

# Tackling The Challenges of Big Data

## Big Data Systems

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# Tackling The Challenges of Big Data

## Big Data Systems

### Multicore Scalability

#### Introduction

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## Goal: Scalability

- With  $n$  cores, do  $n$  times as much work
- One way to think about multi-core performance
- Limit to scalability: serial sections
- Parallel time:  $P$
- Serial time:  $S$



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## Sharing vs. Partitioning

- One approach to multi-core systems: partitioning
- Advantage: avoids sharing between partitions
- Disadvantage: may be hard to choose a partitioning
- Disadvantage: may require load-balancing



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## Outline

- Hardware: cache coherence
- Cache coherence and scalability
  - Example: implementing a lock
  - Avoiding performance collapse
- Improving scalability by avoiding locks
  - Example: lock-free reads in a stack
  - Generalizing lock-free reads with RCU



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### Big Data Systems

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## Module: Big Data Systems

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# Tackling The Challenges of Big Data

## Module: Big Data Systems

### Topic: Multicore Scalability

Cache coherence

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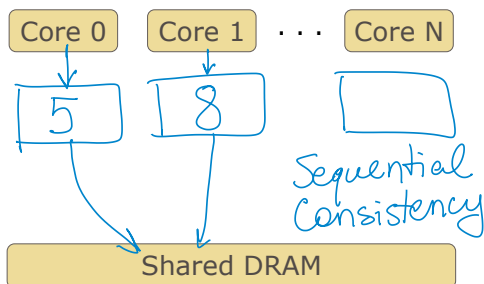
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## Multi-Core Hardware



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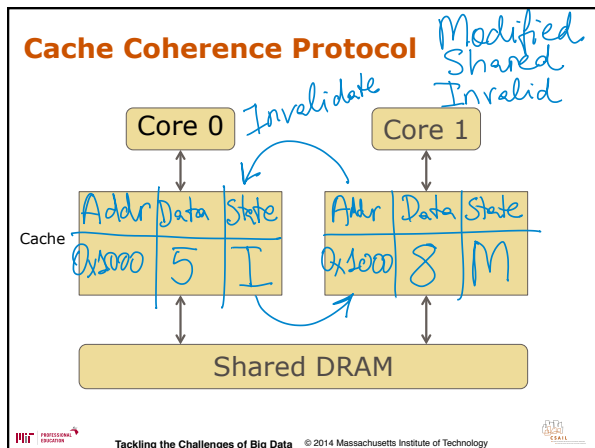
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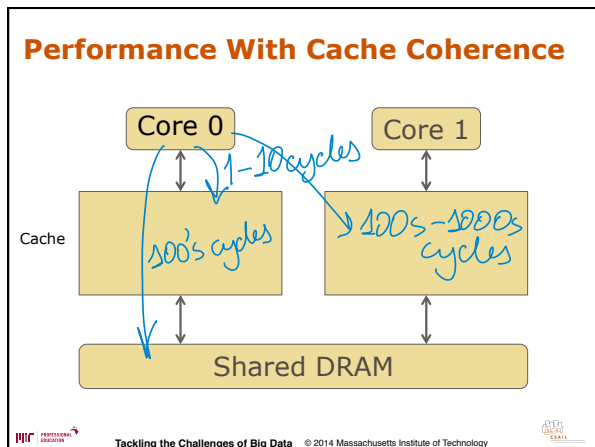
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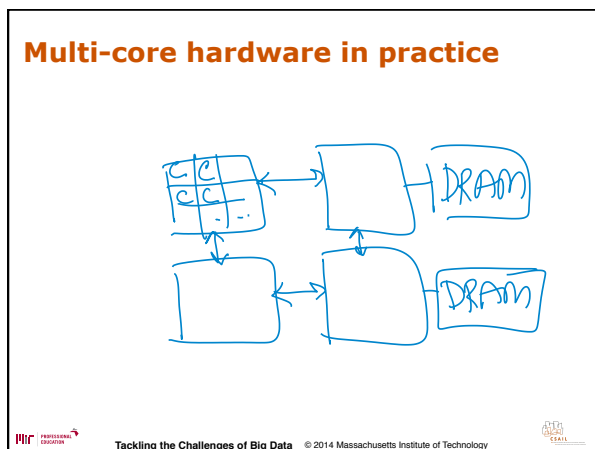
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### Big Data Systems Multicore Scalability

Cache coherence

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## Tackling The Challenges of Big Data

### Big Data Systems Multicore Scalability

Implementing a lock

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## Implementing A Lock

• **acquire(lck):**  
`me = atomic_inc(&lck.last)`  
`while lck.current != me:`  
`pass /* spin */`

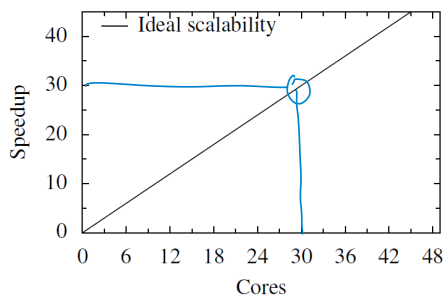
• **release(lck):**  
`lck.current = lck.current + 1`

Ticket  
last current  
lck: 

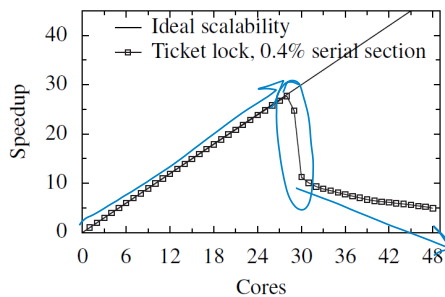
2	1
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Core 0      Core 1  
me=1      me=0  
✓

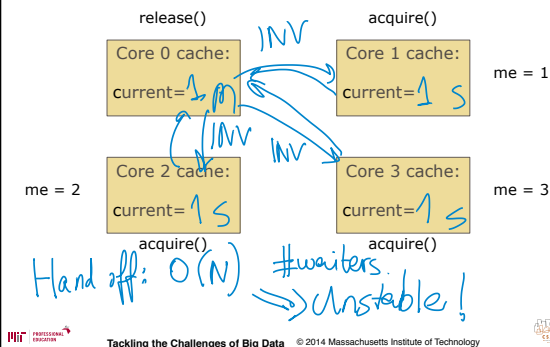
## Performance Of Ticket Locks



## Performance Of Ticket Locks



## Why Do Ticket Locks Collapse?




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### Big Data Systems

### Multicore Scalability

### Implementing a lock

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## Tackling The Challenges of Big Data

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### Non-collapsing locks

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## Avoiding Lock Collapse

### • What's the ideal performance for a contended lock?

- Constant hand-off time: no collapse
- Total performance at best remains flat:  
still have a serial section, so no scalability



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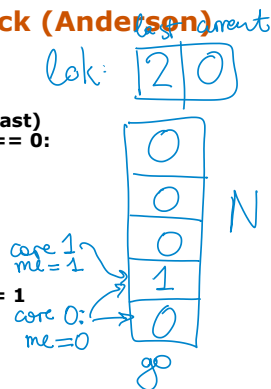
## Non-Collapsing Lock (Anderson)

### • acquire(lck):

```
me = atomic_inc(&lck.last)
while lck.go[me % N] == 0:
    pass /* spin */
lck.current = me
```

### • release(lck):

```
me = lck.current
lck.go[me % N] = 0
lck.go[(me + 1) % N] = 1
```



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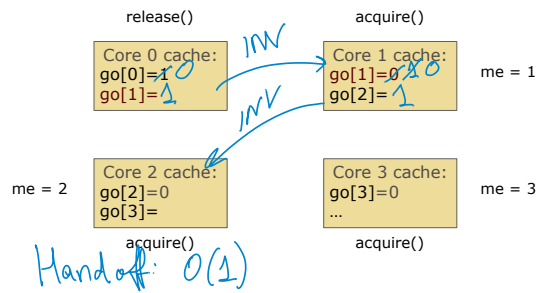
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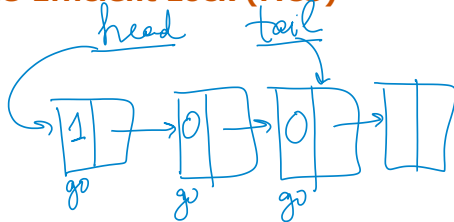


## Non-Collapsing Lock: Cache Coherence



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## Space-Efficient Lock (MCS)



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## Non-Collapsing Locks

- Helps avoid collapse under contention
- Does not improve scalability: serial section remains
- To improve scalability, eliminate contention
  - Fine-grained locks
  - Avoid locks altogether

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Non-collapsing locks

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Lock-free synchronization

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## Example Data Structure: Stack

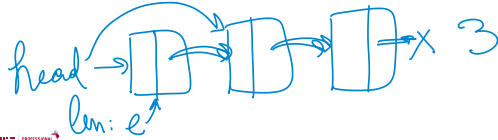
### • length():

```
e = head
while e != NULL:
    i = i + 1
    e = e.next
```

return i

### • pop():

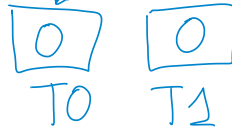
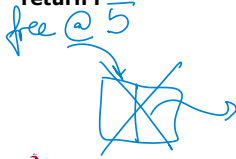
```
e = head
head = e.next
free(e)
```



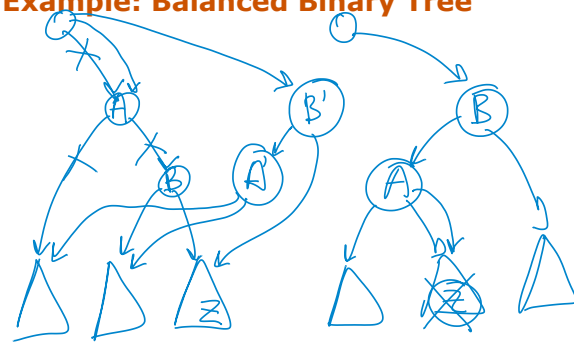
## Epoch-Based Garbage Collection

### • length():

```
thread.gc_epoch = cur_epoch
e = head
while e != NULL:
    i = i + 1
    e = e.next
thread.gc_epoch = 0
return i
```



## Example: Balanced Binary Tree



## RCU Enables Scalable Readers

- **Three rules:**
  - Lock-free readers
  - Single pointer update in writers (update a copy)
  - Delayed free
- **Readers do not modify any shared cache lines**
- **Concurrent readers can execute in private caches**
  - No cache-coherence traffic!
- **Good scalability for read-heavy workloads**



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## Conclusion: Multicore Scalability

- **Cache-coherence protocols in hardware**
- **Lock can collapse due to sharing one cache line**
- **Multiple cache lines help avoid collapse due to a lock**
- **RCU: powerful technique for read-heavy workloads**



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Lock-free synchronization

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