Linear Transformation Matrices

Two Examples:

(1) Let $T: P_2(\mathbb{R}) \to M_{2\times 2}(\mathbb{R})$ be defined by

$$T(at^{2} + bt + c) = (a + 2b - c) \begin{bmatrix} 1 & 1 \\ 2 & 3 \end{bmatrix} + (2a - b) \begin{bmatrix} 1 & 0 \\ 2 & 5 \end{bmatrix} + (5b - 2c) \begin{bmatrix} 1 & 3 \\ 2 & -1 \end{bmatrix}$$

Define the following bases:

$$\alpha = \left\{ t^2 + 2t + 1, \ t^2 + 3t + 1, \ t^2 + 2 \right\} \text{ and } \beta = \left\{ \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix}, \begin{bmatrix} 2 & 2 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ -1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} \right\}$$

and the standard bases:

$$s = \left\{ t^2, t, 1 \right\} \quad \text{and} \quad S = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

(a) Find $_{S}[T]_{s}$ (b) Find $_{\beta}[T]_{\alpha}$

If
$$\begin{bmatrix} \vec{v} \end{bmatrix}_{\alpha} = \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}$$
 (c) Find $\begin{bmatrix} T(\vec{v}) \end{bmatrix}_{\beta}$ (d) Find $T(\vec{v})$ and $\begin{bmatrix} T(\vec{v}) \end{bmatrix}_{S}$

(2) $T: M_{2\times 2}(\mathbb{R}) \to P_3(\mathbb{R})$ be defined by

$$T \begin{bmatrix} a & b \\ c & d \end{bmatrix} = (4a - 3b - 5c + 3d)t^{3} + (a + 3b - c)t^{2} + (-3b - c + 3d)t + (a + b - c + 2d)$$

Define the following bases:

$$\alpha = \left\{ \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix} \right\} \text{ and } \beta = \left\{ t^3 + t + 1, \ t^2 + 1, \ t^3 + t^2 + 1, \ t^3 + t \right\}$$

and the standard bases:

$$S = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\} \text{ and } S = \left\{ t^3, t^2, t, 1 \right\}$$

(a) Find $_{S}[T]_{s}$ (b) Find $_{\beta}[T]_{\alpha}$

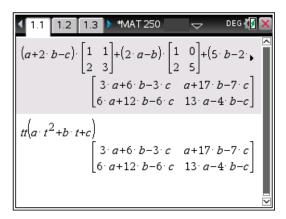
If
$$\vec{v} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$
 (c) Find $[T(\vec{v})]_{\beta}$ (d) Find $T(\vec{v})$ and $[T(\vec{v})]_{S}$

Complete Solution of Example (1):

(a) Let $T: P_2(\mathbb{R}) \to M_{2\times 2}(\mathbb{R})$ be defined by

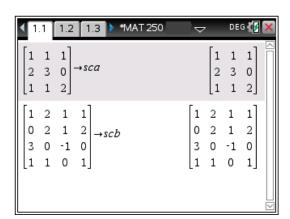
$$T(at^{2} + bt + c) = (a+2b-c)\begin{bmatrix} 1 & 1 \\ 2 & 3 \end{bmatrix} + (2a-b)\begin{bmatrix} 1 & 0 \\ 2 & 5 \end{bmatrix} + (5b-2c)\begin{bmatrix} 1 & 3 \\ 2 & -1 \end{bmatrix}$$

Note:
$$T(at^2 + bt + c) = \begin{bmatrix} 3a + 6b - 3c & a + 17b - 7c \\ 6a + 12b - 6c & 13a - 4b - c \end{bmatrix}$$



Define the following bases:

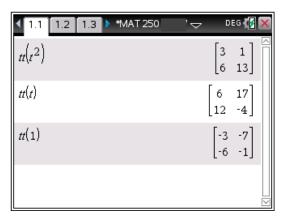
$$\alpha = \left\{ t^2 + 2t + 1, \ t^2 + 3t + 1, \ t^2 + 2 \right\} \text{ and } \beta = \left\{ \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix}, \begin{bmatrix} 2 & 2 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ -1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} \right\}$$



and the standard bases:

$$S = \left\{ t^2, t, 1 \right\} \quad \text{and} \quad S = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

Note that
$$T(at^{2} + bt + c) = \begin{bmatrix} 3a + 6b - 3c & a + 17b - 7c \\ 6a + 12b - 6c & 13a - 4b - c \end{bmatrix}$$
$$= a \begin{bmatrix} 3 & 1 \\ 6 & 13 \end{bmatrix} + b \begin{bmatrix} 6 & 17 \\ 12 & -4 \end{bmatrix} + c \begin{bmatrix} -3 & -7 \\ -6 & -1 \end{bmatrix}$$



So that
$$_{S}[T]_{s} = \begin{vmatrix} 3 & 6 & -3 \\ 1 & 17 & -7 \\ 6 & 12 & -6 \\ 13 & -4 & -1 \end{vmatrix}$$
 and hence

(b)
$$_{\beta}[T]_{\alpha} = _{\beta}C_{S} \cdot _{S}[T]_{s} \cdot _{s}C_{\alpha} = \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 2 & 1 & 2 \\ 3 & 0 & -1 & 0 \\ 1 & 1 & 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 3 & 6 & -3 \\ 1 & 17 & -7 \\ 6 & 12 & -6 \\ 13 & -4 & -1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 2 & 3 & 0 \\ 1 & 1 & 2 \end{bmatrix}$$

$$_{\beta}[T]_{\alpha} = \begin{bmatrix} 44 & 81 & -41 \\ -100 & -189 & 103 \\ 108 & 207 & -117 \\ 60 & 108 & -51 \end{bmatrix}$$

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$\begin{bmatrix} 1 & 1 & 1 \\ 2 & 3 & 0 \\ 1 & 1 & 2 \end{bmatrix} \to sca$	$\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$	1 1 3 0 1 2
$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 2 & 1 & 2 \\ 3 & 0 & -1 & 0 \\ 1 & 1 & 0 & 1 \end{bmatrix} \rightarrow scb$	\begin{bmatrix} 1 & 2 \\ 0 & 2 \\ 3 & 0 \\ 1 & 1 \end{bmatrix}	1 1 1 2 -1 0 0 1

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	60	108	-51	ш
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Let
$$\vec{v} \in P_2(\mathbb{R})$$
 such that $\begin{bmatrix} \vec{v} \end{bmatrix}_{\alpha} = \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}$ then

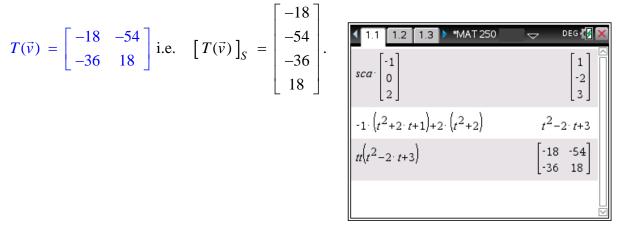
(c)
$$[T(\vec{v})]_{\beta} = {}_{\beta} [T]_{\alpha} \cdot [\vec{v}]_{\alpha} = \begin{bmatrix} 44 & 81 & -41 \\ -100 & -189 & 103 \\ 108 & 207 & -117 \\ 60 & 108 & -51 \end{bmatrix} \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix} = \begin{bmatrix} -126 \\ 306 \\ -342 \\ -162 \end{bmatrix}$$
 so that

(d)
$$T(\vec{v}) = -126 \cdot \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix} + 306 \cdot \begin{bmatrix} 2 & 2 \\ 0 & 1 \end{bmatrix} - 342 \cdot \begin{bmatrix} 1 & 1 \\ -1 & 0 \end{bmatrix} - 162 \cdot \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$$
$$= \begin{bmatrix} -18 & -54 \\ -36 & 18 \end{bmatrix}$$

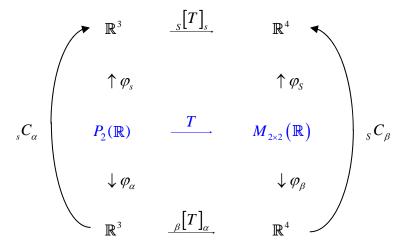
To check this another way: note that $\begin{bmatrix} \vec{v} \end{bmatrix}_{\alpha} = \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}$ implies that

$$\vec{v} = -1 \cdot (t^2 + 2t + 1) + 0 \cdot (t^2 + 3t + 1) + 2 \cdot (t^2 + 2)$$
 so that $\vec{v} = t^2 - 2t + 3$ and hence

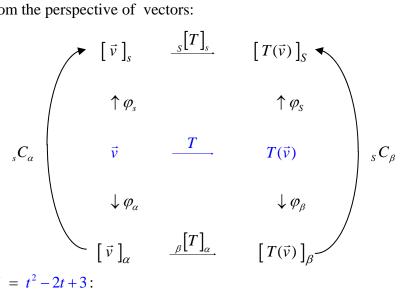
$$T(\vec{v}) = \begin{bmatrix} -18 & -54 \\ -36 & 18 \end{bmatrix}$$
 i.e. $[T(\vec{v})]_S = \begin{bmatrix} -18 \\ -54 \\ -36 \\ 18 \end{bmatrix}$.



The various vector spaces involved, and the linear maps between them are illustrated:



Seen from the perspective of vectors:



e.g.
$$\vec{v} = t^2 - 2t + 3$$
:

$$\begin{bmatrix} \vec{v} \end{bmatrix}_{\alpha} \qquad \qquad \underbrace{{}_{\beta}[T]_{\alpha}} \qquad \qquad \begin{bmatrix} T(\vec{v}) \end{bmatrix}_{\beta}$$

$$\vec{v} = t^{2} - 2t + 3:$$

$$\begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix} \qquad \qquad \underbrace{{}_{S}[T]_{s}} \qquad \qquad \begin{bmatrix} -18 \\ -54 \\ -36 \\ 18 \end{bmatrix}$$

$$\uparrow \varphi_{s} \qquad \qquad \uparrow \varphi_{s}$$

$$t^{2} - 2t + 3 \qquad \qquad T \qquad \qquad \begin{bmatrix} -18 & -54 \\ -36 & 18 \end{bmatrix}$$

$$\downarrow \varphi_{\alpha} \qquad \qquad \downarrow \varphi_{\beta}$$

$$\begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix} \qquad \qquad \underbrace{{}_{\beta}[T]_{\alpha}} \qquad \qquad \downarrow \varphi_{\beta}$$

$$\begin{bmatrix} -126 \\ 306 \\ -342 \\ -162 \end{bmatrix}$$

Complete Solution of Example (2):

 $T: M_{2\times 2}(\mathbb{R}) \to P_3(\mathbb{R})$ defined by

$$T\begin{bmatrix} a & b \\ c & d \end{bmatrix} = (4a - 3b - 5c + 3d)t^3 + (a + 3b - c)t^2 + (-3b - c + 3d)t + (a + b - c + 2d)$$

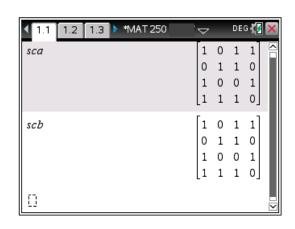
Define the following bases:

$$\alpha = \left\{ \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix} \right\} \text{ and } \beta = \left\{ t^3 + t + 1, \ t^2 + 1, \ t^3 + t^2 + 1, \ t^3 + t \right\}$$

and the standard bases:

$$S = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\} \text{ and } S = \left\{ t^3, t^2, t, 1 \right\}$$

then note that ${}_{s}C_{\alpha} = {}_{S}C_{\beta}$

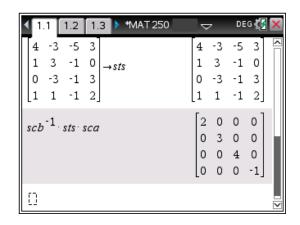


(a)
$$_{S}[T]_{s} = \begin{bmatrix} 4 & -3 & -5 & 3 \\ 1 & 3 & -1 & 0 \\ 0 & -3 & -1 & 3 \\ 1 & 1 & -1 & 2 \end{bmatrix}$$
 so that

(b)
$$_{\beta}[T]_{\alpha} = _{\beta}C_{S} \cdot _{S}[T]_{s} \cdot _{s}C_{\alpha} = \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix}^{-1} \begin{bmatrix} 4 & -3 & -5 & 3 \\ 1 & 3 & -1 & 0 \\ 0 & -3 & -1 & 3 \\ 1 & 1 & -1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix}$$

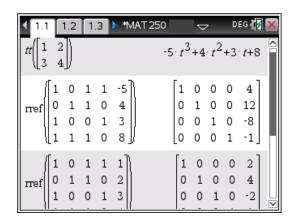
$$\Rightarrow \quad {}_{\beta}[T]_{\alpha} = \begin{vmatrix} 2 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 0 & 0 & -1 \end{vmatrix}$$

So with respect to the bases α and β the transformation matrix is a **diagonal** matrix! Images are easy to compute!



(c) If we take
$$\vec{v} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$
 then $[\vec{v}]_s = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$ and $[\vec{v}]_\alpha = {}_{\alpha}C_s \cdot \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \\ -2 \\ 1 \end{bmatrix}$

$$(\mathbf{d}) \ T(\vec{v}) = -5t^3 + 4t^2 + 3t + 8, \quad [T(\vec{v})]_S = \begin{bmatrix} -5\\4\\3\\8 \end{bmatrix} \text{ and } [T(\vec{v})]_\beta = {}_{\beta}C_S \cdot \begin{bmatrix} -5\\4\\3\\8 \end{bmatrix} = \begin{bmatrix} 4\\12\\-8\\-1 \end{bmatrix}$$



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$$sca^{-1} \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$$

$$scb^{-1} \begin{bmatrix} -5 \\ 4 \\ 3 \\ 8 \end{bmatrix}$$

$$\begin{bmatrix} 4 \\ 12 \\ -8 \\ -1 \end{bmatrix}$$

so that
$$[T(\vec{v})]_{\beta} = {}_{\beta} [T]_{\alpha} \cdot [\vec{v}]_{\alpha} = \begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 2 \\ 4 \\ -2 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 12 \\ -8 \\ -1 \end{bmatrix}$$

Here are the relationships between the vectors and their images using matrices:

