

Math 462: Homework 7 solutions

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1. Consider the motion T of \mathbb{R}^3 defined by $T(\mathbf{x}) = -\mathbf{x}$.

- (a) Is T a direct or opposite motion?
- (b) We classified motions of \mathbb{R}^3 into 6 types: rotations, reflections, rotary reflections, translations, glides, and twists. What type of motion is T ? Give a precise geometric description in these terms (include angle of rotation and/or plane of reflection etc.).
- (c) Now let P be a regular polyhedron in \mathbb{R}^3 with center at the origin (so P is either a tetrahedron, cube, octahedron, dodecahedron, or icosahedron). In which cases is T a symmetry of P ?

(a) $T(\mathbf{x}) = A\mathbf{x}$ where

$$A = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix}.$$

We have $\det A = (-1)^3 = -1$, so T is an opposite motion.

- (b) T is a rotary reflection. More precisely, let L be any line through the origin, and Π the plane through the origin which is normal to L . Then T is given by rotation about the axis L through an angle π followed by reflection in the plane Π . (Note: in this case, the choice of the line L is irrelevant. This is not true in general for rotary reflections, it only happens when the angle of rotation equals π .)
- (c) T is a symmetry for all cases except the tetrahedron.

2. Recall that the *dihedral group* D_n is the group of symmetries of a regular n -sided polygon P . We showed in class that D_n consists of n rotations

(including the identity transformation) and n reflections. Moreover, if a denotes a rotation about the center of P through angle $2\pi/n$ anticlockwise and b denotes reflection in a line of symmetry of P , then D_n is generated by a and b (more precisely, the rotations are $1, a, \dots, a^{n-1}$ and the reflections are $b, ab, \dots, a^{n-1}b$). The symmetries a and b satisfy the relations $a^n = b^2 = 1$ and $ba = a^{-1}b$ (and all other relations can be derived from these). Express the following products in D_5 in the form $a^i b^j$ where $0 \leq i \leq 5$ and $0 \leq j \leq 1$ and describe them geometrically.

- (a) $a^3 bab$.
- (b) $a^2 ba^3 b^2 a$
- (c) $a^2 ba^{-1} b^{-1} a^3 b^3$.

First observe that the relation $ba = a^{-1}b$ implies that $a^k b = a^{-k} b$ for any integer k .

- (a) $a^3 bab = a^3(ba)b = a^3(a^{-1}b)b = a^2 b^2 = a^2$. Rotation about the origin through angle $4\pi/5$ anticlockwise.
- (b) $a^2 ba^3 b^2 a = a^2 ba^3 a = a^2(ba^4) = a^2 a^{-4} b = a^{-2} b = a^3 b$. Reflection in line through the origin making an angle of $3\pi/5$ with the line of reflection for b .
- (c) $a^2 ba^{-1} b^{-1} a^3 b^3 = a^2(ba^4)ba^3 b = a^2(a^{-4}b)ba^3 b = a^{-2} b^2 a^3 b = a^{-2} a^3 b = ab$. Reflection in line through the origin making an angle of $\pi/5$ with the line of reflection for b .

3. In this problem we see that the dihedral group D_n can be realized as a subgroup of the group of *rotations* of \mathbb{R}^3 . Let P be a regular n -sided polygon. Position P in the plane ($z = 0$) $\subset \mathbb{R}^3$ with center O at the origin and one vertex Q on the x -axis.

- (a) What is the matrix A of the rotation S of \mathbb{R}^3 about the z -axis through angle $2\pi/n$ anticlockwise? What is the symmetry of P induced by S ?
- (b) Describe a rotation T of \mathbb{R}^3 which maps P to itself and when regarded as a symmetry of P is given by reflection in the line OQ . What is the matrix B of T ?
- (c) Use parts (a) and (b) to describe the dihedral group D_n (the group of symmetries of P) in terms of rotations of \mathbb{R}^3 . What are the matrices of these rotations?

(a)

$$A = \begin{pmatrix} \cos(2\pi/n) & -\sin(2\pi/n) & 0 \\ \sin(2\pi/n) & \cos(2\pi/n) & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Rotation about the center of P through angle $2\pi/n$ anticlockwise.

(b) Rotation about the line OQ (the x -axis) through an angle of π .

$$B = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

(c) The dihedral group can be realized as the following rotations of \mathbb{R}^3 : the rotations about the z -axis through angles $\pi k/n$ anticlockwise, for $k = 0, 1, \dots, n$, and the rotations through angle π about the lines in the xy -plane making angle $\pi k/n$ with the x -axis, for $k = 0, 1, \dots, n-1$. The matrices are

$$\begin{pmatrix} \cos(2\pi k/n) & -\sin(2\pi k/n) & 0 \\ \sin(2\pi k/n) & \cos(2\pi k/n) & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

and

$$\begin{pmatrix} \cos(2\pi k/n) & \sin(2\pi k/n) & 0 \\ \sin(2\pi k/n) & -\cos(2\pi k/n) & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

4. Recall that a *permutation* of $1, 2, \dots, n$ is a function $f: \{1, 2, \dots, n\} \rightarrow \{1, 2, \dots, n\}$ such that $f(i) \neq f(j)$ for $i \neq j$. The *symmetric group* S_n is the group of all permutations with the group law being composition of functions. A *transposition* is a permutation f that switches two elements i and j and leaves the remaining elements fixed, that is, $f(i) = j$, $f(j) = i$, and $f(k) = k$ for $k \neq i, j$. A permutation f is a *cycle of length* l if there are distinct numbers i_1, \dots, i_l such that $f(i_1) = i_2$, $f(i_2) = i_3$, \dots , $f(i_{l-1}) = i_l$, $f(i_l) = i_1$, and $f(k) = k$ for $k \neq i_1, \dots, i_l$ (for example, a transposition is a cycle of length 2). We say two cycles f, g are *disjoint* if for each k either $f(k) = k$ or $g(k) = k$. In class we explained that every permutation can be written as a product of transpositions. We also explained how to write a permutation as a composition of disjoint cycles.

- (a) Show that order of S_n (the number of permutations of $1, 2, \dots, n$) equals $n! = n \cdot (n-1) \cdots 2 \cdot 1$.
- (b) Write each of the following permutations as a product of disjoint cycles.
- (i) $f: \{1, \dots, 5\} \rightarrow \{1, \dots, 5\}$, $f(1) = 3$, $f(2) = 4$, $f(3) = 5$, $f(4) = 1$, $f(5) = 2$.
 - (ii) $g: \{1, \dots, 7\} \rightarrow \{1, \dots, 7\}$, $g(1) = 7$, $g(2) = 6$, $g(3) = 1$, $g(4) = 2$, $g(5) = 3$, $g(6) = 4$, $g(7) = 5$.
 - (iii) $h: \{1, \dots, 8\} \rightarrow \{1, \dots, 8\}$, $h(1) = 6$, $h(2) = 2$, $h(3) = 5$, $h(4) = 7$, $h(5) = 8$, $h(6) = 1$, $h(7) = 3$, $h(8) = 4$.
- (c) Using part (b) or otherwise, write each of the permutations f, g, h as a composition of transpositions.
- (d) The cycle type of a permutation f is the (unordered) list of the lengths of the cycles in the description of f as a composition of disjoint cycles. For example $f = (123)(45)(67)$ has cycle type $2, 2, 3$. List the possible cycle types for S_4 and S_5 . How can we determine the order of a permutation from its cycle type? (The *order* of a permutation is the least number $r \geq 1$ such that applying the permutation r times gives the identity permutation.)
- (e) We say that a permutation is *even* if it can be written as a product of an even number of transpositions. The set of even permutations is a subgroup of S_n called the *alternating group* A_n . What are the possible cycle types for elements of A_4 and A_5 ? What are their orders?
- (a) Consider choosing the values $f(1), f(2), \dots$ of a permutation f in turn. There are n choices for $f(1)$, then $n-1$ choices for $f(2)$ (remember that we require that $f(2) \neq f(1)$), then $n-2$ choices for $f(3)$, and so on. This shows that the number of permutations of $\{1, 2, \dots, n\}$ equals $n \cdot (n-1) \cdot (n-2) \cdots 2 \cdot 1 = n!$
- (b)
- (i) (13524)
 - (ii) (1753)(264)
 - (iii) (16)(35847)
- (c)
- (i) $(13524) = (13)(35)(52)(24)$.
 - (ii) $(1753)(264) = (17)(75)(53)(26)(64)$.

(iii) $(16)(35847)=(16)(35)(58)(84)(47)$.

- (d) The cycle types for S_4 are the identity, (2), (3), (4) and (2,2). For S_5 they are the identity, (2), (3), (4), (5), (2,2), and (2,3). (Note: we do not list the cycles of length 1 to make the notation more concise.) The order of a permutation with cycle type (l_1, \dots, l_r) equals $\text{lcm}(l_1, \dots, l_r)$, the least common multiple of the lengths l_1, \dots, l_r of the cycles (that is, the smallest positive integer m such that each of l_1, \dots, l_r divides m).
- (e) Recall that a cycle of length l is a composition of l transpositions: $(123 \dots l) = (12)(23) \dots (l-1, l)$ where the composition is read from right to left (this is the usual notation for composition of functions, but beware that some texts use the opposite convention for permutations). So a permutation of cycle type (l_1, \dots, l_r) is a composition of $\sum_{i=1}^r (l_i - 1)$ transpositions. Using this and part (d) we see that the cycle types for A_4 are the identity, (3), and (2,2) (of orders 1, 3, and 2), and the cycle types for A_5 are the identity, (3), (5), and (2,2) (of orders 1, 3, 5 and 2).

5. In HW6 we showed that the group of symmetries of the tetrahedron can be identified with the symmetric group S_4 of permutations of 4 objects by considering the permutations of the vertices of the tetrahedron induced by its symmetries. For each cycle type of S_4 describe the corresponding symmetries geometrically. What is the geometric significance of the subgroup $A_4 \subset S_4$?

Cycle type (2) corresponds to reflection in a plane. Cycle type (3) corresponds to a rotation about an axis joining a vertex to the center of the opposite face through an angle of $\pm 2\pi/3$. Cycle type (2,2) corresponds to a rotation about an axis joining the midpoints of two opposite sides through angle π . Cycle type (4) corresponds to a rotary reflection with axis of rotation the line joining the midpoints of two opposite sides and rotation angle $\pm \pi/2$. The subgroup $A_4 \subset S_4$ corresponds to the subgroup of rotational symmetries.