeneous coordinates.

## JAVA DOCUMENTATION

Here is the [javaDoc](#) concerning the packages and classes used today:

- Jama [documentation](#);
- Processing [documentation](#);
- TD1 [documentation](#).



## TESTING THE CLASS ROTATING3DCUBE

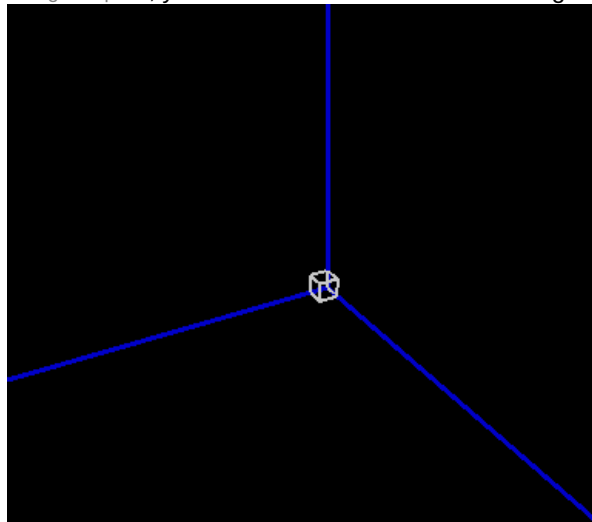
In order to provide a simple way of drawing and animating graphs (skeletons of 3D meshes) we will use classes `Cube` and `Rotating3DCube`.

Class `Rotating3DCube` provides a very basic and simple way of performing drawings in a 3D Processing frame.

Class `Square` provides the main methods for creating and animating 2D meshes. More precisely, it contains

- `Cube cube`, which stores the (geometric) graph to display: it is a 3D cube in our example (located in such a way that one of its vertices coincides with the origin)
- `Draw3DCube` renderer, providing methods for drawing 3D segments in 3D space

When executing the first time class `Drawing2DSquare`, you should obtain a frame visualizing a square, as below:

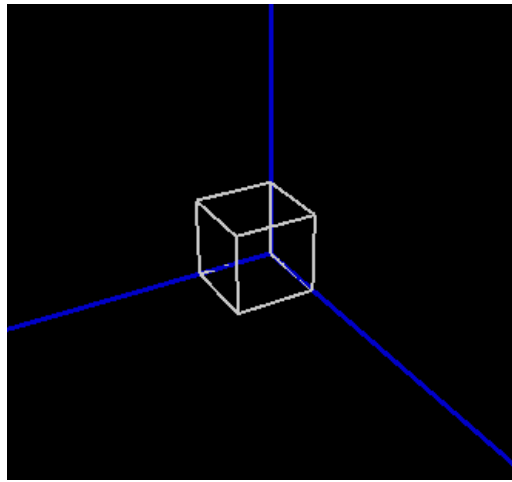


## 1.0 SCALING THE CUBE

Recall that with the use of homogeneous coordinates, any scaling can be expressed in a matrix form.

- complete the function `public static Transformation_3 scaling(double s)` of class `Transformation_3`, which constructs and return a (matrix) transformation corresponding to a scaling.
- Modify method `public void scale(double zoomFactor)` in order to perform a scale of the cube: this method must return a `Transformation_3`

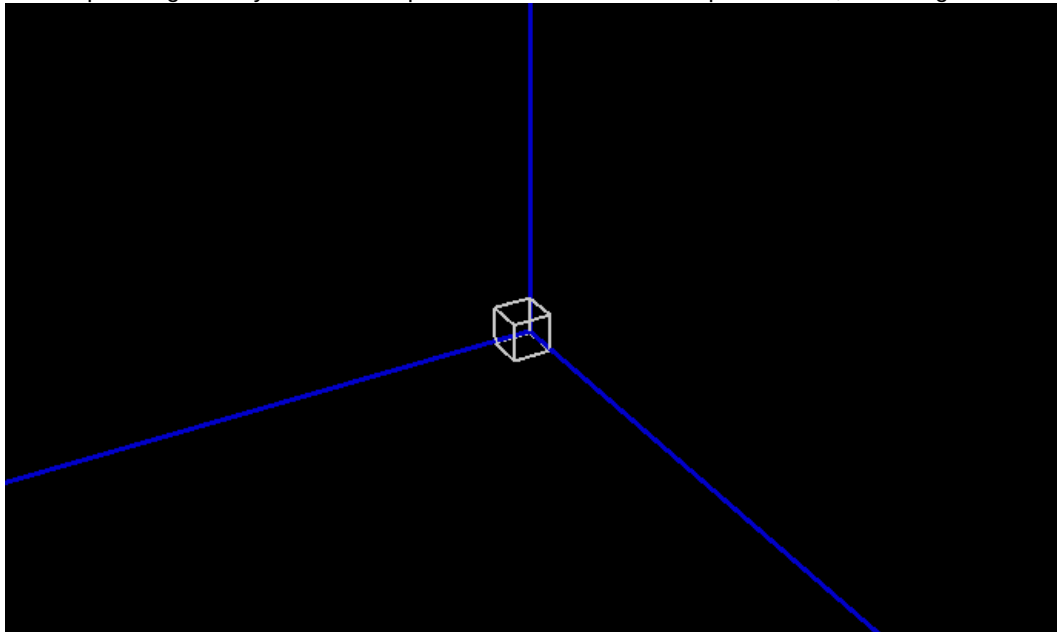
You can test your code pressing the key 'i' and 'o' (on your keyboard) to perform the scaling, obtaining the following result:



### 1.1 MOVING (VERTICALLY) THE CUBE

- Complete method `moveZ(float speed)` which moves the square along vertical direction.

You can test your code pressing the key 'u' and 'd' to perform to move the cube up and down, obtaining the result below:



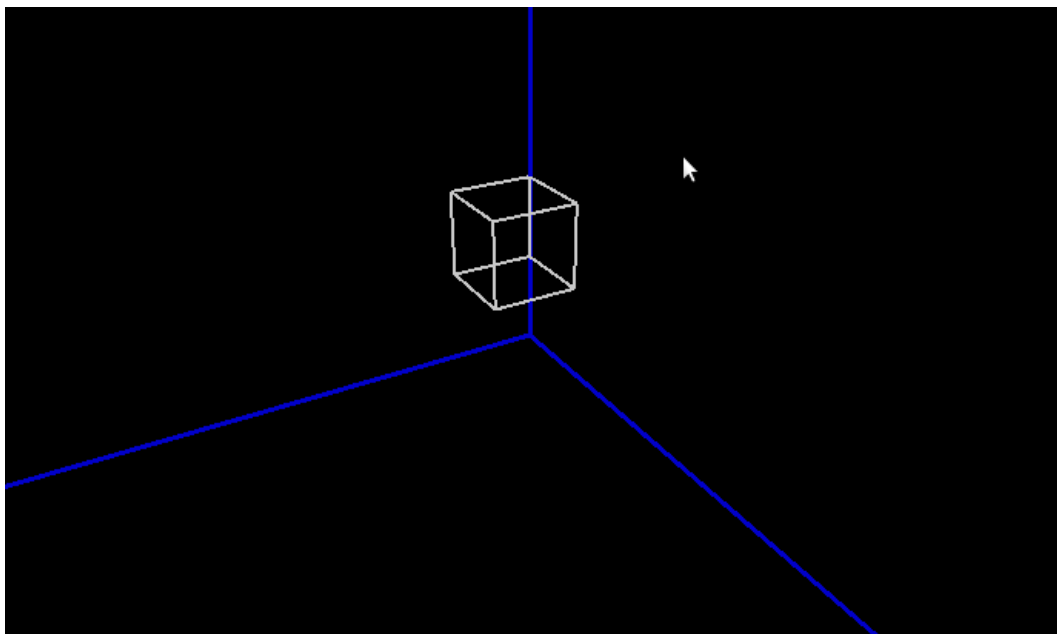
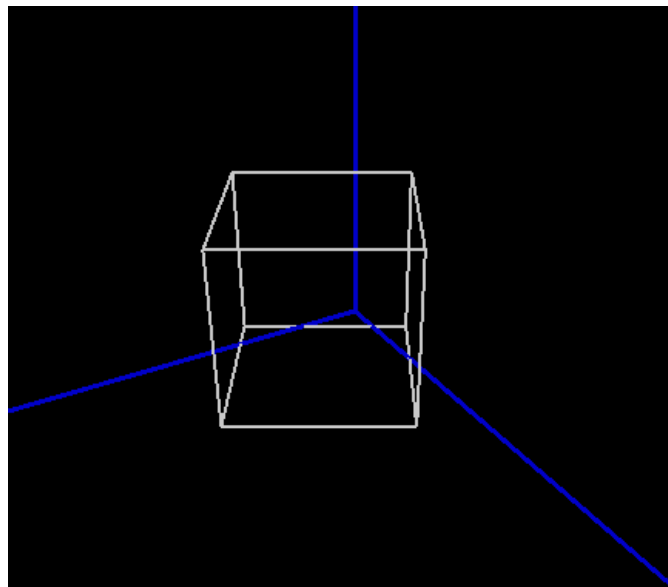
### 1.2 ROTATING THE CUBE (AROUND ITS BARYCENTER)

Recall that rotations can also be expressed in terms matrix multiplications, as in the example below (rotation around z axe). In your case, you should use a matrix of size 4x4, as we make use of homogeneous coordinates.

$$\mathcal{R}_{z,\theta} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x \cos \theta - y \sin \theta \\ x \sin \theta + y \cos \theta \\ z \end{pmatrix}$$

- complete the functions `rotationAxisX(double theta)` of class `Transformation_3`, which construct and return the (matrices) transformations corresponding to rotations around the three axis.
- Complete the functions `rotateX(double angle)`, `rotateY(double angle)` and `rotateZ(double angle)` of class `Rotating3DCube` in order to rotate the cube around its barycenter.

Suggestion: you can first implement and test the rotation around the x-direction, using the key 'x' on your keyboard. Once you have implemented all 3 rotations, you should be able to obtain (using the 3 keys 'x', 'y' and 'z':



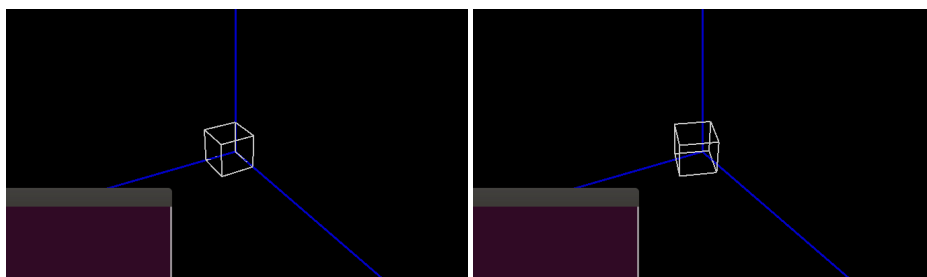
### 1.3 ROTATING THE CUBE AROUND A DIAGONAL (BONUS)

- Complete method `public void rotateAroundDiagonal(double angle)` in order to perform a rotation of the cube around one of its diagonals.

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## 2. ANIMATING THE CUBE

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The Processing library allows us also to animate objects in 3D space: this is done by the `draw()` function, whose instructions are run periodically, in order to have an animation effect.

### 2.1 A DECREASING/INCREASING CUBE

As first example, you can just run the `CubicLimit` class: you should obtain an animating cube, whose size decreases and increases

over time as in the picture above.

Take a look to the function `public Cube animatingCube(double size)`, which creates a small cube and perform the update of the scaling transformation. This function is called by the `draw()` function, in order to create an animation effect.

## 2.2 A ROTATING CUBE

Complete the function `public Cube rotatingCube(double size)`, which creates a small cube and computes the animation of a rotating cube.

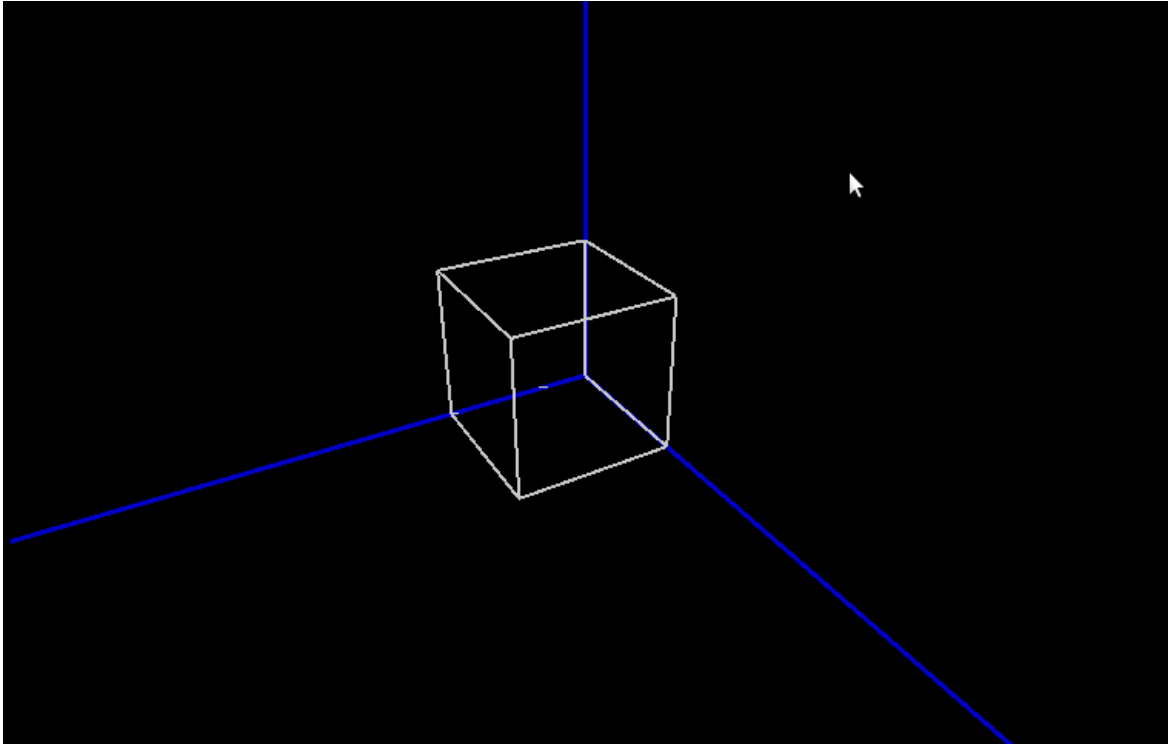
To test your code, you have just to remove the comment in the `draw()` function:

```
//Cube cube=this.rotatingCube(80); // remove comment to test this function
```

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## 3. AN ARCBALL USING QUATERNIONS: DEALING WITH MOUSE EVENTS

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The goal of this section is to provide a basic implementation of an arcball (as in the example above): this allows to deal with mouse events to manipulate the rotation of your 3D scene.

You will be asked to use quaternions to perform rotations in 3D space

You have to complete the class `Quaternion`, in order to:

- ) complete function `multiply()`, which perform the multiplication of two quaternions,
- ) complete function `getValue()`, returning the angle and rotation vector encoded by the quaternion

Then you can test your code by running the class `CubicLimit`: you have just to remove the comment in the function `setup()`:

```
//ArcBall arcball = new ArcBall(this); // for interaction with mouse events and 3D rendering
```