http://paulynomial.com pak79@cornell.edu | 646.369.6726

## **EDUCATION**

CORNELL UNIVERSITY May 2012

### BS IN ELECTRICAL AND COMPUTER ENGINEERING

Double Concentration in Electrical Engineering and Computer Science Honors: John McMullen Dean Scholar, Goldfarb Tradition Fellow

# **EXPERIENCE**

MOAT May 2012 – Present

#### SOFTWARE DEVELOPER

- Developed the full-stack behind Moat Pro, an enterprise ad-intelligence platform that allows markets to research trends in the online advertising industry.
- Developed network of autonomous web crawlers (Moatbots) capable of programmatically detecting, capturing, and indexing online advertisements.
- Developed ETL for consuming warehoused Moatbot data and transforming it into an optimized, queryable form.
- Developed API to cache architecture for client side report generation and Pyramid application to serve reports.
- Developed autocomplete service for web application that served as the primary means of directing site traffic.
- Developed Pyramid middleware for logging user engagement with the client-facing brand intelligence tool.
- Developed homebrew real-time analytics tool for consuming engagement data to build reports on site usage patterns and behaviour.
- Deployed a Jenkins continuous integration server for regression testing.
- Developed homebrew heterogeneous server role and configuration deployment system in Amazon's EC2.

### CORNELL LABORATORY FOR ELEMENTARY-PARTICLE PHYSICS

Jan 2009- May 2012

#### LEAD LINUX INFRASTRUCTURE CONSULTANT

- Designed, installed, and serviced solutions for a network of high-performance computational nodes used in the study of beams and accelerators, photon science, and particle physics.
- Managed a network of Linux nodes responsible for serving the department's administrative tasks.

## RESEARCH

## **CORNELL ROBOT LEARNING LAB**

Jan 2011 - Mar 2011

## Undergraduate Researcher

- Worked with **Prof. Ashutosh Saxena** to create a supervised learning algorithm for finding good object placements using point-clouds of an object and its surrounding area.
- Implemented the algorithm on an Adept Viper s850 robotic arm equipped with a Microsoft Kinect.
- SVM models built from our training examples attained performances in excess of 80% for both precision and recall on both flat and non-flat surface placement. **Publication**.

## **CORNELL SPACE SYSTEMS DESIGN STUDIO**

May 2010 - Dec 2010

#### POWER SUBTEAM MEMBER

• Designed and fabricated the ATxmega 128 based power distribution system for Cornell's operationally responsive, high agility space imaging system codenamed 'Violet'.

# PROGRAMMING SKILLS

Over 60,000 lines: Python

Over 5000 lines: Java • Shell • Matlab • LATEX Over 1000 lines: MySQL • C • C++ • Assembly

Familiar: JavaScript • CSS • PHP

# INTERESTS

Cooking • Boxing • Particle Physics Fusion Engineering • Miyazaki Films Aerospace Engineering • Music

# LINKS

Github:// paulkiernan LinkedIn:// paulkiernan Twitter:// @gaelic