

Air Force Institute of Technology



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Data-Driven Device Failure Prediction

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Introduction

Related Work

Methodology

Experimental Results

Fault Injection
Under-Resourced Central Processing Unit (CPU)
Memory Corruption
Memory Leak

Conclusions & Future Work





- Computer systems fail, not often, but could have devastating consequences
- Redundancy can help, but it is expensive, complex, and only masks the root cause
- ► Survey paper of techniques for predicting failure using machine learning [1]
- Difficulty is in finding or obtaining training data





- ► Adaptive Failure Prediction (AFP) framework [2]
- ► AFP wasn't capable of running on modern operating system
- ► AFP didn't exhaustively emulate all possible/realistic faults [3]





- ► This work presents an extended AFP
- New realistic fault loads:
 - Memory Corruption
 - CPU Limitation
 - Memory Limitation (due to leak)
- Modernized fault injection tool: Windows Software Fault Injection Tool (W-SWFIT)
- Workload Generator: Distributed PowerShell Load Generator (D-PLG) [4]



Proactive Fault Management (PFM)



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Figure: The stages of proactive fault management [1].

- Online Failure Prediction (OFP)
- Diagnosis
- Action Scheduling
- Action Execution



Online Failure Prediction (OFP)



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 Act of evaluating a running system in real time to make a prediction about whether a failure in a future state is imminent [1]



Online Failure Prediction (OFP)



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Figure: The timeline for OFP [1].

- Present Time: t
- ▶ Lead Time: Δt_I , is the total time at which a predictor makes an assessment about the current state.
- ▶ Data Window: Δt_d , represents the time window of data used for a predictor to make its assessment.
- Minimal Warning Time: Δt_w , is the amount of time required to avoid a failure if one is predicted.
- ▶ Prediction Period: Δt_p , is the time for which a prediction is valid.



Faults, Errors, and Failures



- ► Failure: Delivered service deviates from correct service
- Error: The point when things go wrong (Detected vs. Undetected)
- Fault: Hypothesized root cause of an error



Faults, Errors, and Failures



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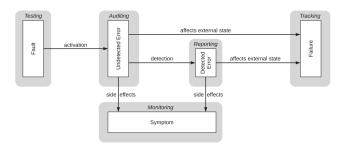


Figure: How faults and errors evolve into failure with the associated methods for detection represented by enclosing gray boxes [1].



Base Adaptive Failure Prediction (AFP)



- Virtually clones target system
- Generates realistic workload for target to accomplish
- Synthesizes realistic faults that lead to failure
- ► Capture data from system to train failure prediction model



Base Adaptive Failure Prediction (AFP)



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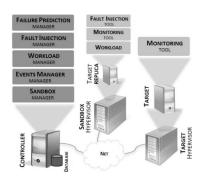


Figure: The AFP framework [2].





Table: Hypervisor 1 configuration (sandbox/target).

Qty.	Role	Operating System	CPU / Mem.
1	DC	Win. Server 2008 R2	2 / 2 GB
1	Web	Win. Server 2008 R2	2 / 2 GB
5	Client	Win. 7	1 / 512 MB

Table: Hypervisor 2 configuration (controller).

Qty.	Role	Operating System	CPU / Mem.
1	RDP	Win. Server 2008 R2	1 / 4 GB
1	Log	Ubuntu 14.04 LTS	1 / 1 GB





- Workload Generator: D-PLG with five client machines
- Fault-Load Generator:
 - W-SWFIT
 - Memory Corruption
 - ► CPU Limitation
 - Memory Limitation (due to leak)
- Events Manager: rsyslog server with SolarWinds syslog forwarder
- Prediction Model: Support Vector Machine (SVM) and boosted decision trees in R





- ► Four fault loads tested on a Windows Domain Controller (DC) and an Apache web server:
 - W-SWFIT
 - Memory Corruption
 - CPU Limitation
 - Memory Limitation (due to leak)





- ► Target process crashes immediately
- DC: restarts the computer
- ► Apache: starts a new child server process or parent process halts
- ▶ No indicators to use to train machine learning algorithm



Under-Resource CPU



- ▶ Third party application consumed all CPU time
- Virtual Machine (VM) resources were reduced
- Results
 - Both cases resulted in same behavior
 - ▶ Slower response times for both the DC and Apache web server
 - Target process would not fail



Memory Corruption



- Different from fault-injection in that it corrupts heap-space instead of program memory
- DC: corrupted the user database
- Apache: corrupted web content
- Results
 - ► Same as fault injection: either would not fail, or would crash immediately with no warning signs





- Third party application consumed all available memory
- Only fault load that caused failure with indicators present in log messages prior to failure
- Trained two statistical models (SVM, and Boosted Decision Trees)
- As expected, both predictors performed adequately before software update, then poorly after
- ► After re-training with newly generated data performance once again was adequate



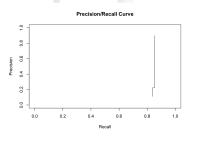


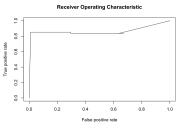
- What is adequate?
 - ▶ Naïve predictor predicts non-failure prone at all times
 - Currently no form of prediction is taking place in operational environment
 - ▶ Machine learning classification algorithms evaluated using confusion matrix at best F-Measure, Receiver Operating Characteristic (ROC), Area Under the Curve (AUC), and Precision/Recall Curves [1, 5]



Support Vector Machine (SVM) Performance AFT

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- (a) Precision/Recall Curve.
- (b) ROC Curve (AUC = 0.8664).

Figure: Test data performance of the SVM prediction method on failure data obtained by consuming all available memory until target application fails.

- ▶ Before software update, AUC: 0.8664
- ► After re-training, AUC: N/A (highest F-Measure: 0.4380)



Support Vector Machine (SVM) Performance AFII

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Table: Confusion matrix on test data created before software updates on threshold with highest F-Measure (0.8739) using SVM.

Actual

	Fail	No-Fail
Fail	52	6
No-Fail	9	607



Boosted Decision Tree Performance





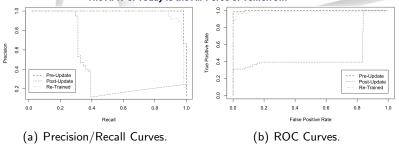


Figure: Performance of the boosting prediction method on data generated by consuming all available memory until target application fails.

- ▶ Before software update, AUC: 0.9984
- ▶ After software update, AUC: 0.4854
- After re-training, AUC: 0.9801



Boosted Decision Tree Performance I



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Table: Confusion matrix on test data created before software updates on threshold with highest F-Measure (0.9917) using boosting.

Actual

	Fail	No-Fail
Fail	60	0
No-Fail	1	412



Boosted Decision Tree Performance II



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Table: Post-update failure data confusion matrix on threshold with highest F-Measure (0.4691) using model trained on failure data generated before software update.

Actual

	Fail	No-Fail
Fail	19	1
No-Fail	42	222



Boosted Decision Tree Performance III



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Table: Post-update failure data confusion matrix on threshold with highest F-Measure (0.9355) using model trained on failure data generated after software update.

Actual

	Fail	No-Fail
Fail	58	5
No-Fail	3	218





- Extended AFP presented can predict realistic failure in production systems
- Capable of adapting to underlying system changes
- Vulnerability to certain types of failure can come and go, consequently, all fault loads should be used





- ► Further explore how best to implement fault injection and its true impact
- Integrate real failure data
- Further validation and automation
- Implement and make operational





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Questions?





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- [2] I. Irrera, M. Vieira, and J. Duraes, "Adaptive failure prediction for computer systems: A framework and a case study," in Proceedings of the 2015 IEEE 16th International Symposium on High Assurance Systems Engineering (HASE 2015), pp. 142–149, 2015.
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- [4] P. Jordan, C. Van Patten, G. Peterson, and A. Sellers, "Distributed powershell load generator (D-PLG): A new tool for dynamically generating network traffic," in *Proceedings of* the 6th International Conference on Simulation and Modeling Methodologies, Technologies, and Applications (SIMULTECH 2016), pp. 195–202, July 2016.
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