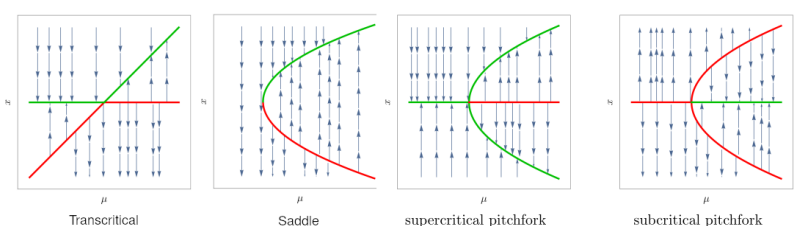


1	§1 Linear System $\dot{\mathbf{x}} = A\mathbf{x}$ $\mathbf{x}(0) = \mathbf{x}_0 \implies \mathbf{x}(t) = e^{tA}\mathbf{x}_0$
2	(If $A = BCB^{-1}$, $e^{tA} = Be^{tC}B^{-1} = B\text{diag}(e^{\lambda_1 t}, \dots, \lambda_n t)B^{-1}$)
3	<u>2D</u> $\lambda_1 \lambda_2 < 0$ Saddle $\lambda_1 \lambda_2 > 0$ Node
4	$\lambda_1 = \lambda_2$ and $\dim E_\lambda = 1$ Degenerate node ($y_1 = y_{10}e^{\lambda t} + y_{20}te^{\lambda t}$, $y_2 = y_{20}e^{\lambda t}$): Secular, but stability
5	still determined by sign.
6	$\lambda_1 = a + ib$, $\lambda_2 = a - ib \implies a = 0$ Center $a \neq 0$ Focus (Spiral)
7	Hyperbolic System: All eigval $\neq 0$
8	Eigenspace is invariant.
9	<u>Lin Subsp</u> : For $A\mathbf{w}_j = \lambda_j \mathbf{w}_j$, $\mathbf{w}_j = \mathbf{u}_j + i\mathbf{v}_j$, $\lambda_j = a_j + ib_j$ (For nonsemisimple, $(A - \lambda I)^k \mathbf{w} = 0$)
10	$E^s = \text{Span}(\mathbf{u}_j, \mathbf{v}_j a_j < 0)$ $E^c = \text{Span}(\mathbf{u}_j, \mathbf{v}_j a_j = 0)$ $E^u = \text{Span}(\mathbf{u}_j, \mathbf{v}_j a_j > 0)$
11	
12	§2 Nonlinear Systems
13	<u>Orbit</u> of \mathbf{x}_0 : curve $\Gamma_{\mathbf{x}_0} \subset E$: $\Gamma_{\mathbf{x}_0} = \{\mathbf{x}(t; \mathbf{x}_0) t \in \mathbb{R}\}$
14	<u>Flow</u> is the map $\varphi_t : E \rightarrow E$ s.t. $\varphi_t(\mathbf{x}_0) = \mathbf{x}(t; \mathbf{x}_0)$
15	$\mathbf{p} \in E$ is <u>ω-limit pt</u> of $\varphi_t(\mathbf{x})$: $\exists t_1 < t_2 < \dots < t_n \rightarrow \infty$ s.t. $\lim_{i \rightarrow \infty} \phi_{t_i} = \mathbf{p}$ cf) α -lim pt
16	Closed invariant set A <u>Attracting set</u> if \exists neighborhood U of A s.t. $\varphi_t(U) \subset U$ and $A = \bigcap_{t>0} \varphi_t(U)$
17	<u>Domain of attraction</u> $D(A) = \bigcup_{t \leq 0} \varphi_t(U)$ (AKA set of all IC s.t. have A as ω -lim set)
18	<u>Attractor</u> : Attracting set with a dense orbit.
19	<u>Poincaré-Bendixson Thrm</u> : $E \subset \mathbb{R}^2$ open, $\mathbf{f} \in C^1(E)$. If $D \subset E$ compact (closed bdd) s.t. $\mathbf{x}(t) \in D$
20	for all $t \geq 0$ where $\dot{\mathbf{x}} = \mathbf{f}(\mathbf{x})$, then orbit is either a limit cycle or approaches a limit cycle, or approaches
21	an equilibrium.
22	Fixed point \mathbf{x}_0 <u>Lyapunov stable</u> : $\forall \epsilon > 0 \exists \delta > 0$ s.t. $\forall \mathbf{x} \in B_\delta(\mathbf{x}_0)$ and $t \geq 0$, $\varphi_t(\mathbf{x}) \in B_\epsilon(\mathbf{x}_0)$
23	Fixed point \mathbf{x}_0 <u>asympt. stable</u> : (i) Lyapunov and (ii) $\exists \delta > 0$ s.t. $\varphi_t(\mathbf{x}) \rightarrow \mathbf{x}_0$ as $t \rightarrow \infty \forall \mathbf{x} \in B_\delta(\mathbf{x}_0)$
24	
25	Lyapunov Function $V(\mathbf{x}_0) = 0, V(\mathbf{x}) > 0 \forall \mathbf{x} \in W \setminus \{\mathbf{x}_0\}$ Tip: $\dot{V}(\mathbf{x}) = \nabla V(\mathbf{x}) \cdot \dot{\mathbf{x}} = \nabla V(\mathbf{x}) \cdot \mathbf{f}(\mathbf{x})$
26	(i) $\dot{V}(\mathbf{x}) \leq 0 \forall \mathbf{x} \in W \setminus \{\mathbf{x}_0\} \implies$ Stable
27	(ii) $\dot{V}(\mathbf{x}) < 0 \forall \mathbf{x} \in W \setminus \{\mathbf{x}_0\} \implies$ Asymptotic Stable
28	(iii) $\dot{V}(\mathbf{x}) > 0 \forall \mathbf{x} \in W \setminus \{\mathbf{x}_0\} \implies$ Unstable
29	
30	§3 Local Analysis
31	From linearized system around origin,
32	$W^s(0) = \{(x, y) \in \mathbb{R}^2 \varphi_t(x, y) \rightarrow 0 \text{ as } t \rightarrow \infty\}$, $W^u(0) = \{(x, y) \in \mathbb{R}^2 \varphi_t(x, y) \rightarrow 0 \text{ as } t \rightarrow -\infty\}$
33	<u>Center manifold</u> : (i) Tangent to E^c at \mathbf{x}_0 (ii) of class C^r (where $f \in C^R(E)$) (iii) invar under flow.
34	(Interested in smoothest center manifold)
35	<u>Shadowing Theorem</u> : $(\mathbf{x}_0, \mathbf{y}_0)$ close enough to origin, $(\mathbf{x}(t), \mathbf{y}(t))$ solution $\implies \exists \tilde{\mathbf{x}}(t)$ on center man.
36	s.t. $\begin{cases} \mathbf{x}(t) = \tilde{\mathbf{x}}(t) + O(e^{-\gamma t}) \\ \mathbf{y}(t) = \mathbf{h}(\tilde{\mathbf{x}}(t)) + O(e^{-\gamma t}) \end{cases}$ for some const $\gamma > 0$.
37	
38	§4. Bifurcations
39	<u>Topological equivalence</u> Two vector field \mathbf{f} and \mathbf{g} and resp. flows $\varphi_t(\mathbf{x})$ and $\psi_t(\mathbf{x})$ are top.equi. if
40	\exists homeomorphism (1-1, cts, cts inv) $\mathbf{h} : \mathbb{R}^n \rightarrow \mathbb{R}^n$ and $\tau(t, \mathbf{x}) \rightarrow \mathbb{R}$ strict. inc. on t s.t. $\tau(t + s, \mathbf{x}) =$
41	$\tau(s, \mathbf{x}) + \tau(t, \varphi_s(\mathbf{x}))$
42	<u>Structural Stability</u> : VF \mathbf{f} structurally stable if \forall ctsly diff. VF \mathbf{v} , $\exists \epsilon_v > 0$ s.t. \mathbf{f} is top.equiv to
43	$\mathbf{f} + \epsilon \mathbf{v} \forall 0 < \epsilon < \epsilon_v$
44	<u>Bifurcation Pt</u> : μ_c point in param. space where f is not structurally stable.
45	<u>Bifurcation</u> : Change in structure of the solution.
46	<u>Step-by-Step</u> : Find fixed point. Compute Jacobian (w.r.t μ as a const) around a fixed pt and set it
47	to zero. Check Hopf.
48	Examples (i) $\dot{x} = \mu x - x^2$ (Transcritical, fp: $x = 0, \mu$) (ii) $\dot{x} = \mu - x^2$ (Saddle, fp: $x = \pm \mu^{1/2}$)
49	(iii) $\dot{x} = \mu x - x^3$ (Sup.crit pitch, fp: $x = 0, \pm \mu^{1/2}$) (iv) $\dot{x} = -\mu x + x^3$ (Sub.crit pitch, fp: $x = 0, \pm \mu^{1/2}$)
	 <div style="display: flex; justify-content: space-around; margin-top: 5px;"> Transcritical Saddle supercritical pitchfork subcritical pitchfork </div>

§5 Local Analysis of Maps $\mathbf{x}_{n+1} = \mathbf{G}(\mathbf{x}_n)$

$$E^s = \text{Span}(\mathbf{u}_j, \mathbf{v}_j | |\lambda_j| < 1) \quad E^c = \text{Span}(\mathbf{u}_j, \mathbf{v}_j | |\lambda_j| = 1) \quad E^u = \text{Span}(\mathbf{u}_j, \mathbf{v}_j | |\lambda_j| > 1)$$

Stability: Fixed pt \mathbf{x}_0 s.t. $\forall \epsilon > 0, \exists \delta > 0$ s.t. $\forall \mathbf{x} \in B_\delta(\mathbf{x}_0)$ for all $n \in \mathbb{Z}^+$

Asympt Stability: \mathbf{x}_0 s.t. stable and $\exists \delta > 0$ s.t. $\forall \mathbf{x} \in B_\delta(\mathbf{x}_0), \mathbf{G}^{(n)}(\mathbf{x}) \rightarrow \mathbf{x}_0$ as $n \rightarrow \infty$

$\forall \mathbf{x} \in W_{loc}^s, \mathbf{G}^{(n)} \rightarrow \mathbf{x}_0$ as $n \rightarrow \infty$ $\forall \mathbf{x} \in W_{loc}^u, \mathbf{G}^{(n)} \rightarrow \mathbf{x}_0$ as $n \rightarrow -\infty$

Periodic orbit Γ is Lyapunov stable if $\forall \epsilon > 0: \exists \delta > 0$ s.t. $\varphi_t(\mathbf{x}) \in U_\epsilon(\Gamma)$ for all $t \geq 0$ and $\mathbf{x} \in U_\delta$

Periodic orbit Γ Asympt stable if Lyapunov + $\exists \delta > 0$ s.t. $d(\varphi_t(\mathbf{x}), \Gamma)$ as $t \rightarrow \infty$ for all $\mathbf{x} \in U_\delta$

Poincaré Map Traversality: $\mathbf{n} \cdot \mathbf{f}(\mathbf{x}_0) > 0$

§6 Limit Cycles and Hopf Bifur

Poincaré-Lindstedt Method: $\ddot{x} + x = \epsilon f(x)$

Define timescale $\tau = \omega t$ s.t. $x(\tau + 2\pi, \epsilon) = x(\tau, \epsilon)$ (Tip: $\frac{d}{dt} = \omega \frac{d}{d\tau}$)

Translation of time: $\dot{x} = 0$ at $t = 0$ Amplitude of oscillation: $a = x(0, \epsilon)$

Expansion: $\omega = \omega_0 + \epsilon \omega_1 + \epsilon^2 \omega_2 + \dots$ $x(\tau, \epsilon) = x_0(\tau) + \epsilon x_1(\tau) + \epsilon^2 x_2(\tau)$ (No secular solution)

(Tip: $\cos^2 \tau = \frac{1+\cos 2\tau}{2}, \cos^3 \tau = \frac{3\cos \tau + \cos 3\tau}{4}$)

Hopf $\Re(\lambda) = 0$ at $\mu = \mu_c$ $\dot{r} = d\mu r + ar^3$ $\dot{\theta} = \omega + c\mu + br^2$ $d = \frac{d}{d\mu} \Re \lambda(\mu)|_{\mu=\mu_c}, c = \frac{d}{d\mu} \Im \lambda(\mu)|_{\mu=\mu_c}$

$\dot{x} = \mu x - \omega y + f(x, y)$ $\dot{y} = \omega y + \mu y + g(x, y)$

$\implies a = \frac{1}{16\omega} ((f_{xxx} + f_{xyy} + g_{xxy} + g_{yyx})\omega + f_{xy}(f_{xx} + f_{yy}) - g_{xy}(g_{xx} + g_{yy}) - f_{xx}g_{xx} + f_{yy}g_{yy})$

Local Bifur

$\lambda = 1$: eg) $x + \mu - x^2$ saddle $x + \mu x - x^2$ transcritical $x + \mu x - x^3$ pitchfork

Bifur of Periodic Orbit: Seek Poincaré map s.t. $\delta \rightarrow \delta + \frac{\delta^2}{2} P_r r(1, 0) + \mu P_\mu(1, 0)$. For $\dot{r} = f(r, \theta, \mu)$, $P_\mu(1, 0) = \int_0^{2\pi} f_\mu(1, \theta, 0) dt$, $P_r(1, 0) = 1$, $P_{rr}(1, 0) = \int_0^{2\pi} f_{rr}(1, \theta, 0) dt$

$\lambda = -1$: eg) $f(x, \mu) = -x - \mu x + x^3$ Period-doubling

§7 Global Bifur, Homoclinic Chaos, Melnikov's Method $\dot{\mathbf{x}} = \mathbf{f}(\mathbf{x}) + \epsilon \mathbf{g}(\mathbf{x}, t)$

f has sensitivity to IC on Λ if $\exists \epsilon > 0$ s.t. for any $p \in \Lambda$ and any neighborhood U of p , $\exists p' \in U$ and $n \in \mathbb{N}$ s.t. $|f^n(p) - f^n(p')| > \epsilon$

f topolo. transitive on Λ if for any open $U, V \subset \Lambda$, $\exists n \in \mathbb{Z}$ s.t. $f^n(U) \cap V \neq \emptyset$

Λ invar compact set for invertible f . f chaotic on Λ if \exists sensitivity to IC on Λ and topo. transitive on Λ

Assumption: $\mathbf{f}(\mathbf{x}) = (f_1, f_2) = \left(\frac{\partial H}{\partial y}, -\frac{\partial H}{\partial x} \right)$ (Hamiltonian)

Melnikov Function: $M(t_0) = \int_{-\infty}^{\infty} \mathbf{f}(\mathbf{q}_0(t - t_0)) \wedge \mathbf{g}(\mathbf{q}_0(t - t_0), t) dt$ ($\mathbf{x} = \mathbf{q}_0(t)$ for $\epsilon = 0$, homoclinic)

M has a simple zero at a point $t_0 = \tau$, then P_ϵ has a transverse homoclinic point for sufficiently small $\epsilon > 0$

If $M(t_0) > 0$ or $M(t_0) < 0$ for all t_0 , then $W^s(\mathbf{x}_\epsilon) \cap W^u(\mathbf{x}_\epsilon) = \emptyset$

Eg) Duffing Oscil. $\ddot{x} = x - x^3 - \delta \dot{x} + \gamma \cos t$

$\dot{x} = y = \pm x \left(1 - \frac{x^2}{2} \right)^{\frac{1}{2}} \implies (x_0(t), y_0(t)) = \mathbf{q}_0(t) = \pm(\sqrt{2} \text{sech } t, -\sqrt{2} \text{sech } t \tanh t)$