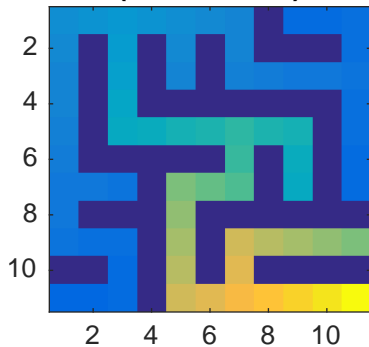
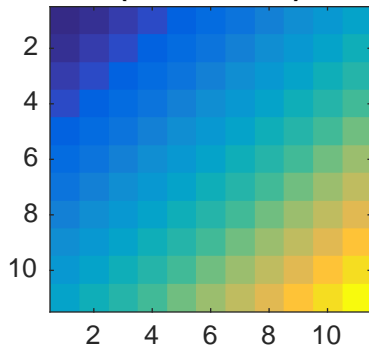


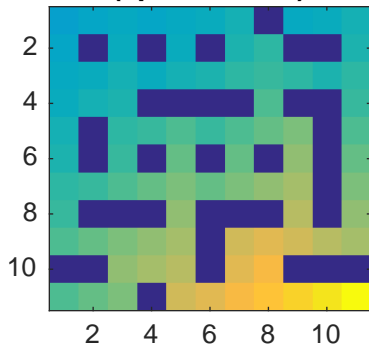
**optimal policy values  
(dense maze)**



**manhattan distance values  
(dense maze)**



**optimal policy values  
(sparse maze)**



**manhattan distance values  
(sparse maze)**

