Group 7 Report
SDP 2014-2015

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1 Abstract

2 Organisation and Management

The model adopted and put into parctice for our team was largely a tiered hierarchial structure with a single official team leader Roy, who was experienced and proficient in electronics and hardware matters, and a lead software developer Chris, as he was most experienced in programming and high level planning. The rest of the members were assigned supportive roles based on their skill and experience.

A private github

3 Hardware

3.1 "Speed is King"

3.2 "The Less Wheels the Better"

3.3 "Building around a Strong Kicker"

4 Software

4.1 Arduino side

4.2 PC side

4.2.1 Vision

4.2.2 Planning

4.2.3 Communication

5 Conclusion

6 Online Resources

The code for the project, presentations, group report, and photographs of our robot(s) are available at our *public TODO* github account at `https://github.com/ChrstSea/sdp`.

The trello board with evidence of our workflow is available on `https://trello.com/b/0zOyrwQd/lucky-strike-7`.