2.3.

(a)
$$g(t) = A \operatorname{vect}(\frac{t}{T} - \frac{1}{2})$$

$$= 7 g_{e}(t) = \frac{1}{2}[g(t) + g(-t)] = \frac{A}{2} \left(\operatorname{vect}(\frac{t}{T} - \frac{1}{2}) + \operatorname{vect}(\frac{-t}{T} - \frac{1}{2}) \right)$$

$$\cdot g_{o}(t) = \frac{1}{2}[g(t) - g(-t)] = \frac{A}{2} \left(\operatorname{vect}(\frac{t}{T} - \frac{1}{2}) - \operatorname{vect}(\frac{-t}{T} - \frac{1}{2}) \right)$$
(b) Let $\chi(t) = \operatorname{vect}(\frac{t}{T}) \left(\text{Note that } \chi(t) = \chi(-t) \right)$

$$= 7 \chi \left(\frac{1}{2} w \right) = \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} e^{iwt} dt = \frac{2fin(w\frac{\pi}{2})}{w} = T \operatorname{sinc}(\frac{wT}{2}) \left(\text{when } w = 2\overline{u}f \right)$$

$$= 7 \chi \left(\frac{1}{2} w \right) = \frac{A}{2} \left(\chi(t - \frac{1}{2}T) + \chi(-t - \frac{1}{2}T) \right)$$

$$= 7 \zeta \left(\frac{1}{2} \left(\frac{1}{2} \right) + \frac{1}{2} \left(\frac{1}{2} \left(\frac{1}{2} \right) + \frac{1}{2} \left(\frac{1}{2} \right) \right) \right)$$

$$= A T e^{-iw\frac{\pi}{2}} \operatorname{sinc}(\frac{wT}{2}) = G_{1}(iw)$$

(a) Let g(t) be real and even

then
$$G''(f) = \left(\int_{-\infty}^{\infty} g(t)e^{j2\pi t}dt\right)^* = \int_{-\infty}^{\infty} g(t)e^{j2\pi t}dt = G(-f)$$
 since $g(t)$ is real $G(-f) = \int_{-\infty}^{\infty} g(-t)e^{j2\pi t}dt = \int_{-\infty}^{\infty} g(t)e^{j2\pi t}dt = G(-f)$ since $g(t)$ is even

=>
$$G(f) = G(-f) = G^*(f)$$
 which implies $G(f)$ is real

Let
$$g(t)$$
 be real and odd
then $G(t) = G^*(-t)$ since $g(t)$ is real
 $G(-t) = \int_{-\infty}^{\infty} g(-t) e^{j2\pi t} dt = -G(t)$ since $g(t)$ is odd

By induction,
$$t^n g(t) = \left(\frac{1}{2\pi}\right)^n G^{(n)}(f)$$
 obviously.

$$\left(\frac{1}{2\pi}\right)^2 G^{(n)}(t) = \int_{-\infty}^{\infty} t^n g(t) e^{-j2\pi t} dt$$

$$=7\left(\frac{1}{2\pi}\right)^{n}G^{(n)}(0)=\int_{-\infty}^{\infty}t^{n}g(t)dt$$

(d) We have $g_{i}(t)g_{i}(t) \Rightarrow \int_{-\infty}^{\infty} G_{i}(\lambda) (g_{i}(t-\lambda)) dt$ for any $g_{i},g_{i}(t)$ $g_{i}(t) \Rightarrow \int_{-\infty}^{\infty} G_{i}(\lambda) (g_{i}(\lambda-t)) d\lambda$ ($g_{i}(t) = G(t)$ then $g_{i}(t) \Rightarrow G_{i}(t-t)$)

(e) $\int_{-\infty}^{\infty} g_{i}(t) g_{i}(t) dt = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} G_{i}(t) g_{i}^{2\pi t} dt g_{i}^{2\pi t} dt$ $= \int_{-\infty}^{\infty} G_{i}(t) \int_{-\infty}^{\infty} g_{i}(t) G_{i}^{2\pi t} dt$ $= \int_{-\infty}^{\infty} G_{i}(t) G_{i}^{2\pi t} dt$

2.10. Let $y(t) = \chi(t)$, $\chi(t) = \chi(f)$ then $y(t) = \chi(t) \chi(t) \rightleftharpoons \chi(f) = \chi(f) \Rightarrow \chi(f)$ $\Rightarrow \chi(f) = \int_{-\infty}^{\infty} \chi(\lambda) \chi(f-\lambda) d\lambda = \int_{-\infty}^{\infty} \chi(\lambda) \chi(f-\lambda) d\lambda$ In the integration $\chi(\lambda) \chi(f-\lambda)$ has nonzero values it $\begin{pmatrix} -w < \lambda < w \\ -w + \lambda < f < w + \lambda \end{pmatrix}$ $\Rightarrow \chi(f)$ has nonzero value only at $0 \le |f| \le 2w$

(a) According to Payleigh's Energy than, we have
$$\int_{-\infty}^{\infty} |g(t)|^2 dt = \int_{-\infty}^{\infty} |G(t)|^2 dt$$
.

Which we can assume $\int_{-\infty}^{\infty} |g(t)|^2 dt = \int_{-\infty}^{\infty} |G(f)|^2 df = 1$

$$\int_{-\infty}^{\infty} \frac{1g(t)^2 = k \neq 1}{\int_{-\infty}^{\infty} \frac{1g(t)^2 dt}{\int_{-\infty}^{\infty} \frac{$$

=> Trms Wrms =
$$\int_{-\infty}^{\infty} t^2 |g(t)|^2 dt \int_{-\infty}^{\infty} f^2 |G(t)|^2 dt$$

Consider L=4 $\int_{-\infty}^{\infty} t^2 |g(t)|^2 dt \int_{-\infty}^{\infty} |g'(t)|^2 dt$

By Schwarz's inequality
$$L \geq \left(\int_{-\infty}^{\infty} t g^{*}(t) g'(t) + t g(t) (g'(t))^{*} dt\right)^{2}$$

$$= \left(\left|t |g(t)|^{2}\right|_{-\infty}^{\infty} - \int_{-\infty}^{\infty} |g(t)|^{2} dt\right)^{2}$$

$$= \left(\int_{-\infty}^{\infty} |g(t)|^2 dt\right)^2 = 1$$

By Rayleigh's Energy thm Otherwise So 19'(t) | dt = 50 |211 / x(f) | df = 411 50 + 1x(f) | df

(b) According to Schwarz's inequality, the equality holds is
$$g'(t) = ctg(t)$$
 for some CEF Non gitl= $e^{-\overline{t}t^2} = g'(t) = 2te^{-\overline{t}t^2} = 2tg(t)$

Ïhý uú

2.19.
$$W_{n} = W_{n+1-n} \quad 0 \le n \le N+1$$

$$H(e^{jw}) = \sum_{N=0}^{N-1} W_{n} e^{-jw} = \left(\sum_{n=0}^{N-1} W_{n} e^{-jw} \frac{N-1}{2}\right) e^{-jw} \frac{N-1}{2}$$

$$= \left[W_{n} + 2\sum_{k=0}^{N-1} W_{k} \left(e^{jw} \frac{N-1}{2}\right) + e^{jw} \frac{N-1}{2}\right]$$

$$= \left[W_{n} + 4\sum_{k=0}^{N-1} W_{k} \cos(k - \frac{N-1}{2})\right] e^{-jw} \frac{N-1}{2}$$

$$= \left[W_{n} + 4\sum_{k=0}^{N-1} W_{k} \cos(k - \frac{N-1}{2})\right] e^{-jw} \frac{N-1}{2}$$

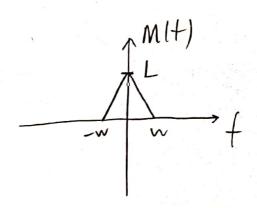
$$\left(0\right) \left[H(e^{jw})\right] = W_{n} + 4\sum_{k=0}^{N-1} W_{k} \cos(k - \frac{N-1}{2})$$

$$\left(0\right) \left[H(e^{jw})\right] = \frac{N-1}{2}w$$

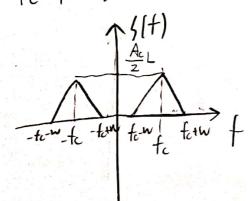
$$\left(0\right) \left[H(e^{jw})\right] = \frac{N-1}{2}w$$

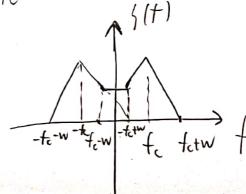
=>
$$5(t) = \frac{Ac}{2} \left(M(-t-tc) + M(+t-tc) \right)$$

BW of MIt) is W= 1 LHZ



fc=1.25/2Hz





The bound for which each component of the modulated signal set) is uniquely determined by mit) is I kHz.

(i.e. there is no aliasing)

3.9.

5.(t) = Ac(1+ka Mlt) cos(2 tot)

5.(t) = Ac(1-ka Mlt)) cos(2 tot)

=> 5(t) = 5.(t) - 52lt) = 2 ka Mlt) cos(2 tot)

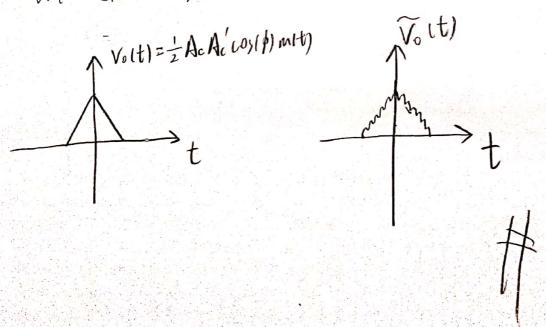
=> 5(t) is a DSB-3C modulated signal with Ac = 2 ka.

3.11.

(a) If there is no frequency error in the local conview frequency then V(t)=s(t) $Ac'(c)s(2\pi t t t t)$ It there is an frequency error of in the local conview frequency then V(t)=s(t) $Ac'(c)s(2\pi (t t t t) t t) = s(t)$ $Ac'(c)s(2\pi (t t t t) t t) = s(t)$ $Ac'(c)s(2\pi (t t t) t t) = s(t)$ $Ac'(c)s(2\pi (t t t) t t) = s(t)$ $Ac'(c)s(2\pi (t t t) t t) = s(t)$

(b) For $s(t) = A_c con(2\pi fct)m(t)$ $\widetilde{V}(t) = A_c con(2\pi fct)m(t) A_c con(2\pi fct)t + \phi)$ $= \frac{1}{2}A_c A_c \left(2\pi (2fct) + \phi\right)m(t) + \frac{1}{2}A_c A_c con(2\pi of t + \phi)m(t)$ $\widetilde{V}(t) \stackrel{LPF}{\longrightarrow} \widetilde{V}_o(t) = \frac{1}{2}A_c A_c con(2\pi of t + \phi)m(t)$

Time CO3(2009tt+) is nonconstant due to the term 2009tt



3.14.

Let the input of receiver be $s(t) = m_1(t) \cos(2\pi f_0 t) + m_2(t) \sin(2\pi f_0 t)$ Now we has a phase error ϕ .

Thus, cosider $\widehat{y}_1(t) = s(t) \cos(2\pi f_0 t + \phi)$ (For convinent I ignore Ac, Ac' here since they are just scalars. $\Rightarrow \widehat{v}(t) = M_1(t) \cos(2\pi f_0 t + \phi) + m_1(t) \sin(2\pi f_0 t + \phi)$ $= \frac{1}{2} \cos(4\pi f_0 t + \phi) m_1(t) + \frac{1}{2} \cos(4\phi) m_1(t) + \frac{1}{2} \sin(4\pi f_0 t + \phi) m_1(t) - \frac{1}{2} \sin(4\phi) m_2(t)$ $\widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_2(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \sin(4\phi) m_2(t)$ $\widehat{v}_2(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \cos(4\phi) m_1(t)$ $\Rightarrow \widehat{v}_2(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \cos(4\phi) m_2(t)$ $\Rightarrow \widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \cos(4\phi) m_2(t)$ $\Rightarrow \widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \cos(4\phi) m_2(t)$ $\Rightarrow \widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \cos(4\phi) m_2(t)$ $\Rightarrow \widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \cos(4\phi) m_2(t)$ $\Rightarrow \widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \cos(4\phi) m_2(t)$ $\Rightarrow \widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \cos(4\phi) m_2(t)$ $\Rightarrow \widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \cos(4\phi) m_2(t)$ $\Rightarrow \widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \cos(4\phi) m_2(t)$ $\Rightarrow \widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \cos(4\phi) m_2(t)$ $\Rightarrow \widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \cos(4\phi) m_2(t)$ $\Rightarrow \widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \cos(4\phi) m_2(t)$ $\Rightarrow \widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \cos(4\phi) m_2(t)$ $\Rightarrow \widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \sin(4\phi) m_2(t)$ $\Rightarrow \widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \sin(4\phi) m_2(t)$ $\Rightarrow \widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \sin(4\phi) m_2(t)$ $\Rightarrow \widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \sin(4\phi) m_2(t)$ $\Rightarrow \widehat{v}_1(t) \xrightarrow{LPF} \widehat{v}_3(t) = \frac{1}{2} \sin(4\phi) m_1(t) + \frac{1}{2} \sin(4\phi) m_2(t)$

$$m_{i}(t) = V_{0} + m_{i}(t) + m_{i}(t) \longrightarrow S_{i}(t) = A_{c} m_{i}(t) cos(2\pi f_{c}t)$$

$$m_{i}(t) = m_{i}(t) - m_{i}(t) \longrightarrow S_{i}(t) = A_{c} m_{i}(t) sin(2\pi f_{c}t)$$

$$(a) \quad \text{We have } \quad \text{ait}) cos(2\pi f_{c}t) + \text{bit}) cos(2\pi f_{c}t) \xrightarrow{Envologe} \quad \sqrt{a^{2}(t) + b^{2}(t)}$$

$$= \sum S_{i}(t) \xrightarrow{\text{detactor}} V_{i}(t) = \int_{A_{c}} m_{i}(t) = A_{c} m_{i}(t) = A_{c} (V_{s} + m_{i}(t) + m_{i}(t))$$

$$= \sum S_{i}(t) \xrightarrow{\text{detactor}} V_{i}(t) = \int_{A_{c}} m_{i}(t) = A_{c} m_{i}(t) = A_{c} (V_{s} + m_{i}(t) + m_{i}(t))$$

$$= \sum S_{i}(t) \xrightarrow{\text{detactor}} V_{i}(t) = \int_{A_{c}} m_{i}(t) = A_{c} m_{i}(t) \text{ and } m_{i}(t) = A_{c} (V_{s} + m_{i}(t) + m_{i}(t))$$

$$= \sum S_{i}(t) \xrightarrow{\text{detactor}} V_{i}(t) = \sum S_{i}(t) \text{ and } m_{i}(t) = A_{c} m_{i}(t) \text{ and } m_{i}(t) + A_{c} m_{i}(t) \text{ and } m_{i}(t)$$

$$= \sum S_{i}(t) \xrightarrow{\text{detactor}} V_{i}(t) = \sum S_{i}(t) \text{ and } m_{i}(t) + A_{c} m_{i}(t) \text{ and } m_{i}(t)$$

$$= \sum S_{i}(t) \xrightarrow{\text{detactor}} V_{i}(t) = \sum S_{i}(t) \text{ and } m_{i}(t) + A_{c} m_{i}(t) \text{ and } m_{i}(t)$$

$$= \sum S_{i}(t) \xrightarrow{\text{detactor}} V_{i}(t) = \sum S_{i}(t) \text{ and } m_{i}(t) + A_{c} m_{i}(t) \text{ and } m_{i}(t)$$

$$= \sum S_{i}(t) \xrightarrow{\text{detactor}} V_{i}(t) + \sum S_{i}(t) \text{ and } m_{i}(t) + \sum S_{i}(t) \text{ and } m_{i}(t)$$

$$= \sum S_{i}(t) \xrightarrow{\text{detactor}} V_{i}(t) + \sum S_{i}(t) \text{ and } m_{i}(t) + \sum S_{i}(t) \text{ and } m_{i}(t)$$

$$= \sum S_{i}(t) \xrightarrow{\text{detactor}} V_{i}(t) + \sum S_{i}(t) \text{ and } m_{i}(t)$$

$$= \sum S_{i}(t) \xrightarrow{\text{detactor}} V_{i}(t) + \sum S_{i}(t) \text{ and } m_{i}(t)$$

$$= \sum S_{i}(t) \xrightarrow{\text{detactor}} V_{i}(t) + \sum S_{i}(t) \text{ and } m_{i}(t)$$

$$= \sum S_{i}(t) \xrightarrow{\text{detactor}} V_{i}(t) + \sum S_{i}(t) \text{ and } m_{i}(t)$$

$$= \sum S_{i}(t) \xrightarrow{\text{detactor}} V_{i}(t) + \sum S_{i}(t) \text{ and } m_{i}(t)$$

$$= \sum S_{i}(t) \xrightarrow{\text{detactor}} V_{i}(t) + \sum S_{i}(t) + \sum S_$$

3.15.