# 通訊系統 (II)

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# Chapter 9 Error-Control Coding

### Introduction

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#### Introduction

- Considering different types of communication channels, such as
  - AWGN channels: AWGN is the main source of channel impairment, such as the satellite communication channels
  - Multipath channels: multipath interference is the main source of channel impairment, such as the wireless channels
  - Interference channels: interference is the main source of channel impairment, such as the random access channels
- These scenarios are naturally quite different from each other
  - But they share a common practical shortcoming: **reliability**
- The use of **error-control coding** is essential for supporting **reliable transmissions**.

### Introduction (Cont.)

- From a communication theoretic perspective, the two key resources for reliable transmissions are
  - Transmitted signal power P
  - Channel bandwidth B
- With the **power spectral density** of the receiver noise, the **signal energy per bit-to-noise power spectral density ratio** is  $E_b/N_0 = E_s/(N_0 \log_2 M) = PT_s/(N_0 \log_2 M) = P/(N_0 B \log_2 M)$ 
  - $-E_s$ : symbol energy;  $T_s$ : symbol duration; M-ary modulation
- $E_b/N_0$  uniquely determines the BER of a particular modulation scheme operating over a **Gaussian noise channel**.
- For a fixed  $E_b/N_0$ , the only practical option available for improving data quality is to use error-control coding

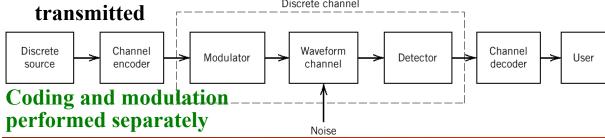
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### Introduction (Cont.)

- Error-control coding: At the transmitter, incorporate a fixed number of redundant bits into the structure of a codeword
- It is feasible to provide **reliable communication** over a noisy channel
  - Provided that **Shannon's code theorem** is satisfied
- In effect, **channel bandwidth** is traded off for **reliability** in communications.
- Another practical motivation for the use of coding is to **reduce** the required  $E_b/N_0$  for a fixed BER. This reduction in  $E_b/N_0$  may, in turn, be exploited to
  - Reduce the required transmitted power
  - Reduce the hardware costs by requiring a smaller antenna size (antenna gain) in the case of radio communications

### Forward Error Correction

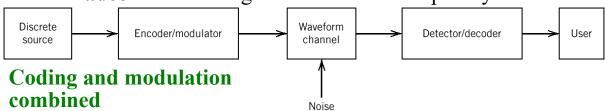
- Error control for data integrity may be achieved by means of forward error correction (FEC).
- The **discrete source** generates information (binary symbols)
- The **channel encoder** accepts message bits and adds **redundancy** according to a prescribed rule
  - Produce an encoded data stream at a higher bit rate
- Based on a **noisy version** of the encoded data stream, the **channel decoder** decide which message bits were **actually**



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### Forward Error Correction (Cont.)

- The combined goal of the channel encoder and decoder is to minimize the effect of channel noise/interference.
  - The number of errors between the channel encoder input and the channel decoder output (source ⇔ sink) is minimized.
- For a fixed **modulation scheme**, the **addition of redundancy** implies the need for
  - Increasing in transmission bandwidth
  - Increasing in system complexity
  - Tradeoff considering bandwidth and complexity is essential



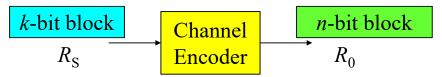
### Types of Error-Correcting Codes

- Historically, error-correcting codes have been classified into **block codes** and **convolutional codes**.
  - The distinguishing feature for this particular classification is the absence or presence of memory in the encoders.
- Block codes, convolutional codes, and trellis codes represent the classical family of codes
  - They follow traditional approaches rooted in algebraic mathematics
  - Block codes and convolutional codes: Coding and modulation are designed separately
  - Trellis codes: Coding and modulation are designed jointly
- In addition, turbo codes and low-density parity-check (LDPC) codes are two types of new generation coding techniques

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#### **Block Codes**

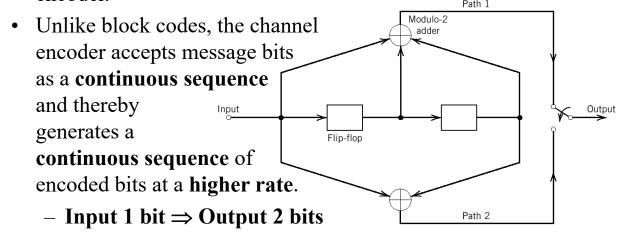
- To generate an (n, k) block code
  - The channel encoder accepts **k-bit blocks** successively
  - For each block, the encoder adds n k redundant bits
    - That are **algebraically related to** the *k* message bits,
    - Thereby producing an encoded block of n bits, n > k
- Codeword: The *n*-bit block, where *n* is the block length
- The **channel data rate** (at the encoder output) is  $R_0 = (n/k)R_S$ 
  - where  $R_{\rm S}$  is the **bit rate** of the **information source**.
- The ratio r = k/n is called the **code rate**, where 0 < r < 1.



#### Convolutional Codes

• In a convolutional code, the encoding operation may be viewed as the **discrete-time convolution** of the **input sequence** with the **impulse response of the encoder**.

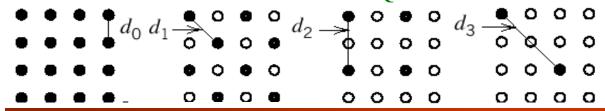
• The duration of the impulse response equals the **memory** of the encoder.



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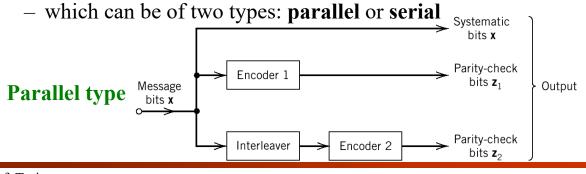
### Trellis Codes

- Conventionally, the operations of channel coding and modulation are design/performed separately at the transmitter
- The **most effective** method of implementing forward error correction coding is to **combine** coding with modulation
- Coding is redefined as a process of imposing certain patterns (constellation points) on the transmitted signal
  - The resulting code is called a **trellis code**
- Based on the concept that different pairs of constellation points have different error distances
   16-OAM



#### Turbo Codes

- **Turbo codes** are a class of high-performance forward error correction (FEC) codes
  - The first practical codes to closely approach the maximum channel capacity or Shannon limit
  - Turbo codes are used in 3G/4G mobile communications
- The design objective of turbo codes is achieved by using concatenated codes

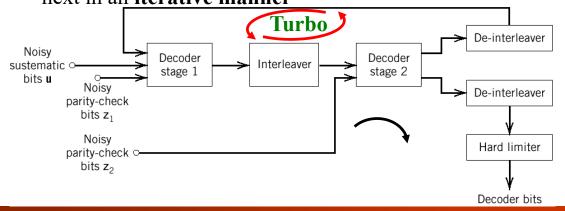


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### Turbo Codes (Cont.)

- The two-stage **turbo decoder** operates on noisy versions of the systematic bits and the two sets of parity-check bits
  - To produce an estimate of the original message bits
- A distinctive feature of the turbo decoder is the use of **feedback**

 To produce extrinsic information from one decoder to the next in an iterative manner



# Low-Density Parity-Check (LDPC) Codes

- Low-Density Parity-Check (LDPC) codes are specified by a parity-check matrix A, represented as  $\mathbf{A}^{T} = \begin{bmatrix} \mathbf{A}_{1} \\ \mathbf{A}_{2} \end{bmatrix}$ 
  - where  $A_1$  is a square matrix of dimensions  $(n-k)\times(n-k)$  and  $A_2$  is a rectangular matrix of dimensions  $k\times(n-k)$ ;
  - A is purposely (randomly with rules) chosen to be sparse;
     that is, A consists mainly of 0s and a small number of 1s
- The 1-by-*n* code vector  $\mathbf{c}$  is partitioned as  $\mathbf{c} = [\mathbf{b} \mid \mathbf{m}]$ 
  - where **m** is the k-by-1 **message vector** and **b** is the (n k)-by-1 **parity-check vector**
- Then, based on the parity-check concept,  $\mathbf{c} \mathbf{A}^T = [\mathbf{b} \mid \mathbf{m}] \mathbf{A}^T = \mathbf{0}$
- The parity vector **b** is obtained by  $\mathbf{b} = \mathbf{mP}$ , where  $\mathbf{P} = \mathbf{A}_2 \mathbf{A}_1^{-1}$

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#### Linear Block Codes

### Channel-Coding Theorem (Revisited)

- Consider a discrete memoryless **source** that has the source alphabet  $\mathbb{S}$  and entropy H(S) bits per source symbol.
- Assume that the source **emits symbols** once every  $T_{\rm s}$  seconds
  - The average information rate:  $H(S)/T_s$  bits per second
  - The decoder delivers decoded symbols to the destination at the same source rate of one symbol every  $T_{\rm s}$  seconds
- The discrete memoryless **channel** has a **channel capacity** equal to *C* bits per use of the channel.
- Assume that the channel can be used once every  $T_{\rm c}$  seconds
  - The channel capacity per unit time:  $C/T_c$  bits per second
  - The **maximum rate** of information transfer over the channel to the destination:  $C/T_{\rm c}$  bits per second

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# Channel-Coding Theorem (Cont.)

- Shannon's second theorem: the channel-coding theorem
- Let a **discrete memoryless source** with an alphabet  $\mathbb{S}$  have entropy H(S) for random variable S and produce symbols once every  $T_s$  seconds.
- Let a **discrete memoryless channel** have capacity C and be used once every  $T_{\rm c}$  seconds.
- Then, if  $H(S)/T_s \le C/T_c$  there exists a **coding scheme** for which the source output can be **transmitted** over the channel and be **reconstructed** with an arbitrarily small probability of error.
- The parameter  $C/T_c$  is called the **critical rate**.
  - When  $H(S)/T_s = C/T_c$ , the system is said to be signaling at the critical rate.

# Channel-Coding Theorem (Cont.)

- Conversely, if  $H(S)/T_s > C/T_c$  it is **not possible** to transmit information over the channel and reconstruct it with an arbitrarily small probability of error.
- The channel-coding theorem is the single **most important** result of information theory.
  - The theorem specifies the channel capacity C as a fundamental limit on the rate at which the transmission of reliable error-free messages can take place over a discrete memoryless channel.

Channel capacity

Error is inevitable

Error-free transmission is possible

Information entropy
Information entropy

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### **Binary Arithmetic**

- Many of the codes are **binary codes**, for which the alphabet consists only of binary symbols **0** and **1**.
- The encoding and decoding functions involve the binary arithmetic operations of **modulo-2 addition** and **multiplication**.
  - Modulo-2 addition: EXCLUSIVE-OR operation

• 
$$0+0=0$$
;  $1+0=1$ ;  $0+1=1$ ;  $1+1=0$ ;

- Modulo-2 multiplication: AND operation

• 
$$0 \times 0 = 0$$
;  $1 \times 0 = 0$ ;  $0 \times 1 = 0$ ;  $1 \times 1 = 1$ ;

#### Linear Block Codes

- Definition of a linear code:
  - A code is said to be linear if any two codewords in the code can be added in modulo-2 arithmetic to produce a third codeword in the code.
- Consider an (n, k) linear block code, in which k bits of the n code bits are always identical to the message sequence.
  - This type of codes are called systematic codes.
  - For applications requiring both error detection and error correction, it simplifies implementation of the decoder.
- The (n k) bits in the remaining portion are computed from the message bits in accordance with a prescribed encoding rule.
  - These (n k) bits are referred to as **parity-check bits**.

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### Linear Block Codes (Cont.)

- Let  $m_0, m_1, \dots, m_{k-1}$  constitute a block of k message bits
  - There are  $2^k$  distinct message blocks
- Let this sequence of message bits be applied to a **linear block** encoder, producing an *n*-bit codeword:  $c_0$ ,  $c_1$ , ...,  $c_{n-1}$ 
  - The (n-k) parity-check bits:  $b_0, b_1, \dots, b_{n-k-1}$
  - For a systematic code, a codeword is divided into two parts:
     the message bits and the parity-check bits
- Assume that the (n k) **leftmost** bits of a codeword are the corresponding **parity-check bits** and the k **rightmost** bits of the codeword are the message bits.

$$c_i = \begin{cases} b_i, & i = 0, \dots, n-k-1 \\ m_{i+k-n}, & i = n-k, \dots, n-1 \end{cases} \underbrace{\begin{bmatrix} b_0, b_1, \dots, b_{n-k-1} \\ p_{arity bits} \end{bmatrix}}_{\text{Parity bits}} \underbrace{\begin{bmatrix} m_0, m_1, \dots, m_{k-1} \\ m_0, m_1, \dots, m_{k-1} \end{bmatrix}}_{\text{Parity bits}}$$

### Linear Block Codes (Cont.)

- The (n-k) parity-check bits are **linear sums** of the k message bits:  $b_i = p_{0,i} m_0 + p_{1,i} m_1 + \cdots + p_{k-1,i} m_{k-1}$ 
  - where  $p_{i,i} = 1$ , if  $b_i$  depends on  $m_i$ ; and  $p_{i,i} = 0$ , otherwise
- The coefficients  $p_{j,i}$  are chosen in such a way that
  - The rows of the generator matrix are **linearly independent**
  - The parity-check equations are **unique**
- This system can be rewritten in a **matrix form**:
  - The 1-by-k message vector  $\mathbf{m} = [m_0, m_1, \dots, m_{k-1}]$
  - The 1-by-(n-k) parity-check vector  $\mathbf{b} = [b_0, b_1, \dots, b_{n-k-1}]$ 
    - $\mathbf{b} = \mathbf{mP}$ , where **P** is the k-by-(n k) coefficient matrix
  - The 1-by-*n* code vector  $\mathbf{c} = [c_0, c_1, \dots, c_{n-1}]$

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### Linear Block Codes: Generator Matrix

• The k-by-(n - k) coefficient matrix is defined as

$$\mathbf{P} = \begin{bmatrix} p_{0,0} & p_{0,1} & \cdots & p_{0,n-k-1} \\ p_{1,0} & p_{1,1} & \cdots & p_{1,n-k-1} \\ \vdots & \vdots & \ddots & \vdots \\ p_{k-1,0} & p_{k-1,1} & \cdots & p_{k-1,n-k-1} \end{bmatrix}$$

• The code vector can be expressed as

$$\mathbf{c} = [\mathbf{b} : \mathbf{m}] = \mathbf{m} [\mathbf{P} : \mathbf{I}_k]$$

- where  $I_k$  is the k-by-k identity matrix
- We then define the k-by-n generator matrix as G

$$\mathbf{G} = \begin{bmatrix} \mathbf{P} : \mathbf{I}_k \end{bmatrix}$$
 Message vector  $\mathbf{G}$  Generator matrix  $\mathbf{G}$   $\mathbf{G}$ 

# Linear Block Codes: Generator Matrix (Cont.)

- The full set of **codewords** (the code) is generated by passing the set of possible message vectors **m** into **c** = **mG** 
  - The set of all  $2^k$  binary k-tuples (1-by-k vectors)
- A basic property of linear block codes is **closure** 
  - The sum of any two codewords in the code is another codeword
- Consider a pair of **code vectors**  $\mathbf{c}_i$  and  $\mathbf{c}_j$  corresponding to a pair of **message vectors**  $\mathbf{m}_i$  and  $\mathbf{m}_j$ , respectively.

$$\mathbf{c}_i + \mathbf{c}_j = \mathbf{m}_i \mathbf{G} + \mathbf{m}_j \mathbf{G} = (\mathbf{m}_i + \mathbf{m}_j) \mathbf{G}$$

- The modulo-2 sum of  $\mathbf{m}_i$  and  $\mathbf{m}_j$  is a new message vector  $\mathbf{m}_k$ 
  - Correspondingly, the modulo-2 sum of  $\mathbf{c}_i$  and  $\mathbf{c}_j$  is a **new** code vector  $\mathbf{c}_k$

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# Linear Block Codes: Parity-Check Matrix

• We define the (n - k)-by-n parity-check matrix as

$$\mathbf{H} = \left[ \mathbf{I}_{n-k} : \mathbf{P}^{\mathrm{T}} \right]$$

- where the (n k)-by-k matrix  $\mathbf{P}^{\mathrm{T}}$  is the transpose of  $\mathbf{P}$
- Accordingly, we have

$$\mathbf{H}\mathbf{G}^{\mathrm{T}} = \begin{bmatrix} \mathbf{I}_{n-k} \vdots \mathbf{P}^{\mathrm{T}} \end{bmatrix} \begin{bmatrix} \mathbf{P}^{\mathrm{T}} \\ \mathbf{I}_{k} \end{bmatrix} = \mathbf{P}^{\mathrm{T}} + \mathbf{P}^{\mathrm{T}} = \mathbf{0}; \quad \mathbf{G}\mathbf{H}^{\mathrm{T}} = \mathbf{0}$$

- In **modulo-2 arithmetic**, the matrix sum  $P^T + P^T$  is 0
- The inner product of a code vector and the transpose of H

 $cH^T = mGH^T = 0$ 

# Linear Block Codes: Syndrome

- The **generator matrix G** is used in the **encoding** operation at the **transmitter**.
- On the other hand, the **parity-check matrix H** is used in the **decoding** operation at the **receiver**.
- Let **r** denote the 1-by-*n* received vector that results from sending the code vector **c** over a **noisy binary channel**.
  - The sum of c and an error vector, or error pattern, e

$$\mathbf{r} = \mathbf{c} + \mathbf{e}$$

• The *i*-th element of **e** equals **0** (or **1**) if the corresponding element of **r** is **the same as** (or **different from**) that of **c**.

 $e_i = \begin{cases} 1, & \text{if an error has occurred in the } i - \text{th location} \\ 0, & \text{otherwise} \end{cases}$ 

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### Linear Block Codes: Syndrome (Cont.)

- The receiver decodes the code vector **c** from **r** 
  - The decoding starts with the computation of a 1-by-(n k) vector called the error-syndrome vector or syndrome
- The **syndrome** (length n k) corresponding to **r** is defined as

$$s = rH^T$$

Depends only on the error pattern and not on the transmitted codeword

$$\mathbf{s} = \mathbf{r}\mathbf{H}^{\mathrm{T}} = (\mathbf{c} + \mathbf{e})\mathbf{H}^{\mathrm{T}} = \mathbf{c}\mathbf{H}^{\mathrm{T}} + \mathbf{e}\mathbf{H}^{\mathrm{T}} = \mathbf{e}\mathbf{H}^{\mathrm{T}}$$

- Equal to the sum of those rows, corresponding to the errors
   have occurred, of the transposed parity-check matrix H<sup>T</sup>
- If errors occur at locations *i* and  $j \Rightarrow \mathbf{s} = \mathbf{h}_i + \mathbf{h}_j$ 
  - where  $\mathbf{h}_i$  and  $\mathbf{h}_j$  are the *i*-th and *j*-th rows of  $\mathbf{H}^T$

# Linear Block Codes: Syndrome (Cont.)

- For an error pattern  $\mathbf{e}$ , all error patterns that differ to  $\mathbf{e}$  by a codeword are  $\mathbf{e}_i$  that satisfy  $\mathbf{e}_i \mathbf{e} = \mathbf{c}_i$ 
  - There are  $2^k$  distinct code vectors:  $\mathbf{c}_i$ ,  $i = 0, 1, \dots, 2^k 1$

- 
$$\mathbf{e}_{i} = \mathbf{e} + \mathbf{c}_{i}$$
, for  $i = 0, 1, \dots, 2^{k} - 1$ 

- The set of vectors  $\mathbf{e}_i$  is called a **coset** of the code
- A coset has exactly  $2^k$  elements
- An (n,k) linear block code has  $2^{n-k}$  possible cosets

• 
$$2^n / 2^k = 2^{n-k}$$

Each coset of the code is characterized by a unique syndrome

$$\mathbf{e}_i \mathbf{H}^{\mathrm{T}} = \mathbf{e} \mathbf{H}^{\mathrm{T}} + \mathbf{c}_i \mathbf{H}^{\mathrm{T}} = \mathbf{e} \mathbf{H}^{\mathrm{T}} + \mathbf{0} = \mathbf{e} \mathbf{H}^{\mathrm{T}}$$

 All error patterns that differ by a codeword have the same syndrome.

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### Linear Block Codes: Syndrome (Cont.)

• With the matrix  $\mathbf{H}$ , the (n-k) elements of the syndrome  $\mathbf{s}$  are linear combinations of the n elements of the error pattern  $\mathbf{e}$ 

$$\mathbf{s} = \mathbf{r} \mathbf{H}^{\mathsf{T}} = \mathbf{r} \begin{bmatrix} \mathbf{I}_{n-k} \\ \mathbf{P} \end{bmatrix} = \mathbf{e} \begin{bmatrix} \mathbf{I}_{n-k} \\ \mathbf{P} \end{bmatrix}$$

$$s_0 = e_0 + e_{n-k} p_{0,0} + e_{n-k+1} p_{1,0} + \dots + e_{n-1} p_{k-1,0}$$

$$s_1 = e_1 + e_{n-k} p_{0,1} + e_{n-k+1} p_{1,1} + \dots + e_{n-1} p_{k-1,1}$$

$$\vdots$$

$$s_{n-k-1} = e_{n-k-1} + e_{n-k} p_{0,n-k-1} + \dots + e_{n-1} p_{k-1,n-k-1}$$
Linear combinations

- The syndrome ((n k) linear equations) contains information about the error pattern and may be used for error detection.
  - There are more unknowns than equations  $((n-k) \le n)$
  - The set of equations is underdetermined
  - There is **no unique solution** for the error pattern

#### Minimum Distance Considerations

- Consider a pair of code vectors  $\mathbf{c}_1$  and  $\mathbf{c}_2$  that have the same number of elements.
  - The **Hamming distance**,  $d(\mathbf{c}_1, \mathbf{c}_2)$ , is defined as the **number** of locations in which their respective elements differ.
  - The **Hamming weight**,  $w(\mathbf{c})$ , of a code vector  $\mathbf{c}$  is defined as the **number of nonzero elements** in the code vector.
    - The distance between **c** and the **all-zero** code vector.
- The minimum distance  $d_{\min}$  of a linear block code is the smallest Hamming distance between any pair of codewords.
  - $-d_{\min}$  is the same as the **smallest Hamming weight** of the **difference** between any pair of code vectors.
  - From the closure property,  $d_{\min}$  is the smallest Hamming weight of the nonzero code vectors in the code.

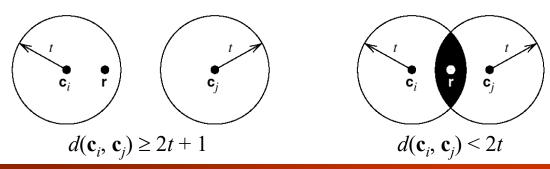
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# Minimum Distance Considerations (Cont.)

- Specifically,  $d_{\min}$  determines the **error-correcting capability** of the code.
- Suppose an (n, k) linear block code is required to detect and correct all error patterns having a Hamming weight less than or equal to t.
  - That is, if a code vector  $\mathbf{c}_i$  is transmitted and the received vector is  $\mathbf{r} = \mathbf{c}_i + \mathbf{e}$ , we require that the **decoder output**  $\hat{\mathbf{c}} = \mathbf{c}_i$ 
    - whenever the error pattern **e** has a Hamming weight  $w(\mathbf{e}) \le t$
- The **best decoding strategy** is to pick the code vector **closest** to the received vector **r** 
  - Maximum Likelihood (ML) decision rule
  - Choose the one with the smallest Hamming distance  $d(\mathbf{c}_i, \mathbf{r})$

# Minimum Distance Considerations (Cont.)

- With the ML strategy, the decoder will be able to detect and correct all error patterns of Hamming weight w(e)
  - Provided that the minimum distance of the code is equal to or greater than 2t + 1
- An (n,k) linear block code has the power to correct all error patterns of weight t or less if, and only if,
  - $-d(\mathbf{c}_i, \mathbf{c}_j)$  ≥ 2t + 1, for all  $\mathbf{c}_i$  and  $\mathbf{c}_j$



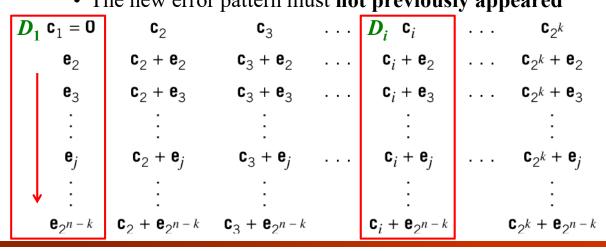
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# Syndrome Decoding

- Consider an (n, k) linear block code with the  $2^k$  code vectors  $\mathbf{c}_i$  for  $1 \le i \le 2^k$ .
- Let  $\mathbf{r}$  denote the **received vector**: one of  $2^n$  possible values
- The receiver partitions the  $2^n$  possible vectors into  $2^k$  disjoint subsets  $D_i$ 
  - The *i*-th subset  $D_i$  corresponds to code vector  $\mathbf{c}_i$  for  $1 \le i \le 2^k$
  - **r** is decoded into **c**<sub>i</sub> if it is in  $D_i$  for  $1 \le i \le 2^k$
- For the decoding to be **correct**,  $\mathbf{r}$  must be in the subset that belongs to the code vector  $\mathbf{c}_i$  that was actually sent.
- The construction of the  $2^k$  disjoint subsets is shown as follows:
  - Step 1: The  $2^k$  code vectors are placed in a row with the all-zero code vector  $\mathbf{c}_1$  as the leftmost element.

# Syndrome Decoding (Cont.)

- Step 2: An error pattern  $\mathbf{e}_2$  is picked and placed under  $\mathbf{c}_1$ , and a second row is formed by adding  $\mathbf{e}_2$  to  $\mathbf{c}_i$
- Step 3: Repeat Step 2 until all the possible error patterns have been accounted for
  - The new error pattern must not previously appeared



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# Syndrome Decoding (Cont.)

- The  $2^k$  columns represent the disjoint subsets  $D_i$
- The  $2^{n-k}$  rows represent the cosets of the code
  - Their first elements  $e_i$ ,  $j = 2, 3, \dots, 2^{n-k}$ , are **coset leaders**
- The probability of **decoding error** is **minimized** when the **most likely error patterns** are chosen as the **coset leaders**.
  - Those with the **largest** probability of occurrence
- In the case of a binary symmetric channel, the smaller the **Hamming weight** of an error pattern is, the **more likely** it is for an error to occur.
- The construction should choose the error pattern with the minimum Hamming weight in its coset as the coset leader

### Syndrome Decoding (Cont.)

- The **syndrome decoding** procedure for linear block codes:
- 1. For the received vector  $\mathbf{r}$ , compute the syndrome  $\mathbf{s} = \mathbf{r}\mathbf{H}^{\mathrm{T}}$ .
- 2. Within the coset characterized by the syndrome s, identify the coset leader.
  - The error pattern corresponding to the codeword  $\mathbf{c}_1$
  - The error pattern is denoted as  $\mathbf{e}_0$
- 3. Compute the code vector  $\mathbf{c} = \mathbf{r} + \mathbf{e}_0$  as the decoded output of the received vector  $\mathbf{r}$ .

$$\mathbf{r} \Rightarrow \mathbf{s} \Rightarrow \mathbf{e}_0 \Rightarrow \mathbf{c} = \mathbf{r} + \mathbf{e}_0$$

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# **Example: Hamming Codes**

- Hamming codes: a family of (n, k) linear block codes that have the following parameters:  $(m \ge 3)$ 
  - − Code length:  $n = 2^m 1$
  - Number of message bits:  $k = 2^m m 1$
  - Number of parity-check bits: n k = m
- Specifically for m = 3, it is the (7, 4) Hamming code with the error-correcting capability of t = 1 error
- The generator of this code is defined by

$$\mathbf{G} = \begin{bmatrix} 1 & 1 & 0 & \vdots & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & \vdots & 0 & 1 & 0 & 0 \\ 1 & 1 & 1 & \vdots & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & \vdots & 0 & 0 & 0 & 1 \end{bmatrix}$$

# Example: Hamming Codes (Cont.)

• The corresponding parity-check matrix is given by

$$\mathbf{H} = \begin{bmatrix} 1 & 0 & 0 & \vdots & 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & \vdots & 1 & 1 & 1 & 0 \\ 0 & 0 & 1 & \vdots & 0 & 1 & 1 & 1 \end{bmatrix}$$

- The columns of **P** consist of all the nonzero m-tuples for m = 3
- With k = 4, there are  $2^k = 16$  distinct message words

Message	Codeword	Weight	Message	Codeword	Weight
0000	0000000	0	1000	1101000	3
0001	1010001	3	1001	0111001	4
0010	1110010	4	1010	0011010	3
0011	0100011	3	1011	1001011	4
0100	0110100	3	1100	1011100	4
0101	1100101	4	1101	0001101	3
0110	1000110	3	1110	0101110	4
0111	0010111	4	1111	1111111	7

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### Example: Hamming Codes (Cont.)

- The smallest Hamming weight of the nonzero codewords is 3.
  - It follows that the minimum distance of the code is  $d_{\min} = 3$
  - The error-correcting capability is t = 1 error
- There are 7 error patterns, each of which contains only 1 error
- The syndrome corresponds to an error pattern:  $\mathbf{s} = \mathbf{r}\mathbf{H}^{\mathrm{T}}$ 
  - If the transmitted codeword is  $\mathbf{c}_1$ , the received vector  $\mathbf{r}$  is the corresponding error pattern of the **coset leader**

• For example: 
$$\mathbf{r} = [0010000]$$

$$\mathbf{s} = \mathbf{r}\mathbf{H}^{\mathrm{T}} = [0010000] \begin{bmatrix} 100 \\ 010 \\ 001 \\ 110 \\ 011 \\ 111 \\ 101 \end{bmatrix} = [001]$$

# Example: Hamming Codes (Cont.)

- Based on the **syndrome decoding** procedure, the **syndrome** of a received vector shows the **location** of the erroneous bit.
  - If  $s = [001] \Rightarrow$  the third bit of r is erroneous
- Thus, adding the error pattern  $e_0$  to the received vector  $\mathbf{r}$  yields the correct code vector actually sent.

$-\mathbf{c} = \mathbf{r} + \mathbf{e}_0$		
- 0	Syndrome	Error Pattern
No error —	000	0000000
	100	1000000
	010	0100000
	001	0010000
	110	0001000
	011	0000100
	111	0000010
	101	0000001

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#### Homework

- You must give detailed derivations or explanations, otherwise you get no points.
- Communication Systems, Simon Haykin (4th Ed.)
- 10.4;
- 10.5;
- 10.7;
- 10.8;