## Math 462 Homework 3

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(1) Let 
$$A = \begin{pmatrix} 0 & 0 & -1 \\ 0 & -1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$
.

- (a) Show that A is an orthogonal matrix.
- (b) Compute the eigenvalues of A.
- (c) Let  $T(\mathbf{x}) = A\mathbf{x}$  be the isometry of  $\mathbb{R}^3$  defined by A. Describe T geometrically as a reflection, rotation, or rotary reflection, specifying the plane and/or rotation angle and axis.

[Hint: For part (c), a reflection plane or rotation axis is determined by an eigenvector with eigenvalue  $\lambda = \pm 1$ . A rotation angle is determined by the complex eigenvalues.]

- (2) Repeat Q1 for the matrix  $A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & -1 \\ 1 & 0 & 0 \end{pmatrix}$ .
- (3) Let  $r_L : \mathbb{R}^2 \to \mathbb{R}^2$  and  $r_M : \mathbb{R}^2 \to \mathbb{R}^2$  be the isometries given by reflection in lines L and M in  $\mathbb{R}^2$ . Suppose L and M meet in a point P such that the angle from L to M is  $\alpha$  (measured counterclockwise). Show that the composition  $r_M \circ r_L$  is the rotation about P through angle  $2\alpha$  counterclockwise.

[Hint: One way to do this is to choose coordinates so that the point P is the origin and the line L is the x-axis. Now compute using matrices: writing  $r_L(\mathbf{x}) = A\mathbf{x}$  and  $r_M(\mathbf{x}) = B\mathbf{x}$ , we have  $r_M \circ r_L(\mathbf{x}) = BA\mathbf{x}$ .]

(4) Let A be a  $3 \times 3$  orthogonal matrix and

$$T: \mathbb{R}^3 \to \mathbb{R}^3, \quad T(\mathbf{x}) = A\mathbf{x}$$

the corresponding isometry. Show that the determinant  $\det A = +1$  if T is the identity or a rotation and  $\det A = -1$  if T is a reflection or rotary reflection.

[Hint: If  $B = P^{-1}AP$  then  $\det B = \det A$  (why?). Now refer to the structure theorem for orthogonal matrices.]

(5) Let L and M be two lines passing through the origin in  $\mathbb{R}^3$ . Let S be the isometry given by rotation about L through an angle  $\theta$  and T the isometry given by rotation about M through an angle  $\phi$ . Show that the composite isometry  $T \circ S$  is either the identity or a rotation about some line N passing through the origin. When is  $T \circ S$  the identity?

[Hint: Use Q4.]

(6) This question explains some of the linear algebra that is needed to prove the structure theorem for orthogonal matrices. For  $\mathbf{z}, \mathbf{w} \in \mathbb{C}^n$  complex vectors, we define the dot product

$$\mathbf{z} \cdot \mathbf{w} = \sum_{i=1}^{n} \bar{z}_i w_i.$$

[Here for  $z=x+iy\in\mathbb{C}$  we write  $\bar{z}=x-iy$  for the complex conjugate of z.]

- (a) Show that  $\mathbf{z} \cdot \mathbf{z} = \|\mathbf{z}\|^2$  for all  $\mathbf{z} \in \mathbb{C}^n$ , where  $\|\mathbf{z}\| := \sqrt{\sum_{i=1}^n |z_i|^2}$  is the length of  $\mathbf{z}$ . [This is the reason we use the complex conjugate in the definition of the dot product for complex vectors.]
- (b) Show that  $(\lambda \mathbf{z}) \cdot \mathbf{w} = \bar{\lambda}(\mathbf{z} \cdot \mathbf{w})$  and  $\mathbf{z} \cdot (\lambda \mathbf{w}) = \lambda(\mathbf{z} \cdot \mathbf{w})$  for all  $\mathbf{z}, \mathbf{w} \in \mathbb{C}^n$  and  $\lambda \in \mathbb{C}$ .
- (c) Now let A be an  $n \times n$  orthogonal matrix. Show that  $(A\mathbf{z}) \cdot (A\mathbf{w}) = \mathbf{z} \cdot \mathbf{w}$  for all  $\mathbf{z}, \mathbf{w} \in \mathbb{C}^n$ .
- (d) Let  $\mathbf{v} \in \mathbb{C}^n$  be an eigenvector of A with eigenvalue  $\lambda \in \mathbb{C}$ . Show that  $|\lambda| = 1$ . [So  $\lambda = e^{i\theta} = \cos \theta + i \sin \theta$  for some  $\theta$ , and if  $\lambda \in \mathbb{R}$  then  $\lambda = \pm 1$ .]

- (e) Let  $\mathbf{v}, \mathbf{w} \in \mathbb{C}^n$  be eigenvectors of A with eigenvalues  $\lambda, \mu$  such that  $\lambda \neq \mu$ . Show that  $\mathbf{v} \cdot \mathbf{w} = 0$ .
- (f) Finally, let  $\mathbf{v} \in \mathbb{C}^n$  be an eigenvector with eigenvalue  $\lambda \in \mathbb{C}$ , and write  $\mathbf{v} = \mathbf{a} + i\mathbf{b}$  where  $\mathbf{a}, \mathbf{b} \in \mathbb{R}^n$ . Then the conjugate vector  $\bar{\mathbf{v}} = \mathbf{a} i\mathbf{b}$  is an eigenvector with eigenvalue  $\bar{\lambda}$  (why?). So, assuming  $\lambda \notin \mathbb{R}$ , we have  $\bar{\mathbf{v}} \cdot \mathbf{v} = 0$  by part (e). Deduce that  $\|\mathbf{a}\| = \|\mathbf{b}\|$  and  $\mathbf{a} \cdot \mathbf{b} = 0$ .

[Remark: The real eigenvectors and the real and imaginary parts  $\mathbf{a}$  and  $\mathbf{b}$  of the pairs of complex conjugate eigenvectors (scaled so that  $\|\mathbf{a}\| = \|\mathbf{b}\| = 1$ ) can be used to form an orthogonal basis of  $\mathbb{R}^n$ . If P is the associated change of basis matrix (with columns given by the vectors of the basis) then P is orthogonal and the matrix  $B = P^{-1}AP = P^TAP$  has the form described in the structure theorem.]