```
D_x^+ D_x^- u(x_i) = u''(x_i) + O(h^2)
             Finite Difference: D_x^{\pm}u(x_i) = u'(x_i) + O(h)
             (V, W)_h := \sum_{i=1}^{N-1} h V_i W_i \quad \text{Sum. by parts: } (-D_x^+ D_x^- U, V)_h = (D_x^- U, D_x^- V) \text{ if } (U, V)_0 = (U, V)_N = 0
\text{L}_2 \text{ norm } ||U||_h = (U, U)^{1/2} \quad \text{Sob. norm } ||U||_{1,h} = (||U||_h^2 + ||D_x^- U||_h^2)^{1/2}
             Discrete Poincaré ||V||_{h}^{2} \le c_{*}||D_{x}^{-}V||_{h}^{2} (1D c_{*} = \frac{1}{2})
              \begin{array}{ll} \textbf{1D Elliptic} \ -u'' + c(x)u = f(x), \ u(0) = 0 = u(1) & Au = (-D_x^+D_x^- + c)u & c \geq 0 \\ (AV,V)_h \geq ||D_x^-V||_h^2 \ (\underline{\text{Uniqueness}}) \ \& \ (AV,V)_h \geq \frac{1}{c_*} ||V||_h^2 \Longrightarrow (1+c_*)(AV,V)_h \geq ||V||_h^2 + ||D_x^-V||_h^2 \\ \end{array} 
             \Longrightarrow (AV,V)_h \geq c_0 ||V||_{1,h}^2 \Longrightarrow ||U||_{1,h} \leq \frac{1}{c_0} ||f||_h \ (\underline{\operatorname{Stability}}) \underline{\operatorname{Global\ error}}\ e_i \coloneqq u(x_i) - U_i \ \text{for}\ i = 0, \cdots, N
             Ae_i = Au(x_i) - f(x_i) = u''(x_i) - D_x^+ D_x^- u(x_i) \Longrightarrow Ae_i = \varphi_i = O(h^2)
10
             By stability result, ||u - U||_{1,h} = ||e||_{1,h} \le \frac{1}{c_0} ||\varphi||_h
11
             Since |\varphi_i| \leq \frac{1}{12}h^2||u^{(4)}(x)||_C, we have ||u - U||_{1,h} \leq \frac{1}{8}||u^{(4)}||_{C[0,1]} (Convergence)
12
              "Stability + Consistency \Longrightarrow Convergence
13
14
             2D Elliptic \Delta u + c(x,y)u = f(x,y) in \Omega and u = 0 on \partial \Omega
15
             AU_{i,j} = -(D_x^+ D_x^- U_{i,j} + D_y^+ D_y^- U_{i,j}) + c_{i,j} U_{i,j} = f_{i,j} \qquad U_{i,j} = 0 \text{ for } \Gamma_h
(V, W)_h = \sum_{i=1}^{N-1} \sum_{j=1}^{N-1} h^2 V_{i,j} W_{i,j}
                                                                                                                                                                 "5-pt + scheme"
16
17
             Sum by Parts \Longrightarrow (AV, V)_h \ge ||D_x^- V||_x^2 + ||D_y^- V||_u^2 (\underline{\text{Uniqueness}})
18
             (Poincaré) ||V||_h^2 \le c_* (||D_x^- V||_x^2 + ||D_y^- V||_n^2) (2D c_* = \frac{1}{4})
19
             SBP + Poincaré: (AV, V)_h \ge c_0 ||V||_{1,h}^2 (c_0 = (1 + c_*)^{-1}) \Longrightarrow ||U||_{1,h} \le \frac{1}{c_0} ||f||_h (Stability)

Global error e_{i,j} := u(x_i, y_j) - U_{i,j} Consistency Error \varphi_{i,j} := Au_{i,j} - f_{i,j}
20
21
             Since \varphi_{i,j} = \frac{h^2}{12} (u_{xxxx}(\xi_i, y_j) + u_{yyyy}(x_i, \eta_j)) and Ae_{i,j} = \varphi_{i,j}, e = 0 on \Gamma_h
22
             ||u - U||_{1,h} \le \frac{5h^2}{48} (||u_{xxxx}||_{C(\bar{\Omega})} + ||u_{yyyy}||_{C(\bar{\Omega})}) (Convergence)
23
             Nonaxiparallel: h_{i+1} = x_{i+1} - x_i, h_i = x_i - x_{i-1}, h_i = \frac{1}{2}(h_{i+1} + h_i)
24
             Discrete Max. Principle Useful for uniqueness, and max norm stability (cts dep on BD).
25

\overline{-D_x^+ D_x^- U_{i,j} - D_y^+ D_y^- U_{i,j}} = f_{i,j} \& U_{i,j} = g_{i,j} \text{ on } \Gamma, f \le 0 

\Longrightarrow (\cdot) U_{i,j} = (\cdot) U_{i+1,j} + (\cdot) U_{i-1,j} + (\cdot) U_{i,j-1} + (\cdot) U_{i,j+1} + f_{i,j}

26
27
             Contradiction: For (f < 0) Replace RHS U_{i\pm 1,j\pm 1} \to U_{i,j} then (\cdot) < (\cdot) (without f), but the expr on
28
       both sides are equal.
29
             For f \leq 0, V_{i,j} := U_{i,j} + \frac{\epsilon}{4}(x_i^2 + y_j^2), consider \max_{(x_i, y_j) \in \Gamma_h} U_{i,j}
30
             Tip: \psi_{i,j} = (x_i - \frac{1}{2})^2 + (y_j - \frac{1}{2})^2 \Longrightarrow \mathcal{L}_h \psi_{i,j} = -4(=-2n) \Longrightarrow \mathcal{L}_h e_{i,j} = \tau_{i,j}. Let \tau := \max |\tau_{i,j}|.
31
       Then \phi_{i,j} = e_{i,j} \mp \frac{\tau}{2n} \psi_{i,j}, \mathcal{L}_h(\phi_{i,j}) \geq (\leq)0. Use min/max principle with e = 0 on \Gamma. (Convergence)
32
33
             Eigen 1D: -D_x^+D_x^-U_i + cU_i = \Lambda U_i with U_0 = 0 = U_N
34
             \implies U_i = \sin k\pi x_i \text{ with } c + 8 \le \Lambda = c + \frac{4}{h^2} \sin^2 \frac{k\pi h}{2} \le c + \frac{4}{h^2} \text{ (Symm 3diag } A \in \mathcal{M}_{n \times n} \text{ s.t. } AU = F)
35
             Eigen 2D: -D_x^+ D_x^- U_{i,j} - D_y^+ D_y^- U_{i,j} + c U_{i,j} = \Lambda U_{i,j} with homogen BC.
36
             \implies U_{i,j} = \sin k\pi x_i + \sin l\pi y_j \text{ with } \Lambda = c + \frac{4}{h^2} (\sin^2 \frac{k\pi h}{2} + (\sin^2 \frac{l\pi h}{2})) \in [c + 16, c + \frac{8}{h^2}]
37
             Iter Method: U^{(j+1)} := U^{(j)} - \tau(AU^{(j)} - F) with \limsup_{j \to \infty} U s.t. U = U - \tau(AU - F) (A sym, + eigval)
38
             \Longrightarrow U - U^{(j+1)} := (I - \tau A)(U - U^{(j)}) \Longrightarrow U - U^{(j)} = (I - \tau A)^{j}(U - U^{(0)})
39
             To ensure convergence ||I - \tau A|| \leq \min_{\tau > 0} \max\{|1 - \tau \beta|, |1 - \tau \alpha|\} < 1 \implies \tau = \frac{2}{\alpha + \beta} for best
       convergence.
41
42
             \begin{array}{l} \textbf{Parabolic} \ u_t = u_{xx} + f \ \text{on} \ \{(x,t) \in (-\infty,\infty) \times [0,T]\} \\ \theta \text{-scheme:} \ \frac{U_j^{m+1} - U_j^m}{\Delta t} = (1-\theta) \frac{U_{j+1}^m - 2U_j^m + U_{j-1}^m}{(\Delta x)^2} + \theta \frac{U_{j+1}^{m+1} - 2U_j^{m+1} + U_{j-1}^{m+1}}{(\Delta x)^2} \end{array}
43
44
             Consistency Error:
45
             \overline{T_{j}^{m}} = \frac{\overline{u_{j}^{m+1} - u_{j}^{m}}}{\frac{\Delta t}{\Delta t}} - (1 - \theta) \frac{\overline{u_{j+1}^{m} - 2u_{j}^{m} + u_{j-1}^{m}}}{(\Delta x)^{2}} - \theta \frac{\overline{u_{j+1}^{m+1} - 2u_{j}^{m} + u_{j-1}^{m+1}}}{(\Delta x)^{2}} \text{ for } j = 0, \pm 1, \pm 2, \ m = 0, \dots, M - 1
46
             T_j^m = \begin{cases} O(\Delta x^2 + \Delta t^2), & \theta = \frac{1}{2} \\ O(\Delta x^2 + \Delta t), & \theta \neq \frac{1}{2} \end{cases} from Taylor expansion around x_j, t_{m+\frac{1}{2}}
             Practical Stability: ||U^m||_{l_2} \le ||U^0||_{l_2} where ||U^m||_{l_2} = (\Delta x \sum_{j=-\infty}^{\infty} |U_j^m|^2)^{\frac{1}{2}}
48
             Semidiscrete FT: \hat{U}(k) = \Delta x \sum_{j=-\infty}^{\infty} U_j e^{-ikx_j} for k \in [-\pi/\Delta x, \pi/\Delta x]
49
             Semidiscrete IFT: U_j = \frac{1}{2\pi} \int_{-\pi/\Delta x}^{\pi/\Delta x} \hat{U}(k) e^{ikj\Delta x} dk
50
```

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\underline{\text{Discrete Parseval:}} \ ||U||_{l_2} = \frac{1}{\sqrt{2\pi}} ||\hat{U}||_{L_2} \quad \text{Pf:} \ ||\hat{U}||_{L_2}^2 = \int \hat{U}(k) \overline{\hat{U}(k)} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta x \sum U_j e^{ikj\Delta x} dk = \int \hat{U}(k) \Delta 
  1
           \sum U_j \Delta x 2\pi \frac{1}{2\pi} \int \hat{U}(k) e^{ikj\Delta x} dk = \sum U_j \Delta x 2\pi U_j = ||U||_{l_2}^2 2\pi
 2
                    Stability Analysis: U_j^m = \frac{1}{2\pi} \int_{-\pi/\Delta x}^{\pi/\Delta x} e^{ikj\Delta x} \hat{U}^m(k) dk Tip: 1 - \cos \varphi = 2 \sin^2 \frac{\varphi}{2}, e^{ik\Delta x} + e^{-ik\Delta x} - 2 = 2 \sin^2 \frac{\varphi}{2}
           2(-1 + \cos k\Delta x) = -4\sin^2\frac{k\Delta x}{2}
                     \hat{U}_{i}^{m}(k) = \lambda(k)\hat{U}^{m}(k), Stable iff |\lambda(k)| \leq 1
                     <u>Von Neumann</u>: On [0,T], \exists C = C(T) s.t. ||U^m||_{l_2} \leq C||U^0||_{l_2}
                     Lemma: \hat{U}^{m+1}(k) = \lambda(k)\hat{U}^m(k), |\lambda(k)| \le 1 + C_0\Delta t for some C_0 \Longrightarrow Neumann Stable,
                                                                                                                                                                                                                                                                                                PT \Longrightarrow NS
                    \theta-scheme has \lambda(k) = \frac{1 - 4(1 - \theta)\mu \sin^2\frac{k\Delta x}{2}}{1 + 4\theta\mu \sin^2\frac{k\Delta x}{2}}
                     \implies Uncond. PS if \theta \in [1/2, 1] and Cond. PS if \theta \in [0, 1/2) where stbl iff 2(1 - 2\theta) \mu \leq 1
                    \underline{\theta\text{-scheme IBVP}} \ \theta\text{-scheme} \Longrightarrow \left(1 - \theta\mu\delta^2\right) U_j^{m+1} = \left(1 + (1 - \theta)\mu\delta^2\right) U_j^m \ \left(\delta^2 U_j \coloneqq U_{j+1} - 2U_j + U_{j-1}\right)
10
                     (I - \theta \mu A) \mathbf{U}_{i}^{m+1} = (I + (1 - \theta) \mu A) \mathbf{U}^{m} + \theta \mu \mathbf{F}^{m+1} + (1 - \theta) \mu \mathbf{F}^{m} \ (A \in \mathcal{M}^{(J-1)^{2}} \text{ 3diag } 1, -2, 1 \text{ entry})
11
                    with \mathbf{U}^m := (U_1^m, \dots, U_{J-1}m)^T, \mathbf{F}^m := (A(t_m), 0, \dots, 0, B(t_m))^T
Discrete max. principle Given 0 \le \theta \le 1, \mu(1-\theta) \le \frac{1}{2} (More street cond)
12
13
                    \overline{\text{Pf}) (1 + 2\theta\mu) U_J^{m+1} = \theta\mu \left( U_{j+1}^{m+1} + U_{j-1}^{m+1} \right) + (1 - \theta)\mu \left( U_{j+1}^{m} + U_{j-1}^{m} \right) + (1 - 2(1 - \theta)\mu) U_j^{m}(\dagger)}
                    Suppose max at U_j^{m+1}. For U^* = \max\left(U_{j\pm 1}^{m+1/2\pm 1/2}, U_j^m\right), replace U_{j\pm 1}^{m\pm 1} \to U^*, then \leq \Longrightarrow U_i^{m+1} \leq \varinjlim U_i^{m+1}
15
           U^*, but U^* \leq U_i^{m+1}
16
                     Convergence in max norm: (\dagger) \Longrightarrow (\dagger\dagger)RHS - LHS = 0
                                                                                                                                                                                                          Replace U \to u \Longrightarrow (\cdot) = \Delta t T_J^m
17

\frac{(1+2\theta\mu)\,e_J^{m+1} = \theta\mu\,\left(e_{j+1}^{m+1} + e_{j-1}^{m+1}\right) + (1-\theta)\,\mu\left(e_{j+1}^{m} + e_{j-1}^{m}\right) + (1-2\,(1-\theta)\,\mu\right)e_j^{m} + \Delta t T_j^{m}}{E^m \coloneqq \max_{0 \le j \le J}|e_j^{m}| \text{ (Analog } T_j^{m}) \Longrightarrow E^{m+1} \le E^m + \Delta t T^m}

18
19
                     \xrightarrow{Telescope} E^m \leq T \max_{0 \leq m \leq M-1} \max_{1 \leq j \leq J-1} |T_j^m| \text{ (Noting } E^0 = 0)
20
                     \max_{0 \le m \le M} \max_{0 \le j \le J} |u_i^m - U_i^m| \le T \max_{0 \le m \le M-1} \max_{1 \le j \le J-1} |T_i^m| (Use consistency error)
21
22
                     Hypberbolic u_{tt} - c^2 u_{xx} = f(x,t) on (x,t) \in (a,b) \times (0,T];
23
                    u(x,0) = u_0(x), u_t(x,0) = u_1(x); u(a,t) = u(b,t) = 0 Energy inequality for analysis. (\cdot, u_t) Implicit: \frac{U_j^{m+1} - 2U_j^m + U_j^{m-1}}{(\Delta t)^2} - c^2 \frac{U_{j+1}^{m+1} - 2U_j^{m+1} + U_{j-1}^{m+1}}{(\Delta t)^2} = f(x_j, t_{m+1}) \text{ for } j = 1, \dots, J-1, m = 1, \dots, M-1
25
26
                    \begin{array}{ll} U_{j}^{0}=u_{0}(x_{j}) & U_{j}^{1}=U_{j}^{0}+\Delta t u_{1}(x_{j}) & U_{0}^{m}=0=U_{J}^{m} \\ \mathrm{Note}\; (A-B,A)=\frac{1}{2}({||A||}^{2}-{||B||}^{2})+\frac{1}{2}{||A-B||}^{2}\; (\mathrm{Analog}\; (A-B,A]) \end{array}
27
28
                   Take inner product of scheme with \frac{U^{m+1}-U^m}{\Delta t}, and define \mathcal{M}^2(U^m) \coloneqq \left\| \frac{U^{m+1}-U^m}{\Delta t} \right\|^2 + c^2 \left\| D_x^- U^{m+1} \right\|^2

Unconditional Stability: \mathcal{M}^2(U^m) \le e^2 \mathcal{M}(U^0) + 2e^2 T \sum_{k=1}^m \Delta t \left\| f(\cdot, t_{k+1}) \right\|^2

Consistency: T_j^{m+1} \coloneqq \frac{u_j^{m+1} - 2u_j^m + u_j^{m-1}}{(\Delta t)^2} - c^2 \frac{u_{j+1}^{m+1} - 2u_j^m + u_{j-1}^{m+1}}{(\Delta x)^2} T_j^1 \coloneqq \frac{u_j^1 - u_j^0}{\Delta t} - u_1(x_j)
29
30
31
                    32
33
                     Explicit
34
                     Conditionally stable: c \frac{\Delta t}{\Delta x} \le c_0 < 1
35
36
                     1st Hyperbolic u_t + b(x)u_x + c(x,t)u = f(x,t) u(x,t) = 0 (inflow) u(x,0) = u_0(x)
37
                     Explicit: u_t + bu_x = f(x, t) on x \in (0, 1), t \in (0, T] b > 0 \Longrightarrow u(0, t) = 0 with t \in (0, T]
38
                      \frac{U_{j}^{m+1} - U_{j}^{m}}{\Delta t} + bD_{x}^{-}U_{j}^{m} = f(x_{j}, t_{m}) \Longleftrightarrow U_{j}^{m+1} = (1 - \mu)U_{j}^{m} + \mu U_{j-1}^{m} + \Delta t f_{j}^{m} \text{ with } 0 \leq \mu = \frac{b\Delta t}{\Delta x} \leq 1
39
                    \underline{\text{Stability:}} \ |U_j^{m+1}| \leq \max_{0 \leq j \leq J} |U_j^m| + \Delta t \max_{0 \leq j \leq J} |f_j^m| \Longrightarrow ||U^{m+1}|_{\infty} \leq ||U^m||_{\infty} + \Delta t f(\cdot, t_m)_{\infty}
40
                     41
42
                     Nonlinear Hyperbolic u_t + (f(u))_x = 0 \ \mathbb{R} \times (0, \infty), \ f(0) = f'(0) = 0, \ f''(s) \ge 0, \ |f'(s)| \le f'(|s|)
43
                    Use f'(u) = [f'(u)]_+ + [f'(u)]_- \Longrightarrow u_t + [f'(u)]_+ u_x + [f'(u)]_- u_x = 0

Scheme: \frac{U_j^{m+1} - U_j^m}{\Delta t} + [f'(U_j^m)]_+ D_x^- U_j^m + [f'(U_j^m)]_- D_x^- U_j^m = 0
44
45
                    Stability: CFL \frac{f'(||U^k||_{\infty})\Delta t}{\Delta x} \le 1 \Longrightarrow ||U^{m+1}||_{\infty} \le ||U^m||_{\infty}
46
                     If u has cts bdd 2nd derivatives w.r.t x and t, then \max_{1 \le m \le M} ||u^m - U^m||_{\infty} = O(\Delta x + \Delta t)
47
```