

Vector and Matrix Differentiation Rules

I) Scalar numerator

We start by considering a scalar function or scalar field that take vectors $x \in \mathbb{R}^n$ as input. Then, define

$$\frac{\partial f(x)}{\partial x} \underset{n \times 1}{=} \begin{bmatrix} \frac{\partial f(x)}{\partial x_1} \\ \vdots \\ \frac{\partial f(x)}{\partial x_n} \end{bmatrix}$$

partial derivatives along a column!

As a special case we have $f(x) = a'x$. therefore

$$\frac{\partial a'x}{\partial x} = \begin{bmatrix} \frac{\partial a'x}{\partial x_1} \\ \vdots \\ \frac{\partial a'x}{\partial x_n} \end{bmatrix} = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} = a.$$

And recall that $a'x = x'a$ because it's a scalar, so that

$$\frac{\partial x'a}{\partial x} = \begin{bmatrix} \frac{\partial x'a}{\partial x_1} \\ \vdots \\ \frac{\partial x'a}{\partial x_n} \end{bmatrix} = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} = a.$$

Similarly,

$$\frac{\partial f(x)}{\partial x'} \underset{l \times n}{=} \begin{bmatrix} \frac{\partial f(x)}{\partial x_1} & \dots & \frac{\partial f(x)}{\partial x_n} \end{bmatrix}$$

partial derivatives along a row!

$$= \left[\frac{\partial f(x)}{\partial x} \right]'$$

RULE 1:

$$\frac{\partial f(x)}{\partial x'} \underset{l \times k}{=} \left[\frac{\partial f(x)}{\partial x_k} \right]'$$

II) Vector numerator

Let A be a $m \times n$ matrix,

$$A = \begin{pmatrix} a_1' \\ \vdots \\ a_m' \end{pmatrix}_{m \times n} \quad \text{where } a_j \in \mathbb{R}^n \text{ for } j=1, \dots, m.$$

$$\frac{\partial A x}{\partial x'}_{m \times 1} = \begin{pmatrix} \frac{\partial a_1' x}{\partial x'}_{1 \times 1} \\ \vdots \\ \frac{\partial a_m' x}{\partial x'}_{1 \times 1} \end{pmatrix} = \begin{pmatrix} a_1' \\ \vdots \\ a_m' \end{pmatrix} = A_{m \times n}$$

we know how
to compute
each one of these

$$\begin{aligned} \frac{\partial x' A'}{\partial x}_{n \times 1} &= \left(\frac{\partial x' a_1}{\partial x} \cdots \frac{\partial x' a_m}{\partial x} \right) \\ &= (a_1 \cdots a_m)' = A'_{n \times n}. \end{aligned}$$

III) Chain Rules on I and II

Multivariate chain rule: let $f(x)$ and $x(\alpha)$, $\alpha \in \mathbb{R}$

$$\begin{aligned} \frac{\partial f(x)}{\partial \alpha}_{1 \times 1} &= \frac{\partial f(x)}{\partial x_1} \frac{\partial x_1}{\partial \alpha} + \cdots + \frac{\partial f(x_n)}{\partial x_n} \frac{\partial x_n}{\partial \alpha} \\ &= \sum_{i=1}^n \frac{\partial f}{\partial x_i}_{1 \times 1} \frac{\partial x_i}{\partial \alpha}_{1 \times 1} = \left(\frac{\partial f}{\partial x}_{m \times 1} \right)' \frac{\partial x}{n \times 1} \frac{\partial \alpha}{1 \times 1} \end{aligned}$$

(Re writer)

let $\alpha \in \mathbb{R}^r$ and $x = x(\alpha)$. Then

$$\frac{\partial x}{\partial \alpha'}_{n \times r} = \begin{pmatrix} \frac{\partial x_1}{\partial \alpha'}_{1 \times r} \\ \vdots \\ \frac{\partial x_n}{\partial \alpha'}_{1 \times r} \end{pmatrix}_{n \times r} = \begin{pmatrix} \frac{\partial x}{\partial \alpha_1}_{n \times 1} & \cdots & \frac{\partial x}{\partial \alpha_r}_{n \times 1} \end{pmatrix}_{n \times r}$$

$$\frac{\partial f(x)}{\partial \alpha_{r \times 1}} = \left(\begin{array}{c} \frac{\partial f(x)}{\partial \alpha_1} \\ \vdots \\ \frac{\partial f(x)}{\partial \alpha_r} \end{array} \right)$$

=

$$\left(\begin{array}{c} \sum_{i=1}^n \frac{\partial f}{\partial x_i} \frac{\partial x_i}{\partial \alpha_1} \\ \vdots \\ \sum_{i=1}^n \frac{\partial f}{\partial x_i} \frac{\partial x_i}{\partial \alpha_r} \end{array} \right)$$

Use Multivariate chain rule

Recall

$$\begin{bmatrix} a_1' \\ \vdots \\ a_n' \end{bmatrix} [b_1 \dots b_K] = \begin{bmatrix} a_1' b_1 & \dots & a_1' b_K \\ \vdots & & \vdots \\ a_n' b_1 & \dots & a_n' b_K \end{bmatrix}$$

$$= \left(\begin{array}{c} \left(\frac{\partial f}{\partial x} \right)' \frac{\partial x}{\partial \alpha_1} \\ \vdots \\ \left(\frac{\partial f}{\partial x} \right)' \frac{\partial x}{\partial \alpha_r} \end{array} \right)$$

we can transpose scalars!

$$= \left(\begin{array}{c} \frac{\partial x'_{r \times n}}{\partial \alpha_1} \frac{\partial f}{\partial x_{r \times 1}} \\ \vdots \\ \frac{\partial x'_{r \times n}}{\partial \alpha_r} \frac{\partial f}{\partial x_{r \times 1}} \end{array} \right) = \left(\begin{array}{c} \frac{\partial x'_{r \times n}}{\partial \alpha_1} \\ \vdots \\ \frac{\partial x'_{r \times n}}{\partial \alpha_r} \end{array} \right) \frac{\partial f}{\partial x_{r \times 1}}$$

$$= \underbrace{\frac{\partial x'_{r \times n}}{\partial \alpha_{r \times 1}}}_{r \times n} \underbrace{\frac{\partial f}{\partial x_{r \times 1}}}_{r \times 1}.$$

Rule 2

$$\frac{\partial f(x)}{\partial \alpha_{r \times 1}} = \frac{\partial x'}{\partial \alpha} \underbrace{\frac{\partial f}{\partial x}}_{r \times 1}$$

Def. - let $A = \begin{pmatrix} a_1 & \dots & a_K \end{pmatrix}_{n \times K}$. Then

$$\text{vec}(A) := \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_K \end{pmatrix}.$$

Notice that

$$\begin{pmatrix} \frac{\partial x}{\partial \alpha_1} \\ \vdots \\ \frac{\partial x}{\partial \alpha_r} \end{pmatrix}_{n \times 1} = \text{vec} \left(\begin{bmatrix} \frac{\partial x}{\partial \alpha_1} & \dots & \frac{\partial x}{\partial \alpha_r} \end{bmatrix} \right) = \text{vec} \left(\frac{\partial x}{\partial \alpha'} \right)$$

Hence

$$\begin{pmatrix} \left(\frac{\partial f}{\partial x} \right)' & \frac{\partial x}{\partial \alpha_1} \\ \vdots & \\ \left(\frac{\partial f}{\partial x} \right)' & \frac{\partial x}{\partial \alpha_r} \end{pmatrix} = \begin{pmatrix} \frac{\partial f}{\partial x_1} & \dots & 0_{1 \times n} \\ 0_{n \times n} & \dots & \frac{\partial f}{\partial x'}_{1 \times n} \end{pmatrix} \text{vec} \left(\frac{\partial x}{\partial \alpha'} \right)_{n \times 1}$$

$$= \underbrace{\left(I_r \otimes \frac{\partial f}{\partial x'} \right)_{r \times n}}_{r \times r n} \text{vec} \left(\frac{\partial x}{\partial \alpha'} \right)_{n \times 1}$$

Rule 3
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$$M v_{r \times n} = (I_r \otimes v') \text{vec}(M')$$

Why is this useful?

- $\frac{\partial}{\partial \alpha'} \left(\underbrace{\frac{\partial x}{\partial \alpha'}}_{n \times 1} \right)$ is not well-defined.

- $\frac{\partial}{\partial \alpha'} \underbrace{\text{vec} \left(\frac{\partial x}{\partial \alpha'} \right)}_{n \times 1}$ is well-defined.

This allows us to generalize to the derivative of a vector

$$\begin{aligned} \bullet \frac{\partial}{\partial \alpha'} \underbrace{Ax}_{n \times 1} &= \begin{pmatrix} \frac{\partial (a_1' x)}{\partial \alpha'} \\ \vdots \\ \frac{\partial (a_m' x)}{\partial \alpha'} \end{pmatrix} = \begin{pmatrix} a_1' \frac{\partial x}{\partial \alpha'} \\ \vdots \\ a_m' \frac{\partial x}{\partial \alpha'} \end{pmatrix} \\ &\stackrel{\text{we Transposed}}{=} \begin{pmatrix} a_1' \\ \vdots \\ a_m' \end{pmatrix} \frac{\partial x}{\partial \alpha'} = A \frac{\partial x}{\partial \alpha'} \end{aligned}$$

$$\begin{aligned} \bullet \frac{\partial}{\partial \alpha} \underbrace{x' A'}_{r \times n} &= \begin{pmatrix} \frac{\partial x' a_1}{\partial \alpha} & \dots & \frac{\partial x' a_m}{\partial \alpha} \end{pmatrix} \\ &= \left(\frac{\partial x'}{\partial \alpha} a_1, \dots, \frac{\partial x'}{\partial \alpha} a_m \right) \\ &= \frac{\partial x'}{\partial \alpha} (a_1 \dots a_m) = \frac{\partial x'}{\partial \alpha} A' \end{aligned}$$

Notice that

$$\frac{\partial x}{\partial \alpha'} = \begin{pmatrix} \frac{\partial x_1}{\partial \alpha'} \\ \vdots \\ \frac{\partial x_n}{\partial \alpha'} \end{pmatrix} = \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & & & \\ 0 & 0 & \dots & 1 \end{pmatrix} = I.$$

Rule 4 : $\frac{\partial Ax}{\partial \alpha} \underset{m \times 1}{\underset{x \times 1}{=}} = A \frac{\partial x}{\partial \alpha}$

IV) Chain Rule on Quadratic Forms

Let $x \in \mathbb{R}^n$, $z \in \mathbb{R}^m$ and A is $m \times n$. Also let $x := x(\alpha)$, $z := z(\alpha)$. Then

$$\begin{aligned} \frac{\partial (z' Ax)}{\partial \alpha} \underset{m \times 1}{=} & \frac{\partial}{\partial \alpha} (z' \underbrace{Ax}_{\text{fixed } c}) + \frac{\partial}{\partial \alpha} (z' \underbrace{Ax}_{\text{fixed } d}) \\ \stackrel{\text{Rule 2}}{=} & \frac{\partial z'}{\partial \alpha} \frac{\partial z' c}{\partial z} + \frac{\partial z'}{\partial \alpha} \frac{\partial d' x}{\partial x} \\ = & \frac{\partial z'}{\partial \alpha} Ax + \frac{\partial x'}{\partial \alpha} A' z. \end{aligned}$$

As a special case we have

$$\begin{aligned} \frac{\partial x' Ax}{\partial x} &= \frac{\partial x' \underbrace{Ax}_{c}}{\partial x} + \frac{\partial x' \underbrace{Ax}_{d}}{\partial x} \\ &= \underbrace{Ax}_{c} + \underbrace{A' x}_{d} = (A + A')x \\ &= 2Ax \text{ iff } A \text{ is symmetric.} \end{aligned}$$

Rule 5 : $\frac{\partial z' Ax}{\partial \alpha} = \frac{\partial z'}{\partial \alpha} A' z + \frac{\partial z'}{\partial \alpha} Ax$

V) Second Derivative

$$\frac{\partial}{\partial \alpha} \left[\underbrace{z' A \frac{\partial x}{\partial \alpha}}_{K \times 1} \right] = \frac{\partial}{\partial \alpha} \left[z' \underbrace{A \frac{\partial x}{\partial \alpha'}}_{\text{fixed}} \right] + \frac{\partial}{\partial \alpha} \left[z' A \underbrace{\frac{\partial x}{\partial \alpha'}}_{\text{fixed}} \right]$$

$$= \frac{\partial z'}{\partial \alpha} \left[A \frac{\partial x}{\partial \alpha} \dots A \frac{\partial x}{\partial \alpha} \right] + \frac{\partial}{\partial \alpha} \left[z' A \frac{\partial x}{\partial \alpha'} \right]$$

from Rule 5

$$= \underbrace{\frac{\partial z'}{\partial \alpha}}_{K \times 1} \underbrace{A}_{L \times L} \underbrace{\frac{\partial x}{\partial \alpha'}}_{L \times K} + \frac{\partial}{\partial \alpha} \left[\underbrace{z' A}_{r'} \underbrace{\frac{\partial x}{\partial \alpha'}}_{M'} \right]$$

$$= \underbrace{\frac{\partial z'}{\partial \alpha}}_{K \times 1} A \frac{\partial x}{\partial \alpha'} + \frac{\partial}{\partial \alpha} \left\{ \text{vec} \left(\frac{\partial x}{\partial \alpha'} \right)' \underbrace{(J_K \otimes A' z)}_{K \times K} \right\}$$

from Rule 3

$$= \frac{\partial z'}{\partial \alpha} A \frac{\partial x}{\partial \alpha'} + \frac{\partial}{\partial \alpha} \left\{ \text{vec} \left(\frac{\partial x}{\partial \alpha'} \right)' \right\} (J_K \otimes A' z)$$

Rule 6 : $\frac{\partial}{\partial \alpha} \left[z' A \frac{\partial x}{\partial \alpha'} \right] = \frac{\partial z'}{\partial \alpha} A \frac{\partial x}{\partial \alpha'} + \frac{\partial}{\partial \alpha} \left\{ \text{vec} \left(\frac{\partial x}{\partial \alpha'} \right)' \right\} (J_K \otimes A' z)$

EXAMPLE 2: Linear GMM

Let X be $n \times k$, Z be $n \times l$, $\theta \in \mathbb{R}^k$, $y \in \mathbb{R}^n$, and W be $l \times l$ and symmetric.
The sample criterion function is

$$Q_n(\theta) = \frac{1}{2} [Z'(y - X\theta)]' W [Z'(y - X\theta)] := a' W a$$

$$\cdot \frac{\partial Q_n(\theta)}{\partial \theta} = \frac{1}{2} \frac{\partial a'}{\partial \theta} W a + \frac{1}{2} \frac{\partial a'}{\partial \theta} W' a$$

$$= \frac{\partial a'}{\partial \theta} W a$$

$$= \frac{\partial}{\partial \theta} \left[y' Z - \theta' \underset{n \times n \times l}{X' Z} \right] W \left[Z'(y - X\theta) \right]$$

④ $c_1 \dots c_l$
are the
columns of
 $X' Z$

$$= \frac{\partial}{\partial \theta} \left[\theta' c_1 \dots \theta' c_l \right] W \left[Z'(y - X\theta) \right]$$

$$= [c_1 \dots c_l] W [Z'(y - X\theta)]$$

$$= X' Z W Z'(y - X\theta)$$

$$\cdot \frac{\partial^2 Q_n(\theta)}{\partial \theta \partial \theta'} = \frac{\partial}{\partial \theta} \left[a' W \frac{\partial a}{\partial \theta'} \right]$$

\hookrightarrow doesn't depend on θ anymore!

$$= \frac{\partial}{\partial \theta} \left[(y - X\theta)' I W Z' X \right]$$

$$= \frac{\partial}{\partial \theta} \left[\theta' X' Z W Z' X \right]$$

$$= \frac{\partial}{\partial \theta} \begin{bmatrix} \theta' c_1 & \dots & \theta' c_K \end{bmatrix}$$

$$= X' Z W Z' X.$$

In summation notation it's not that different.

$$\hat{Q}_n(\theta) = \frac{1}{2} \left[\frac{1}{n} \sum_{i=1}^n (y_i - x_i' \theta) z_i' \right] W \left[\frac{1}{n} \sum_{i=1}^n z_i (y_i - x_i' \theta) \right]$$

$$\cdot \frac{\partial \hat{Q}_n(\theta)}{\partial \theta} = \frac{\partial a'}{\partial \theta} W a$$

$$= \frac{1}{n} \sum_{i=1}^n \frac{\partial}{\partial \theta} \left[\theta' x_i z_i' \right] W \left[\frac{1}{n} \sum_{i=1}^n z_i (y_i - x_i' \theta) \right]$$

$$= \frac{1}{n} \sum_{i=1}^n x_i z_i' W \left[\frac{1}{n} \sum_{i=1}^n z_i (y_i - x_i' \theta) \right]$$

$$\cdot \frac{\partial^2 \hat{Q}_n(\theta)}{\partial \theta \partial \theta'} = \frac{\partial}{\partial \theta} \left\{ \left[\frac{1}{n} \sum_{i=1}^n (y_i - x_i' \theta) z_i' \right] W \left[\frac{1}{n} \sum_{i=1}^n x_i z_i' \right] \right\}$$

$$= \frac{1}{n} \sum_{i=1}^n x_i z_i' W \frac{1}{n} \sum_{i=1}^n x_i z_i'$$

Notice the connection with the asymptotic linear representation of $\hat{\theta}_n$:

$$\sqrt{n} (\hat{\theta}_n - \theta) = \left(\left[\frac{1}{n} \sum_{i=1}^n x_i z_i' \right] W \left[\frac{1}{n} \sum_{i=1}^n x_i z_i' \right] \right)^{-1} \left[\frac{1}{n} \sum_{i=1}^n x_i z_i' \right] W \frac{1}{\sqrt{n}} \sum_{i=1}^n z_i u_i + o_p(n)$$

Hessian gradient

EXAMPLE 2: Non-linear GMM

Consider the criterion function $Q_n(\theta) = \frac{1}{2} \left[\frac{1}{n} \sum_{i=1}^n g(w_i, \theta)' \right] A'A \left[\frac{1}{n} \sum_{i=1}^n g(w_i, \theta) \right]$

where w_i is the data (y_i, x_i', z_i') .

$$\bullet \quad \frac{\partial Q_n(\theta)}{\partial \theta} = \left[\frac{1}{n} \sum_{i=1}^n \frac{\partial g(w_i, \theta)'}{\partial \theta} \right] A'A \left[\frac{1}{n} \sum_{i=1}^n g(w_i, \theta) \right]$$

$$\bullet \quad \frac{\partial Q_n(\theta)}{\partial \theta \partial \theta'} = \frac{\partial}{\partial \theta} \left\{ \left[\frac{1}{n} \sum_{i=1}^n g(w_i, \theta)' \right] A'A \left[\frac{1}{n} \sum_{i=1}^n \frac{\partial g(w_i, \theta)}{\partial \theta'} \right] \right\}$$

$$= \left[\frac{1}{n} \sum_{i=1}^n \frac{\partial g(w_i, \theta)'}{\partial \theta} \right] A'A \left[\frac{1}{n} \sum_{i=1}^n \frac{\partial g(w_i, \theta)}{\partial \theta'} \right] +$$

RULE

$$\begin{aligned} 6 \quad & \frac{\partial}{\partial \theta} \left[\frac{1}{n} \sum_{i=1}^n \text{vec} \left(\frac{\partial g(w_i, \theta)}{\partial \theta'} \right)' \right] \left[I_K \otimes A'A \frac{1}{n} \sum_{i=1}^n g(w_i, \theta) \right] \\ &= \left[\frac{1}{n} \sum_{i=1}^n \frac{\partial g(w_i, \theta)'}{\partial \theta} \right] A'A \left[\frac{1}{n} \sum_{i=1}^n \frac{\partial g(w_i, \theta)}{\partial \theta'} \right] + \\ & \quad \left[\frac{1}{n} \sum_{i=1}^n \frac{\partial}{\partial \theta} \text{vec} \left(\frac{\partial g(w_i, \theta)'}{\partial \theta} \right)' \right] \left[I_K \otimes A'A \frac{1}{n} \sum_{i=1}^n g(w_i, \theta) \right] \end{aligned}$$

If correctly specified, this term is 0.

linear models are robust to misspecification in terms of asymptotic variance.