CSCI E-82
Advanced Machine Learning, Data Mining & Artificial Intelligence
Lecture 4

Probability, Statistics, Regression
Time Series Part I

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Fall 2018

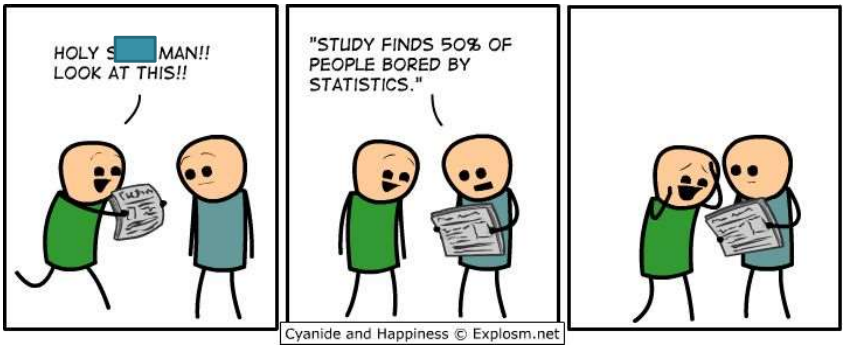
Administrivia

- HW2 – how is it going?
- Topic Presentations
  - Accepting groups of 2 or 3
  - Sign up using the same Google spreadsheet
  - Welcome to keep your partner or switch
    - Please talk to your existing partner regardless
  - Goal: 15 minute presentation
    - Will schedule presentations shortly but you will have a week to prepare from them
  - Need to select a moderately narrow topic
    - I will review topics on the sheet.
    - First sign-ups for a given topic win

1D Data Statistics

Let's Review Statistics

- Boringem.org



Zoom Sign-in Times (min after hour) N=36

14	23	27
15	23	27
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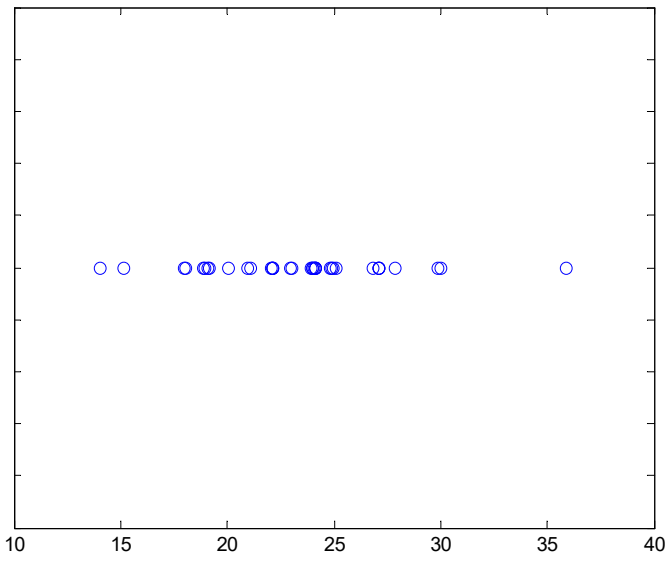
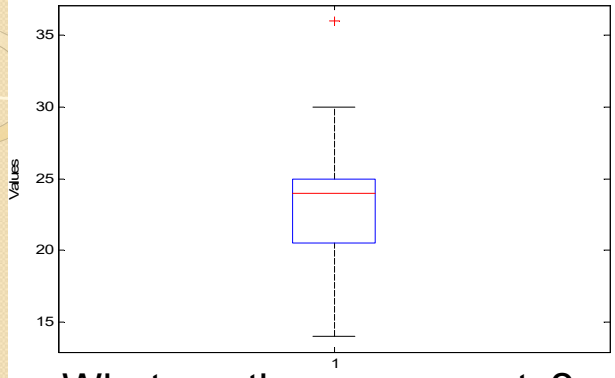
Plot (with jitter)

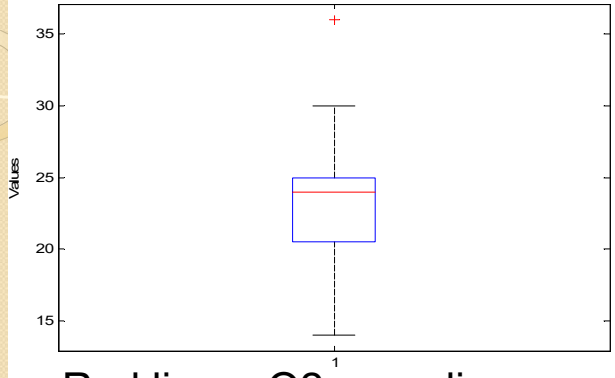


Box-Whisker Plot



- What are the components?

Box-Whisker Plot



- Red line = Q2 = median
- Box = Q1 to Q3
- Whiskers vary but might be:
  - Q1 - 1.5 IQR and Q3 + 1.5 IQR where
  - IQR = Inter Quartile Range = Q3-Q1

Sample Statistics & Robustness

- Mean $\bar{\bar{x}} = \frac{1}{N}\sum_{i=0}^{N} x_i$
- Median =
  - x_i that is middle value of sorted X of odd N
  - $(x_i + x_{i+1})/2$ that is average of 2 central points
- Range = max(X) – min(X)
- Sample variance $s^2 = \frac{\sum_{i=1}^{N}(x_i - \bar{\bar{x}})^2}{N-1}$
- Robustness = immunity to outliers
- Which of these are robust?

Sample Statistics?

- Mean $\bar{\bar{x}} = \frac{1}{N}\sum_{i=0}^{N} x_i$
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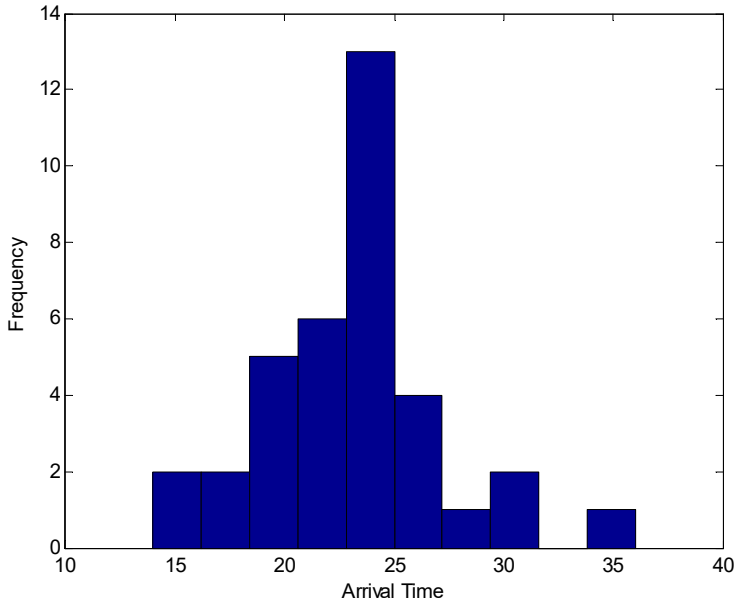
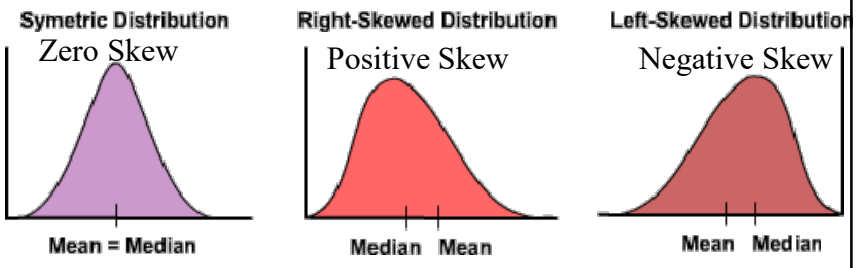
- Why are these “sample” statistics?

Histogram

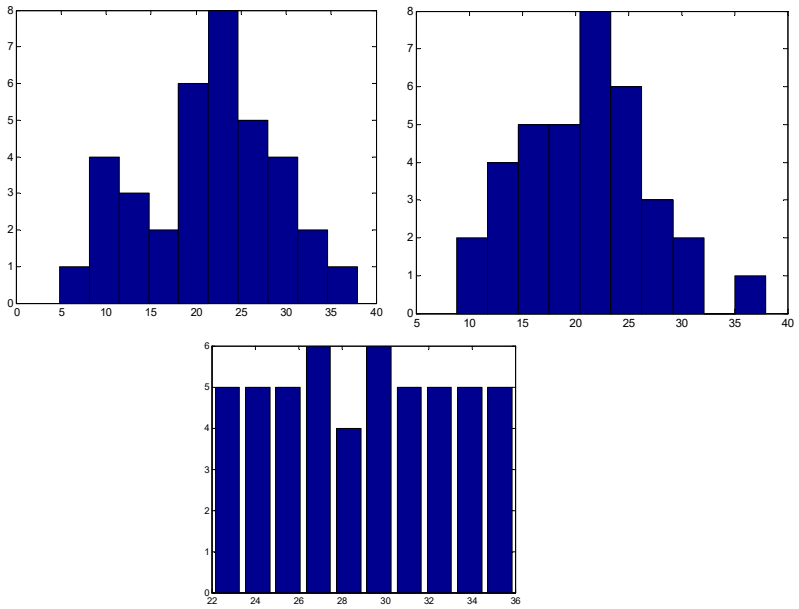


Skewness



- $Skewness = \frac{3(mean - media\ )}{s}$
- $Skewness = \frac{\sum(X_i - mean)^3}{(N-1)s^3}$
- N samples of X
- s = sample standard deviation
- https://onlinecourses.science.psu.edu/stat100/node/10

Modality ~ # of peaks



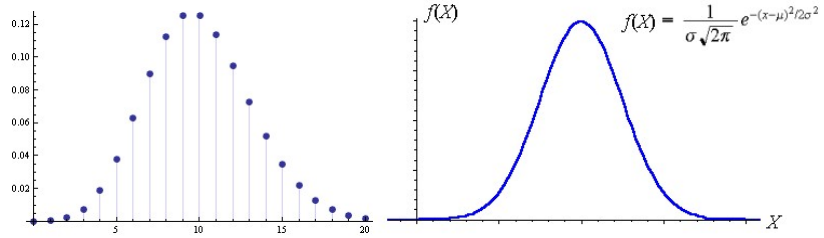
Distributions

Random Variable

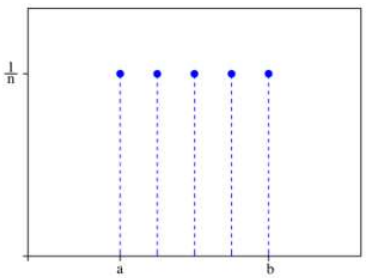
- Variable that takes on a specific value
- Member of a group
- Group values are described according to a frequency distribution
- Types
  - Discrete
  - Continuous
- Frequently drawn from a distribution

Probability Mass/Densities Function

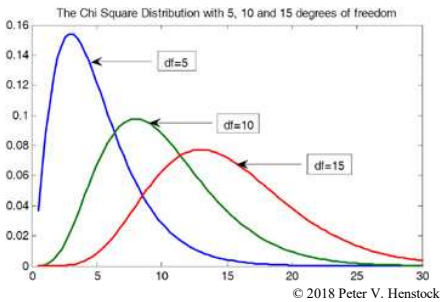
Gaussian or Normal PMF (left), PDF (right)



Uniform PMF



Chi-squared PDF



Common density functions

- Uniform(a,b)
  - $f(x) = \frac{1}{b-a}$ for $x \in [a, b]$
- Bernoulli(p) for p in [0,1]
  - f(0) = 1-p = failure f(1) = p = success
- Binomial(n, p) = sum n Bernoulli trials
  - $f(x) = \binom{n}{x} p^x p^{n-x} \quad x = 0, \ldots n$
- Normal (Gaussian) distribution $N(\mu, \sigma)$
  - $f(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp(-\frac{(x-\mu)^2}{2\sigma^2})$

Other Discrete/Continuous densities

- http://aleph0.clarku.edu/~djoyce/ma218/distributions.pdf

Distribution	Type	Mass/density function $f(x)$	Mean μ	Variance σ^2
UNIFORM(n)	D	$1/n$, for $x = 1, 2, \ldots, n$	$(n+1)/2$	$(n^2-1)/12$
UNIFORM(a, b)	C	$\frac{1}{b-a}$, for $x \in [a, b]$	$\frac{a+b}{2}$	$\frac{(b-a)^2}{12}$
BERNOULLI(p)	D	$f(0) = 1-p, f(1) = p$	p	$p(1-p)$
BINOMIAL(n, p)	D	$\binom{n}{x} p^x (1-p)^{n-x}$, for $x = 0, 1, \ldots, n$	np	npq
GEOMETRIC(p)	D	$q^{x-1}p$, for $x = 1, 2, \ldots$	$1/p$	$(1-p)/p^2$
NEGATIVEBINOMIAL(p,r)	D	$\binom{x-1}{r-1} p^r q^{x-r}$, for $x = r, r+1, \ldots$	r/p	$r(1-p)/p^2$
HYPERGEOMETRIC(N,M,n)	D	$\frac{\binom{M}{x}\binom{N-M}{n-x}}{\binom{N}{n}}$, for $x = 0, 1, \ldots, n$	np	$np(1-p)$
POISSON(λt)	D	$\frac{1}{x!}(\lambda t)^x e^{-\lambda t}$, for $x = 0, 1, \ldots$	λt	λt
EXPONENTIAL(λ)	C	$\lambda e^{-\lambda x}$, for $x \in [0, \infty)$	$1/\lambda$	$1/\lambda^2$
GAMMA(λ, r)	C	$\frac{1}{\Gamma(r)} \lambda^r x^{r-1} e^{-\lambda x}$	r/λ	r/λ^2
GAMMA(α, β)		$= \frac{x^{\alpha-1} e^{-x/\beta}}{\beta^\alpha \Gamma(\alpha)}$, for $x \in [0, \infty)$	$= \alpha\beta$	$= a\beta^2$

Other Discrete/Continuous densities

- http://aleph0.clarku.edu/~djoyce/ma218/distributions.pdf

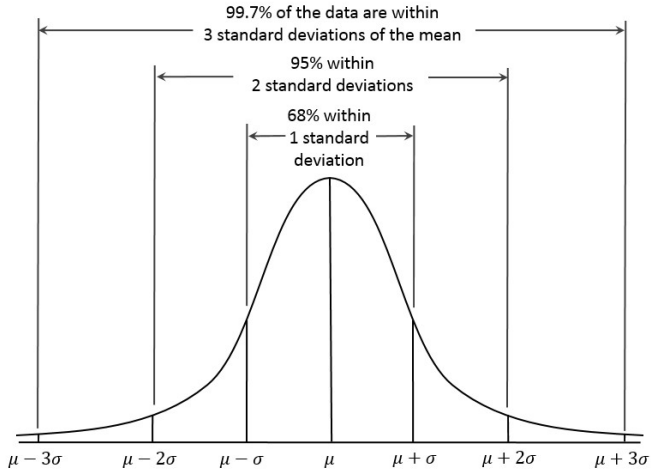
$\text{BETA}(\alpha,\beta)$	C	$\frac{1}{\mathrm{B}(\alpha,\beta)}\,x^{\alpha-1}(1-x)^{\beta-1}$, for $0 \le x \le 1$	$\frac{\alpha}{\alpha+\beta}$	$\frac{\alpha\beta}{(\alpha+\beta)^2(\alpha+\beta+1)}$
$\text{NORMAL}(\mu,\sigma^2)$	C	$\frac{1}{\sigma\sqrt{2\pi}}\exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right)$, for $x \in \mathbf{R}$	μ	σ^2
$\text{CHISQUARED}(\nu)$	C	$\frac{x^{\nu/2-1}e^{x/2}}{2^{\nu/2}\Gamma(\nu/2)}$, for $x \ge 0$	ν	2ν
$\mathrm{T}(\nu)$	C	$\frac{\Gamma(\frac{\nu+1}{2})}{\sqrt{\pi\nu}\,\Gamma(\frac{\nu}{2})\,(1+x^2/\nu)^{(\nu+1)/2}}$ for $x \in \mathbf{R}$	0	$\nu/(\nu-2)$
$\mathrm{F}(\nu_1,\nu_2)$	C	$\frac{1}{\mathrm{B}(\frac{\nu_1}{2},\frac{\nu_2}{2})}\,\frac{(\frac{\nu_1}{\nu_2})^{\nu_1/2}x^{\nu_1/2-1}}{(1+\frac{\nu_1}{\nu_2}x)^{(\nu_1+\nu_2)/2}}$ for >0	$\frac{\nu_2}{\nu_2-2}$	$\frac{2\nu_2^2(\nu_1+\nu_2-2)}{\nu_1(\nu_2-2)^2(\nu_2-4)}$

Properties of PMF/PDF

- prob(x) = p(x) = f(x) for discrete
- p(x $\in$ [a,b]) = $\sum_{i=a}^{b} f(x_i)$ for discrete
- p(x $\in$ [a,b]) = $\int_a^b f(x_i)\,dx$ for continuous
- $\sum_{-\infty}^{\infty} f(x_i) = 1$ $\quad\quad$ $\int_{-\infty}^{\infty} f(x_i)dx = 1$

How to use this?

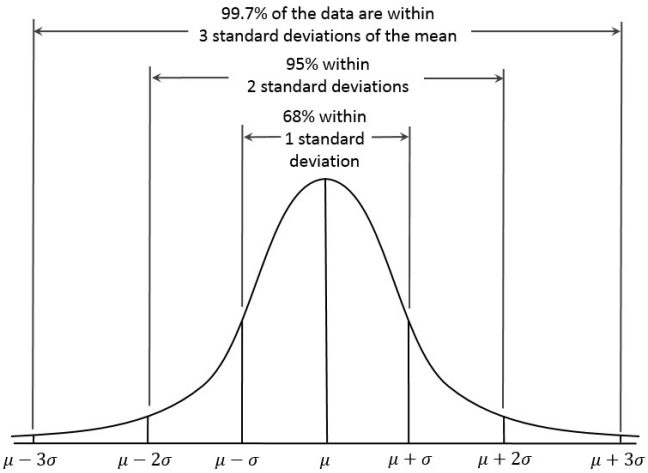
- Einstein had 160 IQ which is N(100,15)
- P(X >=160) = $\int_{160}^{\infty} f(x)dx$



https://en.wikipedia.org/wiki/68%E2%80%9395%E2%80%9399.7_rule#/media/File:Empirical_Rule.PNG

How to use this?

- What is probability of being within 1 stdev of "average"?

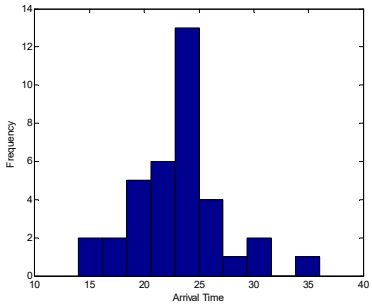


https://en.wikipedia.org/wiki/68%E2%80%9395%E2%80%9399.7_rule#/media/File:Empirical_Rule.PNG

Statistics from PMF

- $Mean = \ \mu = \sum_{i=0}^{N} p_i x_i$
- $Var = \ \sigma^2 = \sum_{i=0}^{N} p_i (x_i - \mu)^2$

Why bother with PDF/PMFs?



- Provide an abstraction of actual sample histogram (normalized)
  - Avoids issues of outliers, etc.
- Data compression: N pts → parameters
- Enables statistical analyses

Randomness

Characteristic	Pseudo-Random Number Generators	True Random Number Generators
Efficiency	Excellent	Poor
Determinism	Determinstic	Nondeterministic
Periodicity	Periodic	Aperiodic

- https://www.random.org/randomness/

Normal Distribution

- If X and Y are random variables from a normal distribution, X+Y is also normal
- If you take many independent random variables from any single distribution, the sum approximates a normal distribution
  - Central Limit Theorem (with caveats)

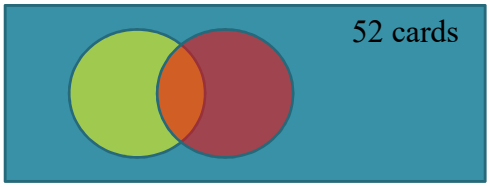
Probabilities

Random Variable

- Variable that takes on a specific value
- Member of a group
- Group values are described according to a frequency distribution
- Types
  - Discrete
  - Continuous
- Frequently randomly drawn from a distribution

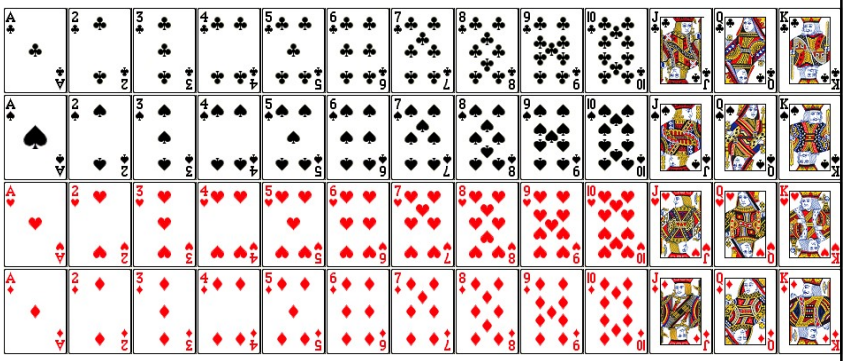
Probability Functions

- P(x) = probability of x occurring
  - Depends on the space of possibilities
- P(x) = 1 – P(~X)



- P(spades) = ?
- P(~spades) = ?
- P(Red “Royalty”)

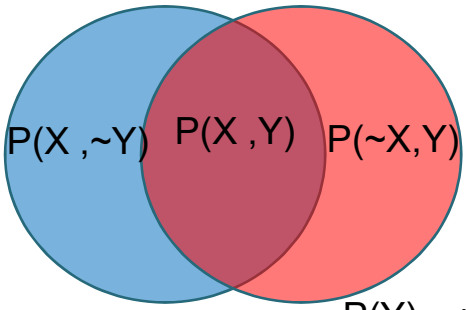
Deck of Cards



- http://www.milefoot.com/math/discrete/counting/cardfreq.htm

Joint Probabilities

- P(X,Y) = P(X and Y)
- P(X or Y) = P(X) + P(Y) – P(X and Y)



P(X) = blue circle

P(Y) = red circle

Joint Probabilities

- If X and Y are independent
  - P(X,Y) = P(X)P(Y)
- Example 1
  - X = probability of flipping coin
  - Y = probability of rolling a die (dice)
- Example 2
  - X = probability of grass is wet
  - Y = probability of rain

What does this imply statistically?

A major airlines company received an anonymous bomb threat. To figure out ways of reducing the risk, a team was assembled. One of the members was a statistician. After careful thought and calculations, he handed a sealed bag to the airlines company and ordered them to put this bag in their plane during every journey. After a few journeys, the flight team were intrigued, and decided to open the bag. Inside, they found a bomb. They quickly confronted the statistician and asked for an explanation. He replied, "Well. Statistics show that there is a 1 in a 1,000,000 chance of a bomb being on a plane. But for 2 bombs to be on the same plane, the chances are only 1 in a 1,000,000,000,000."

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This is a joke. Neither the course staff nor Harvard endorses carrying bombs on planes

Conditional Probabilities

- P(X|Y) = Probability of X “given” Y
- P(X|Y) = P(X,Y) / P(Y)

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- P(X|Y) = Probability of X “given” Y
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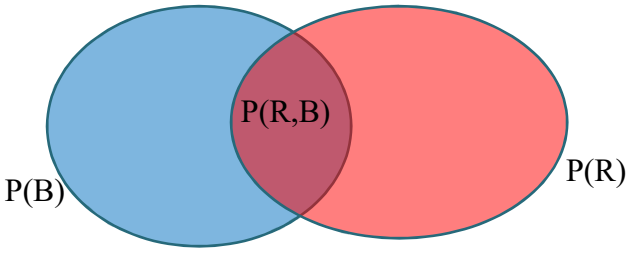
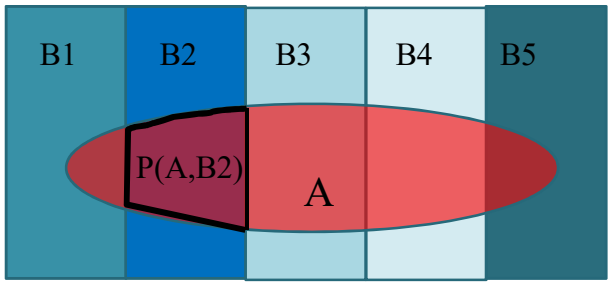
- Probability in blue given it’s in red?



Visual Idea

- P(A) = $\sum_{i=0}^{n} P(A \mid B_i)P(B_i)$

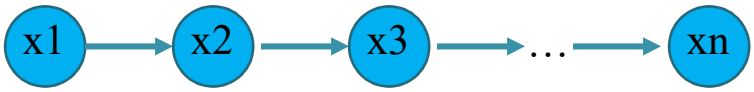


- Region overlap: P(B2, A)
- P(B2,A) = P(A|B2)P(B2)
- If we add up all intersections over B's:
  - P(A) = $\sum_{i=0}^{n} P(A \mid B_i)P(B_i)$

Basic Rules for Probabilities

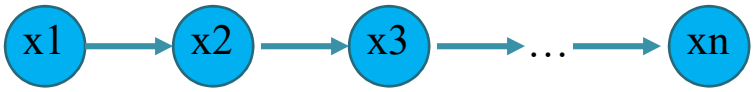
- Sum Rule:
  - P(A U B) = P(A) + P(B) – P(A $\cap$ B)
- Product Rule:
  - P(A $\cap$ B) = P(A,B) = P(A|B)P(B) = P(B|A)P(A)
- Joint→Marginal
  - P(A) = $\sum_{i=0}^{n} P(A, B_i)$
  - P(A) = $\sum_{i=0}^{n} P(A \mid B_i)P(B_i)$

Chain Rule



What is the probability of this whole thing?

Chain Rule



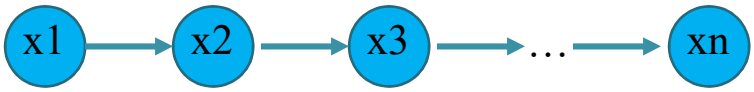
What is the probability of this whole thing?

P(x1,x2,…xn)

How can we compute this using conditional probabilities?

P(X1)*

Chain Rule



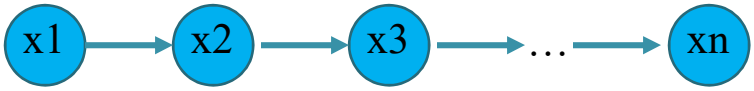
What is the probability of this whole thing?

P(x1,x2,…xn)

How can we compute this using conditional probabilities?

P(X1)*P(X2|X1)

Chain Rule



What is the probability of this whole thing?

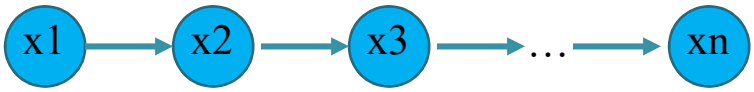
P(x1,x2,…xn)

How can we compute this using conditional probabilities?

P(X1)*P(X2|X1)*P(X3|X1,X2)…

…

Chain Rule



What is the probability of this whole thing?

P(x1,x2,…xn)

How can we compute this using conditional probabilities?

P(X1)*P(X2|X1)*P(X3|X1,X2)…

…P(Xn | X1..XN-1)

Bayes Rule

Bayes Rule

Thomas Bayes 1702-1761
Presbyterian minister in UK

Wikipedia

- $P(h|e) = \frac{P(e|h)P(h)}{P(e)}$
- Basis of classifiers
- Basis of network inferences
- Basis of structuring information or expert systems

Bayes Rule

Thomas Bayes 1702-1761
Presbyterian minister in UK

Wikipedia

- $P(h|e) = \frac{P(e|h)P(h)}{P(e)}$
- $P(h|e) = \frac{P(h,e)}{P(e)}$ $P(h,e) = P(e|h)P(h)$

Components of Bayes Rule

- $P(hyp|data) = \frac{P(data|hyp)P(hyp)}{P(data)}$
- p(data|hyp) = p(data, hyp) / p(hyp)
- What is p(hyp|data) if hyp and data are independent?

Conditional Independence

- P(X,Y|Z) = P(X|Z)P(Y|Z)
  - "X is independent of Y given Z"
  - X and Y are conditionally independent
- Clearly an extension of the general independence
  - P(A,B) = P(A)P(B)
- If X and Y are independent, can we say they are conditionally independent?

Conditional Independence Examples

- https://www.quora.com/What-are-examples-of-events-that-are-independent-but-not-conditionally-independent-and-vice-versa

- Good examples to navigate:
  - [in]dependence
  - conditional [in]dependence

  - P(x|y) if independent p(x) →
  - P(x|y) = P(x,y) / P(y) = P(x)P(y)/P(y) → P(x)

Components of Bayes Rule

- $P(hyp|data) = \frac{P(data|hyp)P(hyp)}{P(data)}$

- P(hyp) = "Prior"
  - Prior probability of a hypothesis
- P(hyp|data) = "posterior"
  - Probability of hypothesis given data
- P(data|hyp) = "likelihood"
  - Probability of data fitting a given hypothesis
- P(data) = normalizing constant
  - Data is same across all hypotheses

2 Random Variables

Two random variables

- Mean values are the same
- Standard deviations are the same

- Relationship:
  - Correlation Coefficient
  - Covariance

Covariance

- Cov(X,Y) = σ(X,Y) = E[X-E(X)] E[Y-E(Y)]
- Cov(X,Y) $= \frac{1}{N-1}\sum_{i=1}^{N}(X_i - \bar{X})(Y_i - \bar{Y})$
- Sample Covariance(X,Y)
  - $= \frac{1}{N-1}\sum_{i=1}^{N}(X_i - \bar{X})(Y_i - \bar{Y})$

Covariance

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  - $= \frac{1}{N-1}\sum_{i=1}^{N}(X_i - \bar{X})(Y_i - \bar{Y})$
- What is the Cov(X,X)?

Covariance

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- Cov(X,Y) $= \frac{1}{N-1}\sum_{i=1}^{N}(X_i - \bar{X})(Y_i - \bar{Y})$
- Sample Covariance(X,Y)
  - $= \frac{1}{N-1}\sum_{i=1}^{N}(X_i - \bar{X})(Y_i - \bar{Y})$
- What is the Cov(X,X)?
- If X and Y are independent, what is Cov(X,Y)?

Covariance Matrix

- Let $X = [X_1 \ldots X_n]^T$ be a column vector
- Covariance matrix is written with Σ
- $\Sigma_{ij} = \text{cov}(X_i, X_j) = E[(X_i-\mu_i)(X_j-\mu_j)]$

$$\Sigma = \begin{bmatrix} \mathrm{E}[(X_1 - \mu_1)(X_1 - \mu_1)] & \mathrm{E}[(X_1 - \mu_1)(X_2 - \mu_2)] & \cdots & \mathrm{E}[(X_1 - \mu_1)(X_n - \mu_n)] \\ \mathrm{E}[(X_2 - \mu_2)(X_1 - \mu_1)] & \mathrm{E}[(X_2 - \mu_2)(X_2 - \mu_2)] & \cdots & \mathrm{E}[(X_2 - \mu_2)(X_n - \mu_n)] \\ \vdots & \vdots & \ddots & \vdots \\ \mathrm{E}[(X_n - \mu_n)(X_1 - \mu_1)] & \mathrm{E}[(X_n - \mu_n)(X_2 - \mu_2)] & \cdots & \mathrm{E}[(X_n - \mu_n)(X_n - \mu_n)] \end{bmatrix}.$$

- $\Sigma = E(XX^T) - \mu\mu^T$

Covariance Matrix

- Let $X = [X_1 \ldots X_n]^T$ be a column vector
- Covariance matrix is written with Σ
- $\Sigma_{ij} = \text{cov}(X_i, X_j) = E[(X_i - \mu_i)(X_j - \mu_j)]$

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- If X1…Xn are all independent, what does the covariance matrix look like?

Sample Covariance Matrix example

X	Y
1	3
4	2
2	4
5	3
3	3
6	3

- Compute mean of X
- Compute mean of Y
- Sample cov of X, X
- Sample cov of Y, Y

Sample Covariance Matrix example

X	Y
1	3
4	2
2	4
5	3
3	3
6	3

- Compute mean of X
  - Sum(X)/6 = 3.5
- Compute mean of Y
- Sample cov of X, X
- Sample cov of Y, Y
- Sample cov of X, Y

Sample Covariance Matrix example

X	Y
1	3
4	2
2	4
5	3
3	3
6	3

- Compute mean of X
  - Sum(X)/6 = 3.5
- Compute mean of Y
  - Sum(Y)/6 = 3
- Sample cov of X, X
- Sample cov of Y, Y
- Sample cov of X, Y

Sample Covariance Matrix example

X	Y
1	3
4	2
2	4
5	3
3	3
6	3

- Compute mean of X
  - Sum(X)/6 = 3.5
- Compute mean of Y
  - Sum(Y)/6 = 3
- Sample cov of X, X
  - $[\Sigma (x\text{-}meanX)^2] / (N-1)$
- Sample cov of Y, Y
- Sample cov of X, Y

Sample Covariance Matrix example

X	Y
1	3
4	2
2	4
5	3
3	3
6	3

- Compute mean of X
  - Sum(X)/6 = 3.5
- Compute mean of Y
  - Sum(Y)/6 = 3
- Sample cov of X, X
  - $[\Sigma (xi\text{-}meanX)^2] / (N-1) = 3.5$
  - $[\Sigma (xi-3.5)^2] / (6-1) = 3.5$
- Sample cov of Y, Y
  - $[\Sigma (yi\text{-}meanY)^2] / (N-1) = 0.4$
- Sample cov of X, Y

Sample Covariance Matrix example

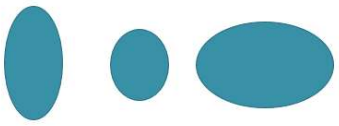
X	Y
1	3
4	2
2	4
5	3
3	3
6	3

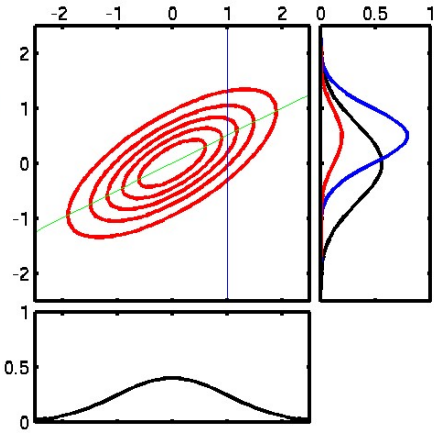
- Compute mean of X
  - Sum(X)/6 = 3.5
- Compute mean of Y
  - Sum(Y)/6 = 3
- Sample cov of X, X
  - $[\Sigma (x\text{-meanX})^2] / (N-1) = 3.5$
  - $[\Sigma (x-3.5)^2] / (6-1) = 3.5$
- Sample cov of Y, Y
  - $[\Sigma (y\text{-meanY})^2] / (N-1) = 0.4$
- Sample cov of X, Y
  - $[\Sigma (x\text{-meanX})(y\text{-meanY})] / (N-1) = -0.4$

2D Normal Distributions

Normal Distribution

- What can we say about the covariance of these?



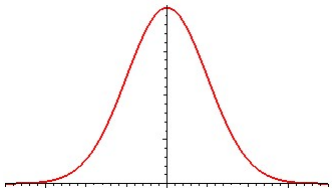


Normal Distribution

- What can we say about the covariance of these?

http://www.atmos.washington.edu/~hakim/591/code/

Gaussian or Normal Distribution

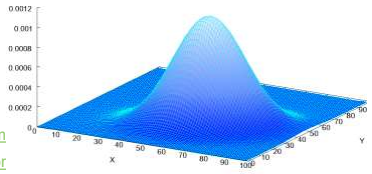


Univariate Gaussian

$$f(x) = \frac{1}{\sqrt{2\pi}} e^{-\frac{(\mu - x)^2}{2\sigma^2}}$$

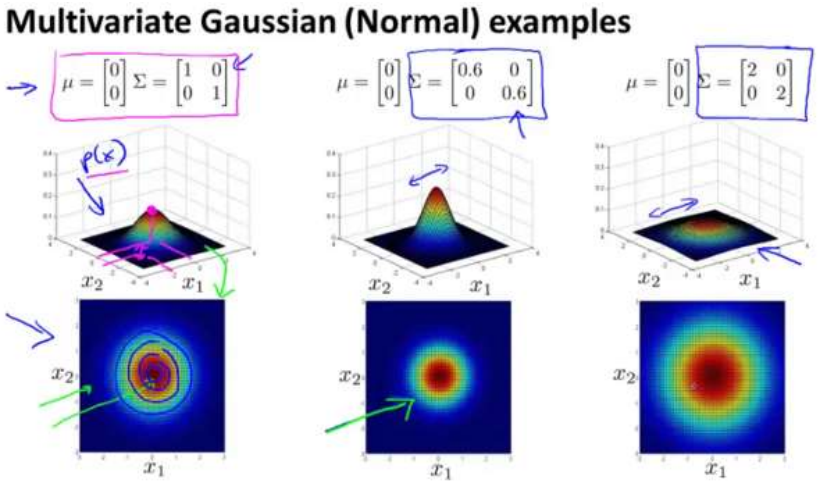
Multivariate Gaussian

$$f_{\mathbf{x}}(x_1, \ldots, x_k) = \frac{1}{\sqrt{(2\pi)^k |\boldsymbol{\Sigma}|}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^{\mathrm{T}} \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})\right)$$



- http://mydov.blogspot.com/2014/06/anomaly-detection.htm
- https://www.quora.com/What-is-an-intuitive-explanation-for multivariate-Gaussian-distribution-aka-multivariate-normal

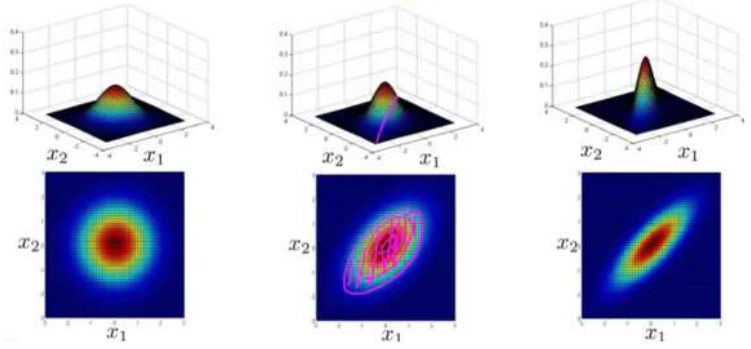
Zero Covariance Term



Non-zero Covariance Term

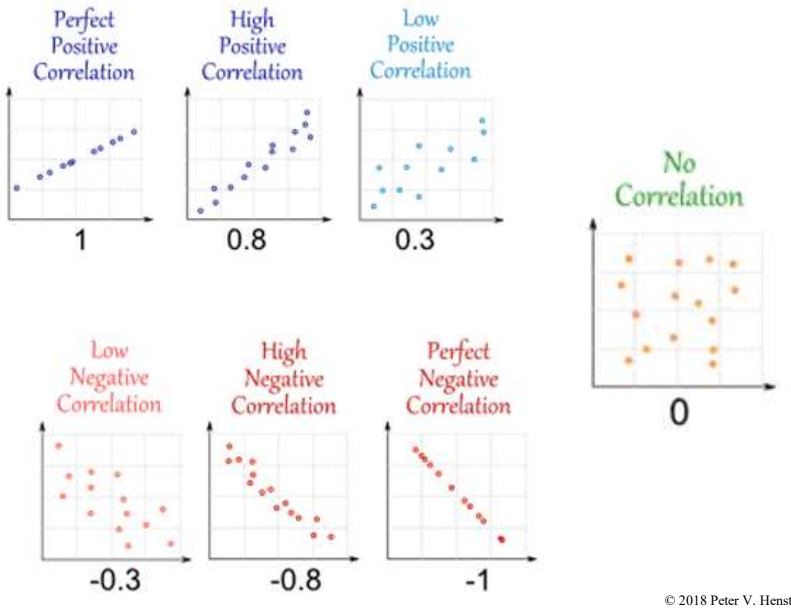
The above figure shows, that by changing the values of μ, the overall position of the contour profile

$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ $\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix}$ $\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0.8 \\ 0.8 & 1 \end{bmatrix}$



Correlation

https://www.mathsisfun.com/data/correlation.html

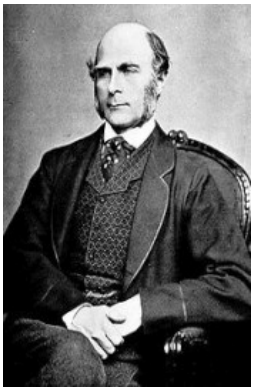


Correlation coefficient

- r = CorrCoef(X,Y) = cov(X,Y) / ($s_X s_Y$)
  - Technically, the Pearson corr. Coef.
- $r = \frac{\sum(x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum(x_i - \bar{x})^2 \sum(y_i - \bar{y})^2}}$
- Range of values for correlation is [-1, 1]
- No units

Regression

Sir Francis Galton



- 1822-1911 Victorian England
- Statistician & scientist
  - Regression
  - Standard deviation
  - Correlation
  - Psychometrics
  - Fingerprint classification
  - Weather map and scientific meteorology
- Coined terms in our lexicon:
  - Eugenics
  - Nature vs. Nurture

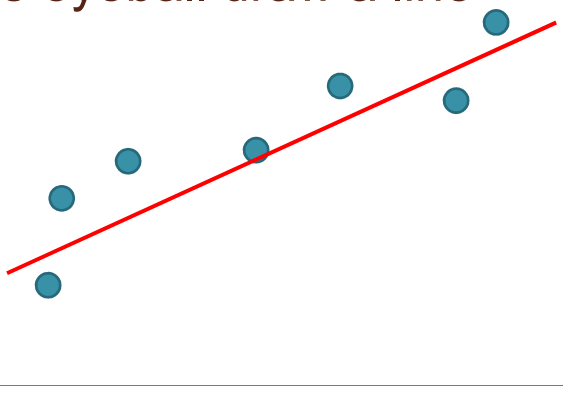
Types of Learning

- Supervised
  - Provide output labels/values & input features
- Unsupervised
  - Provide only input features
- Semi-supervised learning
- Reinforcement learning

Let's model data

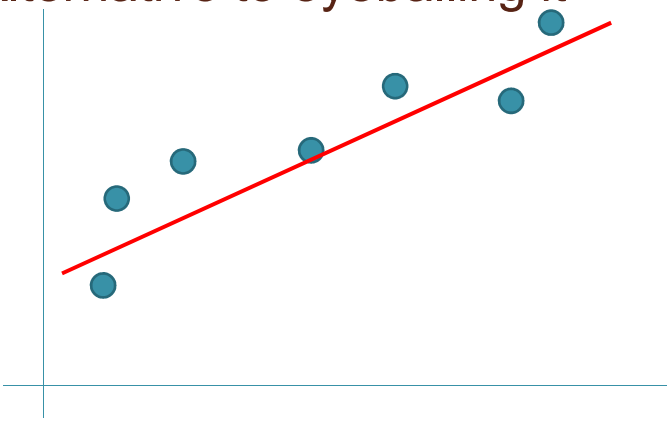
- What would be the simplest model for this type of result

Let's eyeball draw a line



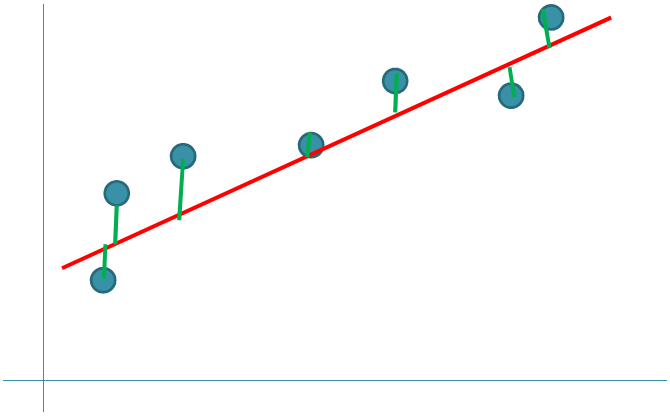
- How is this model?
- Does it fit the data well?

Alternative to eyeballing it



- How could we come up with a description of what a good linear fit would be for this set of blue dots?

Residuals



- Residual = estimate on line – actual blue
- Residuals are drawn with green lines

Regression vs. PCA

- Is this regression line fit the same one as the principal component?

Generative Model

- What is it?

Generative Model

- What does generative mean?
  - Could try to model the residuals and come up some useful ideas on model
  - Instead we are going to create a model that assumes the points were distributed by a generating model
  - Specifically, we start with points on a line and randomly shift the points according to a distribution
- $y_i = w_0 + w_1 x_i + \varepsilon_i$
- $\varepsilon_i \sim N(\text{mean}=0, \text{stdev}=\sigma)$
- What does this have to do with residuals?

Residuals

- Residuals come from a normal distribution centered on the line
- http://stats.stackexchange.com/questions/148803/how-does-linear-regression-use-the-normal-distribution

Residuals → Best Fit Model

- How can we use the residuals to come up with a best fit line?

- What would be a good function to optimize?

a) Σ residuals
b) Σ |residuals|
c) Σ [residuals]^2
d) Σ [yi - residuals]^2
e) Σ [residuals / yi]^2

Simple case

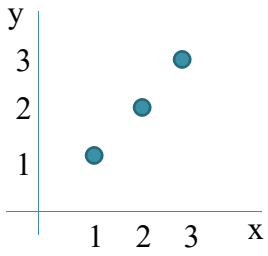
- Optimize the least squares function

- $SumsqError = \sum_{i=1}^{N} \epsilon_i^2$
- But $y_i = w_0 + w_1 x_i + \epsilon_i$ but we don't know the true weights so we estimate
- so $\epsilon_i = y_i - \widehat{w_o} - \widehat{w_1}\ x_i$
- $SumsqError = \sum_{i=1}^{N} (y_i - \widehat{w_o} - \widehat{w_1}\ x_i)^2$

- How can we minimize the error?
- How can we find the best $\widehat{w_0}$ and $\widehat{w_1}$?

Sanity check example

- Sumsq error = cost function = J
- Goal is to minimize J
- J = sum-square distance between
  - predicted y values of line given parameters
  - the actual y values
  - at each x point



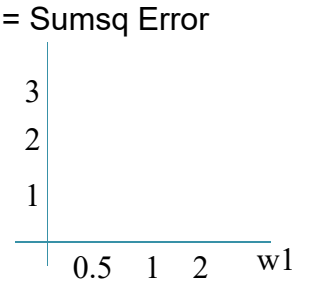
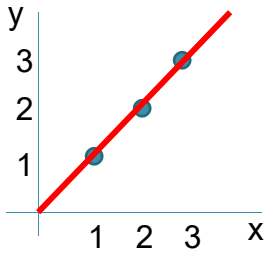
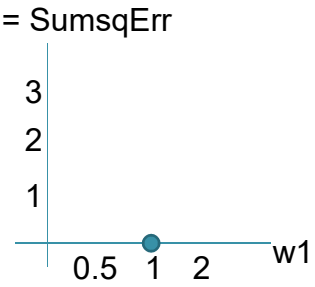


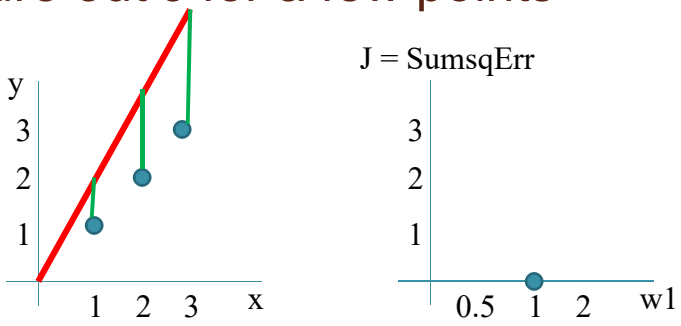
Figure out J for a few points





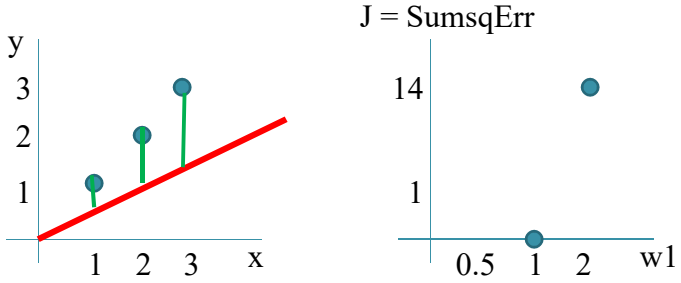
- Assume w0 = 0 (zero y-intercept)
- For w1 = 1:

Figure out J for a few points



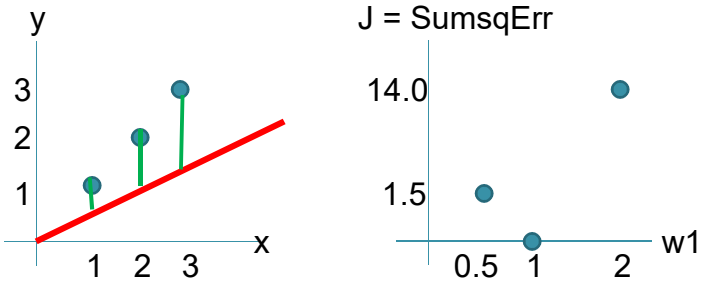
- Assume w0 = 0 (zero y-intercept)
- For w1 = 1: = 0
- For w1 = 2:

Figure out J for a few points



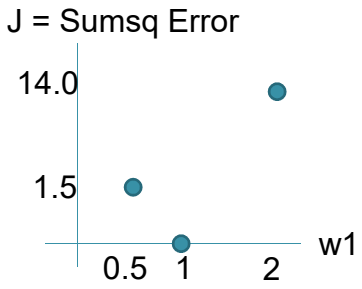
- Assume w0 = 0 (zero y-intercept)
- For w1 = 1: = 0
- For w1 = 2: $=(2-1)^2 + (4-2)^2 + (6-3)^2=14$
- For w1 = 0.5 =

Figure out J for a few points



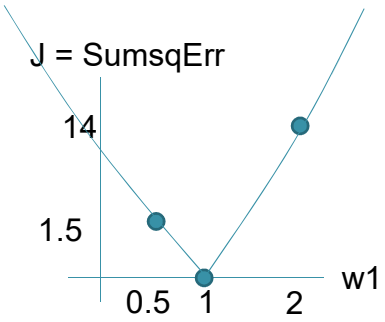
- Assume w0 = 0 (zero y-intercept)
- For w1 = 1: = 0
- For w1 = 2: $=(2-1)^2 + (4-2)^2 + (6-3)^2=14$
- For w1 = 0.5 = $(1-1/2)^2 + (2-1)^2 + (1.5-1)^2$ = 1.5

Modeling the error



What shape is J vs. w1?

- Parabola (badly drawn below)

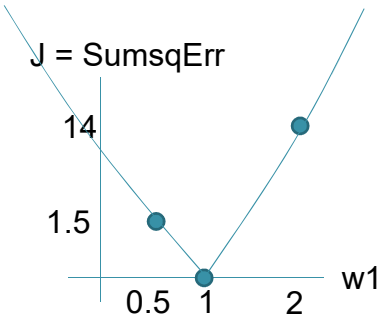


- Min value will be 0 in this case—why?
- How could we optimize the J as a function of w1?

Derivative Formulation

What shape is J vs. w1?

- Parabola (badly drawn below)



- Min value will be 0 in this case—why?
- How could we optimize the J as f(w1)?

Take derivative and set to 0

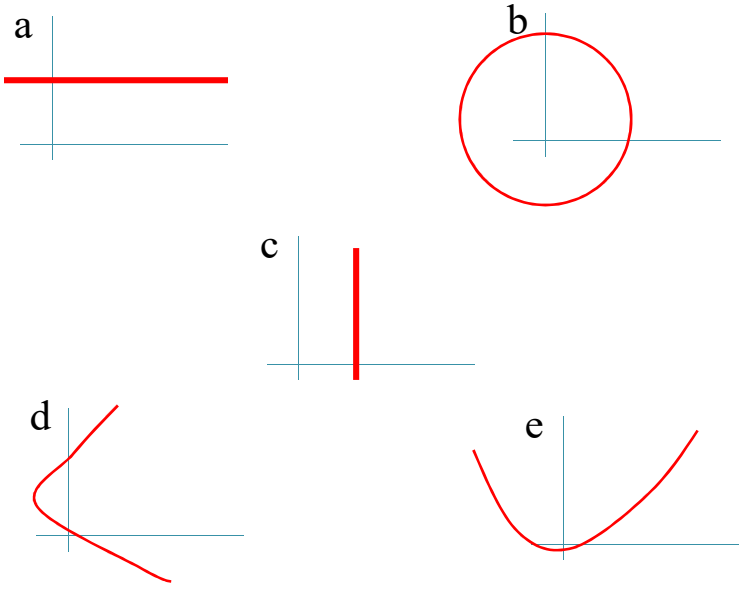
- $\sum_{i=1}^{N}(y_i - \widehat{w_o} - \widehat{w_1}\ x_i)^2$
- Differentiate with respect to….?

Take derivative and set to 0

- $\sum_{i=1}^{N}(y_i-\hat{y}_i\ )^2 = \sum_{i=1}^{N}(y_i-\widehat{w_o}\ -\widehat{w_1}\ x_i)^2$
- Differentiate with respect to the w_o & w_1
- $\frac{\partial y}{\partial w}\sum_{i=1}^{N}(y_i-\widehat{w_o}\ -\widehat{w_1}\ x_i)^2 =$
- $2\sum_{i=1}^{N}\ y_i-2N\widehat{w_o}\ -\widehat{w_1}\ \sum_{i=1}^{N}x_i\ )^2$
- $\widehat{w_o}\ = \frac{1}{N}[\sum_{i=1}^{N}\ y_i-\widehat{w_1}\ \sum_{i=1}^{N}x_i\ )]$
- $\widehat{w_1}\ =$ $\dfrac{\sum_{i=1}^{N}y_ix_i-\frac{\sum_{i=1}^{N}y_i\sum_{i=1}^{N}x_i}{N}}{\sum_{i=1}^{N}x_i^2-\frac{\left(\sum_{i=1}^{N}x_i\right)^2}{N}}$

http://isites.harvard.edu/fs/docs/icb.topic515975.files/OLSDerivation.pdf

Which work for linear regression?



Ordinary Least Squares vs. MLE

- Previous derived a generative model that was based on least-squares
- Reasonable approach

- MLE = maximum likelihood estimation
- Different framework for optimizing

- Likelihood = P(Data | hyp)
- MLE = arg max P(Data | hyp)
  - Select the parameters that maximize this quantity as our estimates

MLE Estimate

- Assume P(data$_i$ | hyp) are independent
- MLE = argmax $\prod_{i=1}^{N} P(data_i \mid hyp)$

- What is this P(data$_i$ | hyp) using our previous assumptions?

- argmax $\prod_{i=1}^{n} \frac{1}{(2\pi\sigma^2)^{1/2}} e^{-\frac{1}{2\sigma^2}(Y_i-\beta_0-\beta_1 X_i)^2}$

- What are we optimizing over in argmax?

MLE Optimizing

- Argmax $\prod_{i=1}^{n} \frac{1}{(2\pi\sigma^2)^{1/2}} e^{-\frac{1}{2\sigma^2}(Y_i-\beta_0-\beta_1 X_i)^2}$
- To make the math easy, take a log
- To optimize, take derivative with respect to the betas
- Result in this case will be identical to the least squares approach
  - MLE estimates equal to OLS in this case

MLE Estimate

- Assume P(data$_i$ | hyp) are independent
- MLE = argmax $\prod_{i=1}^{N} P(data_i \mid hyp)$
- What is this P(data$_i$ | hyp) using our previous assumptions?

Multiple Linear Regression

Multiple Linear Regression

- Previously had $y = w_0 + w_1 x_1$
- What if we had 3 or 10 variables?
- We can still use regression
- Here is a simple case:

$$Y = w_0 + w_1 x_1 + w_2 x_2 + \ldots w_k x_k = \Sigma w_i x_i = w^T x$$

Multiple Regression with Matrices

- Y = XW + e
- Y is Nx1 matrix
  - What do we usually call Y?

Multiple Regression with Matrices

- Y = XW + e
- Y is N x 1 matrix
- X is N x (k+1) include a column of 1s
- W is (k+1) x 1
- What do we usually call Y?

Multiple Regression with Matrices

- Y = XW + e

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- What do we usually call Y?
- What do we usually call X?

Multiple Regression with Matrices

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- What do we usually call Y?
- What do we usually call X?
- What do we usually call W?

Multiple Regression with Matrices

- Y = XW + e

- Y is N x 1 matrix (column vector)
- X is N x (k+1) include a column of 1s
- W is (k+1) x 1 matrix
- e is N x 1 column vector

- What are the rows and column referring to for the X?

Matrix Inverse

- For numbers:
  - Consider x * 1/x → 1
  - In a sense, 1/x is inverse of x
  - In a sense, x is inverse of 1/x

- For matrices
  - $A A^{-1} = I$ and $A^{-1}A = I$
  - Fairly easy for 2x2 matrices
  - Possible for 3x3 matrices by hand
  - Challenging for anything larger so use any linear algebra software or python

Matrix Inverse

- Do all numbers have an inverse?
- Do all matrices have an inverse?

Matrix Inverse

- Do all numbers have an inverse?
- Do all matrices have an inverse?
  - Officially, has to be a square matrix
  - (Note: there are pseudo inverses otherwise)
  - If it's square it also has to have "full rank"
    - Can't have rows that are products of each other
    - Can't have zero rows
    - Can't have rows that are weighted sums of any other rows
    - Determinant cannot be 0

Least Squares Estimate

- SSE = $e^T e$
  - Is this an inner product or outer product?
- e = Y-XW
- SSE = $(Y-XW)^T(Y-XW)$
- SSE = $(Y^T-W^TX^T)(Y-XW)$
  - Note that $(AB)^T = B^TA^T$
- SSE = $(Y^TY – W^TX^TY + W^TX^TXW - Y^TXW)$
  - The 2nd and 4th term are equivalent
    - Not obvious from the matrix format
    - True when you multiply them out

Least Squares Estimate

- SSE = $e^T e$
  - Is this an inner product or outer product?
- e = Y-XW
- SSE = $(Y-XW)^T(Y-XW)$
- SSE = $(Y^T-W^TX^T)(Y-XW)$
  - Note that $(AB)^T = B^TA^T$
- SSE=$(Y^TY – W^TX^TY + W^TX^TXW - Y^TXW)$
  - The 2nd and 4th term are equivalent
- SSE = $(Y^TY - 2Y^TXW + W^TX^TXW)$

Least Squares Estimate

- SSE = $(Y^TY - 2Y^TXW + W^TX^TXW)$
- How to minimize this?
- Derivative wrt W and set to 0
- d/dW→ $0 – 2X^TY + 2X^TXW = 0$
  - Note that d/dW of $U^TVW = V^TU$
  - Last term with the W's on either side is a quadratic which yields 2 and removal of W^T
  - $X^TXW = X^TY \rightarrow W = (X^TX)^{-1}X^TY$
  - $(X^TX)^{-1}X^T$ is the Moore-Penrose Pseudoinverse of X
- Why can't we just do an inverse of X?

Observation

- From before:
  - $Y = w_0 + w_1x_1 + w_2x_2 + \ldots w_kx_k = \Sigma w_ix_i$
- What does x_1 actually look like?
- If we modified it to be $3x_1$, what would happen to the overall equation?
- What if we used x_1^2 or cubed it to x_1^3 ?

Observation

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- What does x_1 actually look like?
- If we modified it to be $3x_1$, what would happen to the overall equation?
- What if we used x_1^2 or cubed it to x_1^3 ?
  - Obtain polynomial regression

Full multiple linear regression

- $Y = w_0 + w_1x_1 + w_2x_2 + \ldots w_kx_k = \Sigma w_ix_i$
- $Y = w_0 + w_1x_1 + w_2x_2 + \ldots w_kx_k + b_0x_1x_2 + b_1x_1x_3 + \ldots bzx_{k-1}x_k + c_0x_1x_2x_3 + \ldots$
- Y = sum of
  - Independent factors +
  - 2-way interactions +
  - 3-way interactions +
  - K-way interactions
- Can include squared, cubed, power terms

Hierarchy Principles

- Only found this is statistics and never machine learning
- Need to include all lower terms if you include a higher order term
- If you have x_1^3
  - Need to include x_1^2 as well as x_1
- If you have $x_1^2x_2$
  - Need to include x_1^2, x_1x_2, x_1, x_2

Further options

- $Y = \text{sqrt}(X_1^5X_2X_3^3X_4)$
- Can multiple linear regression work for this kind of model?
- What does Y look like?
- What is log(ab)? → log(a) + log(b)
- log(sqrt(x))? → 1/2log(x)

Big O notation

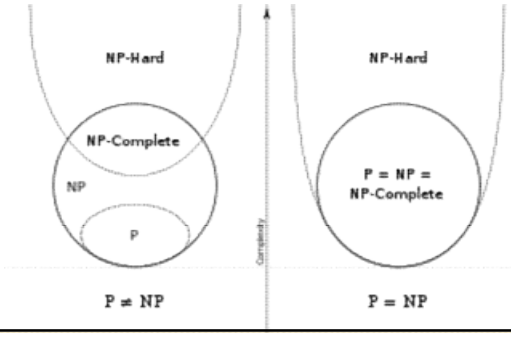
- Algorithms tend to be characterized by their approximate computational load
- Computation is a function of a parameter like n = size

- Sum of N numbers is O(N)
- Tree search is O(logN)

- We tend to round down so if the actual computation was $O(5N^3 + 4N + 17)$
  - Use just $O(N^3)$

Complexity

- P = polynomial
- NP = nondeterministic polynomial time
- NP-complete = NP and NP-hard
- NP-hard =
  - at least as hard as hardest problem in NP



https://en.wikipedia.org/wiki/NP-hard#/media/File:P_np_np-complete_np-hard.svg

Computational aspects

- Pseudoinverse
- Solution parameters = $(X^TX)^{-1}X^Ty$

- What is the computational requirement?

- Matrix addition?
- Matrix multiplication?
- Matrix inverse?

Gradient Descent

Gradient Descent

- Problem:
  - You are placed on a hill in fog
- Goal:
  - Find the bottom of the hill
- Method
  - How would you do that?

Gradient Descent

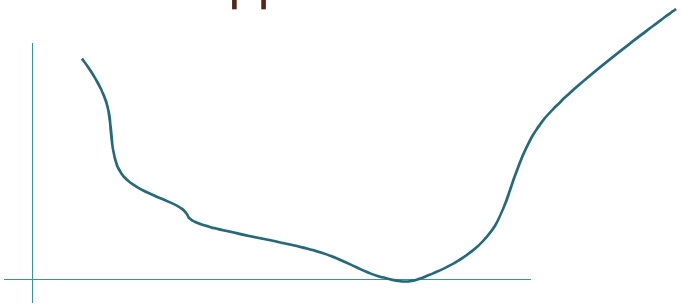
- Idea: you are placed on a hill in fog
  - Find the bottom of the hill

do {
- Figure out which way is “down”
- Move a certain distance in that direction

} until at lowest spot

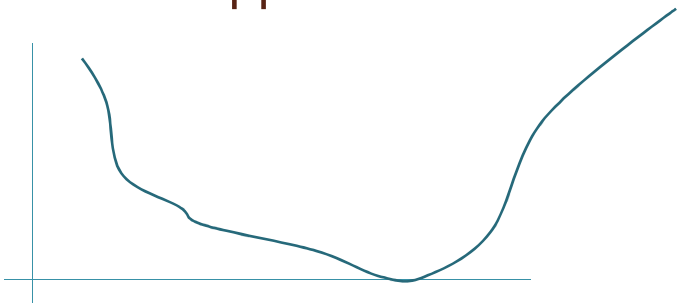
- What assumptions are we making?

Calculus Approach



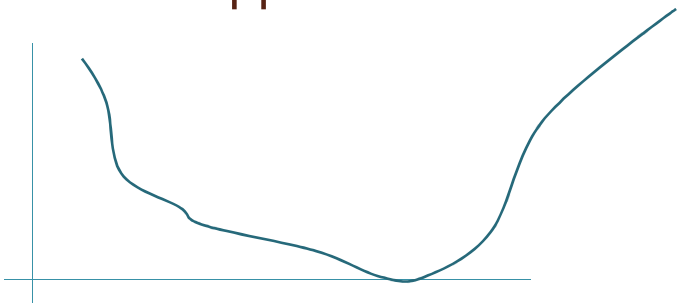
- Calculus tells us if that we have a function f then we need to do 2 things to find the minimum
  1)
  2)

Calculus Approach



- Calculus tells us if that we have a function f then we need to do 2 things to find the minimum
  1) Compute the derivative
  2) Check the concavity using 2nd derivative

Calculus Approach



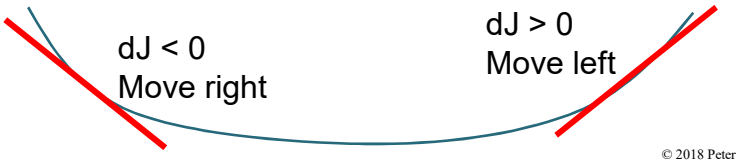
- Calculus tells us if that we have a function f then we need to do 2 things to find the minimum
  1) Compute the derivative
  2) Check the concavity using 2nd derivative

How do we actually locate the minimum?

General Gradient Descent

$$\mathbf{x}_{n+1} = \mathbf{x}_n - \gamma_n \nabla F(\mathbf{x}_n), \ n \geq 0.$$

- For a partial derivative of 1 variable
  - $w_{n+1} = w_n - \alpha \frac{\partial}{\partial w_n} J(w_n)$
  - α is the learning rate
  - J() is the cost function
  - Iteratively adjusting w_n with better estimates using the gradient of the cost function as the direction.



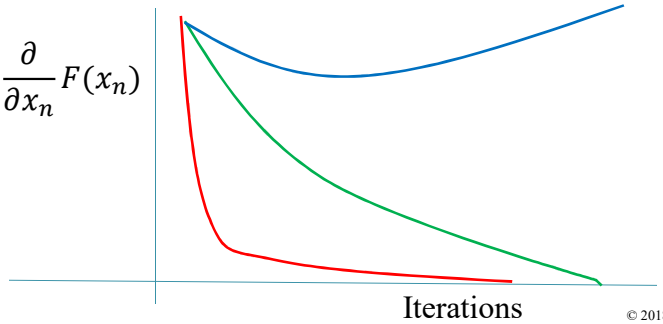
Diagnostics for Gradient Descent

- What should the gradient look like as a function of time (iterations)?
- Hint:
  - When should gradient descent end?

Diagnostics for Gradient Descent

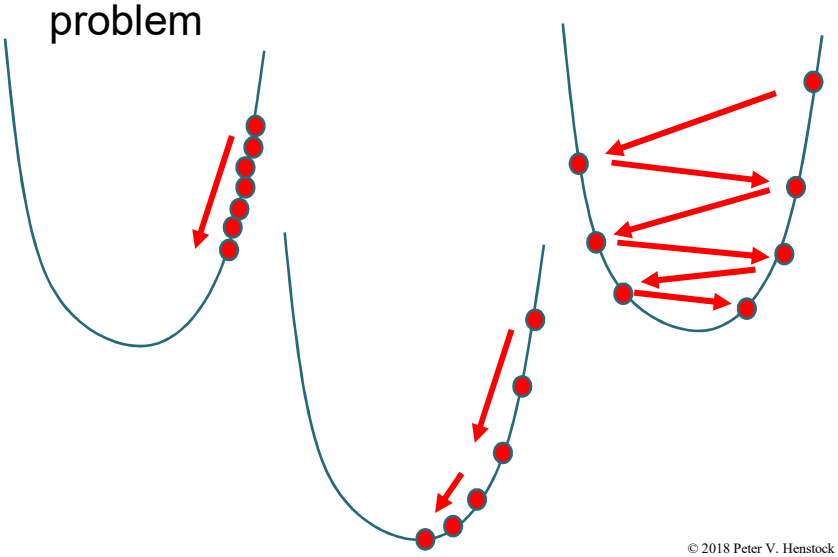
- What should the gradient look like as a function of time (iterations)?
- Hint:
  - When should gradient descent end?

$$\gamma \frac{\partial}{\partial x_n} F(x_n)$$



How large a learning rate?

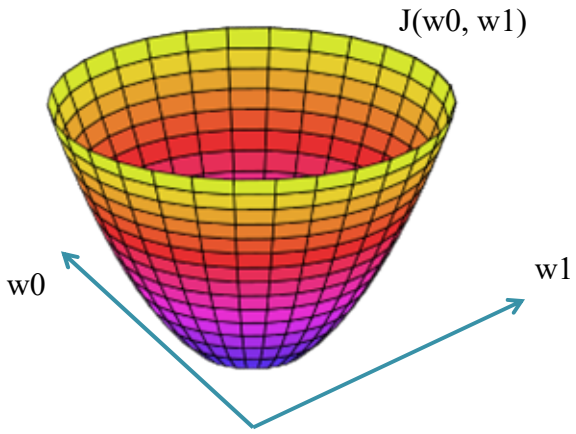
- It depends…because it's a Goldilocks problem



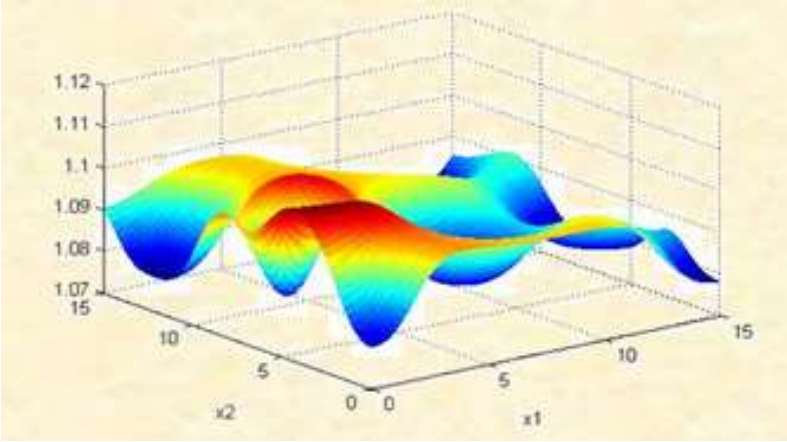
Gradient Descent

- Have an optimization function J we are trying to minimize
- Have 2 parameters w0 and w1
- Start with an initial guess of w0' and w1'
- Iteratively shift w0 and w1 in the direction to make J better until "done"

2D problem is same idea



Will Gradient Descent Work?



2D Gradient Descent

- For each loop
  - $w_1 \leftarrow w_1 - \alpha\, \partial J/\partial w_1$
  - $w_0 \leftarrow w_0 - \alpha\, \partial J/\partial w_0$
- Note: J is a function of w_0 and w_1
  - Be sure to update both new values using the older values
  - Do not update w_1 and use the updated w_1 to update w_0

2D Gradient Descent

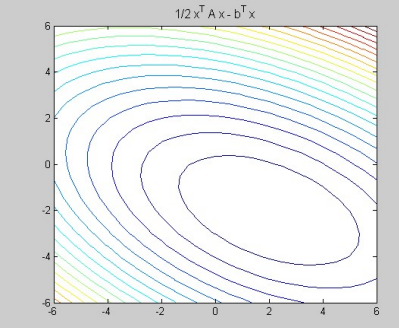
- For each loop
  - $w_1 \leftarrow w_1 - \alpha\, \partial J/\partial w_1$
  - $w_0 \leftarrow w_0 - \alpha\, \partial J/\partial w_0$
- $\partial J/\partial w_0 = 2\Sigma_i\, (w_1 x_i + w_0 - y_i)$
- $\partial J/\partial w_1 = 2\Sigma_i\, (w_1 x_i + w_0 - y_i) x_i$

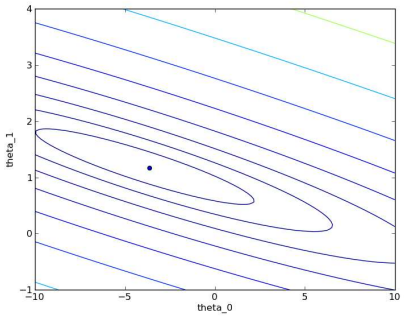
How to ensure achieved optimal?

How to ensure achieved optimal?

- Start with multiple starting points
- Typically try a few different learning rates and plot the change of gradient to ensure things are going the right direction

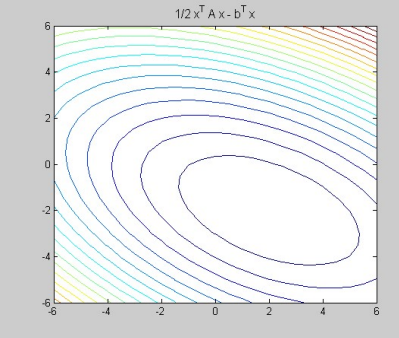
Which is easier for gradient descent?

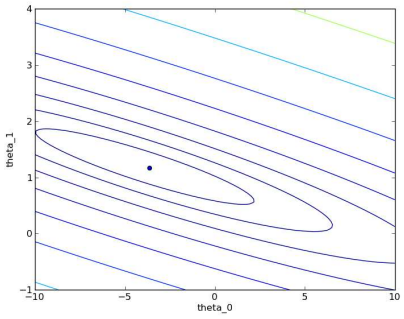




- http://www.informatik.uni-konstanz.de/fileadmin/informatik/ag-saupe/Webpages/lehre/na_08/Lab1/10_CG/html/myCG.html
- http://aimotion.blogspot.com/2011/10/machine-learning-with-python-linear.html

How to solve this problem?





- http://www.informatik.uni-konstanz.de/fileadmin/informatik/ag-saupe/Webpages/lehre/na_08/Lab1/10_CG/html/myCG.html
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Regression Diagnostics

Regression Process

- We load the data
- We perform a fit
- We're done!

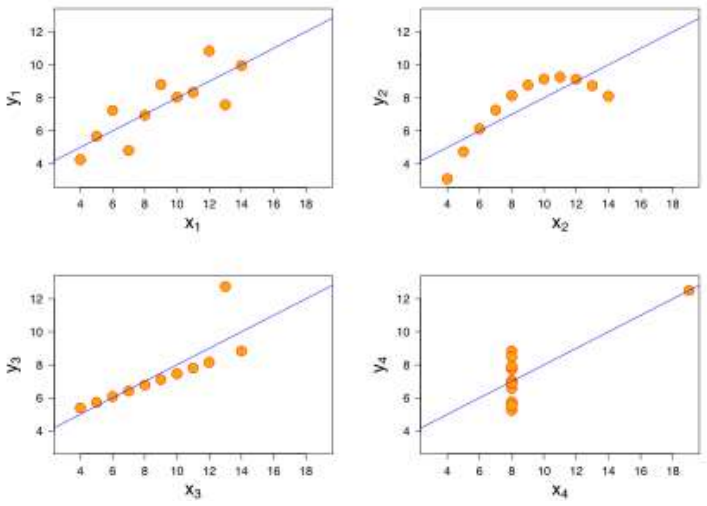
- What could go wrong?

Regression Process

- We load the data
- We perform a fit
- We're done!

- What could go wrong?
- Assumptions:
  - iid errors = independent & identically distributed
  - Common variance
  - N(0, variance)
  - Y and X are related

Classic Anscombe Example

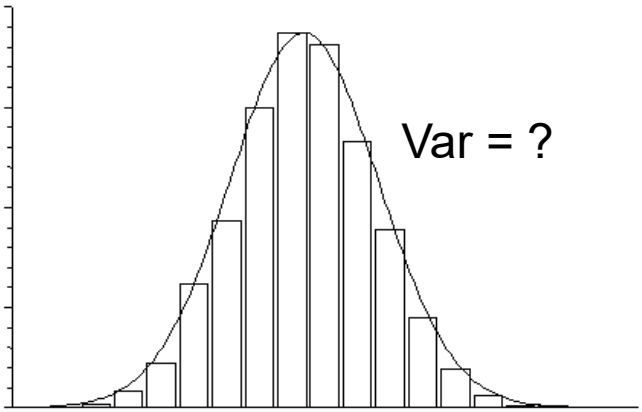


https://en.wikipedia.org/wiki/Anscombe%27s_quartet 1973
Anscombe, F. J. 1973. Graphs in statistical analysis. The American Statistician, 27, pp 17-21.

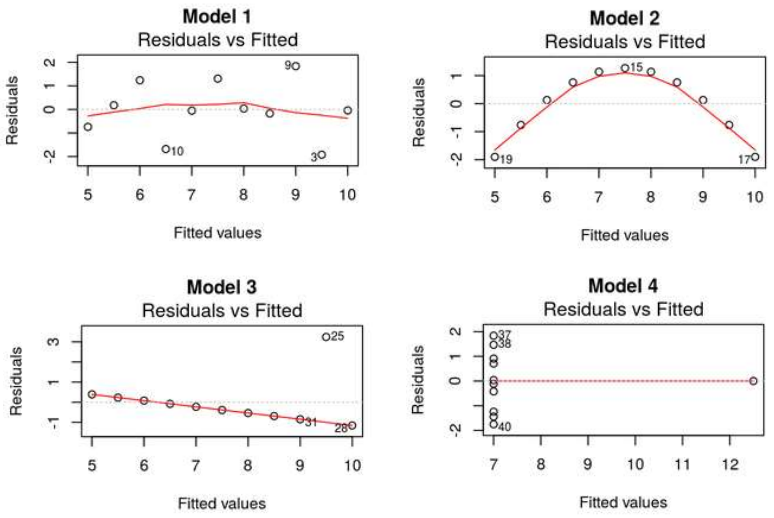
How can we diagnose the issues?

- Residuals should have a common variance
- Residuals should have a N(0, variance)
- Residuals should be iid

Histogram of Residuals



Residuals vs. X



Heteroscedascity

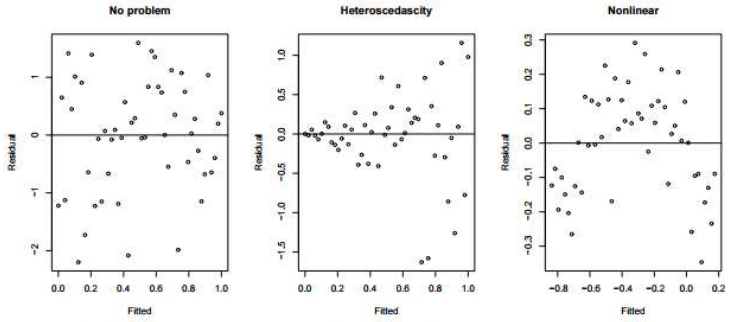


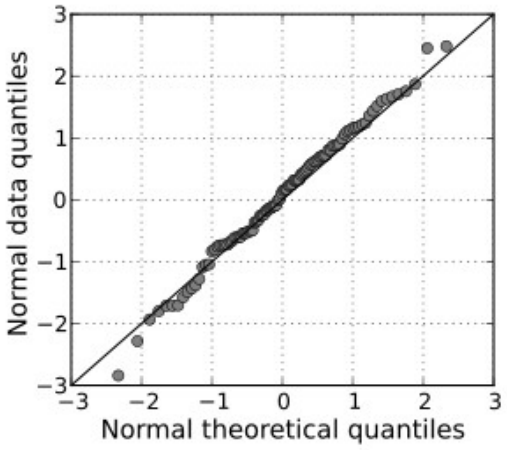
Figure 7.5: Residuals vs Fitted plots - the first suggests no change to the current model while the second shows non-constant variance and the third indicates some nonlinearity which should prompt some change in the structural form of the model

- Faraway: "Practical Regression and ANOVA using R" July 2002

Data Transformations

- Common transformations include:
  - Log
  - Sqrt
  - Arcsin
- What do we apply these to?
  - Y?
  - X?

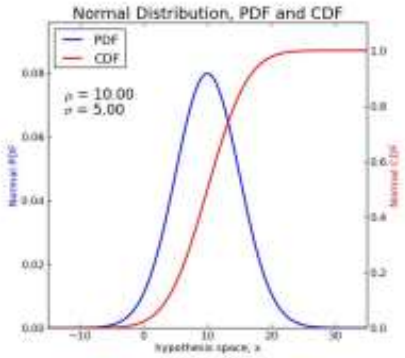
Quantile-Quantile (Q-Q) Plot



- Look for linear relationship
- Should have at least [-1 1] linear

CMF = cumulative mass function

- Prob(a to b) = $\sum_a^b pmf$
- Cmf(x) = cumulative pmf = $\sum_{-\infty}^{x} pmf$
  - Maps from x → [0, 1] probability
- InvCmf(p) maps [0, 1] to an x-value



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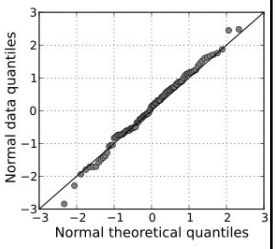
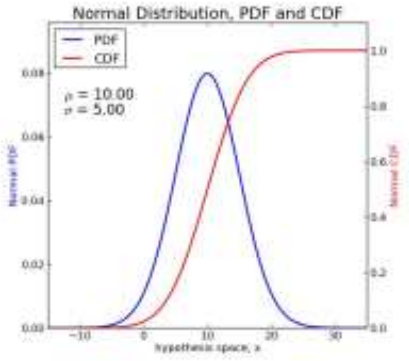
Quantile-Quantile (Q-Q) Plot



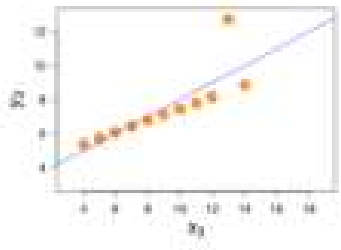
- Sort the residuals (y-axis)
  - Use Order Statistics
- Sample invnormal cdf evenly
  - Sample at probabilities 1/(n+1), 2/(n+1)…n/n+1
  - Convert the probabilities back to x-values for the x-axis
- Plot the sampled invcdf vs. residuals

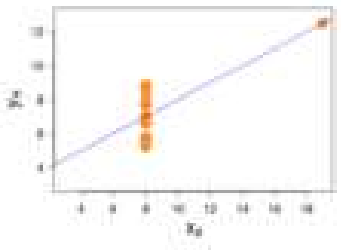
Q-Q plot intuition



- Central value of the distribution (50%)
  - Should match the mean
- Value mean ± stdev should line up
- Method works for other distributions too

What about these cases?





Leverage Points

- A single isolated point might have a lot of influence on the overall fit
- What characteristics might go into such a point?

Leverage Points

- A single isolated point might have a lot of influence on the overall fit
- What characteristics might go into such a point?

1) Shifts the line
2) Isolated in x from other points

Leverage Points

1) Shifts the line
2) Isolated in x from other points

- $h_{ii} = \frac{1}{n} + \frac{(x_i - \bar{\bar{x}})^2}{\sum_{j=1}^{n} (x_j - \bar{\bar{x}})^2}$

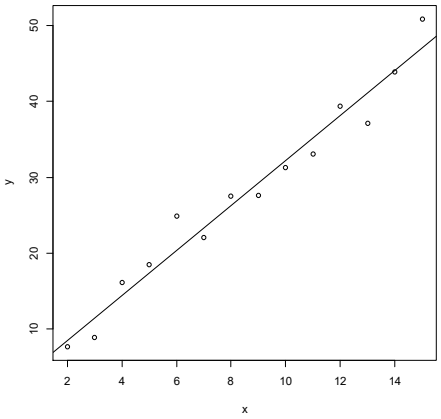
- High leverage point if > 4/n

- Bad leverage point: distorts line (outlier)
- Good leverage point: consistent with line

R Example for Regression

What does R do?

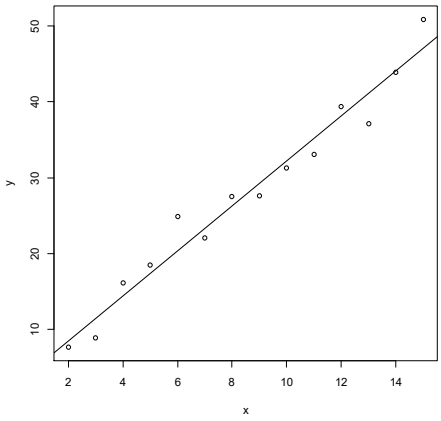
```
x <- 2:15
y <- 1:length(x)*3 + 5 +
rnorm(length(x))*2.5
plot(x,y)

fit <- lm(y ~ x)
summary(fit)
hist(resid(fit))
plot(fit)
```

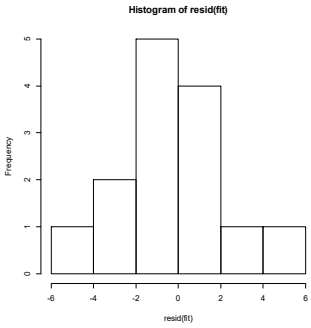


R call

```
Call:
lm(formula = y ~ x)

Residuals:
    Min      1Q  Median      3Q     Max
-2.2088 -1.3598  0.3992  1.3213  1.6921

Coefficients:
            Estimate Std. Error t value Pr(>|t|)
(Intercept)   1.0393     0.9639   1.078    0.302
x             3.0456     0.1025  29.724 1.31e-12 ***
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 1.545 on 12 degrees of freedom
Multiple R-squared:  0.9866,    Adjusted R-squared:  0.9855
F-statistic: 883.5 on 1 and 12 DF,  p-value: 1.314e-12
```

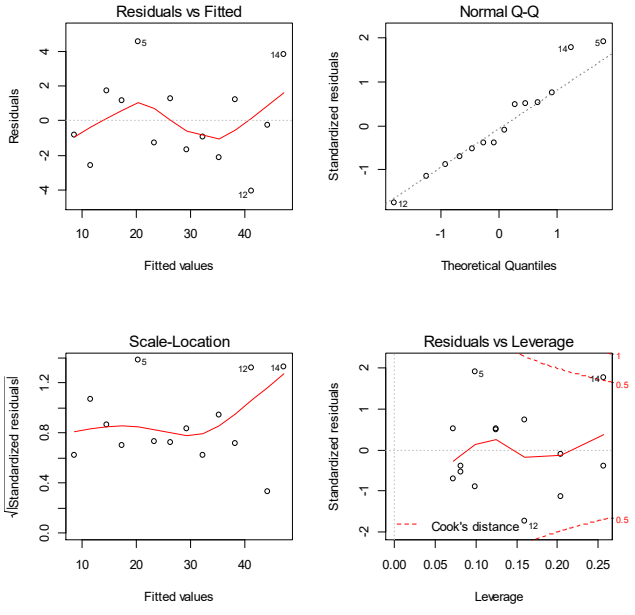
Original data with fit





- Checking fit and residual distribution

Regression diagnostics



Actual Fit Values

```
Call:
lm(formula = y ~ x)

Residuals:
    Min      1Q  Median      3Q     Max
-2.2088 -1.3598  0.3992  1.3213  1.6921

Coefficients:
            Estimate Std. Error t value Pr(>|t|)
(Intercept)   1.0393     0.9639   1.078    0.302
x             3.0456     0.1025  29.724 1.31e-12 ***
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 1.545 on 12 degrees of freedom
Multiple R-squared:  0.9866,    Adjusted R-squared:  0.9855
F-statistic: 883.5 on 1 and 12 DF,  p-value: 1.314e-12
```


Time Series Modeling

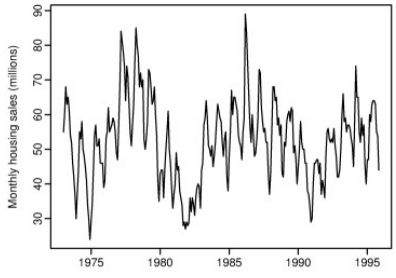
http://www.artnet.com/artists/ert%C3%A9/complete-numbers-suite-set-of-10-HLI_PTOIsn_8aIdkjAWWWw2

Why Do Time Series Analysis?

- Model of data
- Interpretation
- Forecasting
- Control
- Hypothesis testing
- Simulation

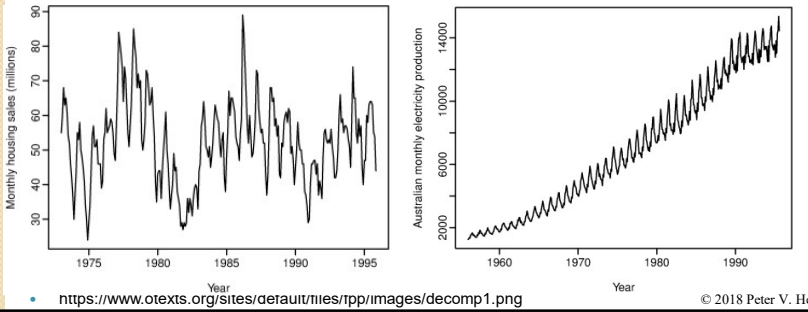
Time Series Modeling

- Previously with regression:
  - Y ~ f(X)
  - X samples are i.i.d.
  - Generative model: Y is f(x) + N(0,sigma)
- Why don't just use Y ~ f(t) ?



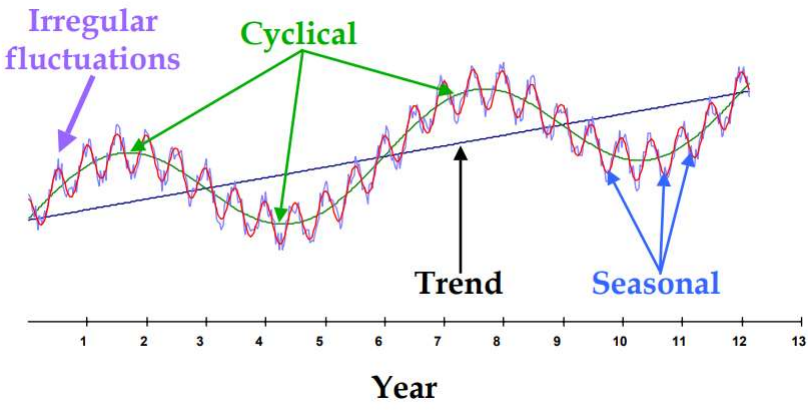
Signal vs. Noise Issue

- Regression model would probably smooth the data to provide a good trend
- Decomposition:
  - Could extract the trend and seasonality
  - Are they additive or multiplicative?
  - Then model the remainder which is what?



- https://www.otexts.org/sites/default/files/fpp/images/decomp1.png

Time Series Components



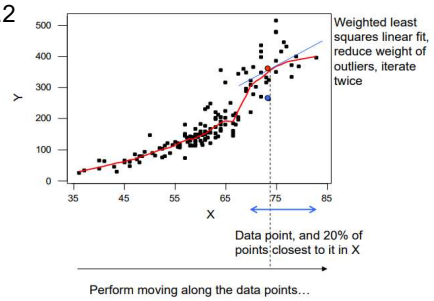
- http://www.statoek.wiso.uni-goettingen.de/veranstaltungen/graduateseminar/SmoothingMethods_Narodzonek-Karpowska.pdf

Smoothing

- Moving Average: average over last m
  - $x(n) = \frac{1}{m}\sum_{k=0}^{m-1} x(n-k)$
- Weighted Moving Average: avg over last m
  - $x(n) = \frac{1}{\sum_{k=0}^{m} w_k}\sum_{k=0}^{m} w_k x(n-k)$
  - Weights usually sum to 1
  - Use this to heavily weight more recent
- Exponential Smoothing
  - Single: s(n) = αx(n) + (1-α)s(n-1)
  - Double: s(n) = αx(n) + (1-α)[s(n-1) + b(n-1)]
    - b(n) = β[s(n)-s(n-1)] + (1-β) b(n-1)

Lowess smoothing

- Lowest (weighted) regression
- Non-parametric model
- http://sites.stat.psu.edu/~fxc11/Stat462_STABLE/Lect12_lowess.pdf
  - Smoothing param 0.2 = fraction of points
  - Degree 1 = linear



Weighted least squares linear fit

$$\min_{\beta_0,\beta_1} \sum_{j\in N_i} w_j (y_j - (\beta_0 + \beta_1 x_j))^2$$

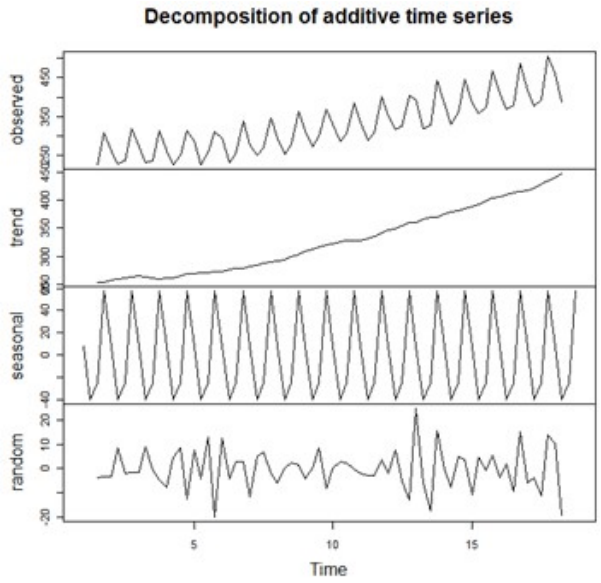
Weight function

$$w_i = \left(1 - \left(\frac{d(x_j, x_i)}{\max_{\ell \in N_i} d(x_\ell, x_i)}\right)^3\right)^3$$

F. Chiaromonte

3

Signal Decomposition

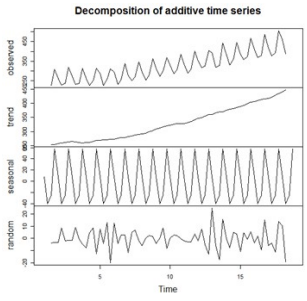


https://onlinecourses.science.psu.edu/stat510/node/69

In this lecture and next

- Remove the trend
- Figure out seasonality*
- Figure out frequency*
- Model the "random"

- * = next lecture



Time Series Framework

- Need a model to explain random signals
- Existing models may not be explainable by the Y~f(t) + noise
- Existing models may not be predictable
- But, we know something about Y
- Framework: random signals
  - Y(t) characterized by a distribution at each t

Framework is Random Sequence

- $x_1, x_2, \ldots x_n$ (Changed notation to x)
- Need to exploit the order of sequence
- As random, it cannot be predicted
- Deterministic process: known / predictable
- Stochastic or Random process:
  - System that generates all possible random sequences of which we have a realization $x_1 \ldots x_n$ with the specific random values
  - Goal is to model the process
  - Model process as random since it's either random or we do not have a better model

Time Series Review

- Random Process
  - w(k) = 0, 2, 0, -1, 2, -1, 2, 1, 0, 0, 1, 2, -1, -2
- AR Model
  - $x(k) = \phi_1 x(k-1) + \phi_2 x(k-2) + \ldots \phi_p x(k-p) + w(k)$
  - Let's use a 1st order model $\phi_1 = 0.9$
  - x(0) = 0
  - x(1) = 0.9*0 + 2 = 2
  - x(2) = 0.9*2 + 0 = 1.8
  - x(3) = 0.9*1.8 + -1 = 0.62

Time Series Review

- Random Process
  - w() = 0, 2, 0, -1, -2, -1, 2, 1, 0, 0, 1, 2, -1, -2
- MA Model (clearer notation)
  - $x(k) = w(k) + \theta_1 w(k-1) + \theta_2 w(k-2) + \ldots \theta_p w(k-p)$
  - Let's use a 2nd order model $\theta_1 = 0.7$, $\theta_2 = 0.3$
  - Assume x(-1) = 0
  - x(0) = 0
  - x(1) = 2 + 0.7(0) = 2
  - x(2) = 0 + 0.7(2) + 0.3(0) = 1.4
  - x(3) = -1 + 0.7(0) + 0.3(2) = -0.4

Ergodic Process

- Time estimate converges to the true estimate as N → infinity
  - Ergodic mean
    - True if 1/N Σ x(k) = E[x(k)] = μ as N→infinity
- If we take a reasonably long sample,
  - Then we can infer the statistical properties of the whole sequence

Strict Stationary

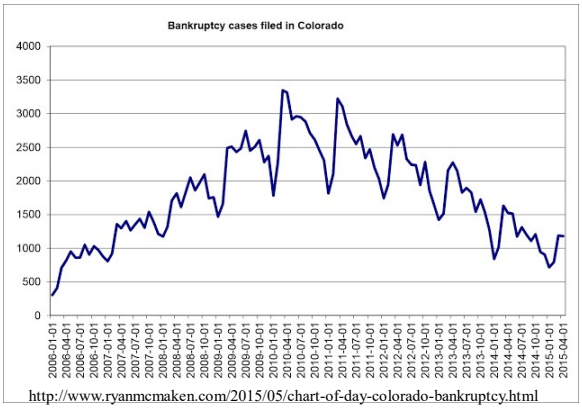
- If joint distribution of N observations is invariant to time shifts
- $F_{x(k1)}(x1) = F_{x(k1+T)}(x1)$
  - All have same distribution regardless of T

(Wide Sense or Weak) Stationarity

- Few real systems are strictly stationary
  - Joint distribution of all vectors of d dimensions remains the same for any fixed d
- Weaker definition is WSS
  - First order stationary: E[X(t)] is same for all t
  - Second order:
    1) First order stationary and
    2) Cov[X(t),X(t-lag)] is function of only lag

Note: Gaussian processes described by mean & cov

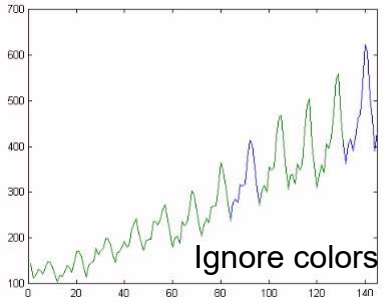
Exploratory analysis

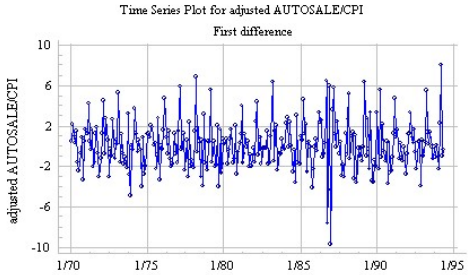


http://www.ryanmcmaken.com/2015/05/chart-of-day-colorado-bankruptcy.html

Constant mean or trend?
Constant variance?
Seasonality?
Outliers?
Cycles?

Which is stationary? Which order?





http://www.es.lancs.ac.uk/cres/captain/dhrdemo.html
https://people.duke.edu/~rnau/411diff.htm

Mathematical idea of stationary

$x(k) = A\cos(wk + u)$ where u is $U(0,\pi)$

Is this stationary?

How would we determine the answer?

Mathematical idea of stationary

x(k) = Acos(wk + u) where u is U(0,π)
Is this stationary?
How would we determine the answer?

E(x|k) = ?

Mathematical idea of stationary

x(k) = Acos(wk + u) where u is U(0,π)
Is this stationary?
How would we determine the answer?

E(x|k) = $\int_0^{\pi} [?]\, f(u) du$ where f(u) = ?

Mathematical idea of stationary

x(k) = Acos(wk + u) where u is U(0,π)
Is this stationary?
How would we determine the answer?

$E(x|k) = \int_0^{\pi} A\cos(wk + u) f(u) du$

$E(x|k) = A \int_0^{\pi} \cos(wk + u) \frac{1}{\pi} du = \frac{-2}{\pi} \sin(wk)$

So what can you conclude?

Mathematical idea of stationary

x(k) = Acos(wk + u) where u is U(0,π)
Is this stationary?
How would we determine the answer?

$E(x|k) = \int_0^{\pi} A\cos(wk + u) f(u) du$

$E(x|k) = \frac{A}{\pi} \int_0^{\pi} \cos(wk + u) 1 du = \frac{-2A}{\pi} \sin(wk)$

E(x|k) depends on k so not stationary

Random Walk