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1.

2.

2. (8%+8%+4%) In linear regression, we adopt the linear model

$$Y = X^T \beta + \epsilon,$$

where $X = (1, X_1, \dots, X_p)^T$, $\beta = (\beta_0, \beta_1, \dots, \beta_p)^T$, and $\epsilon \sim \mathcal{N}(0, \sigma^2)$. Let $\mathcal{D} = \{(x_1, y_1), \dots, (x_n, y_n)\} \left(\text{or concisely written as } \{\mathbf{X}, \mathbf{y}\}\right)$

be the set of available data points that are generated independently by the above model.

- (a) Find β that maximizes the likelihood ratio $p(\mathbf{y}|\mathbf{X},\beta)$, assuming that σ^2 is known.
- (b) Now suppose that the entries of β are i.i.d. $\mathcal{N}(0, \gamma^2)$. Find β that maximizes the posterior probability

$$p(\beta|\mathbf{y}, \mathbf{X}).$$

(c) Comment on the similarities and differences between least squares linear regression and the above schemes.

(a)

 $Y = X^T \beta + \epsilon$, 由題目知 $\epsilon \sim \mathbb{N}(0, \sigma^2)$, 那麼 Y 為 Normal Distribution 的線

性組合,所以 Y~(
$$X^T\beta$$
, σ^2), $f_Y(y|X;\beta) = (2\pi\sigma^2)^{-0.5} * \exp(\frac{-1}{2}(\frac{y-X^T\beta}{\sigma})^2)$ 。

→所以 Likelihood Function:

$$L(\beta) = \prod_{i=1}^{N} f_{Y}(y_{i}|X;\beta)$$

$$= \prod_{i=1}^{N} (2\pi\sigma^{2})^{-0.5} * \exp\left(\frac{-1}{2} \left(\frac{y_{i} - x_{i}^{T} \beta}{\sigma}\right)^{2}\right)$$

=
$$(2\pi\sigma^2)^{-N/2} * \exp\left(\frac{-1}{2\sigma^2} * \sum_{i=1}^{N} (y_i - x_i^T \beta)^2\right)$$
 , i :表示觀察的數目

→log-Likelihood:

$$\ln(L(\beta)) = \sum_{i=1}^{N} \ln(f_Y(y_i|X,\beta)) = \frac{-N}{2} \ln(2\pi) - \frac{N}{2} \ln(\sigma^2) - \frac{-1}{2\sigma^2} \sum_{i=1}^{N} (y_i - x_i^T \beta)^2$$

→ Maximum Likelihood:

對 log-Likelihood 最大化等效於對 Likelihood 做最大化。

求取全微分: $\nabla_{\beta}(\ln(L(\beta)))$

$$= \nabla_{\beta} \left(-\frac{N}{2} \ln(2\pi) - \frac{N}{2} \ln(\sigma^2) - \frac{1}{2\sigma^2} \sum_{i=1}^{N} (y_i - x_i \beta)^2 \right)$$
 左邊的圖示抓來的,他的 xi 是我的 xi.transpose!!
$$= \frac{1}{\sigma^2} \sum_{i=1}^{N} x_i^{\mathsf{T}} (y_i - x_i \beta)$$

$$= \frac{1}{\sigma^2} \left(\sum_{i=1}^{N} x_i^{\mathsf{T}} y_i - \sum_{i=1}^{N} x_i^{\mathsf{T}} x_i \beta \right)$$

→ "極值"必發生在全微分=0(梯度為零)

$$\sum_{i=1}^{N} x_{i}^{\top} y_{i} - \sum_{i=1}^{N} x_{i}^{\top} x_{i} \beta = 0 \qquad \beta = \left(\sum_{i=1}^{N} x_{i}^{\top} x_{i} \right)^{-1} \sum_{i=1}^{N} x_{i}^{\top} y_{i} = (X^{\top} X)^{-1} X^{\top} y \\ \# \mathcal{A} \beta \beta X_{i}^{\top} Y_{i} - \sum_{i=1}^{N} x_{i}^{\top} X_{i} \beta = 0$$

左邊的圖示抓來的,他的 xi 是我的 xi.transpose!!

(b)這種算法稱為 最大後驗估計(Maximum-a-Posteriori (MAP) Estimation) 我先將 $P(\beta|y;X)$ 利用貝氏定理化為以下式子

$$P(\beta|y,X) = \frac{P(y|\beta,X)P(\beta|X)}{P(y|X)}$$
 這裡感覺有點像直接先把 |X 隔開來化簡 \rightarrow 因為 X Given $\rightarrow \frac{P(y|\beta,X)P(\beta|X)}{C(nx)}$

由(a)知式子可以化簡,並且我們要求取B使的後驗機率最大

$$\rightarrow \operatorname{argmax}_{\beta} \left(\frac{\prod_{i=1}^{N} P(y_i | \beta, X) P(\beta | X)}{C} \right)$$

同樣的,我們先對 $P(\beta|y;X)$ 取 In,並由於 p(y,X)是一個常數,所以會得到以下等效的式子:

$$\rightarrow \underset{\beta}{\operatorname{argmax}} \left(\sum_{i=1}^{N} \left(\ln \left(P(y_i | \beta, X) \right) + \ln \left(p(\beta | X) \right) \right) \right),$$

where
$$p(\beta) = (2\pi\gamma^2)^{-0.5} * \exp\left(\frac{-1}{2}\left(\frac{\beta}{\gamma}\right)^2\right)$$

$$\rightarrow \underset{\beta}{\operatorname{argmax}} \left(\sum_{i=1}^{N} \left(\ln \left(P(y_i | \beta; X) \right) \right) - \ln \left((2\pi \gamma^2)^{0.5} \right) - \frac{1}{2} \left(\frac{\beta}{\gamma} \right)^2 \right) - (A)$$

這邊要注意: $P(y_i|\beta;X)$ 意味著在給定 Data X 下 y 在 β 下發生的機率, 這說 $\left(-1\left(y_i-y_i^T\beta\right)^2\right)$

明了其機率分布為
$$(2\pi\sigma^2)^{-0.5} * \exp\left(\frac{-1}{2}\left(\frac{y_i - x_i^T \beta}{\sigma}\right)^2\right)$$

對
$$\left(\sum_{i=1}^{N} \left(\ln\left(P(y_i|\beta,X)\right)\right) - \ln\left((2\pi\gamma^2)^{0.5}\right) - \frac{1}{2}\left(\frac{\beta}{\gamma}\right)^2\right)$$
做 β 的偏微分得

$$\sum_{i=1}^{N} \left(\frac{y_i - x_i^T \beta}{\sigma^2} \right) * x_i - \left(\frac{\beta}{\gamma^2} \right)$$
,則最大值出現在左式為零時。

$$\textstyle \sum_{i=1}^N \left(\frac{y_i - x_i^T \beta}{\sigma^2}\right) * x_i = \left(\frac{\beta}{\gamma^2}\right) \to \sum_{i=1}^N \left(\frac{y_i}{\sigma^2}\right) = \frac{\beta}{\gamma^2} + \frac{\beta}{\sigma^2} * \sum_{i=1}^N (x_i^T) \to \beta =$$

$$\frac{\sum_{i=1}^{N} \left(\frac{y_i}{\sigma^2} * x_i\right)}{I * \frac{1}{\gamma^2} + \frac{1}{\sigma^2} * \sum_{i=1}^{N} \left(x_i \ * x_i^T\right)} \ \# \#$$

先轉化為矩陣比較好表示

$$\frac{\partial L}{\partial \beta} = 0 \Rightarrow (-2X^{T}y + 2X^{T}X\beta) + \frac{\sigma_{2}}{\Gamma^{2}} = 0$$

$$\frac{\partial L}{\partial \beta} = (-2X^{T}y + 2X^{T}X\beta) + \frac{\sigma_{2}}{\Gamma^{2}} = 0$$

(c)

這邊我分點描述:

- 1. 最小平方估計是利用最小化 L2-Norm 求取參數 β。
- 2. 最大似然估計則是利用機率的觀點,求取一組參數 β 使 $P(D|\beta)$ 機率最大。
- 3. 當觀測值來自指數族且滿足輕度條件時,最小平方估計和最大似然估計是相 同的。
- 4. 最大似然估計(MLE)是求參數 β ,使似然函數 $P(D|\beta)$ 最大。而最大後驗機率估計(MAP)則是想求 β 使 $P(D|\beta)$ P(β)最大。求得的 β 不單單讓似然函數大, β 自己出現的先驗概率也盡可能的大。這裡有點神似之後上課應該會上到的正則化概念(懲罰),只不過一般正則化是使用加法,而這邊使用了乘法,附帶提一點:正則化是避免模型過度擬合(Overfitting)的方法。
- 5. 最大似然估計(MLE)認為參數本身的機率分布是均勻的(Uniform),即其機率會是一個常數。

ML: $\beta = \underset{\beta}{\text{ary min}} \frac{1}{\sum_{i=1}^{n} (y_i - x_i^T \beta)^2}$ MAP: $\beta = \underset{\beta}{\text{ary min}} \frac{1}{\sum_{i=1}^{n} (y_i - x_i^T \beta)^2} + \frac{\sigma^2}{r^2} \frac{1}{\sum_{i=1}^{n} \beta_i} \delta^2$ least square sol.

The prior distribution acts as a regularier in IMAP estimation

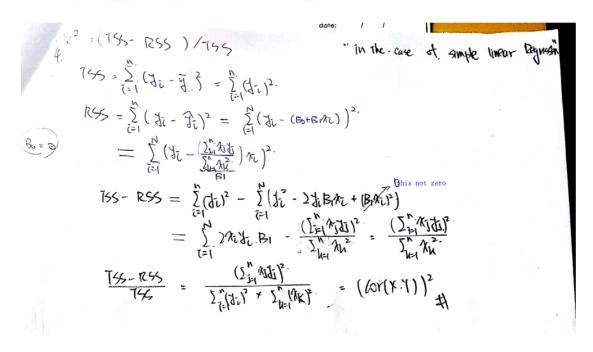
3.

- 3. (10%+10%+8%) Suppose that there were 200 coupons for each of the discount percentages 5%, 10%, 15%, 20%, and 30% (i.e., the input values x_i , for i = 1, ..., 1000), and that the number of coupons redeemed for the above cases are 31, 52, 68, 101, and 144, respectively (i.e., the number of responses in each case that yields $y_i = 1$).
 - (a) Fit a simple linear regression to the observed proportions 31/200, 52/200, 68/200, 101/200, and 144/200. List the fitted values for the above discount values. According to this regression, at what price reduction will you get a 25% redemption rate?
 - (b) Repeat (a) using logistic regression.
 - (c) Repeat (a) using linear discriminant analysis. (Hint: You will need to use the estimated normal distribution to compute Pr(Y = 1|X = x).)

4.

7. It is claimed in the text that in the case of simple linear regression of Y onto X, the R^2 statistic (3.17) is equal to the square of the correlation between X and Y (3.18). Prove that this is the case. For simplicity, you may assume that $\bar{x} = \bar{y} = 0$.





5.

4. When the number of features p is large, there tends to be a deterioration in the performance of KNN and other local approaches that perform prediction using only observations that are near the test observation for which a prediction must be made. This phenomenon is known as the curse of dimensionality, and it ties into the fact that non-parametric approaches often perform poorly when p is large. We mensionality will now investigate this curse.



curse of di-

(a) Suppose that we have a set of observations, each with measurements on p = 1 feature, X. We assume that X is uniformly (evenly) distributed on [0,1]. Associated with each observation is a response value. Suppose that we wish to predict a test observation's response using only observations that are within 10% of the range of X closest to that test observation. For instance, in order to predict the response for a test observation with X = 0.6,

4.7 Exercises

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we will use observations in the range [0.55, 0.65]. On average, what fraction of the available observations will we use to make the prediction?

- (b) Now suppose that we have a set of observations, each with measurements on p=2 features, X_1 and X_2 . We assume that (X_1, X_2) are uniformly distributed on $[0,1] \times [0,1]$. We wish to predict a test observation's response using only observations that are within 10% of the range of X_1 and within 10% of the range of X_2 closest to that test observation. For instance, in order to predict the response for a test observation with $X_1 = 0.6$ and $X_2 = 0.35$, we will use observations in the range [0.55, 0.65] for X_1 and in the range [0.3, 0.4] for X_2 . On average, what fraction of the available observations will we use to make the prediction?
- (c) Now suppose that we have a set of observations on p = 100 features. Again the observations are uniformly distributed on each feature, and again each feature ranges in value from 0 to 1. We wish to predict a test observation's response using observations within the 10% of each feature's range that is closest to that test observation. What fraction of the available observations will we use to make the prediction?
- (d) Using your answers to parts (a)-(c), argue that a drawback of KNN when p is large is that there are very few training observations "near" any given test observation.
- (e) Now suppose that we wish to make a prediction for a test observation by creating a p-dimensional hypercube centered around the test observation that contains, on average, 10% of the training observations. For p = 1, 2, and 100, what is the length of each side of the hypercube? Comment on your answer.

Note: A hypercube is a generalization of a cube to an arbitrary number of dimensions. When p = 1, a hypercube is simply a line segment, when p = 2 it is a square, and when p = 100 it is a 100-dimensional cube.

If $x \in [0.0s, 0.9s]$, the interval will be $[x-0.0s, x+0.0s] \Rightarrow 100\%$.

If x < 0.0s, the interval we use is [0, x+0.0s]. $\Rightarrow (100x+s)\%$.

If x > 0.9s, the interval we use is [x-0.0s, 1]. $\Rightarrow (10s-100x)\%$.

The average fraction is $\int_{0}^{0.0s} (100x+s) dx + \int_{0.8s}^{0.4s} 10 dx + \int_{0.4s}^{1} (10s-100x) dx = 9.7s\%$ (b) $(9.7s\%) \times (9.7s\%) = 0.95062s\%$ (c) $(9.7s\%)^{100}$ (d) $p = 1 \Rightarrow l = 0.1$ $p = 2 \Rightarrow l = (0.1)^{\frac{1}{100}}$

(e) P=1 => 0.1.
P=) => (0.1) = ≈ 0.316
P=(0.2) (11) = ≈ 0.5777
也就是就當我 特徽数越高時,在使用國家的觀察星時,我們更越需要包含有個特徽的所有範圍我